

Mathematical model for the concentration and electric potential profiles in a solution of electrolytes under a redox reaction

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Diffusion Of Electrolytes In Aqueous Solution

Steady State Solution

Dynamic solution

Diffusion Of Electrolytes In Aqueous Solution

Diffusion equation with external electric field

- The problem of diffusion

$$\frac{\partial C_s}{\partial t}(x, t) + \nabla \cdot \mathbf{N}_s(x, t) = 0.$$

- Electric potential due to charge distribution (electrolytes)

$$\nabla^2 \phi = -\frac{\rho(x, t)}{\epsilon \epsilon_0}.$$

Here ϵ is water's permittivity and ϵ_0 the permittivity of free space.
 $s = \pm$.

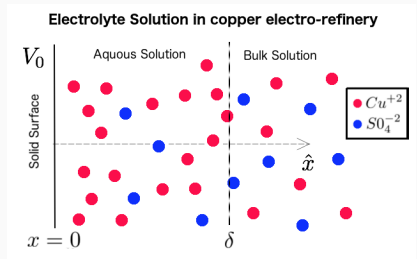


Figure 1

Mathematical model of the flux

Model for the flux of electrolyte

$$\mathbf{N}_s = -D_s \left(\nabla \cdot C_s(x)_+ + s \frac{zF}{RT} C_s(x) \nabla \phi(x) \right)$$

It is convenient to work with the dimensionless potential $\Psi = \frac{zF}{RT} \phi$

$$\mathbf{N}_s = -D_s (\nabla \cdot C_s(x)_+ + s C_s(x) \nabla \Psi(x))$$

The charge distribution is given by the concentration of each electrolyte on every point of the solution times its electrical charge.

$$\rho(x, t) = \sum_{s=\pm} s z F C_s(x, t)$$

Mathematical model of the system

Dimensionless length parameter $\xi = \kappa x$ Infinitely large plate implies

$$\nabla_{\xi}^2 \rightarrow \frac{\partial^2}{\partial \xi^2}$$

. With these considerations, the equations take the form

$$\frac{\partial C_+}{\partial t}(\xi, t) = -D_+ \nabla^2 C_s(\xi) - \nabla(C_+(\xi) \nabla \Psi(\xi, t)), \quad (1)$$

$$\frac{\partial C_-}{\partial t}(\xi, t) = -D_- \nabla^2 C_s(\xi) + \nabla(C_-(\xi) \nabla \Psi(\xi, t)), \quad (2)$$

$$\frac{\partial^2 \Psi(\xi, t)}{\partial \xi^2} = -\frac{\kappa^2}{C_b} (C_+(\xi, t) - C_-(\xi, t)). \quad (3)$$

where $\kappa^2 = \frac{(zFC_b)^2}{RT \epsilon_r \epsilon_0}$ and C_b the bulk concentration.

Border conditions

The border conditions for this problem can be obtained looking at figure 2

- $(\partial C_+ / \partial t + \nabla \cdot \mathbf{N}_+) |_{interface} = r,$
- $(\partial C_- / \partial t + \nabla \cdot \mathbf{N}_-) |_{interface} = 0,$
- $C_+ = C_- = C_b,$
- $\Phi(0) = \frac{zFV_0}{RT} = \Phi_0 ,$
- $\Phi(\delta) = 0 .$

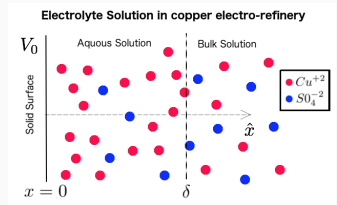


Figure 2

Steady State Solution

Steady state approach

As a first approach to solving the system, we compute the steady state solution.

$$\frac{\partial C_+}{\partial t}(\xi, t) = 0 \Rightarrow \nabla \cdot \mathbf{N}_+ = 0 \quad \Rightarrow \mathbf{N}_+(\xi)|_{\text{surface}} = r, \quad (4)$$

$$\frac{\partial C_-}{\partial t}(\xi, t) = 0 \Rightarrow \nabla \cdot \mathbf{N}_- = 0 \quad \Rightarrow \mathbf{N}_-(\xi)|_{\text{surface}} = r, \quad (5)$$

which yields the following system of equations for the steady state problem

$$\nabla C_+(\xi) - C_+(\xi) \nabla \Psi(\xi) = r, \quad (6)$$

$$C_-(\xi) + C_-(\xi) \nabla \Psi(\xi) = 0, \quad (7)$$

$$\nabla^2 \Psi(\xi) = -\kappa^2 (C_+(\xi) - C_-(\xi)). \quad (8)$$

Perturbation solution of the system

By means of a perturbation analysis with r as a control parameter we obtain solve the previous system up to first order in r . The zero order solution is

$$\Phi^{(0)}(\xi) = 2 \log \left(\tanh \left(\frac{\xi - \xi_0}{2} \right) \right), \quad (9)$$

Where

$$C_s^{(0)}(x) = C_{b,s} e^{s\Phi^{(0)}(x)}$$

Perturbative solution of the system

In order to solve the system to first order in r , the following approximation was made.

$$\left| \frac{\partial \phi^{(1)}}{\partial x} \right| \ll \frac{\kappa V_0}{r}, \quad (10)$$

Which yields

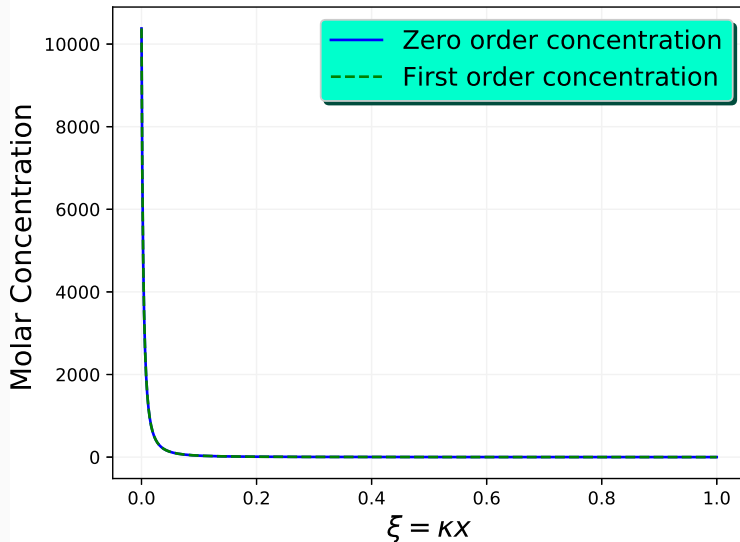
$$C_+^{(1)}(\xi) = -\frac{1}{\kappa} e^{-\Phi^{(0)}(\xi)} \left(\xi - 2 \left(\tanh \left(\frac{\xi - \xi_0}{2} \right) + \tanh \left(\frac{\xi_0}{2} \right) \right) \right),$$

and

$$C_-^{(1)}(\xi) = 0. \quad (11)$$

Analytic results for the concentration

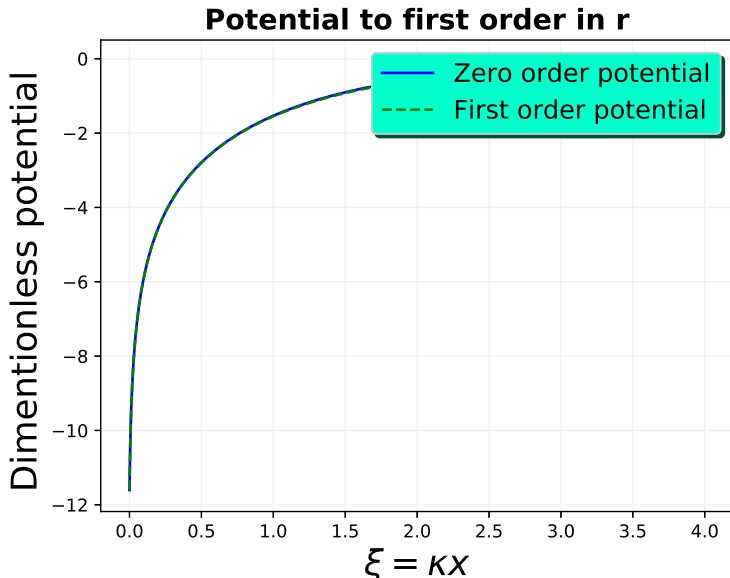
Analytic concentration to zero and first order in r



The first order term in the potential expansion is

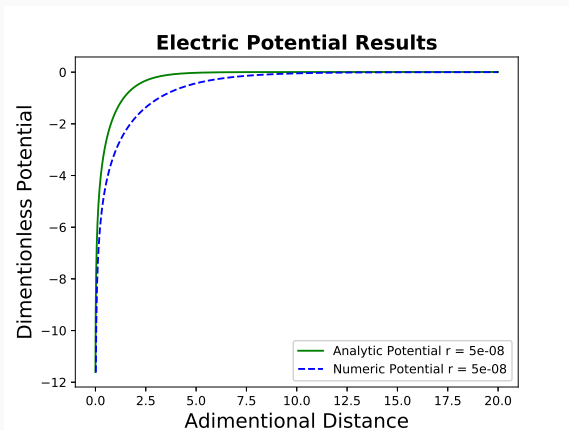
$$\begin{aligned}\Phi'^{(1)}(\xi) &= \frac{1}{\kappa} \left(\frac{1}{2} \xi^2 - 2\gamma\xi + 2(2\gamma - \xi) \coth \left(\frac{\xi - \xi_0}{2} \right) \right) + C \\ C &= -\frac{1}{\kappa} \left(\frac{1}{2} \xi_\delta^2 - 2\gamma\xi_\delta + 2(2\gamma - \xi_\delta) \coth \left(\frac{\xi_\delta - \xi_0}{2} \right) \right) .\end{aligned}$$

Analytic results for the potential



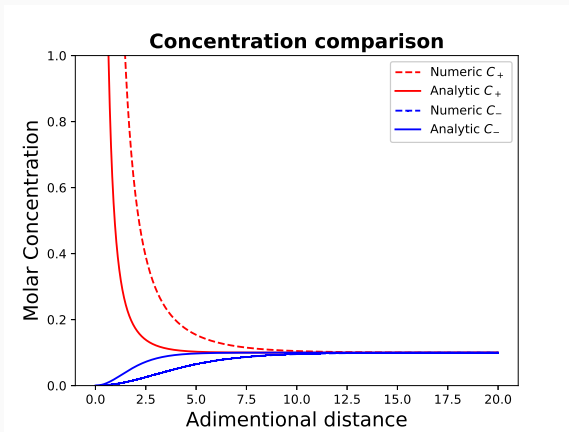
Numeric Results

For numeric computation the Runge-Kutta of fourth order was used. The following graph shows a comparison between the numeric and analytic system for $r = \kappa \times 10^{-5} \approx 2.28$.



Numeric Results

The following graph shows a comparison between the numeric and analytic concentrations.



Dynamic solution

Stage of the project

We are currently working on solving the complete problem, including the dynamics.

$$\frac{\partial C_+}{\partial t}(\xi, t) = -D_+ \nabla^2 C_s(\xi) - \nabla(C_+(\xi) \nabla \Psi(\xi, t)), \quad (12)$$

$$\frac{\partial C_-}{\partial t}(\xi, t) = -D_- \nabla^2 C_s(\xi) + \nabla(C_-(\xi) \nabla \Psi(\xi, t)), \quad (13)$$

$$\frac{\partial^2 \Psi(\xi, t)}{\partial \xi^2} = -\frac{\kappa^2}{C_b} (C_+(\xi, t) - C_-(\xi, t)). \quad (14)$$

To-do list

1. Finish numerical computation of the dynamical system
2. Include stochastic reaction rate to measure noise
3. Couple to NV-center.