Dynamics with precision 3 and 5 time points: 5 best solutions 2.0 1.5 1.0 0.5 - $\langle \sigma_z \rangle$ 0.0 --0.5QuTiP (baseline) Gap: 0.00% -1.0Gap: 0.14% Gap: 0.29% -1.5Gap: 0.43% Gap: 0.58% 0.0 1.0 1.5 2.5 3.0 0.5 3.5 2.0 4.0 Time t