

Browser tabs: (29) WhatsApp, Home - Google Drive, Untitled1.ipynb - Colaboratory

Address bar: colab.research.google.com/drive/1LLu\_hx1TjdH4JTCKOA5KIFIMONC2wSk#scrollTo=CGgGJGokmaA

Colaboratory interface: Untitled1.ipynb

Menu: File Edit View Insert Runtime Tools Help All changes saved

RAM: 100% Disk: 100% Colab AI

```
[1] from sklearn.datasets import load_iris
import numpy as np
import matplotlib.pyplot as plt
%matplotlib inline

[2] # flowers dataset tes of three different species of the flowers
iris = load_iris()
print(iris.feature_names)

['sepal length (cm)', 'sepal width (cm)', 'petal length (cm)', 'petal width (cm)']

[3] # three classes of flowers
print(iris.target_names)

['setosa' 'versicolor' 'virginica']

[4] # features
x = iris.data
#labels
y = iris.target
print(x.shape,y.shape)
#150 rows with 4 columns

(150, 4) (150,)
```

[5] x[:5]

0s completed at 22:57

System tray: 28°C Sunny, Search, ENG IN, 22:59, 17-03-2024

Google

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0s

[5] x[:5]

array([[5.1, 3.5, 1.4, 0.2],  
[4.9, 3. , 1.4, 0.2],  
[4.7, 3.2, 1.3, 0.2],  
[4.6, 3.1, 1.5, 0.2],  
[5. , 3.6, 1.4, 0.2]])

0s

[6] y[:5]

array([0, 0, 0, 0, 0])

0s

np.unique(y)

array([0, 1, 2])

0s

[9] # create the boolean mask which gives the all flowers  
mask = np.where((y==0) | (y==1))  
x = x[mask][:,[0,2]]  
y = y[mask]

0s

[10] print(np.unique(y))

[0 1]

0s

[11] print(x.shape,y.shape)

0s completed at 22:57

28°C Sunny

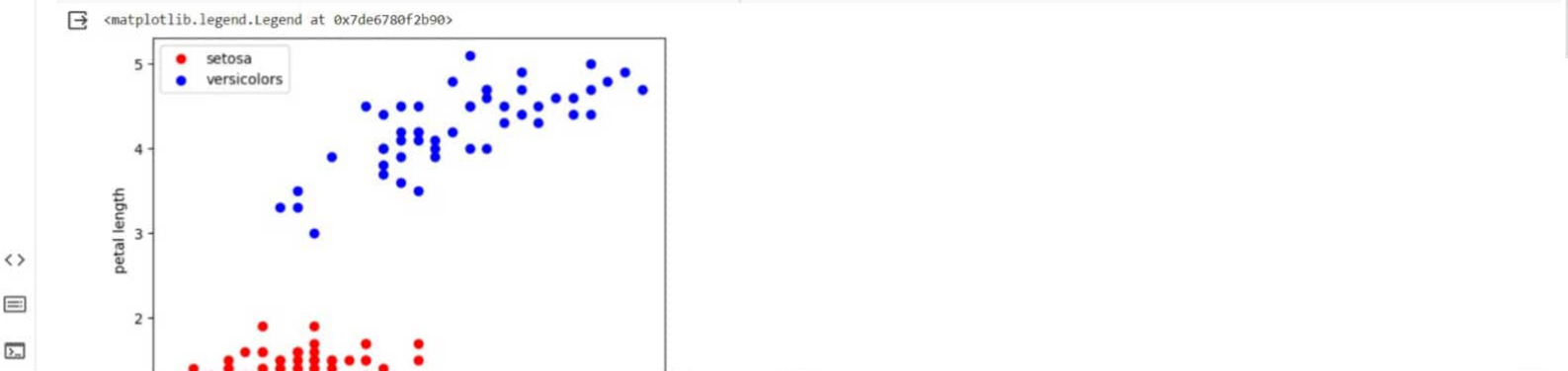
Search

ENG IN

23:00 17-03-2024

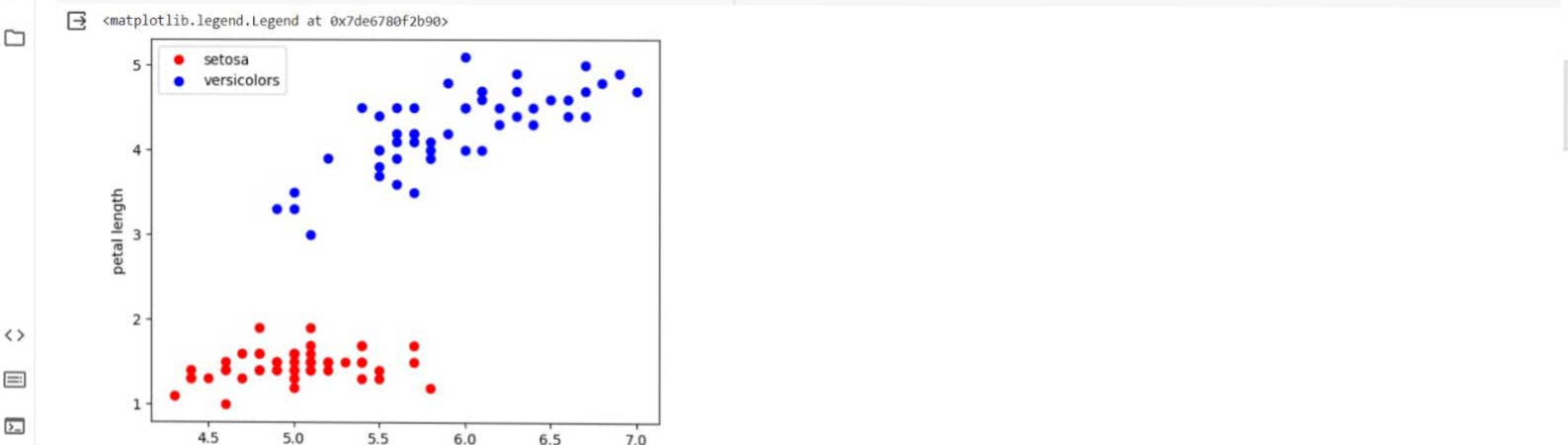
```
[12] setosas = x[np.where(y==0)]  
versicolors = x[np.where(y==1)]
```

```
# linearly separable data  
plt.scatter(setosas[:,0],setosas[:,1],color = 'r',label='setosa')  
plt.scatter(versicolors[:,0],versicolors[:,1],color = 'b',label='versicolors')  
plt.xlabel('sepal length')  
plt.ylabel('petal length')  
plt.legend()
```



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```
# linearly separable data
plt.scatter(setosas[:,0],setosas[:,1],color = 'r',label='setosa')
plt.scatter(versicolors[:,0],versicolors[:,1],color = 'b',label='versicolors')
plt.xlabel('sepal length')
plt.ylabel('petal length')
plt.legend()
```



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Colab interface: Untitled1.ipynb

Code editor content:

```
[14] print(x.shape,y.shape)

(100, 2) (100,)
```

```
import sys

class Perceptron(object):

    def __init__(self,input_dim):
        self.weights = np.random.normal(loc=0.0,scale=1.0,size=input_dim)
        self.bias = np.random.normal(loc= 0.0,scale =1.0,size=1)

    def activation(self,pred):
        return np.where(pred>=0,1,0)

    def predict(self,data):
        return self.activation(np.dot(data,self.weights.T))

    def train(self,input_data,targets,epochs,lr=0.01):
        losses = []
        for e in range(1,epochs + 1):
            epoch_loss = 0
            for data, target in zip(input_data,targets):
                pred = self.predict(data)
                error = target - pred
                update = lr * error
                epoch_loss += error ** 2
```

Status: 0s completed at 22:57

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Google Colaboratory interface showing a Jupyter Notebook titled "Untitled1.ipynb". The browser address bar shows the Google Drive link: [colab.research.google.com/drive/1LLu\\_hx1TjdH4JTCKOA5KIFIMONC2wSk#scrollTo=CGgG/GokcmaA](https://colab.research.google.com/drive/1LLu_hx1TjdH4JTCKOA5KIFIMONC2wSk#scrollTo=CGgG/GokcmaA).

The notebook contains three code cells:

```
[31] def train(self,input_data,targets,epochs,lr=0.01):
      losses = []
      for e in range(1,epochs + 1):
          epoch_loss = 0
          for data, target in zip(input_data,targets):
              pred = self.predict(data)
              error = target - pred
              update = lr * error
              epoch_loss += error ** 2
              self.weights += update * data
              self.bias += update
          losses.append(epoch_loss)

      print(f"\rEpoch {e} / {epochs}, Loss: {epoch_loss}",end="")
      sys.stdout.flush()

      return losses
```

```
[32] p = Perceptron(input_dim=2)
      losses = p.train(x,y ,epochs = 50)

      Epoch 50 / 50, Loss: 25
```

```
[36] print(p.weights,p.bias)

[0. 0.] [-13.68894092]
```

The interface includes a menu bar (File, Edit, View, Insert, Runtime, Tools, Help), a toolbar with icons for RAM, Disk, Colab AI, and user profile, and a left sidebar with navigation icons.