

ICESC-2020

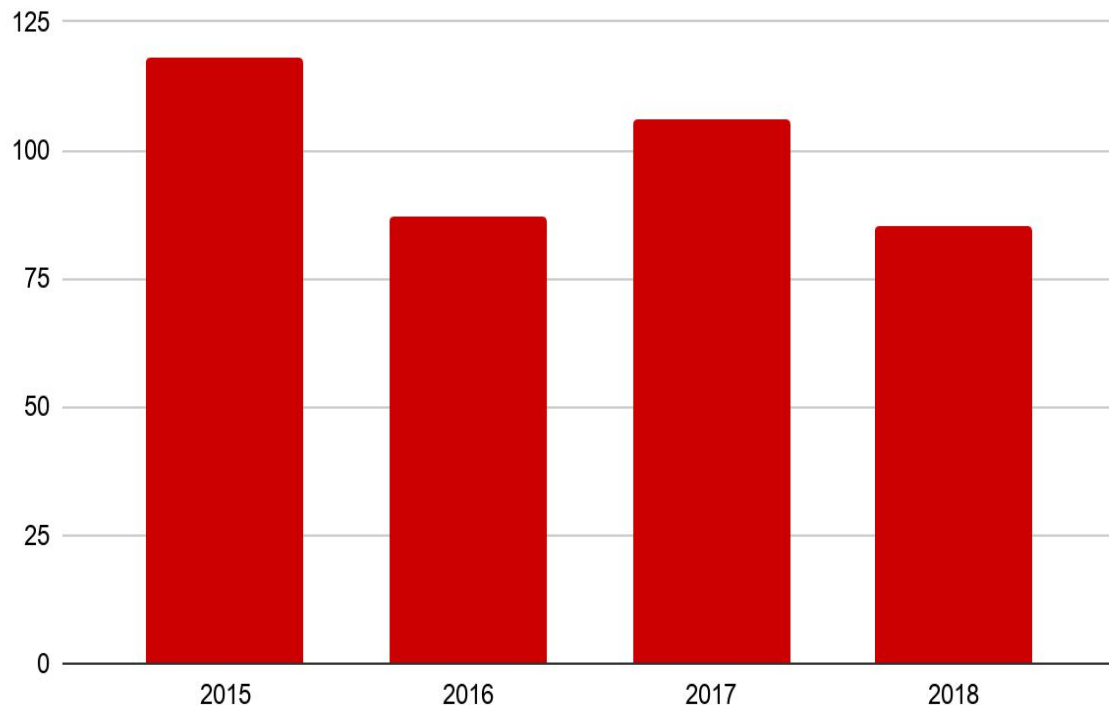
Indoor Fire Localisation using WSN and Fire Map Generation for Industrial Environment

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Introduction - Industrial Fire

- Industrial Fire kills more than 6,000 people in India every year.
- In Maharashtra alone there were ~350 major fire accidents in last four years.

Industrial Fire Accidents - Maharashtra



SOURCE: MAHARASHTRA DIRECTORATE OF INDUSTRIAL SAFETY AND HEALTH

Related Work

Fire Detection -

1. *Lim, Yeon-sup, et al. "A fire detection and rescue support framework with wireless sensor networks." 2007 International Conference on Convergence Information Technology (ICCIT 2007). IEEE, 2007*
- Primary focus is on Fire detection and escape system using Wireless sensor Network for indoor environment

Fire Localization -

2. *Azmil, Muhammad Salihin Ahmad, et al. "Wireless fire detection monitoring system for fire and rescue application." 2015 IEEE 11th International Colloquium on Signal Processing & Its Applications (CSPA). IEEE, 2015.*
- Utilized smoke sensor along side vision sensor for fire detection and localisation in industrial environment.

Objective



For Class A,B,C,D Fire types

Proposed System



Fig.- Overview of the system

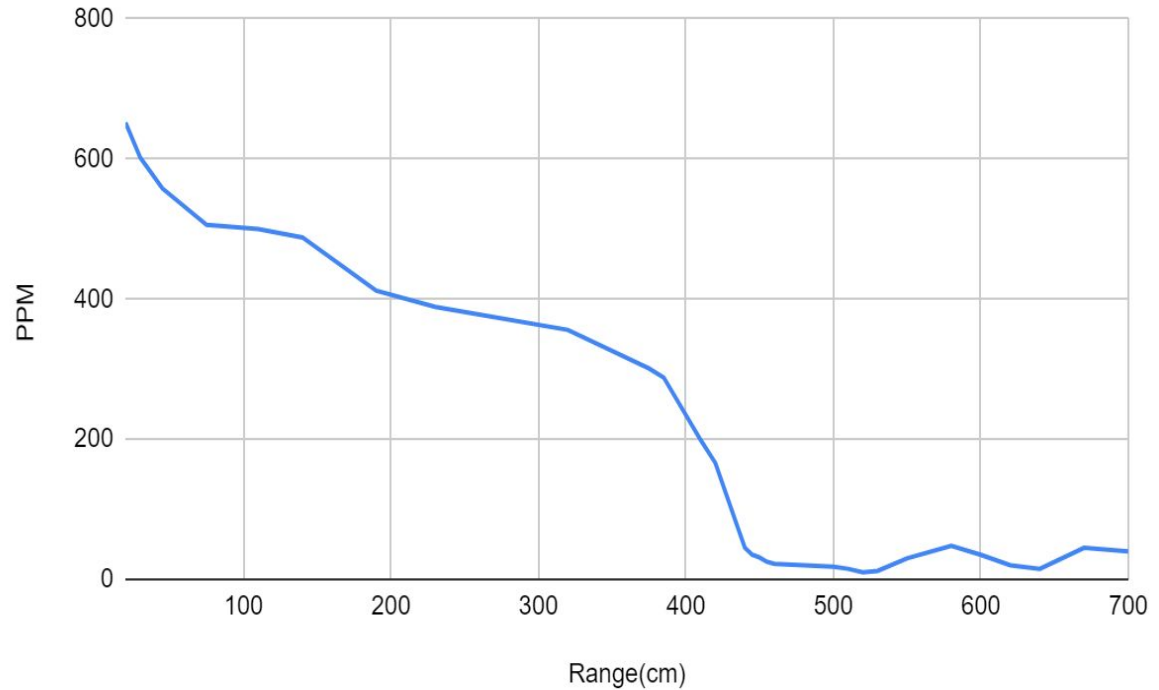
Fire Detection

Smoke Sensor:
MQ - 2

High Sensitivity
and Low Directivity

Effective Range:
~4 - 4.5 meters

PPM vs. Range



Fire Localization

IR Temperature
Sensor:
MLX90614ESF-A

High Accuracy and
Non Contact

Effective Range:
~1.3 - 1.5 meters

Distance from the fire source (m)	Temperature Sensor (°C)	Thermometer (°C) At 10 cm from Fire Source	Error
0.1	72	73	-1
0.3	74	73	+1
0.5	72	74	-2
0.7	70	73	-3
1.0	71.5	74	-2.5
1.3	71	75	4
1.5	71.5	77	5.5
1.7	68.5	76	7.5

Unit Wireless Node Structure

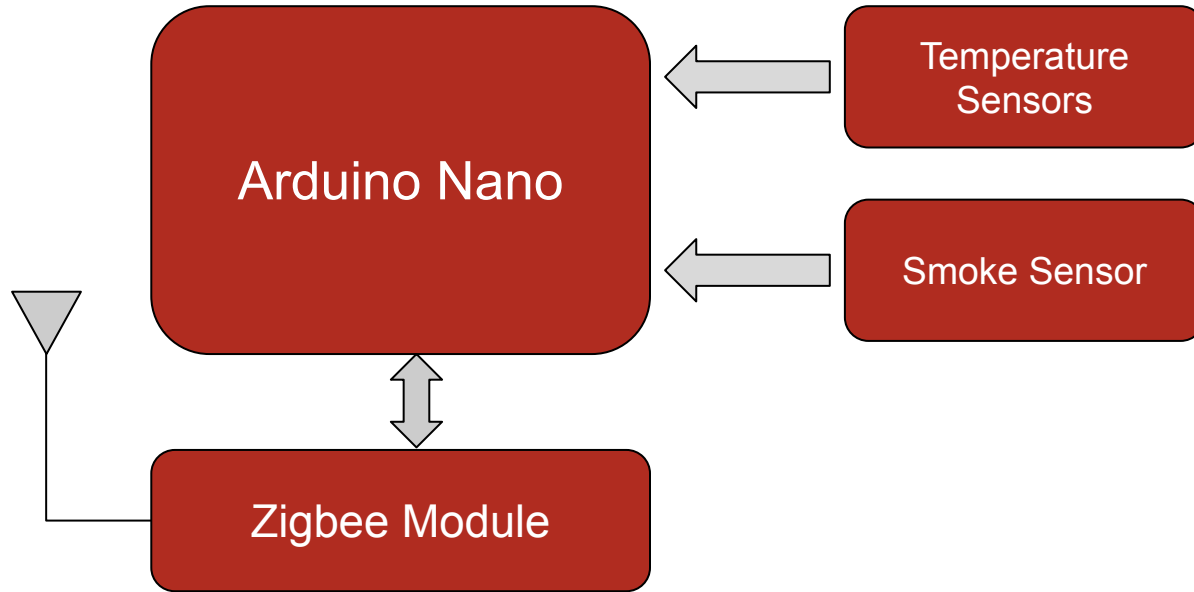
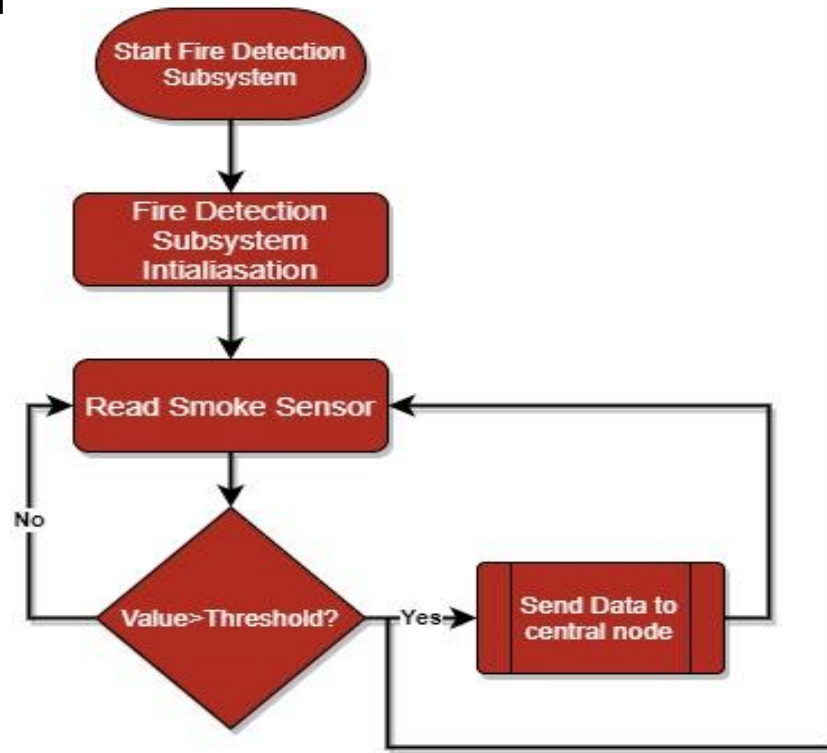
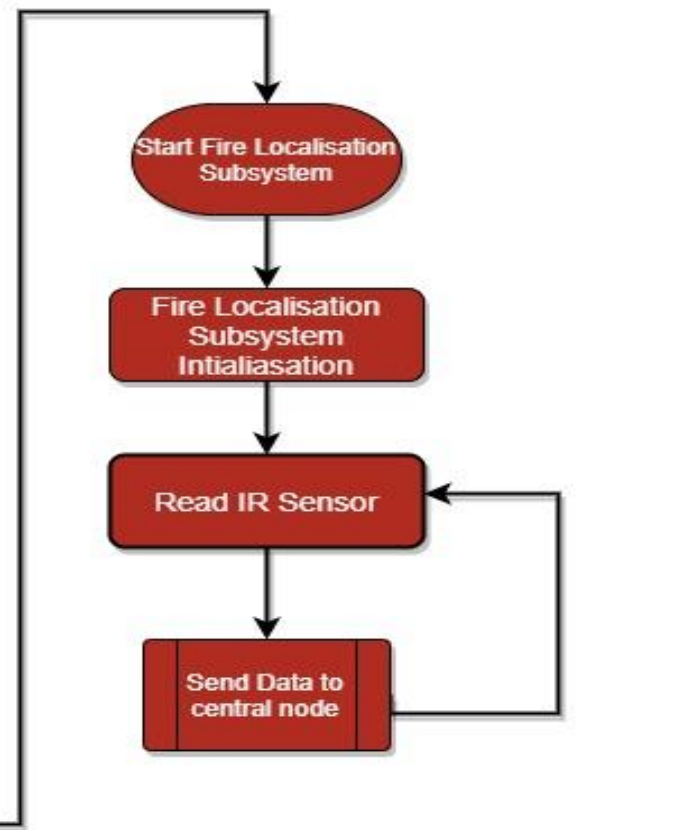


Fig.-Block diagram of wireless node

Fire Localisation and Detection Sub-System



Fire Detection Subsystem

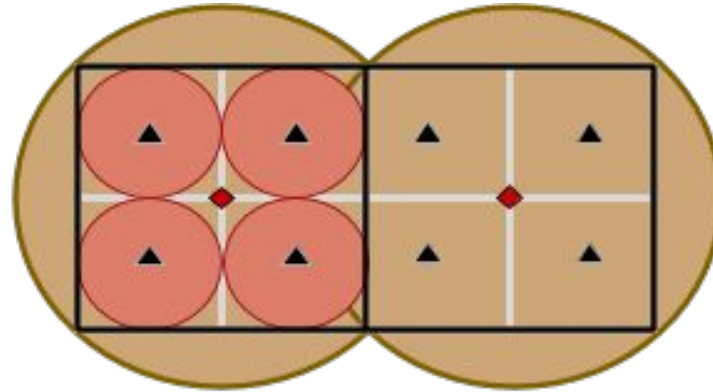


Fire Localisation Subsystem

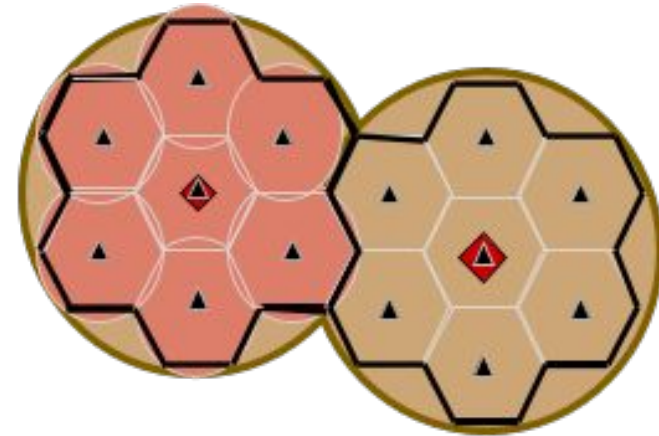
Pod Configurations

Design Characteristics -

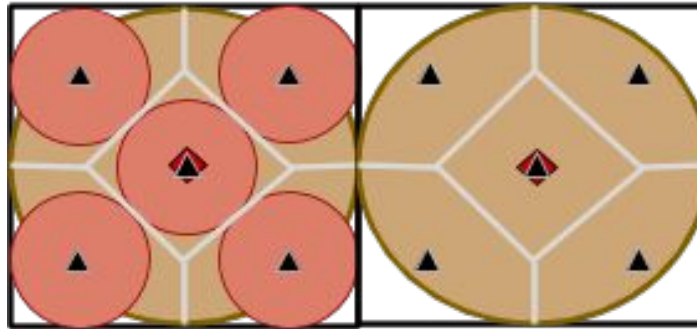
1. No. of Sensors per Pod
2. Scalability
3. Percentage of Detection Area
4. Percentage of Localisation Area



Configuration A



Configuration C

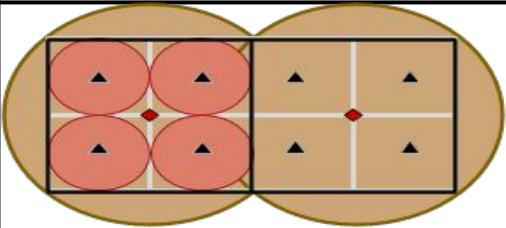
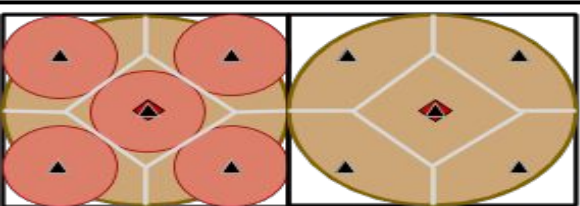
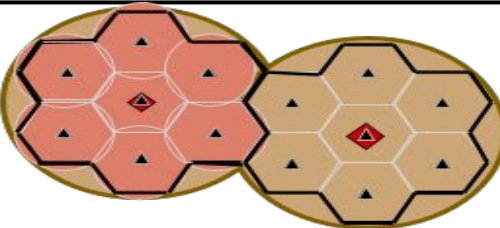


Configuration B

	Pod boundary
	Area covered by IR sensor
	Area covered by smoke sensor
	IR Sensor(~1.5m)
	Smoke Sensor(~4m)

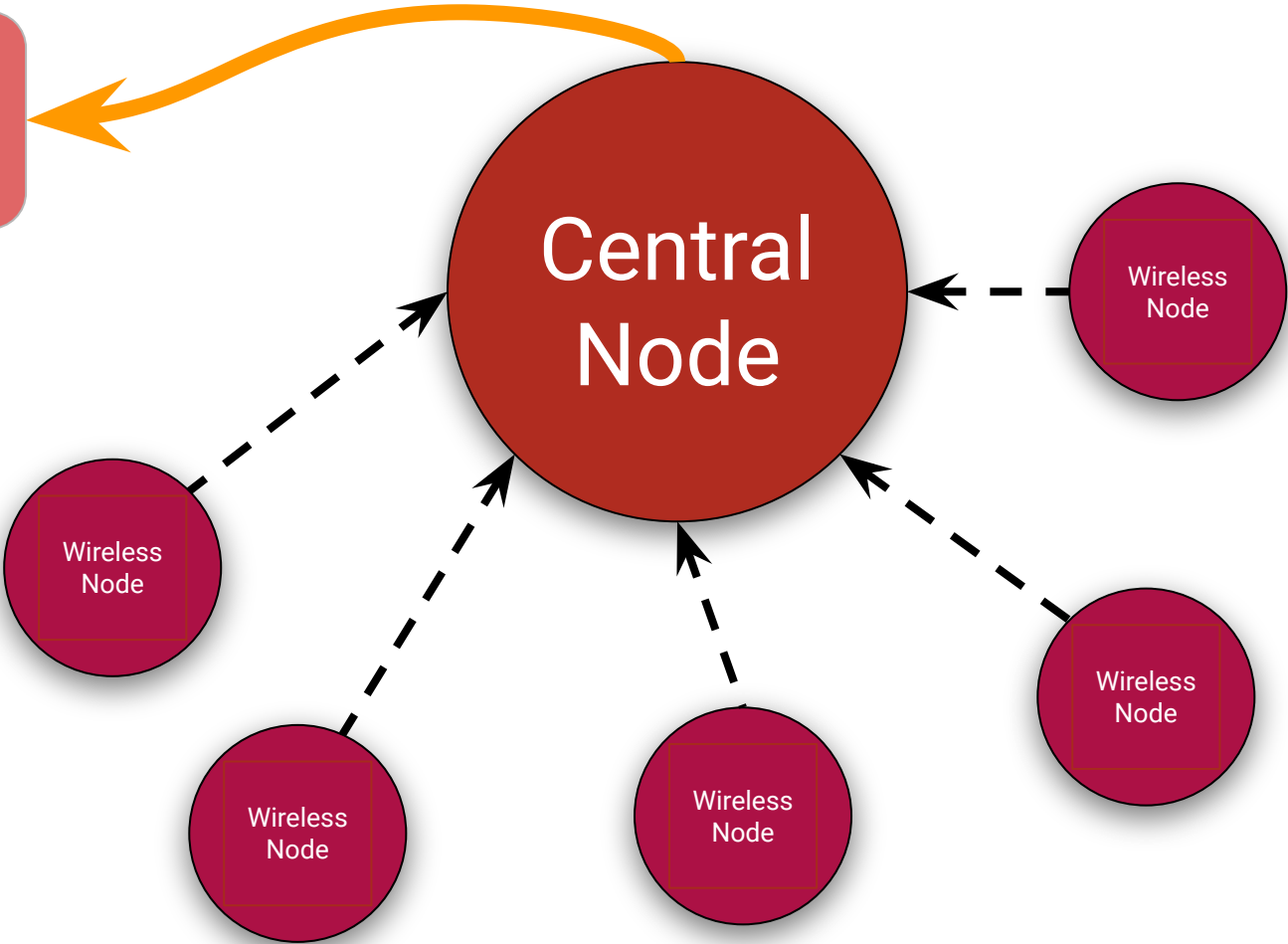
Result Analysis

		Value
1	Floor Area	400m ²
2	Smoke Sensor Radius	4 m
3	Area Covered by Smoke Sensor	50.26 m ²
4	IR Temperature Sensor Radius	1.5 m
5	Area Covered by IR Temperature Sensor	7.06 m ²

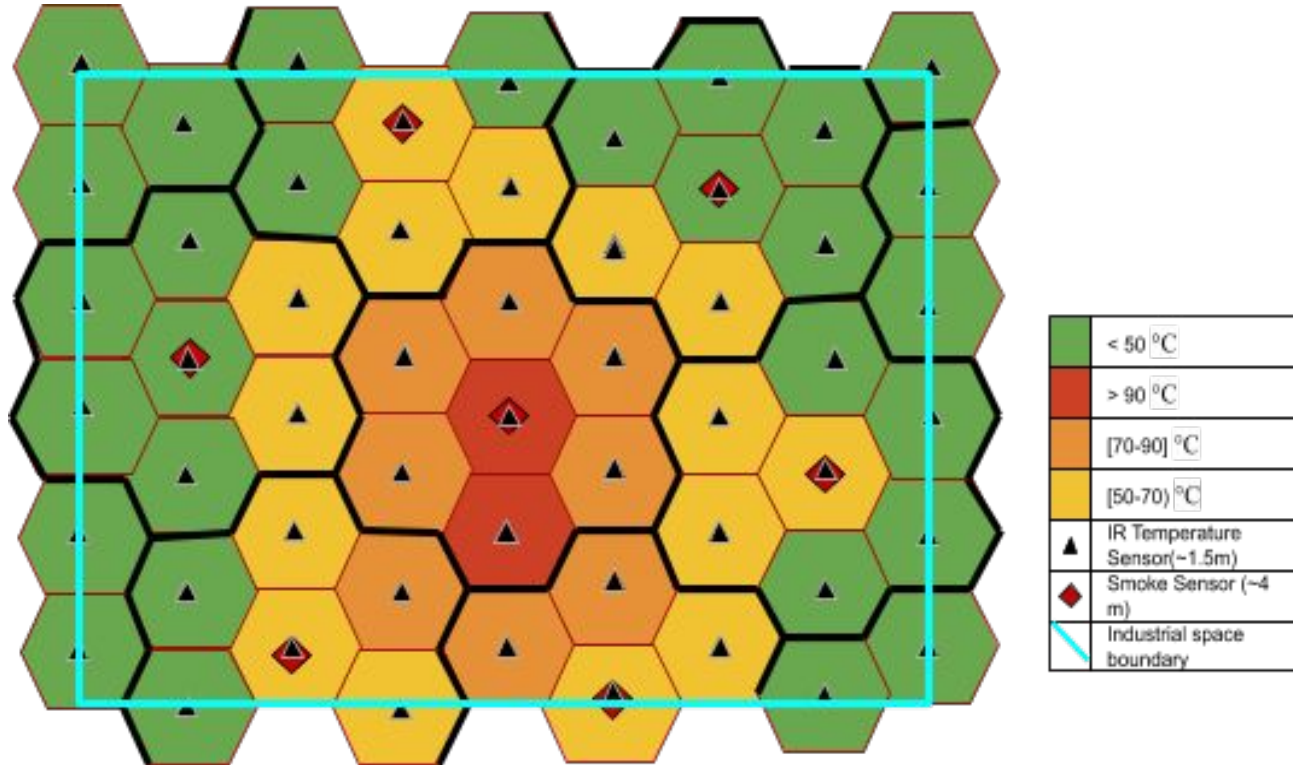
Configuration	 <p>Configuration A</p>	 <p>Configuration B</p>	 <p>Configuration C</p>
Area of Cell(m ²)	8	16	5.8
No. of Cells in Pod	4	5	7
Area of Pod(m ²)	32	64	41
No. of IR Sensors	50	31	69
No. of Smoke Sensors	13	7	10
Total Sensor	63	38	79
Detection %	100	78.5	100
Localisation %	87.5	55.1	100
Use Case	Large Factories	Small to medium size enterprise factories	Critical facilities: Nuclear facilities, Ordnance factories



Fire Monitoring



Fire Map



Thank You