(12/04/2020)

The meeting started at 9:00am. Swapnil Mane started with the presentation and gave a overall review of the project work. He explained kinematic analysis process that is put into use in our project, specifically focussing on the Jacobian inverse technique, moving on to the gripper cad model. This was followed by some very useful suggestions and guidelines explained via presentation given by Atharva sir . Few of the major points mentioned were: to deal with the unplanned movements of the human hand that will be copied by the robotic arm(ex:sneezing); two way communication instead of one way communication between the robotic arm and human hand. Many other things were discussed like the software to be used, the resources.

The immediate work to be done was get linked via github account(all, Aditya sir) ;to submit a list of distribution of responsibilities among members(Parth) .