

# Applied Maths III Lec 6

## Method of Steepest Descents / Saddle point approximation

In last lecture, we introduced  $\Gamma(x)$ , and Stirling's Approximation for approximating  $\Gamma(x)$  when  $|x| \rightarrow \infty$ . This lecture we will begin by introducing few more Approximation method for evaluating (Contour) integrals.

### "Quick and Dirty Revisit of Stirling's Approximation"

Recall the integral representation of  $\Gamma(x)$

$$\Gamma(x+1) = \int_0^\infty dt t^x e^{-t} \quad \text{Restrict } x \text{ to } \mathbb{R}^+$$

Performing change of variable  $t = s^x$

$$\begin{aligned} \sim \Gamma(x+1) &= x^{x+1} \int_0^\infty ds s^x \exp(-s^x) = x^{x+1} \int_0^\infty ds \exp(x(\log s - s)) \\ &= x^{x+1} \int_0^\infty ds \exp(x\phi(s)), \quad \phi(s) = \log s - s \sim s \text{ variable} \end{aligned}$$

Now if  $x \gg 1$ , the integrand  $\Gamma(x+1)$  is dominated by the maximum of  $\phi(s)$

$$\begin{aligned} \Rightarrow \phi'(s) &= \frac{1}{s} - 1, \quad \phi'(1) = 0 \quad \rightarrow \text{Maximum} \\ \phi''(s) &= -\frac{1}{s^2}, \quad \phi''(1) = -1 < 0 \\ \phi'''(s) &= \frac{2}{s^3}, \quad \phi'''(1) = 2 \end{aligned}$$

Expanding around  $s=1$ ,

$$\phi(s) = \phi(1) + (s-1)\phi'(1) + \frac{(s-1)^2}{2}\phi''(1) + \dots = -1 - \frac{(s-1)^2}{2} + \frac{2}{3}(s-1)^3 + \dots$$

-ve - needed for convergence

Extremum

$$\text{Let } u = s-1, \quad \Gamma(x+1) = x^{x+1} \int_{-1}^{\infty} du \exp(x(-1 - \frac{u^2}{2} + \dots))$$

Need to deal with

$$\int_{-1}^{\infty} du \exp(x(-u^2/2 + \dots)) \quad (u = s-i)$$

Two assumptions (to be justified later)

→ See later session

1 Dropping  $u^3$  and higher power → Suppressed by  $1/x$

2  $\int_{-1}^{\infty} \rightarrow \int_{-\infty}^{\infty} = \int_{-1}^{\infty} + \int_{-\infty}^{-1}$  → increasing the integration range

$$\sim \int_{-1}^{\infty} du \exp(x(-u^2/2 + \dots)) \rightarrow \int_{-\infty}^{\infty} du \exp(-xu^2/2) = \sqrt{\frac{2\pi}{x}}$$

$$\Rightarrow \Gamma(x+1) \simeq x^{x+1/2} e^{-x} \sqrt{2\pi} \sim \text{Stirling's Approx}$$

$$(\log \Gamma(x+1) \simeq (x+1-1/2) \log x - x + 1/2 \log 2\pi)$$

Some words abt 2nd assumption

$$\begin{aligned} \int_{-1}^{\infty} du \exp(-xu^2/2) &= \sqrt{\frac{2}{x}} \int_{-\sqrt{\frac{x}{2}}}^{\infty} dy \exp(-y^2) = \sqrt{\frac{2}{x}} \left\{ \frac{\sqrt{\pi}}{2} (1 - \operatorname{erf}(-\sqrt{\frac{x}{2}})) \right\} \\ &= \sqrt{\frac{\pi}{2x}} (1 + \operatorname{erf}(\sqrt{\frac{x}{2}})) = \sqrt{\frac{\pi}{2x}} (2 + \operatorname{erf}(\sqrt{\frac{x}{2}}) - 1) = \sqrt{\frac{2\pi}{x}} + \sqrt{\frac{\pi}{2x}} (\operatorname{erf}(\sqrt{\frac{x}{2}}) - 1) \end{aligned}$$

$$\operatorname{erf}(z) = \frac{2}{\sqrt{\pi}} \int_0^z dt e^{-t^2} \sim \text{error function}$$

For large  $z$

$$1 - \operatorname{erf}(z) = \frac{e^{-z^2}}{z\sqrt{\pi}} \sum_{l=0}^{\infty} (-1)^l \frac{(2l-1)!!}{(2z^2)^l}, \quad (2l-1)!! = 1 \cdot 3 \cdot 5 \cdots (2l-1) \quad (2l-1)$$

⇒ Corrections are suppressed by  $\frac{e^{-x/2}}{x}$  factor

## More General Analysis / Laplace's Method

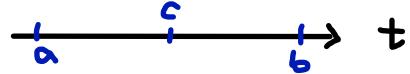
The "quick & dirty" derivation of Stirling's approx is a special case of so-called **Laplace's method** for dealing with integrals of the form

Type

$$I(x) = \int_a^b dt f(t) e^{x\phi(t)} \quad , a, b \in \mathbb{R} \quad , x \gg 0$$

Three Steps for analyzing these

① If  $\phi(t)$  has maximum at  $t=c$ , then only the neighborhood of  $c$  contribute (Assuming  $a < c < b$ )



$$I(x) \simeq \int_{c-\epsilon}^{c+\epsilon} dt f(t) e^{x\phi(t)} \quad , \epsilon \sim \text{small \& tve}$$

→ classic example Path integral

② Expanding  $f(t)$  and  $\phi(t)$  around  $t=c$ , obtaining a series of integrals

③ Extending the integration range so we can obtain Gaussian integral which we can perform

$$f(t) \simeq f(c) + (t-c) f'(c) + \frac{(t-c)^2}{2} f''(c) +$$

$$\phi(t) \simeq \phi(c) + (t-c) \cancel{f'(c)} + \frac{(t-c)^2}{2} \phi''(c) +$$

↑ Negative

Leading contribution (  $a \rightarrow -\infty, b \rightarrow +\infty$  )

$$I(x) \simeq \int_{-\infty}^{\infty} dt f(c) \exp(x(\phi(c) + \frac{1}{2}\phi''(c)(t-c)^2))$$

$$= f(c) \exp(x\phi(c)) \int_{-\infty}^{\infty} dt \exp(-x|\phi''(c)|\frac{(t-c)^2}{2})$$

$$= f(c) \exp(x\phi(c)) \sqrt{\frac{2\pi}{|\phi''(c)|}} \frac{1}{x^{1/2}} \sim \text{Large } x \text{ approx of } I(x)$$

If we want the higher order corrections, we can consider the expansion

$$(u=t-c) \quad I(x) \simeq \int_{-\epsilon}^{\epsilon} du \left[ f(c) + u f'(c) + \frac{u^2}{2} f''(c) \right] x$$

Exp {  $x\phi(c) - x|\phi''(c)|\frac{u^2}{2} + x\phi'''(c)\frac{u^3}{3!} + x\phi''''(c)\frac{u^4}{4!} + \dots$  }

If we now factor out  $\exp(x(\phi^{(3)}(c)\frac{u^3}{3!} + \phi^{(4)}(c)\frac{u^4}{4!} + \dots))$  and expand

$$\exp(x(\phi^{(3)}(c)\frac{u^3}{3!} + \phi^{(4)}(c)\frac{u^4}{4!} + \dots))$$

$$\approx 1 + x(\phi^{(3)}(c)\frac{u^3}{3!} + \phi^{(4)}(c)\frac{u^4}{4!} + \dots) + \frac{x^2}{2!} (\phi^{(3)}(c)\frac{u^3}{3!} + \phi^{(4)}(c)\frac{u^4}{4!} + \dots)^2 + \dots$$

and take  $x \rightarrow \pm\infty$ , we have various Gaussian integrals to do

General form

$$J_n = \int_{-\infty}^{+\infty} du u^n \exp(-\frac{\alpha}{2} u^2), \quad \alpha = x|\phi''(c)| \quad \text{in our case}$$

$$n = \text{odd}, \quad J_n = 0 \quad (\text{odd under } u \rightarrow -u)$$

$$n = \text{even}, \text{ consider } J_0 = \int_{-\infty}^{\infty} du \exp(-\frac{\alpha}{2} u^2) = \sqrt{\frac{2\pi}{\alpha}}$$

Differentiation w.r.t.  $\alpha$

$$\frac{dJ_0}{d\alpha} = -\frac{1}{2} \int_{-\infty}^{\infty} du u^2 \exp(-\frac{\alpha}{2} u^2) = -\frac{1}{2} \frac{\sqrt{2\pi}}{\alpha^{3/2}} = -\frac{1}{2} J_2$$

$$J_2 = \frac{\sqrt{2\pi}}{\alpha^{3/2}}, \quad \sim \quad \frac{dJ_n}{d\alpha} = -\frac{1}{2} J_{n+2} \Rightarrow J_n = \frac{\sqrt{2\pi}}{\alpha^{\frac{n+1}{2}}} (n-1)(n-3) \quad 531$$

Now collecting the terms with same power of  $x$ , we can obtain e.g.

$$\exp(x\phi(c)) \sqrt{\frac{2\pi}{|\phi''(c)|}} \frac{1}{x^{3/2}} \left\{ -\frac{f^{(1)}}{2\phi^{(2)}} + \frac{f\phi^{(4)}}{\delta(\phi^{(2)})^2} + \frac{1}{2} \frac{f^{(1)}\phi^{(3)}}{(\phi^{(2)})^2} - \frac{5}{24} \frac{f(\phi^{(3)})^2}{(\phi^{(2)})^3} \right\}$$

Most important to note that

$$I(x) = \exp(x\phi(c)) \sqrt{\frac{2\pi}{|\phi''(c)|}} \frac{f(c)}{x^{3/2}} \left\{ 1 + \frac{A_1}{x} + \frac{A_2}{x^2} + \dots \right\}$$

~ Another example of asymptotic series

~ higher order corrections are suppressed by  $\frac{1}{x} \ll 1$

A couple of comments

- If  $\phi(t)$  has no maximum between the interval  $(a, b)$ , i.e. monotonically decreasing/increasing or just inflection point ( $\phi' = \phi'' = 0$ )

~ integral is dominated by  $t=a$  or  $t=b$ ,  $\phi'(a)$  or  $\phi'(b) \neq 0$  ~ completely square

- If there are several local maxima of  $\phi(t)$  between  $(a, b)$ , consider expansion around the global maximum

### Method of Stationary Phase / WKB Approx (useful for Fourier series)

We can also extend the analysis above to purely imaginary  $\phi(t) = i\psi(t)$

i.e

$$I(x) = \int_a^b dt f(t) e^{ix\psi(t)}, \quad x \gg 0, \quad x \in \mathbb{R}$$

~ Due to large  $x$ ,  $f(t) e^{ix\psi(t)}$  oscillates very rapidly, if  $f(t)$  is smooth, we "expect" these high frequency contribution "NEARLY CANCEL"



But now if  $\psi'(c) = 0$  at  $t=c$ , the phase becomes stationary

~ or for  $\psi(t)$ , we expect contribution near it dominates, since less rapid oscillations/cancellations ~ Stationary Phase

Expanding around  $t=c$ , we can perform similar analysis as before we obtain

$$I(x) \approx f(c) \exp(ix\psi(c)) \int_{-\infty}^{\infty} du \exp(ix\psi''(c) \frac{u^2}{2})$$

~ Need to evaluate  $\int_{-\infty}^{\infty} du \exp(ix\psi''(c) \frac{u^2}{2})$

General Result  $\int_{-\infty}^{\infty} du \exp(i\alpha u^2) = \sqrt{\frac{\pi}{\alpha}} e^{i\frac{\pi}{4}}$

Proof  $\int_{-\infty}^{\infty} du \exp(i\alpha u^2) = \int_0^{\infty} du \exp(i\alpha u^2) + \int_{-\infty}^0 du \exp(i\alpha u^2)$   
 $= 2 \int_0^{\infty} du \exp(i\alpha u^2)$

$$u = |u| e^{i\varphi} \rightarrow u^2 = |u|^2 (\cos 2\varphi + i \sin 2\varphi)$$



$$0 \leq \varphi \leq \frac{\pi}{4}, \quad \varphi = \frac{\pi}{4} \Rightarrow u^2 = |u|^2 i \rightarrow$$

$$|u| \geq 0 \quad \text{~Contour int gives 0 along C,}$$



$\int_{\rightarrow} = -\int_{\leftarrow} = \int_{\nearrow} \Rightarrow$  along  $\nearrow$  or  $\varphi = \frac{\pi}{4}$ , integral becomes

$$\int_0^\infty du |u| e^{i\frac{\pi}{4}} \exp(i\alpha u^2) = e^{i\frac{\pi}{4}} \int_0^\infty du |u| \exp(-\alpha u^2) = e^{i\frac{\pi}{4}} \sqrt{\frac{2\pi}{2\alpha}}$$

$$\Rightarrow = \int_0^\infty du \exp(i\alpha u^2) \Rightarrow \int_{-\infty}^\infty du \exp(i\alpha u^2) = \sqrt{\frac{2\pi}{\alpha}} e^{i\frac{\pi}{4}} \text{ as claimed}$$

$$I(x) \simeq f(c) \exp(i x \psi(c)) \sqrt{\frac{2\pi}{x f''(c)}} e^{i\frac{\pi}{4}} = f(c) \exp(i x \psi(c)) \sqrt{\frac{2\pi}{x |f'(c)|}} e^{i\frac{\pi}{4}}$$

- ~ Max + ~ Min

Example Airy Function The large, negative behavior of Airy function is given by

$$Ai(-x) = \frac{1}{\pi} \int_0^\infty dt \exp(i(-t|x| + \frac{t^3}{3})) , |x| \gg 0, x \text{ real}$$

Change variable  $t = |x|^{\frac{1}{2}} z$

negative  $x$

We can turn the integral expression into

Massing it into

Stationary phase form

$$\frac{1}{2\pi} \int_{-\infty}^\infty dt \exp(i(-\frac{t^3}{3} - t|x|)) = \frac{|x|^{\frac{1}{2}}}{2\pi} \int_{-\infty}^\infty dz \exp(i|x|^{\frac{3}{2}} (\frac{z^3}{3} - z))$$

For  $-ve x$

$\psi(z) = \frac{z^3}{3} - z$  has two stationary pts  $\psi'(z) = z^2 - 1 \sim \psi'(z) = 0$  at  $z = \pm 1$

Need to sum over both, also  $\psi''(z) = 2z = \pm 2$  at  $z = \pm 1$

Expanding around the stationary pts to quadratic order, we have

$$Ai(-x) \simeq \frac{|x|^{\frac{1}{2}}}{2\pi} \sum_{\pm} \int_{-\infty}^\infty dz \exp(i|x|^{\frac{3}{2}} (\mp \frac{2}{3} z \pm (z \mp 1)^2))$$

$$= \frac{|x|^{\frac{1}{2}}}{2\pi} \sum_{\pm} \exp(\mp \frac{2}{3} |x|^{\frac{3}{2}}) \left(\frac{\pi}{|x|^{\frac{3}{2}}} \right)^{\frac{1}{2}} \exp(\pm i\frac{\pi}{4})$$

$$= \frac{1}{|x|^{\frac{1}{4}} \sqrt{\pi}} \cos\left(\frac{2}{3} |x|^{\frac{3}{2}} - \frac{\pi}{4}\right) \sim \text{Large, -ve approx of Airy function}$$

Airy function is actually an eigenfunction to Schrödinger equation with linear potential  $V(y) \sim y$ , i.e. an equation of the form

$$\frac{\partial^2}{\partial x^2} \bar{\Psi}(x) - x \bar{\Psi}(x) = 0, \quad x = \alpha(y - y_0) \sim \frac{y}{y_0}$$

Absorbing  
 $\hbar, m, 2, \text{etc}$   $\leadsto$   $\alpha$

Particle Position  
Classical turning point  
Constant of Proportionality

Classical turning point  $y_0$  can be worked by  $E = V(y)$

### WKB Approximation

For a general 1-dimensional quantum mechanical system, it is described by Schrödinger Equation (time-independent)

$$\left(-\frac{\hbar^2}{2m} \frac{\partial^2}{\partial y^2} + V(y)\right) \bar{\Psi}(y) = 0 \leftrightarrow 0 = \left\{ \frac{\partial^2}{\partial y^2} + \frac{2m}{\hbar^2} (E - V(y)) \right\} \bar{\Psi}(y)$$

The so-called WKB approx in "classically allowed region", i.e.  $E > V(y)$  is given by

$$\bar{\Psi}(y) = \sum_{\pm} \frac{C_{\pm}}{\sqrt{K(y)}} \exp(\pm i \int dy K(y)), \quad K(y) = \frac{\sqrt{2m(E - V(y))}}{\hbar}$$

This approx is valid if  $V(x)$  is smooth so that  $K(x)$  changes slowly over  $\sim \frac{1}{K(y)}$

The approximation breaks down at Classical turning point  $y_0$  s.t.

$V(y_0) = E$ , expand  $V(y)$  around  $y_0$ , we get  $V(y) \approx E + (y - y_0) \frac{\partial V}{\partial y}|_{y_0}$ , e to the lowest order, we have linear potential!

$\leadsto$  Airy function becomes a good Approximation for wave function  $\bar{\Psi}(y)$

$$K(y) \approx \frac{1}{\hbar} \sqrt{\frac{2m}{\partial V / \partial y}} (y - y_0)^{\frac{1}{2}}$$

In particular, if  $K(y)$  becomes large, e.g.  $\hbar \rightarrow 0$  (classical limit), Airy function and WKB have the same asymptotic behavior

Ex - What is the behavior of the WKB-approximated wave function in "Classically forbidden region", i.e  $V(x) > E$ ? How is this related to Airy function? What about asymptotics?

## Saddle Point Approximation

The Laplace integral and stationary phase are in fact **special cases** of the general **Saddle Point approximation**, and we can understand it by combining the two previous special cases

We are considering integral of the form

$$I(N) = \int_a^b dz g(z) e^{Nf(z)}, \quad N \gg 0 \quad f(z) \rightarrow \text{Complex analytic func}$$

Setting  $f(x,y) = U(x,y) + iV(x,y)$

~ Intuitively, we expect  $I(N)$  to be dominated by maximum of  $U(x,y)$  and stationary pt of  $V(x,y)$   $\Rightarrow f'(z) = 0$  is needed

~ Actually, we only expect "Saddle Point" as "Extremum", reason being  $U(x,y)$  &  $V(x,y)$  satisfies Laplace's equation

$$\frac{\partial^2 U}{\partial x^2} + \frac{\partial^2 U}{\partial y^2} = 0 \Rightarrow \text{if } \frac{\partial^2 U}{\partial x^2} < 0 \rightsquigarrow \text{maximum in } x \text{ direction}$$

$$\frac{\partial^2 U}{\partial y^2} > 0 \rightsquigarrow \text{minimum in } y \text{ direction}$$



We expect the integral to be dominated by Highest Saddle Point, say at  $z_0$ , We can deform the contour  $\gamma$  to include  $z_0$  by Cauchy. Near  $z_0$ , we have

$$f(z) = f(z_0) + \frac{1}{2} f''(z_0)(z-z_0)^2, \quad g(z) = g(z_0)$$

and  $I(N)$  becomes

$$I(N) = g(z_0) e^{Nf(z_0)} \int_{\gamma} dz \exp(\frac{1}{2} N f''(z_0)(z-z_0)^2)$$

Now if we set  $z - z_0 = re^{i\phi}$ ,  $f''(z_0) = |f''(z_0)| e^{i\theta}$

The angles  $(\phi, \theta)$  determines how we approach the Saddle pt

~ we now have

$$I(N) \approx g(z_0) e^{Nf(z_0)} \int dr e^{i\phi} \exp(\frac{1}{2} N |f''(z_0)| r^2 e^{i\theta + i2\phi})$$

We can make convenient choice to render integral simple, we make a choice of  $\underline{\theta + 2\phi = \pi} \Rightarrow \underline{\phi = \frac{\pi - \theta}{2}}$

$$\Rightarrow I \approx g(z_0) e^{Nf(z_0)} e^{i\phi} \int dr \exp(-\frac{1}{2} N |f''(z_0)|) dr$$

Extend the integration range to  $\pm \infty$ , we can perform the Gaussian integral, we obtain an approximation of  $I(N)$

$$I(N) \approx g(z_0) e^{Nf(z_0)} e^{i\phi} \left( \frac{2\pi}{N |f''(z_0)|} \right)^{1/2}, \text{ where } \phi = \frac{\pi - \theta}{2}$$

- To recover Laplace's method, ~ Saddle pt on real axis with  $\frac{\partial^2 u}{\partial x^2} < 0$   
 $\rightarrow \frac{\partial^2 u}{\partial y^2} > 0$  ~ can go through the Saddle pt along real axis  $\phi = 0$ ,  $f''$  is negative  $\Rightarrow \theta = \pi$
- To recover Stationary method  $\rightarrow$  Instead of having  $\theta + 2\phi = \pi$ , we have  $\theta + 2\phi = \pi$ , such that

$$\int dz \exp \left\{ \frac{N}{2} f''(z_0) (z - z_0)^2 \right\} = e^{-\frac{N}{2} + i\frac{\pi}{4}} \int dr \exp \left( \frac{iN}{2} |f''(z_0)| r^2 \right)$$

## Examples

### ① Binomial Coefficient

Consider the following representation of Binomial Coefficient

$${N \choose M} = \oint_C \frac{dz}{2\pi i} \frac{(1+z)^N}{z^{M+1}}$$

$C \sim$  Unit Circle around origin

Now consider large  $N, M$ , we can set  $M = Ny$  and turn the integral representation into

$$\binom{N}{M} = \oint_C \frac{dz}{2\pi i} \frac{1}{z} \exp(N(\log(1+z) - y \log z))$$

Identifying the saddle pt, Let  $f(z) = \log(1+z) - y \log z$

$$f'(z) = \frac{1}{1+z} - \frac{y}{z} \quad , \quad f''(z) = -\frac{1}{(1+z)^2} + \frac{y}{z^2}$$

$$\Rightarrow f'(z_0) = 0 \Rightarrow z_0 = \frac{y}{1-y} \quad , \quad f(z_0) = -y \log y - (1-y) \log(1-y)$$

$$f''(z_0) = (1-y)^3/y$$

Notice that the integrand only has **Simple pole** at  $z=0$ , we can deform the contour to include  $z_0$ .

$$z_0 \sim \text{on real axis} \quad , \quad f''(z_0) \sim \text{real} \quad , \quad \theta = 0 \rightarrow \phi = \frac{\pi}{2} \quad (\text{going through the contour from imaginary direction})$$

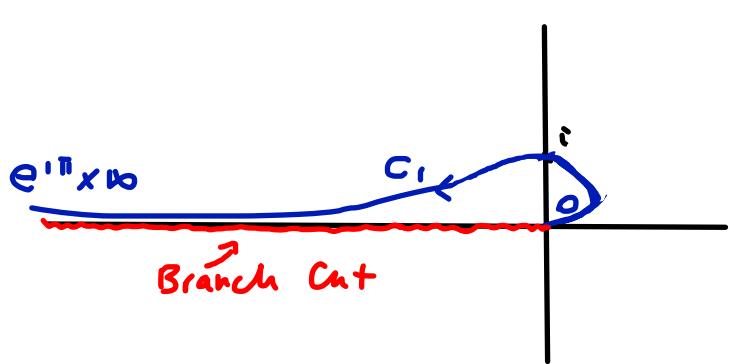
$$\Rightarrow \binom{N}{M} \simeq \frac{1}{2\pi i} \frac{e^{i\frac{\pi}{2}}}{z_0} e^{Nf(z_0)} \left( \frac{3\pi}{Nf''(z_0)} \right)^{\frac{1}{2}}$$

$$= \left( \frac{1}{2\pi N y (1-y)} \right)^{\frac{1}{2}} \exp(-N(y \log y + (1-y) \log(1-y))) \quad *$$

## ② Hankel Function

Hankel function of first kind

$$H_v^{(1)}(s) = \frac{1}{\pi i} \int_{C_1, 0}^{\infty} \frac{dz}{z^{v+1}} \exp\left(\frac{s}{z}(z - \frac{1}{z})\right)$$



To apply saddle pt method

$$f(z) = \frac{1}{2}(z - \frac{1}{z}) \quad (s \sim \text{large})$$

$$f'(z) = \frac{1}{2}(1 + \frac{1}{z^2}) \Rightarrow f'(z) = 0 \text{ at } z = \pm i$$

Without going through branch cut, we can deform the contour to go through  $z = +i$  Saddle pt  $\Rightarrow f''(i) = -i \Rightarrow \theta = -\frac{\pi}{2}$

$\sim \phi = \frac{3\pi}{4}$  approaching saddle pt at  $z = +i$  along  $\phi = \frac{3\pi}{4}$