Athindran Ramesh Kumar

r.athindran@gmail.com

Pittsburgh, PA

Webpage: https://athindran.github.io/

OUTLINE

Domain expertise in control, machine learning and robotics. Focus of PhD is on safety certification using optimization, learning and control. Taught several courses on machine learning and data science as a TA.

EDUCATION

Princeton University

NJ, USA

MA + PhD, Electrical and Computer Engineering

Sep. 2018 - Sep 2023 GPA: 3.93/4.0

Advisor: Prof. Peter J. Ramadge

- Key Courses: Machine learning and Pattern Recognition, Modern Control, Safe Robotics, Theoretical Machine Learning, Optimization for Machine Learning, Reinforcement Learning.
- M.A. degree in Electrical Engineering awarded.
- Ph.D. dissertation not complete. Other requirements met and retained candidacy.

University of Illinois at Urbana-Champaign

Illinois, USA

MS (fully funded by Dept.), Electrical and Computer Engineering Advisor: Prof. Grace Gao

Aug. 2013 - Aug 2015 GPA: 3.95/4.0

• Key Courses: GNSS systems, Computer Vision, Convex Optimization.

Indian Institute of Technology, Madras

Chennai, India

B. Tech, Electrical Engineering Advisor: Prof. Radhakrishna Ganti Aug. 2009 - July 2013 GPA: 9.27/10.0

SELECT PUBLICATIONS

Journal Papers

- A.R. Kumar, K. -C. Hsu, P. J. Ramadge and J. F. Fisac, "Fast, Smooth, and Safe: Implicit Control Barrier Functions through Reach-Avoid Differential Dynamic Programming," in IEEE Control Systems Letters, doi: 10.1109/LCSYS.2023.3292132.
- Heng, Liang, A.R. Kumar, and Grace Gao. "Private proximity detection using partial GPS information." IEEE Transactions on Aerospace and Electronic Systems 52.6 (2016): 2873-2885.

Conference and Workshop Papers

- S. Liu, A.R. Kumar, Jaime F. Fisac, Ryan P. Adams, Peter J. Ramadge. "ProBF: Probabilistic Safety Certificates with Barrier Functions." Presented at SafeRL workshop at NeurIPS 2021.
- A.R. Kumar and Peter J. Ramadge. "Learning to Control Using a Convex Combination of Controllers." 2021 American Control Conference (ACC). IEEE, 2021.
- A.R. Kumar and Peter J. Ramadge, 2021, March. DiffLoop: "Tuning PID controllers by differentiating through the feedback loop." In 2021 55th Annual Conference on Information Sciences and Systems (CISS) (pp. 1-6). IEEE.
- T. H. Fan, A. R. Kumar and P. J. Ramadge. Safety Control for Prime Focus Spectrograph. In 2022 56th Annual Conference on Information Sciences and Systems (CISS) (pp. 269-274). IEEE.
- A.R. Kumar, Balaraman Ravindran, and Anand Raghunathan. "Pack and detect: Fast object detection in videos using region-of-interest packing." Proceedings of the ACM India Joint International Conference on Data Science and Management of Data. 2019.
- A.R. Kumar, Liang Heng, and Grace X. Gao. "GPS privacy: Enabling proximity-based services while keeping GPS location private." Proceedings of the 27th International Technical Meeting of the Satellite Division of the Institute of Navigation (ION GNSS+ 2013), (Tampa, FL). 2014.

Patents

• Athindran R, Navinnath P, Klutto Milleth, Bhaskar Ramamurthi, "Frequency Assignment for SINR and Throughput Management in Battlefield Communication", India Patent granted 27th June 2024.

SELECT ACADEMIC ACHIEVEMENTS

- Awarded full-tuition waiver and stipend for MS degree program at University of Illinois, Urbana-Champaign.
- Received first-year fellowship at Princeton University for PhD program.
- Outstanding merit in Mathematics from Srinivas Ramanujan academy of Maths talent awarded in 2008.
- Ranked 294 out of 1,000,000 students in AIEEE and 1561 out of 800,000 students in JEE.

PROFESSIONAL EXPERIENCE

• Aurora Tech

Pittsburgh, PA

Software Engineer II - L5 Engineer

October 2023 - present

- Software Engineer in Control until October 2024.
- Motion Planning Software Engineer currently working on transformer models for scene forecasting.

• Nokia Bell Labs Research Intern Murray Hill, NJ

Jun - Aug 2021

• Reinforcement learning algorithms for a multi-link robotic arm in simulation.

• Center of Excellence in Wireless Technology

Research Engineer

Chennai, India

Apr 2016 - June 2018

• Frequency planning in a communication system.

• IIT Madras

Chennai, India

Project Associate

Nov 2015 - Mar 2016, Jul 2017 - Jul 2018

- Wrote a proposal seeking funding for the 5G mmWave cellular project at IIT Madras.
- Efficient deep learning for video processing.

• Google Inc.

Mountain View, CA

Software Intern - Street View

May - Aug 2014

• Implemented ambiguity resolution algorithms in Python on GPS carrier phase data obtained from receivers installed on Street View cars to achieve sub-meter accurate positioning.

ACADEMIC SERVICE

Teaching Experience

- Three-time TA for ECE 435-535 (Machine learning course with strong math foundations)
- Assistantship in Teaching for 11 semesters

Reviewing Service

- Conferences: ICLR (2021, 2023, 2024), NeurIPS (2022-2024), ICML (2023-2025), CISS 2022, IJCAI 2024.
- Journals: IEEE Transactions on Control Systems Technology, IEEE Robotics and Automation Letters.
- Top reviewer for NeurIPS 2023.

SELECT PROJECTS

-Optimization and Learning methods for Safety-Critical Control-

Princeton University, NJ

Guide: Prof. Peter Ramadge

Jul 2019 - Aug 2023

- Safety certification for autonomous control systems.
- Learning residual dynamics using probabilistic models.

-Efficient Deep Learning for Videos-

IIT Madras, Chennai

Guide: Prof. B. Ravindran and Prof. Anand Raghunathan (Purdue University)

Jul 2017 - Jul 2018

- Novel inference time method to accelerate object detection in videos.
- Published ACM India Joint International Conference on Data Science and Management of Data 2019.

-Direct Position Tracking using the Vector Correlator-

University of Illinois, Urbana-Champaign

Aug 2014 - Aug 2015

Guide: Prof. Grace Gao
 Proposed a novel direct position tracking loop for GPS using the Unscented Kalman Filter (UKF).

-Object recognition at a road intersection-

University of Ulm, Germany

- Tensorflow

Guide: Dr. Klaus Dietmayer

Apr 2012 - Aug 2012

 $\bullet\,$ Developed a labeling tool used by the Ko-FAS team for sensor data fusion.

PROGRAMMING SKILLS

- C++ - Python - Matlab - PyTorch - JAX