## Machine Learning Project

Athirah K. June 08, 2018

The data was download on my Mac and then I used them

```
Train_Data <- read.csv("./data/pml-training.csv")
dim(Train_Data)
```

## [1] 19622 160

The data seems has alarge number of columns in the dataset, Lets check if there are missing data in it

```
na <- apply(Train_Data, 2, function(x) sum(x %in% c(NA, "")))
na
```

##         X         user_name         raw_timestamp_part_1           ##         raw_timestamp_part_2         cvtd_timestamp         new_window           ##         num_window         roll_belt         pitch_belt           ##         yaw_belt         total_accel_belt         kurtosis_roll_belt           ##         yaw_belt         total_accel_belt         kurtosis_roll_belt           ##         kurtosis_picth_belt         kurtosis_yaw_belt         skewness_roll_belt           ##         kurtosis_picth_belt         kurtosis_yaw_belt         skewness_roll_belt           ##         skewness_roll_belt         skewness_yaw_belt         max_roll_belt           ##         skewness_roll_belt         skewness_yaw_belt         max_roll_belt           ##         num_inter         num_inter         num_inter           ##         num_inter         num_inter         n				
## raw_timestamp_part_2				raw_timestamp_part_1
##			•	<u> </u>
##         num_window         roll_belt         pitch_belt           ##         yaw_belt         total_accel_belt         kurtosis_roll_belt           ##         yaw_belt         total_accel_belt         kurtosis_roll_belt           ##         kurtosis_pich_belt         kurtosis_yaw_belt         skewness_roll_belt           ##         skewness_roll_belt.1         skewness_yaw_belt         max_roll_belt           ##         skewness_roll_belt.1         skewness_yaw_belt         max_roll_belt           ##         ng216         19216         19216         19216           ##         max_picth_belt         max_yaw_belt         min_roll_belt           ##         min_pitch_belt         min_yaw_belt         amplitude_roll_belt           ##         ng216         19216         19216         19216           ##         amplitude_pitch_belt         amplitude_yaw_belt         var_total_accel_belt         19216<		raw_timestamp_part_2	cvtd_timestamp	new_window
## yaw_belt total_accel_belt kurtosis_roll_belt			0	•
##         yaw_belt         total_accel_belt         kurtosis_roll_belt           ##         kurtosis_picth_belt         kurtosis_yaw_belt         skewness_roll_belt           ##         19216         19216         19216           ##         skewness_roll_belt.1         skewness_yaw_belt         max_roll_belt           ##         19216         19216         19216           ##         max_picth_belt         max_yaw_belt         min_roll_belt           ##         min_pitch_belt         max_yaw_belt         amplitude_roll_belt           ##         min_pitch_belt         min_yaw_belt         amplitude_roll_belt           ##         19216         19216         19216           ##         19216         19216         19216           ##         19216         19216         19216           ##         19216         19216         19216           ##         19216         19216         19216           ##         19216         19216         19216           ##         19216         19216         19216           ##         19216         19216         19216           ##         19216         19216         19216           ##		num_window	roll_belt	pitch_belt
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## 19216 19216 19216 19216 ## avg_roll_belt stddev_roll_belt var_roll_belt ## 19216 19216 19216 19216 ## avg_pitch_belt stddev_pitch_belt var_pitch_belt ## 19216 19216 19216 ## avg_yaw_belt stddev_yaw_belt var_yaw_belt ## 19216 19216 19216 19216 ## gyros_belt_x gyros_belt_y gyros_belt_z ## 0 0 0 0 ## accel_belt_x accel_belt_y accel_belt_z ## 0 0 0 0 ## magnet_belt_x magnet_belt_y magnet_belt_z ## 0 0 0 0 ## roll_arm pitch_arm yaw_arm ## 0 0 0 0 ## total_accel_arm var_accel_arm				
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##       19216       19216       19216         ##       avg_pitch_belt       stddev_pitch_belt       var_pitch_belt         ##       19216       19216       19216         ##       19216       19216       19216         ##       19216       19216       19216         ##       gyros_belt_x       gyros_belt_y       gyros_belt_z         ##       accel_belt_x       accel_belt_y       accel_belt_z         ##       magnet_belt_x       magnet_belt_y       magnet_belt_z         ##       roll_arm       pitch_arm       yaw_arm         ##       total_accel_arm       var_accel_arm       avg_roll_arm				
##       avg_pitch_belt       stddev_pitch_belt       var_pitch_belt         ##       19216       19216       19216         ##       19216       19216       19216         ##       19216       19216       19216         ##       19216       19216       19216         ##       19216       19216       19216         ##       19216       19216       19216         ##       19216       19216       19216         ##       19216       19216       19216         ##       19216       19216       19216         ##       19216       19216       19216         ##       19216       19216       19216         ##       19216       19216       19216         ##       19216       19216       19216         ##       19216       19216       19216       19216         ##       19216       19216       19216       19216       19216         ##       19216       19216       19216       19216       19216       19216       19216       19216       19216       19216       19216       19216       19216       19216       19216				
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## 19216 19216 19216 19216  ## gyros_belt_x gyros_belt_y gyros_belt_z  ## 0 0 0 0  ## accel_belt_x accel_belt_y accel_belt_z  ## 0 0 0 0  ## magnet_belt_x magnet_belt_y magnet_belt_z  ## 0 0 0  ## roll_arm pitch_arm yaw_arm  ## 0 0 0  ## total_accel_arm var_accel_arm avg_roll_arm				
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## 0 0 0 0 ## magnet_belt_x magnet_belt_y magnet_belt_z ## 0 0 0 0 ## roll_arm pitch_arm yaw_arm ## 0 0 0 0 ## total_accel_arm var_accel_arm avg_roll_arm		0	0	0
## magnet_belt_x magnet_belt_y magnet_belt_z ## 0 0 0 0 ## roll_arm pitch_arm yaw_arm ## 0 0 0 0 ## total_accel_arm var_accel_arm avg_roll_arm	##	accel_belt_x	accel_belt_y	accel_belt_z
## 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	##	0	0	0
## roll_arm pitch_arm yaw_arm ## 0 0 0 0 ## total_accel_arm var_accel_arm avg_roll_arm	##	magnet_belt_x	magnet_belt_y	magnet_belt_z
## 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0		0	0	0
## total_accel_arm var_accel_arm avg_roll_arm	##	roll_arm	pitch_arm	yaw_arm
		0	0	•
## 0 19216 19216	##	total_accel_arm	var_accel_arm	avg_roll_arm
	##	0	19216	19216

1

##	stddev_roll_arm	var roll arm	avg_pitch_arm
##	19216	vai_ioii_aiiii 19216	avg_pilci1_aiiii 19216
##	stddev_pitch_arm	var_pitch_arm	avg_yaw_arm
##	19216	19216	19216
##	stddev_yaw_arm	var_yaw_arm	gyros_arm_x
##	19216	19216	0
##	gyros_arm_y	gyros_arm_z	accel_arm_x
##	0	0	0
##	accel_arm_y	accel_arm_z	magnet_arm_x
##	0	0	0
##	magnet_arm_y	magnet_arm_z	kurtosis_roll_arm
##	0	0	19216
##	kurtosis_picth_arm	kurtosis_yaw_arm	skewness_roll_arm
##	19216	19216	19216
##	skewness_pitch_arm	skewness_yaw_arm	max_roll_arm
##	19216	19216	19216
##	max_picth_arm	max_yaw_arm	min_roll_arm
## ##	19216	19216	19216
##	min_pitch_arm 19216	min_yaw_arm 19216	amplitude_roll_arm 19216
##	amplitude_pitch_arm	amplitude_yaw_arm	roll_dumbbell
##	19216	19216	0
##	pitch_dumbbell	yaw_dumbbell	kurtosis_roll_dumbbell
##	0	0	19216
##	kurtosis_picth_dumbbell	kurtosis_yaw_dumbbell	skewness_roll_dumbbell
##	_, _ 19216		19216
##	skewness_pitch_dumbbell	skewness_yaw_dumbbell	max_roll_dumbbell
##	19216	19216	19216
##	max_picth_dumbbell	max_yaw_dumbbell	min_roll_dumbbell
##	19216	19216	19216
##	min_pitch_dumbbell		amplitude_roll_dumbbell
##	19216	19216	19216
##	amplitude_pitch_dumbbell 19216	amplitude_yaw_dumbbell 19216	total_accel_dumbbell 0
##	var_accel_dumbbell	avg_roll_dumbbell	stddev_roll_dumbbell
##	19216	19216	19216
##	var_roll_dumbbell	avg_pitch_dumbbell	stddev_pitch_dumbbell
##	19216	19216	19216
##	var_pitch_dumbbell	avg_yaw_dumbbell	stddev_yaw_dumbbell
##	19216	19216	19216
##	var_yaw_dumbbell	gyros_dumbbell_x	gyros_dumbbell_y
##	19216	0	0
##	gyros_dumbbell_z	accel_dumbbell_x	accel_dumbbell_y
##	0	0	0
##	accel_dumbbell_z	magnet_dumbbell_x	magnet_dumbbell_y
##	0	0	0
## ##	magnet_dumbbell_z 0	roll_forearm 0	pitch_forearm
## ##	•	•	0 n kurtosis nieth forearm
##	yaw_forearm 0	19216	n kurtosis_picth_forearm 19216
##	kurtosis_yaw_forearm	skewness_roll_forearm	skewness_pitch_forearm
##	19216	19216	19216
##	skewness_yaw_forearm	max_roll_forearm	max_picth_forearm
##	19216	19216	19216
	. 52.10	.5=.0	.52.10

```
##
                                       min_roll_forearm
            max_yaw_forearm
                                                                 min_pitch_forearm
##
                        19216
                                                   19216
                                                                               19216
##
             min_yaw_forearm amplitude_roll_forearm amplitude_pitch_forearm
 ##
                         19216
                                                    19216
                                                                               19216
 ##
        amplitude_yaw_forearm
                                       total_accel_forearm
                                                                   var_accel_forearm
 ##
                         19216
                                                                               19216
 ##
               avg_roll_forearm
                                       stddev_roll_forearm
                                                                     var_roll_forearm
 ##
                         19216
                                                    19216
                                                                               19216
 ##
             avg_pitch_forearm
                                      stddev_pitch_forearm
                                                                    var_pitch_forearm
 ##
                         19216
                                                    19216
                                                                               19216
 ##
             avg_yaw_forearm
                                      stddev_yaw_forearm
                                                                    var_yaw_forearm
 ##
                         19216
                                                    19216
                                                                               19216
 ##
                                                                     gyros_forearm_z
               gyros_forearm_x
                                          gyros forearm y
 ##
                                                                                   0
                             0
 ##
               accel_forearm_x
                                          accel_forearm_y
                                                                     accel_forearm_z
 ##
 ##
            magnet_forearm_x
                                        magnet_forearm_y
                                                                   magnet_forearm_z
 ##
 ##
                        classe
 ##
                             0
```

Seems there lots of NAs, so we skip these variables and analyze only complete ones.

```
index <- which(na == 0)
Train_Data <- Train_Data[,index]
Train_Data <- Train_Data[,8:60]
```

Lets see the Matrix Model

```
library(randomForest)
```

```
## Warning: package 'randomForest' was built under R version 3.1.1
```

```
## randomForest 4.6-10
## Type rfNews() to see new features/changes/bug fixes.
```

## library(caret)

```
## Warning: package 'caret' was built under R version 3.1.1
```

```
## Loading required package: lattice## Loading required package: ggplot2
```

```
model <- randomForest(classe~., data = Train_Data)
pred <- predict(model, Train_Data)
confusionMatrix(Train_Data$classe, pred)
```

```
## Confusion Matrix and Statistics
##
## Reference
## Prediction A B C D E
```

```
##
             A 5580
                         0
                              0
                                    0
                                         0
 ##
             В
                   0 3797
                              0
 ##
             С
                   0
                         0 3422
                                    0
                                         0
 ##
             D
                   0
                         0
                              0 3216
                                         0
 ##
             Ε
                   0
                         0
                              0
                                    03607
 ##
## Overall Statistics
##
 ##
                     Accuracy: 1
                      95% CI: (1, 1)
 ##
##
        No Information Rate: 0.284
##
        P-Value [Acc > NIR]: <2e-16
##
##
                       Kappa: 1
   Mcnemar's Test P-Value: NA
##
##
## Statistics by Class:
##
##
                                  Class: A Class: B Class: C Class: D Class: E
                               1.000
## Sensitivity
                                         1.000
                                                    1.000
                                                              1.000
                                                                       1.000
## Specificity
                               1.000
                                         1.000
                                                    1.000
                                                              1.000
                                                                       1.000
## Pos Pred Value
                                         1.000
                                                              1.000
                                                                       1.000
                               1.000
                                                    1.000
## Neg Pred Value
                               1.000
                                         1.000
                                                    1.000
                                                              1.000
                                                                       1.000
## Prevalence
                               0.284
                                         0.194
                                                    0.174
                                                              0.164
                                                                       0.184
## Detection Rate
                                                                       0.184
                               0.284
                                         0.194
                                                    0.174
                                                              0.164
## Detection Prevalence
                               0.284
                                         0.194
                                                    0.174
                                                                       0.184
                                                              0.164
## Balanced Accuracy
                               1.000
                                         1.000
                                                    1.000
                                                              1.000
                                                                       1.000
```

We should check the model on different dataset.

```
Test_Data <- read.csv("./data/pml-testing.csv")
Test_Data <- Test_Data[,index]
Test_Data <- Test_Data[,8:59]
Test_Data$classe <- factor(nrow(Test_Data))
levels(Test_Data$classe) <- levels(Train_Data$classe)
Test2 <- rbind(Train_Data[1,], Test_Data)
Test2 <- Test2[2:21,]
```

Lets see the Model

```
TestModel <- predict(model, Test2)
TestModel
```

```
## 2 3 4 5 6 7 8 9 10 11 12 13 14 15 16 17 18 19 20 21
## В А В А А Е D В А А В С В А Е Е А В В в
## Levels: A В С D Е
```