Markov Melding Notes

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Logistic regression

Consider response $Y \in \{0,1\}$ modelled as $Y \sim \text{Bern}(q)$ and covariates $x \in \mathbb{R}^p$ with

$$\log\left(\frac{q(x)}{1-q(x)}\right) = \beta^T x,$$

where $\beta \in \mathbb{R}^p$. Then

$$q(x) = \frac{\exp\left(\beta^T x\right)}{1 + \exp\left(\beta^T x\right)}$$

Observe labelled data $\{(x_1, y_1), \dots, (x_n, y_n)\}$. The likelihood function is

$$\mathcal{L}(\beta_0, \beta) = \prod_{i=1}^{n} q(x_i)^{y_i} (1 - q(x_i))^{1 - y_i}$$

Place Gaussian prior on β such that

$$\beta \sim \mathcal{N}_p(\mu, \operatorname{diag}(\sigma_1^2, \dots, \sigma_p^2))$$

Then the posterior is proportional to

$$p(\beta_0, \beta | y_1, \dots, y_n) \propto \prod_{j=1}^p \exp\left(\frac{1}{2\sigma_j^2}(\beta_j - \mu_j)^2\right) \prod_{j=1}^n q(x_i)^{y_i} (1 - q(x_i))^{1-y_i}.$$

Taking the logarithm gives

$$\log p(\beta_0, \beta | y_1, \dots, y_n) \propto \sum_{j=0}^{p} \frac{1}{2\sigma_j^2} (\beta_j - \mu_j)^2 + \sum_{i=1}^{n} y_i \log q(x_i) + (1 - y_i) \log (1 - q(x_i))$$

The log-likelihood can be rewritten as

$$\sum_{i=1}^{n} y_{i} \log q(x_{i}) + (1 - y_{i}) \log (1 - q(x_{i})) = \sum_{i=1}^{n} y_{i} \log \left(\frac{q(x_{i})}{1 - q(x_{i})}\right) + \log (1 - q(x_{i}))$$

$$= \sum_{i=1}^{n} y_{i} \log \left(\frac{q(x_{i})}{1 - q(x_{i})}\right) + \log (1 - q(x_{i}))$$

$$= \sum_{i=1}^{n} y_{i} \left(\beta^{T} x\right) - \log \left(1 + \exp(\beta^{T} x)\right)$$

Monte Carlo

(Johansen 2018)

For the following samplers targeting density f and starting with $\mathbf{X}^{(0)} := \left(X_1^{(0)}, \dots, X_p^{(0)}\right)$, iterate for $t = 1, 2, \dots$

Metropolis-Hastings sampler

- 1. Draw $\mathbf{X} \sim q\left(\cdot | \mathbf{X}^{(t-1)}\right)$
- 2. With probability $\min \left\{ 1, \frac{f(\mathbf{X}) \cdot q(\mathbf{X}^{(t-1)}|\mathbf{X})}{f(\mathbf{X}^{(t-1)}) \cdot q(\mathbf{X}|\mathbf{X}^{(t-1)})} \right\} \text{ set } \mathbf{X}^{(t)} = \mathbf{X}, \text{ else set } \mathbf{X}^{(t)} = \mathbf{X}^{(t-1)}$

Note that if the proposal q is symmetric (as in random-walk metropolis-hastings) then the acceptance probability simplifies to $\min \left\{ 1, \frac{f(\mathbf{X})}{f(\mathbf{X}^{(t-1)})} \right\}$.

(Random scan) Gibbs sampler

1. Draw $j \sim \text{Unif}\{1, \dots, p\}$ 2. Draw $X_j^{(t)} \sim f_{X_j|X_{-j}}\left(\cdot | X_1^{(t-1)}, \dots, X_{j-1}^{(t-1)}, X_{j+1}^{(t-1)}, \dots, X_p^{(t-1)}\right)$, and set $X_i^{(t)} := X_i^{(t-1)}$ for all $i \neq j$

(Random scan) Metropolis-within-Gibbs

- 1. Draw $j \sim \text{Unif}\{1, \dots, p\}$
- 2. a) Draw $X_j \sim q_j\left(\cdot|\mathbf{X}^{(t-1)}\right)$ and set $\mathbf{X} = \left(X_1^{(t-1)}, \dots, X_j, \dots, X_p^{(t-1)}\right)$ b) With probability min $\left\{1, \frac{f(\mathbf{X}) \cdot q(\mathbf{X}^{(t-1)}|\mathbf{X})}{f(\mathbf{X}^{(t-1)}) \cdot q(\mathbf{X}|\mathbf{X}^{(t-1)})}\right\}$ set $\mathbf{X}^{(t)} = \mathbf{X}$, else set $\mathbf{X}^{(t)} = \mathbf{X}^{(t-1)}$

(Divide-and-Conquer with) Sequential Monte Carlo

- Bayesian network is a directed acyclic graph
- Factor graphs (Bishop 2016): "Factor graphs make this decomposition explicit by introducing additional nodes for the factors themselves in addition to the nodes representing the variables."

Markov Melding

(Goudie 2018)

Introduction to Markov melding

- Aims of work:
- 1. Join submodels p_m into a single joint model
 - Must implicitly handle two different priors for same quantity
 - Must handle non-invertible deterministic transformations
- 2. Fit the submodels one at a time
 - Minimize burden on practitioners

- 3. Understanding of reverse operation to joining splitting
- Models m = 1, ..., M each with joint density $p_m(\phi, \psi_m, Y_m)$ where:
 - $-\phi$ is the common parameter linking the models
 - $-\psi_m$ are model specific unobserved parameters
 - $-Y_m$ are model specific observed quantities
- Join together to create $p(\phi, \psi_1, \dots, \psi_M, Y_1, \dots, Y_M)$

Pooling marginal distributions

- Linear pooling
- Logarithmic pooling
- Product of Experts (special case of logarithmic pooling)
- Dictatorial pooling

Inference and computation

Joint posterior, given data $Y_m = y_m$ for m = 1, ..., M, under Melded model is

$$p_{\text{meld}}(\phi, \psi_1, \dots, \psi_M | y_1, \dots, y_M) \propto p_{\text{pool}}(\phi) \prod_{m=1}^M \frac{p_m(\phi, \psi_m, y_m)}{p_m(\phi)}$$

Metropolis-Hastings candidate values $(\phi^*, \psi_1^*, \dots, \psi_M^*)$ drawn from a proposal $q(\phi^*, \psi_1^*, \dots, \psi_M^* | \phi, \psi_1, \dots, \psi_M)$ and accepted with probability min(1, r) where

$$r = \frac{R\left(\phi^{\star}, \psi_{1}^{\star}, \dots, \psi_{M}^{\star}, \phi, \psi_{1}, \dots, \psi_{M}\right)}{R\left(\phi, \psi_{1}, \dots, \psi_{M}, \phi^{\star}, \psi_{1}^{\star}, \dots, \psi_{M}^{\star}\right)}$$

where $R(\phi^{\star}, \psi_1^{\star}, \dots, \psi_M^{\star}, \phi, \psi_1, \dots, \psi_M)$ is the target-to-proposal density ratio

$$R\left(\phi^{\star}, \psi_{1}^{\star}, \dots, \psi_{M}^{\star}, \phi, \psi_{1}, \dots, \psi_{M}\right) = p_{\text{pool}}\left(\phi^{\star}\right) \prod_{m=1}^{M} \frac{p_{m}\left(\phi^{\star}, \psi_{m}^{\star}, y_{m}\right)}{p_{m}\left(\phi^{\star}\right)} \times \frac{1}{q\left(\phi^{\star}, \psi_{1}^{\star}, \dots, \psi_{M}^{\star} \middle| \phi, \psi_{1}, \dots, \psi_{M}\right)}$$

Metropolis-within-Gibbs

Sample from the full conditionals using Metropolis-Hastings.

For each of the **latent parameter updates** (ψ_m for m = 1, ..., M) we have

$$R\left(\phi,\psi_{1},\ldots,\psi_{m}^{\star},\ldots,\psi_{M},\phi,\psi_{1},\ldots,\psi_{M}\right)=p_{\text{pool}}\left(\phi\right)\prod_{j\neq m}\frac{p_{j}\left(\phi,\psi_{j},y_{j}\right)}{p_{j}\left(\phi\right)}\times\frac{p_{m}\left(\phi,\psi_{m}^{\star},y_{m}\right)}{p_{m}\left(\phi\right)}\frac{1}{q\left(\psi_{m}^{\star}|\psi_{m}\right)}$$

so that

$$r = \frac{p_m\left(\phi, \psi_m^{\star}, y_m\right) \times \frac{1}{q(\psi_m^{\star}|\psi_m)}}{p_m\left(\phi, \psi_m, y_m\right) \times \frac{1}{q(\psi_m|\psi_m^{\star})}}$$

and for the link parameter update

$$R\left(\phi,\psi_{1},\ldots,\psi_{m}^{\star},\ldots,\psi_{M},\phi,\psi_{1},\ldots,\psi_{M}\right)=p_{\mathrm{pool}}\left(\phi^{\star}\right)\prod_{m=1}^{M}\frac{p_{m}\left(\phi^{\star},\psi_{m},y_{m}\right)}{p_{m}\left(\phi^{\star}\right)}\times\frac{1}{q\left(\phi^{\star}|\phi\right)}$$

Multi-stage Metropolis-within-Gibbs

Factorise the pooled prior (can be done in many ways)

$$p_{\text{pool}}(\phi) = \prod_{m=1}^{M} p_{\text{pool},m}(\phi)$$

Define lth stage posterior as

$$p_{\text{meld},l}\left(\phi,\psi_1,\ldots,\psi_\ell|y_1,\ldots,y_\ell\right) \propto \prod_{m=1}^{\ell} \left(\frac{p_m\left(\phi,\psi_m,y_m\right)}{p_m(\phi)}p_{\text{pool},m}(\phi)\right)$$

Basis obtain samples $\left(\phi^{(h,1)}, \psi_1^{(h,1)}\right)$ for $h = 1, \dots, H_1$ from $p_{\text{meld},1}\left(\phi, \psi_1 | y_1\right)$ (by MCMC typically)

Inductive construct a Metropolis-within-Gibbs sampler for $(\phi, \psi_1, \dots, \psi_\ell)$ given the data (y_1, \dots, y_ℓ)

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