

# Computational Learning Theory

# Learning Theory

- Theorems that characterize classes of learning problems or specific algorithms in terms of **computational complexity** or **sample complexity** (the number of training examples necessary or sufficient to learn hypotheses of a given accuracy)
- **Complexity of a learning problem depends on**
  - ▲ Size or expressiveness of the hypothesis space
  - ▲ Accuracy to which target concept must be approximated
  - ▲ Probability with which the learner must produce a successful hypothesis
  - ▲ Manner in which training examples are presented, e.g., randomly or by query to an oracle

# Types of Results

- **Learning in the limit:** Is the learner guaranteed to converge to the correct hypothesis in the limit as the number of training examples increases to infinity?
- **Sample complexity:** How many training examples are needed for a learner to construct (with high probability) a highly accurate concept?
- **Computational complexity:** How much computational resources (time and space) are needed for a learner to construct (with high probability) a highly accurate concept?
- **Mistake bound:** Learning incrementally, how many training examples will the learner misclassify before constructing a highly accurate concept

# Learning in the Limit vs. PAC Model

- **Learning in the limit model is too strong**
  - ▲ Requires learning correct exact concept
- **Learning in the limit model is too weak**
  - ▲ Allows unlimited data and computational resources
- **PAC Model** (Leslie Valiant got a Turing Award!)
  - ▲ Only requires a **Probably Approximately Correct** (PAC) concept: learn a decent approximation most of the time
  - ▲ Requires polynomial sample complexity and computational complexity

# PAC Learning

- The only reasonable expectation of a learner is that with *high probability* it learns a *close approximation* to the target concept
- In the PAC model, we specify two parameters,  $\epsilon$  and  $\delta$ , and require that with probability at least  $(1 - \delta)$  a system learn a concept with error at most  $\epsilon$

# PAC Learning

- How to prove PAC learnability?
  - ▲ First, prove sample complexity of learning a target concept  $h^*$  using a hypothesis space  $H$  is polynomial
  - ▲ Second, prove that the learner can train on a polynomial-sized data set in polynomial time
- To be PAC-learnable
  - ▲ There must be a hypothesis in  $H$  with arbitrarily small error for every target concept  $h^*$

# Consistent Learners

- A learner using a hypothesis space  $H$  and training data  $D$  is said to be a consistent learner if it **always outputs a hypothesis with zero error on  $D$  whenever  $H$  contains such a hypothesis**

# Sample Complexity Result

- Any consistent learner, given at least
  - ▲  $\left(\ln \frac{1}{\delta} + \ln |H|\right) \cdot \frac{1}{\epsilon}$  examples will produce a result that is PAC
- Just need to determine the size of a hypothesis space to instantiate this result for learning specific target concepts
- This gives a *sufficient* number of examples for PAC learning, but *not a necessary* number – meaning the bound is very loose in practice



# Infinite Hypothesis Spaces

- The preceding analysis was restricted to finite hypothesis spaces
- Some infinite hypothesis spaces (such as those including real-valued thresholds or parameters) are more expressive than others
- Need some measure of the expressiveness of infinite hypothesis space
- The *Vapnik-Chervonenkis (VC)* dimension provides such a measure, denoted  $VC(H)$

# The VC Dimension

- A set of instances  $S$  is *shattered* by hypothesis space  $H$  if and only if for every dichotomy of  $S$  there exists some hypothesis in  $H$  consistent with this dichotomy
- The *Vapnik-Chervonenkis dimension*,  $VC(H)$ , of hypothesis space  $H$  defined over instance space  $X$  is the size of the largest finite subset of  $X$  shattered by  $H$ . If arbitrarily large finite sets of  $X$  can be shattered by  $H$ , then  $VC(H)=\infty$

# Sample Complexity with VC dimension

- Using VC dimension as a measure of expressiveness, the following number of examples have been shown to be sufficient for PAC Learning (Blum et al., 1989)

$$m \geq \frac{1}{\varepsilon} \left( 4 \log_2(2 / \delta) + 8VC(H) \log_2(13 / \varepsilon) \right)$$

- In general, this can provide a tighter upper bound on the number of examples needed for PAC learning

# Summary of Learning Theory

- The PAC framework provides a theoretical mechanism for analyzing the effectiveness of learning algorithms
- The sample complexity for any consistent learner using some hypothesis space,  $H$ , can be determined from a measure of its expressiveness  $|H|$  or  $VC(H)$
- If sample complexity is tractable, then the computational complexity of finding a consistent hypothesis in  $H$  governs its PAC learnability
- Constant factors are more important in sample complexity than in computational complexity, since our ability to gather data is generally not growing exponentially
- Experimental results suggest that theoretical sample complexity bounds over-estimate the number of training examples needed in practice since they are worst-case bounds!

# More Readings

- Michael Kearns and Umesh Vazirani: *Introduction to Computational Learning Theory*, MIT Press, 1994.
  - ▶ <https://mitpress.mit.edu/books/introduction-computational-learning-theory>