

EE 523 Homework - 2

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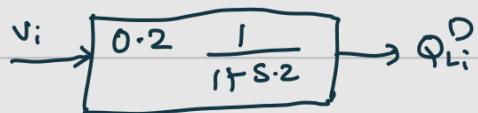
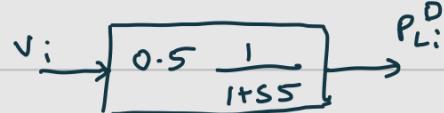
① @

$$\text{Given } P_{L_i} = P_{L_i}^D + P_{L_i}^S ; 100 \text{ MW}$$

$$Q_{L_i} = Q_{L_i}^D + Q_{L_i}^S ; 50 \text{ MVAR}$$

$$P_{L_i}^S = 0.5 V_i^{0.7}$$

$$Q_{L_i}^S = 0.8 V_i^{0.6}$$



for $t < 10 \text{ sec}$

$$V = 1 \text{ pu} ; P_{L_i}^S = 0.5 (1)^{0.7} = 0.5 \text{ pu} ; P_{L_i}^D = (1) (0.5) = 0.5 \text{ pu}$$

$$Q_{L_i}^S = 0.8 (1)^{0.6} = 0.8 \text{ pu} ; Q_{L_i}^D = (1) (0.2) = 0.2 \text{ pu}$$

at $t = 10^+ \text{ sec}$

$$V = 0.9 \text{ p.u. } P_{L_i}^S = 0.5 (0.9)^{0.7} = 0.464 \text{ pu}$$

$$Q_{L_i}^S = 0.8 (0.9)^{0.6} = 0.751 \text{ pu}$$

Steady state values of $P_{L_i}^D$ & $Q_{L_i}^D$

$$P_{L_i}^D = (0.9) (0.5) = 0.45 \text{ pu}$$

$$Q_{L_i}^D = (0.9) (0.2) = 0.18 \text{ pu}$$

at $t = 20^+ \text{ sec}$

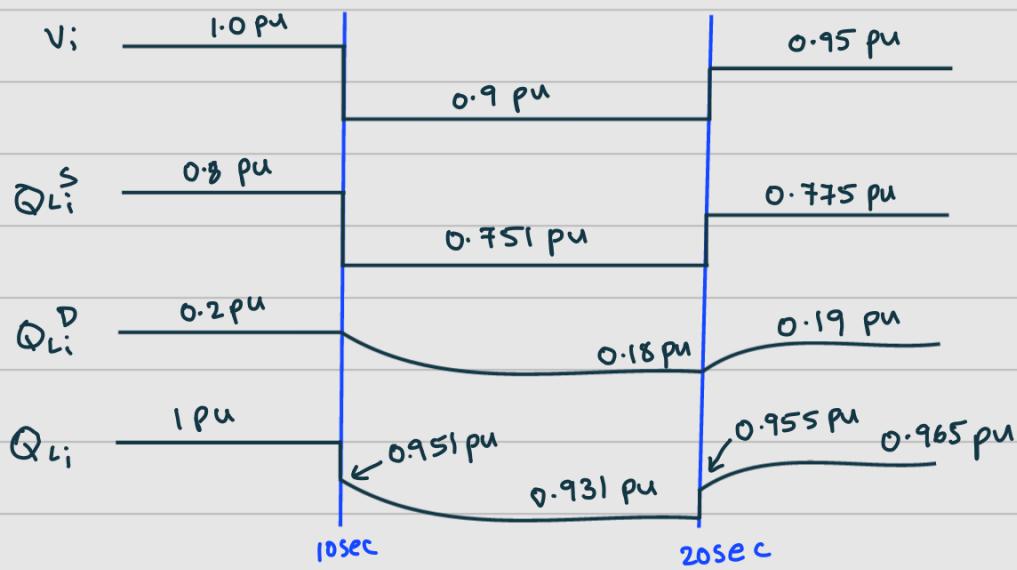
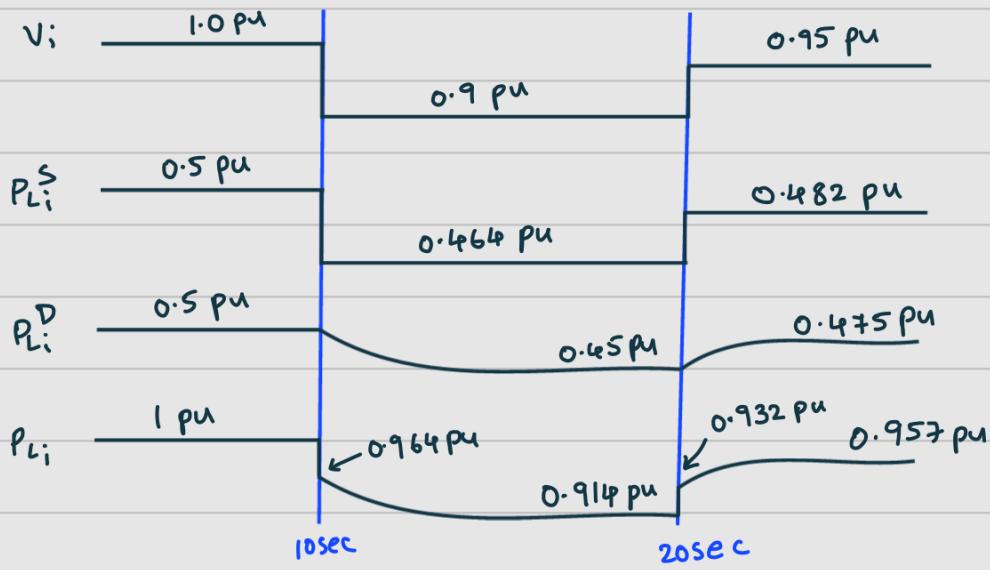
$$V = 0.95 \text{ p.u. } P_{L_i}^S = 0.5 (0.95)^{0.7} = 0.482 \text{ pu}$$

$$Q_{L_i}^S = 0.8 (0.95)^{0.6} = 0.775 \text{ pu}$$

Steady state values of $P_{L_i}^D$ & $Q_{L_i}^D$

$$P_{L_i}^D = (0.95) (0.5) = 0.475 \text{ pu}$$

$$Q_{L_i}^D = (0.95) (0.2) = 0.19 \text{ pu}$$



(1b) Given

$$V_i \rightarrow \boxed{0.5 \frac{1}{1+0.002s+0.025s^2}} \rightarrow P_{L_i}^D$$

$$V_i \rightarrow \boxed{0.2 \frac{1}{1+0.002s+0.05s^2}} \rightarrow Q_{L_i}^D$$

Consider CE for $P_{L_i}^D$ $1+0.002s+0.025s^2=0$

$$\div 0.025 \Rightarrow 40+0.08s+s^2=0$$

Compare with $\omega_n^2 + 2\xi\omega_n s + s^2 = 0$

$$\begin{aligned} \omega_n^2 &= 40 \\ \omega_n &= \sqrt{40} \end{aligned} \quad \left| \begin{aligned} 2\xi\omega_n &= 0.08 \\ \xi &= \frac{0.08}{2\omega_n} = \frac{0.08}{2\sqrt{40}} = 0.0063 \end{aligned} \right.$$

$\xi < 1 \Rightarrow$ underdamped system

$$-\pi\xi/\sqrt{1-\xi^2} - \pi 0.0063/\sqrt{1-0.0063^2}$$

$$M_p = e = e$$

$$M_p = 98.04 \text{ kNm}$$

$$T_s = \frac{4}{\xi\omega_n} = \frac{4}{0.0063\sqrt{40}} = 100 \text{ sec}$$

$$T_p = \frac{4}{\omega_n\sqrt{1-\xi^2}} = \frac{4}{\sqrt{40}\sqrt{1-0.0063^2}} = 0.632 \text{ sec}$$

$$\text{Consider CE for } Q_{L_i}^D \quad 1 + 0.002s + 0.05s^2 = 0$$

$$\div 0.05 \Rightarrow 20 + 0.04s + s^2 = 0$$

$$-\pi\xi/\sqrt{1-\xi^2} - \pi 0.0044/\sqrt{1-0.0044^2}$$

$$M_p - e = e$$

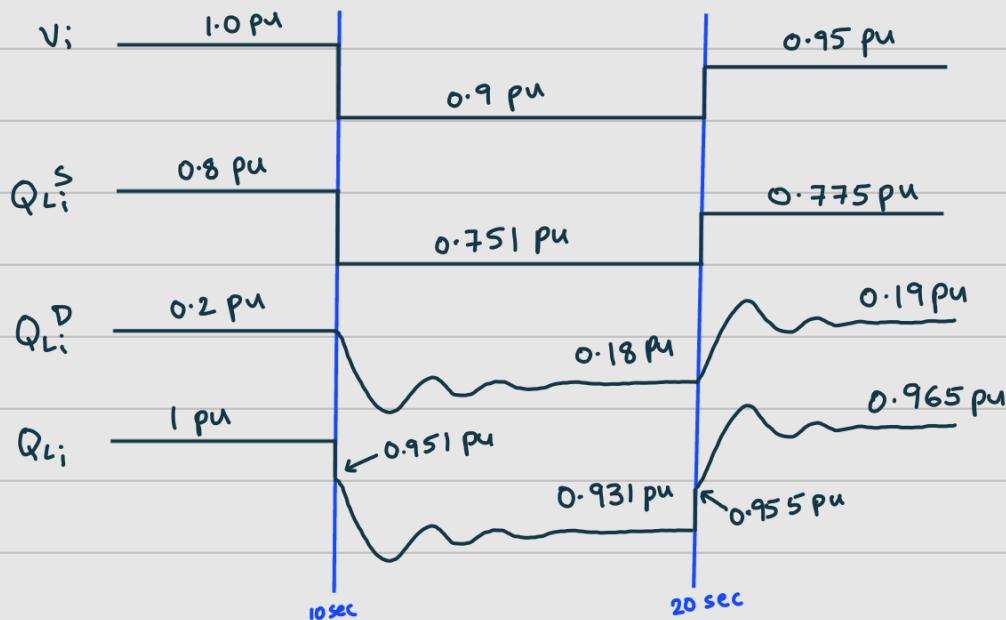
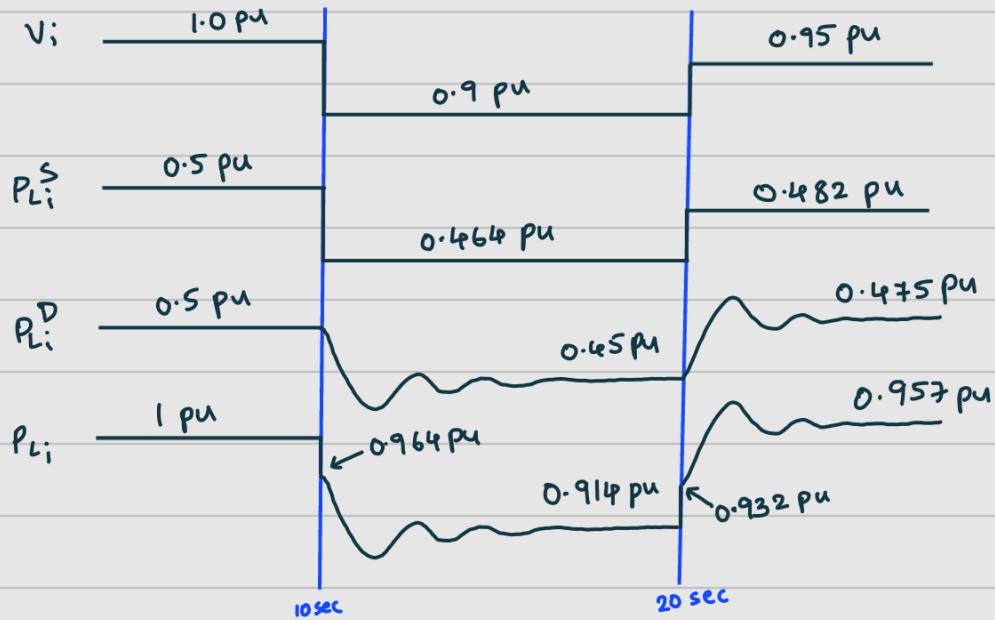
$$M_p = 98.62 \text{ J.}$$

$$T_s = \frac{4}{\xi \omega_n} = \frac{4}{0.0044\sqrt{20}} = 203 \text{ sec}$$

$$T_p = \frac{4}{\omega_n \sqrt{1-\xi^2}} = \frac{4}{\sqrt{20} \sqrt{1-0.0044^2}} = 0.894 \text{ sec}$$

$\xi < 1 \Rightarrow$ underdamped system

Assuming the response settles down before next disturbance

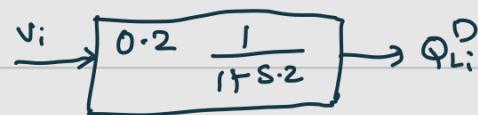
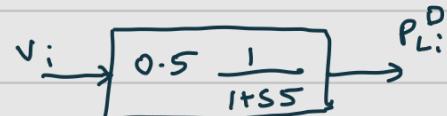


i) C a Given $P_{L_i}^D = P_{L_i}^S + P_{L_i}^S ; 100 \text{ MW}$

$Q_{L_i} = Q_{L_i}^D + Q_{L_i}^S ; 50 \text{ MVAR}$

$$P_{L_i}^S = 0.5 V_i^{0.7}$$

$$Q_{L_i}^S = 0.8 V_i^{0.6}$$



for $t < 10 \text{ sec}$

$$V = 1 \text{ pu} ; P_{L_i}^S = 0.5 (1)^{0.7} = 0.5 \text{ pu} ; P_{L_i}^D = (1)(0.5) = 0.5 \text{ pu}$$

$$Q_{L_i}^S = 0.8 (1)^{0.6} = 0.8 \text{ pu} ; Q_{L_i}^D = (1)(0.2) = 0.2 \text{ pu}$$

at $t = 10^+ \text{ sec}$

$$V = 1.05 \text{ p.u. } P_{L_i}^S = 0.5 (1.05)^{0.7} = 0.517 \text{ pu}$$

$$Q_{L_i}^S = 0.8 (1.05)^{0.6} = 0.824 \text{ pu}$$

Steady state values of $P_{L_i}^D$ & $Q_{L_i}^D$

$$P_{L_i}^D = (1.05)(0.5) = 0.525 \text{ pu}$$

$$Q_{L_i}^D = (1.05)(0.2) = 0.21 \text{ pu}$$

at $t = 20^+ \text{ sec}$

$$V = 0.95 \text{ p.u. } P_{L_i}^S = 0.5 (0.95)^{0.7} = 0.482 \text{ pu}$$

$$Q_{L_i}^S = 0.8 (0.95)^{0.6} = 0.775 \text{ pu}$$

Steady state values of $P_{L_i}^D$ & $Q_{L_i}^D$

$$P_{L_i}^D = (0.95)(0.5) = 0.475 \text{ pu}$$

$$Q_{L_i}^D = (0.95)(0.2) = 0.19 \text{ pu}$$

at $t = 30^+ \text{ sec}$

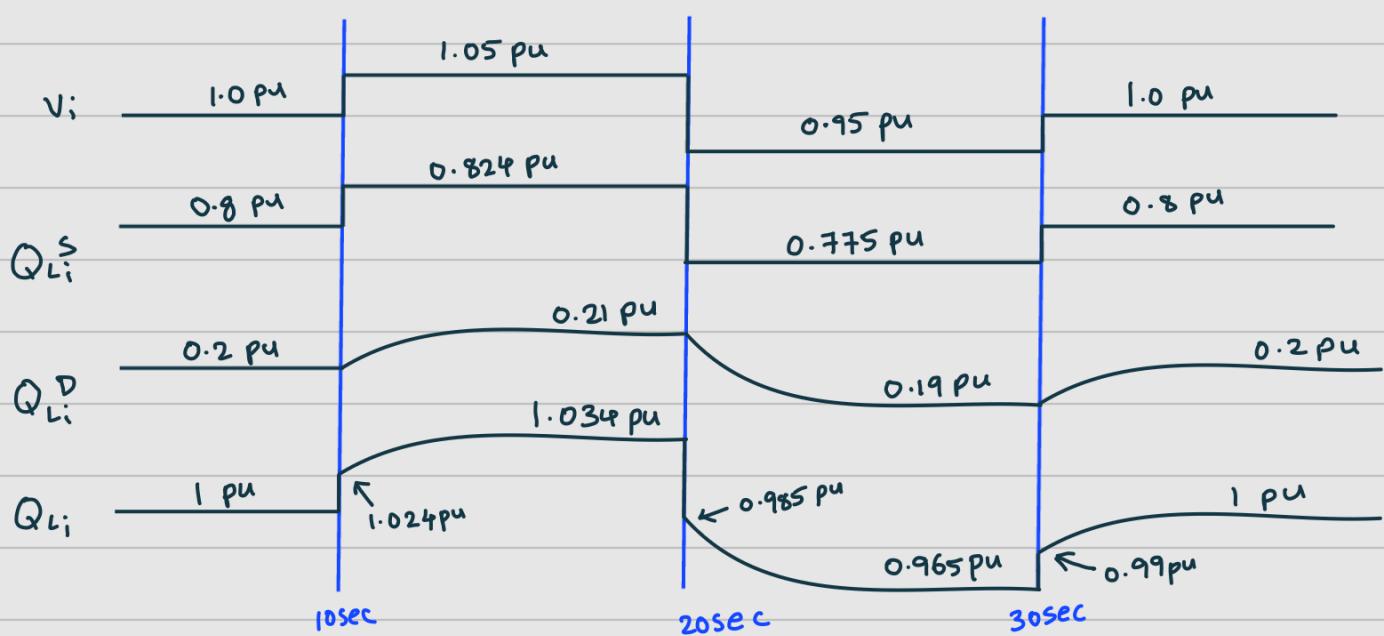
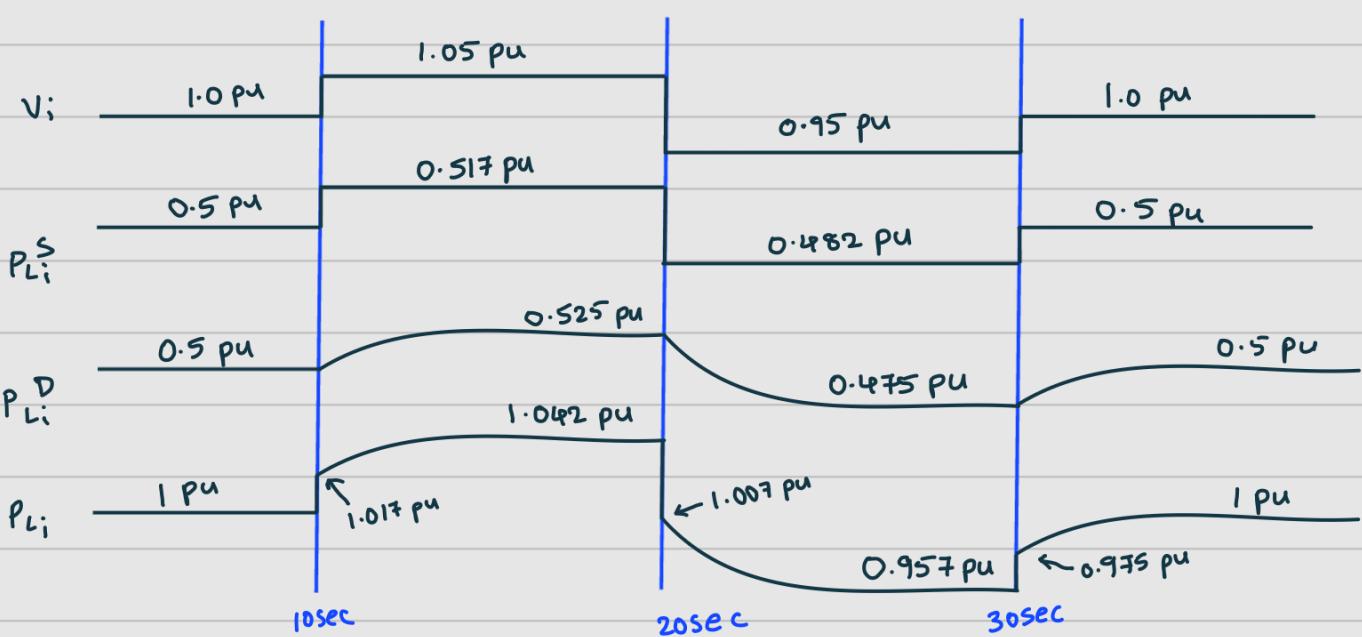
$$V = 1 \text{ pu} ; P_{L_i}^S = 0.5 (1)^{0.7} = 0.5 \text{ pu}$$

$$Q_{L_i}^S = 0.8 (1)^{0.6} = 0.8 \text{ pu}$$

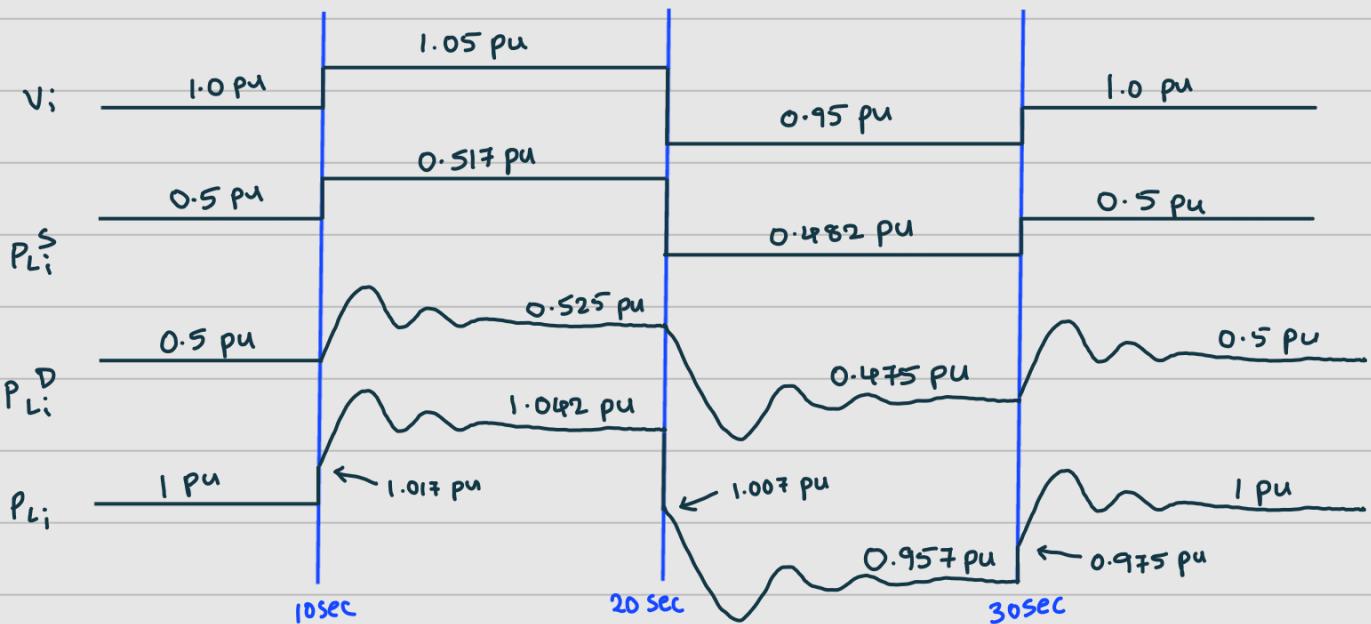
Steady state values of $P_{L_i}^D$ & $Q_{L_i}^D$

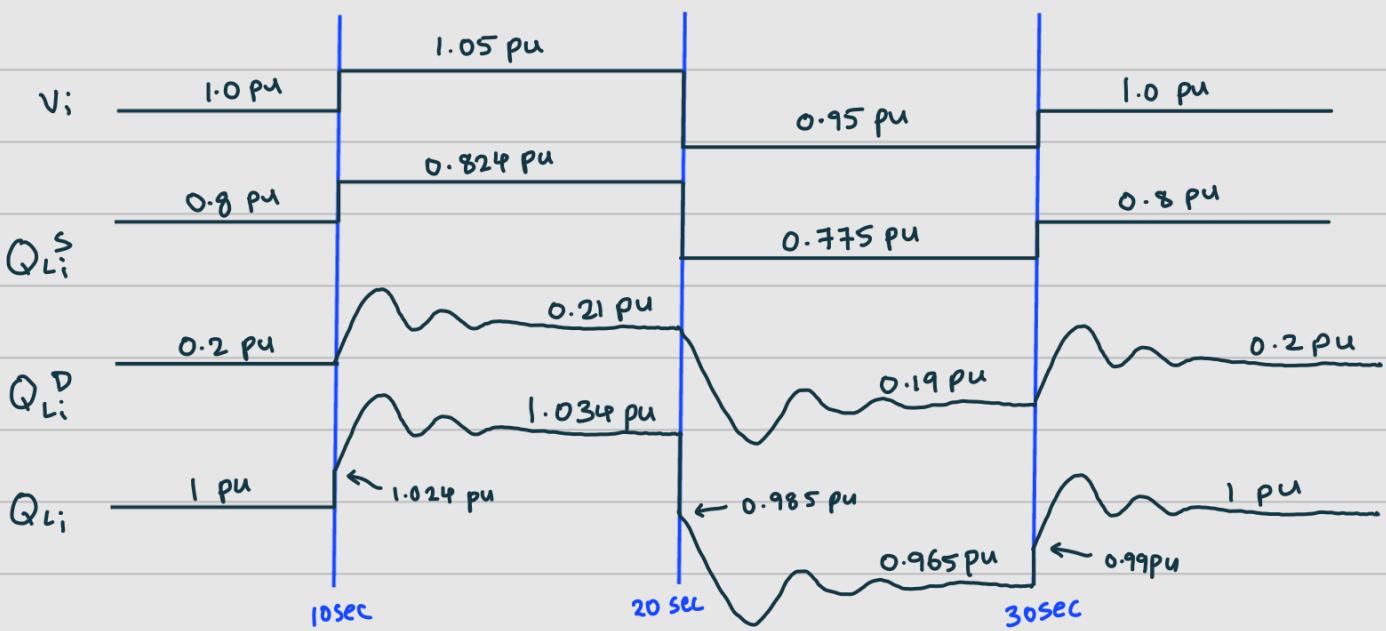
$$P_{L_i}^D = (1)(0.5) = 0.5 \text{ pu}$$

$$Q_{L_i}^D = (1)(0.2) = 0.2 \text{ pu}$$

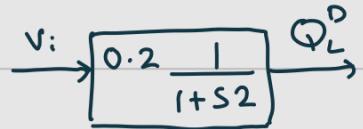
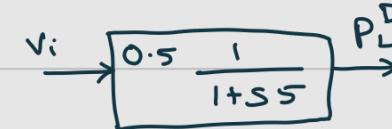


①(c)b the response follows same values as ①(c)a however a second order response is observed.





① d) Given $P_L^S = 0.2 + 0.2V + 0.1V^2$
 $Q_L^S = 0.1V + 0.1V^2$



for $t < 10 \text{ sec}$

$$V = 1 \text{ pu} ; P_{L_i}^S = 0.2 + 0.2(1) + 0.1(1)^2 = 0.5 \text{ pu}$$

$$Q_{L_i}^S = 0.1(1) + 0.1(1)^2 = 0.2 \text{ pu}$$

$$P_{L_i}^D = (1)(0.5) = 0.5 \text{ pu}$$

$$Q_{L_i}^D = (1)(0.2) = 0.2 \text{ pu}$$

at $t = 10^+$ sec

$$V = 0.9 \text{ p.u. } P_{L_i}^S = 0.2 + 0.2(0.9) + 0.1(0.9)^2 = 0.461 \text{ pu}$$

$$Q_{L_i}^S = 0.1(0.9) + 0.1(0.9)^2 = 0.171 \text{ pu}$$

Steady state values of $P_{L_i}^D$ & $Q_{L_i}^D$

$$P_{L_i}^D = (0.9)(0.5) = 0.45 \text{ pu}$$

$$Q_{L_i}^D = (0.9)(0.2) = 0.18 \text{ pu}$$

at $t = 20^+$ sec

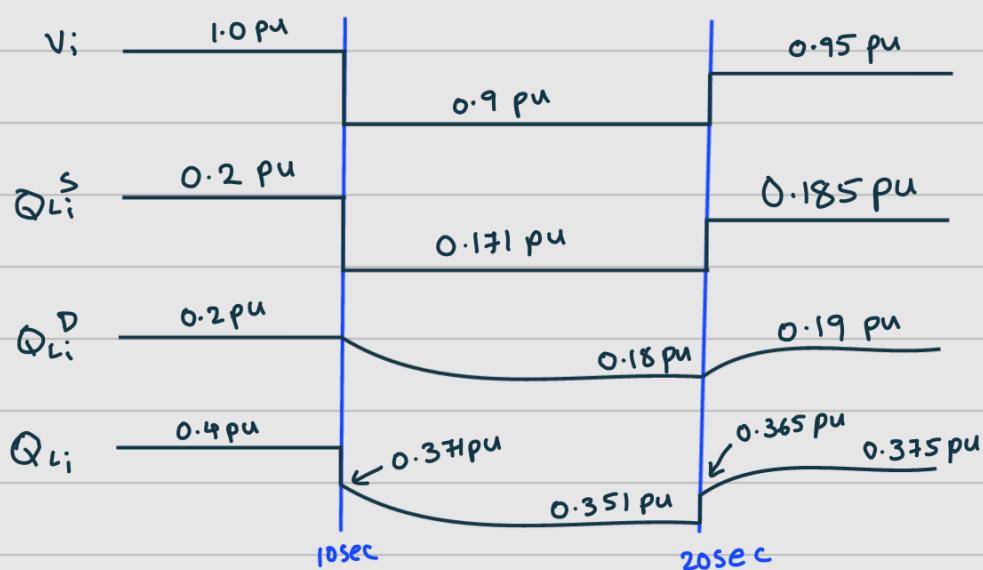
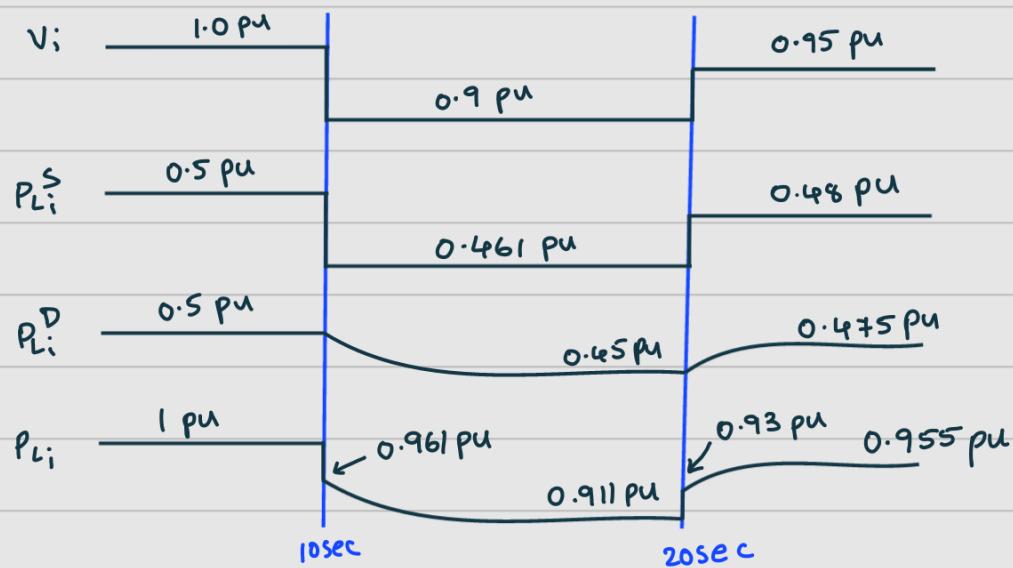
$$V = 0.95 \text{ p.u. } P_{L_i}^S = 0.2 + 0.2(0.95) + 0.1(0.95)^2 = 0.48 \text{ pu}$$

$$Q_{L_i}^S = 0.1(0.95) + 0.1(0.95)^2 = 0.185 \text{ pu}$$

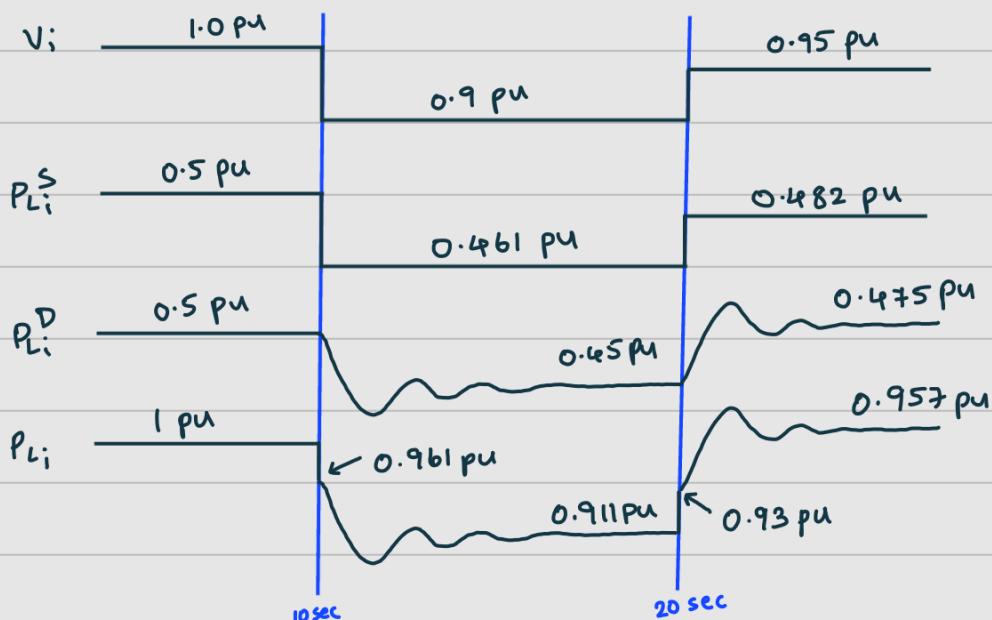
Steady state values of $P_{L_i}^D$ & $Q_{L_i}^D$

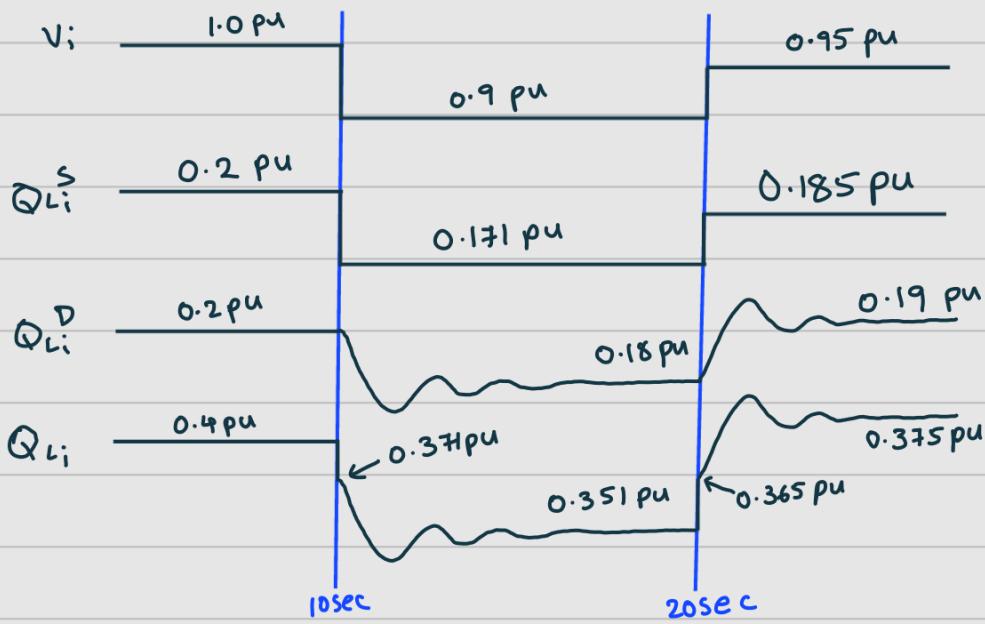
$$P_{L_i}^D = (0.95)(0.5) = 0.475 \text{ pu}$$

$$Q_{L_i}^D = (0.95)(0.2) = 0.19 \text{ pu}$$



①(d)b the response follows same values as ①(d)a however, a second order response is observed.





(1) (d) Given $P_L^S = 0.2 + 0.2V + 0.1V^2$ $V_i \rightarrow [0.5 \frac{1}{1+5s}] P_L^D$ $V_i \rightarrow [0.2 \frac{1}{1+52s}] Q_L^D$

$$Q_L^S = 0.1V + 0.1V^2$$

for $t < 10$ sec

$$V = 1 \text{ pu} ; P_{L_i}^S = 0.2 + 0.2(1) + 0.1(1)^2 = 0.5 \text{ pu}$$

$$Q_{L_i}^S = 0.1(1) + 0.1(1)^2 = 0.2 \text{ pu}$$

$$P_{L_i}^D = (1)(0.5) = 0.5 \text{ pu}$$

$$Q_{L_i}^D = (1)(0.2) = 0.2 \text{ pu}$$

at $t = 10^+$ sec

$$V = 1.05 \text{ p.u. } P_{L_i}^S = 0.2 + 0.2(1.05) + 0.1(1.05)^2 = 0.52 \text{ pu}$$

$$Q_{L_i}^S = 0.1(1.05) + 0.1(1.05)^2 = 0.215 \text{ pu}$$

Steady state values of $P_{L_i}^D$ & $Q_{L_i}^D$

$$P_{L_i}^D = (1.05)(0.5) = 0.525 \text{ pu}$$

$$Q_{L_i}^D = (1.05)(0.2) = 0.21 \text{ pu}$$

at $t = 20^+$ sec

$$V = 0.95 \text{ p.u. } P_{L_i}^S = 0.2 + 0.2(0.95) + 0.1(0.95)^2 = 0.48 \text{ pu}$$

$$Q_{L_i}^S = 0.1(0.95) + 0.1(0.95)^2 = 0.185 \text{ pu}$$

Steady state values of $P_{L_i}^D$ & $Q_{L_i}^D$

$$P_{L_i}^D = (0.95)(0.5) = 0.475 \text{ pu}$$

$$Q_{L_i}^D = (0.95)(0.2) = 0.19 \text{ pu}$$

at $t = 30^+$ sec

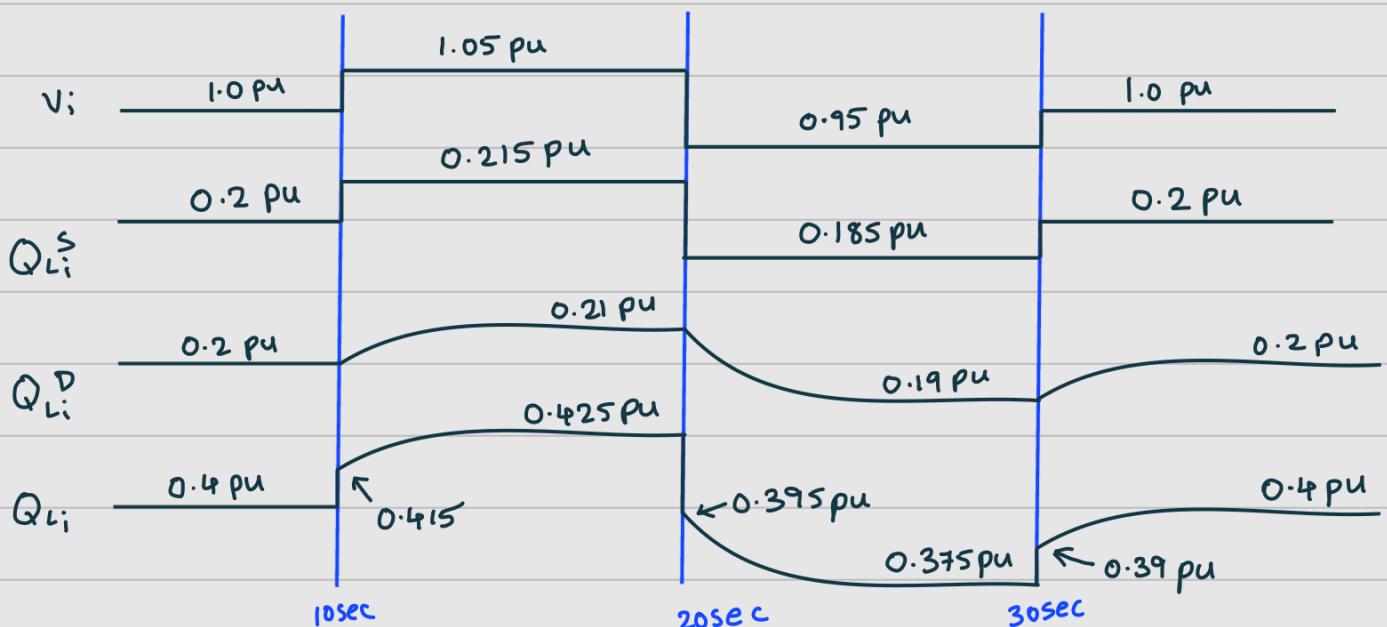
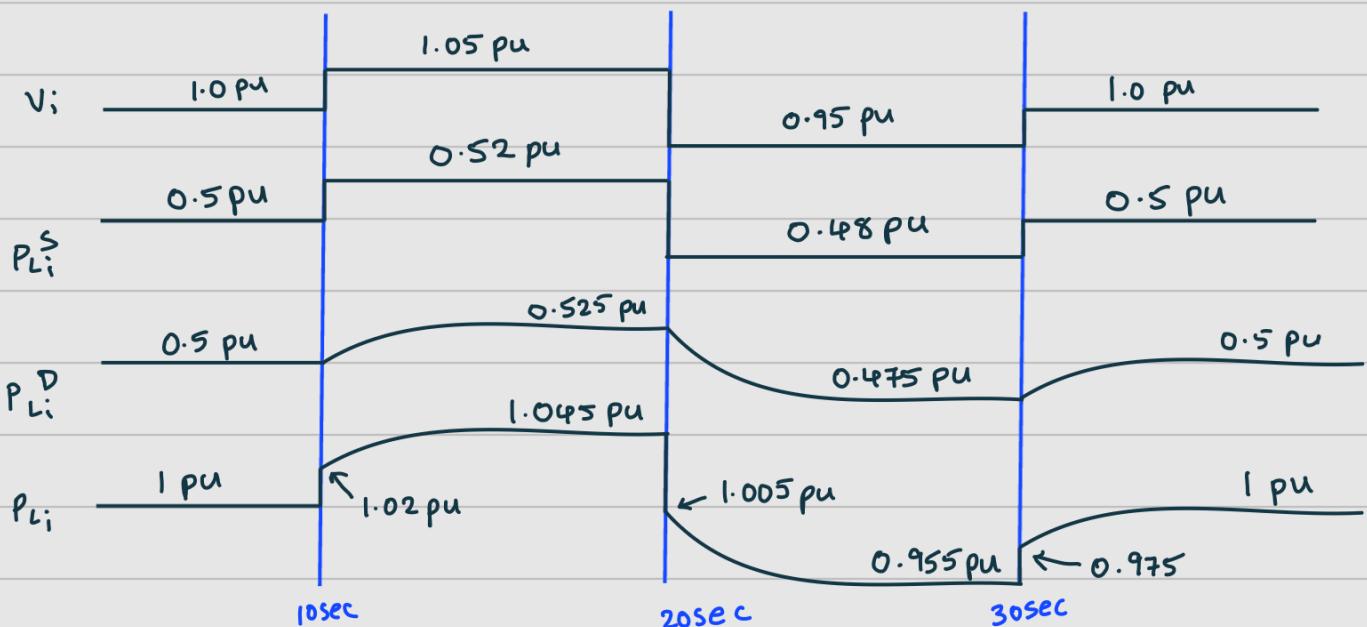
$$V = 1 \text{ pu}; P_{L_i}^S = 0.2 + 0.2(1) + 0.1(1)^2 = 0.5 \text{ pu}$$

$$Q_{L_i}^S = 0.1(1) + 0.1(1)^2 = 0.2 \text{ pu}$$

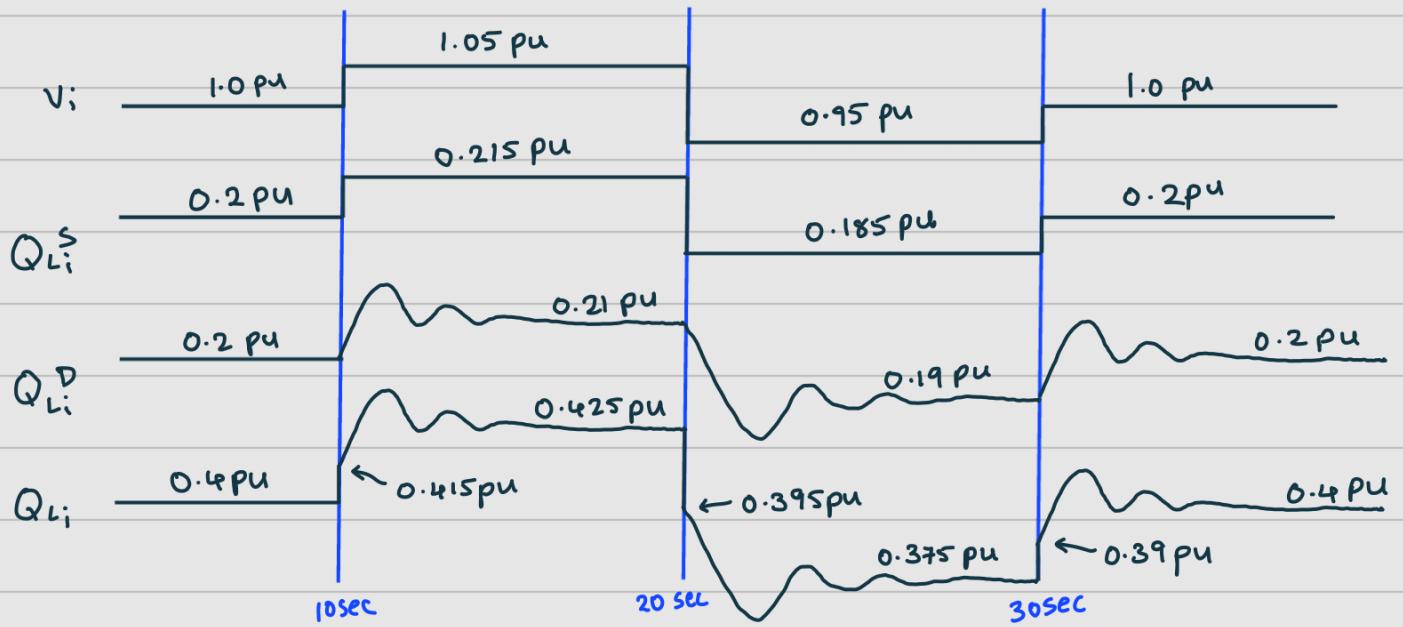
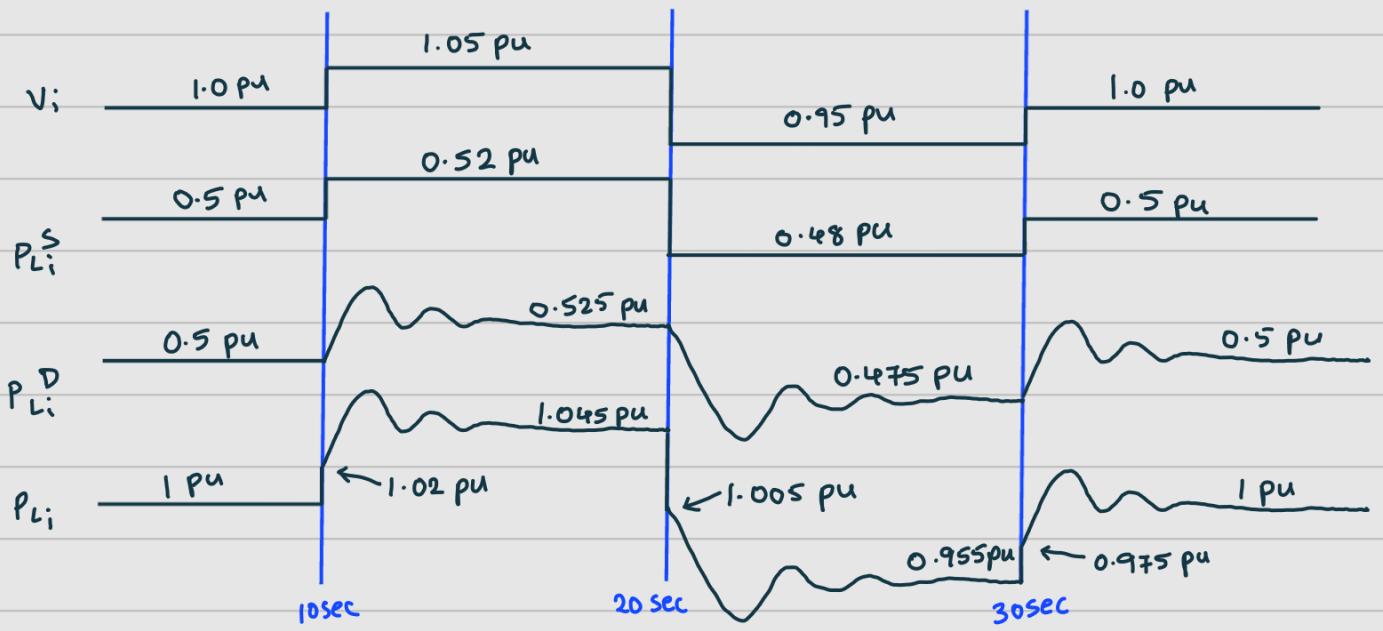
Steady state values of $P_{L_i}^D$ & $Q_{L_i}^D$

$$P_{L_i}^D = (1)(0.5) = 0.5 \text{ pu}$$

$$Q_{L_i}^D = (1)(0.2) = 0.2 \text{ pu}$$



①(d)cb the response follows same values as ①(d)ca however, a second order response is observed.



(2)

Assume first order ZIP model

$$P_L^S = P_{L0} + M_p V + G_p V^2; P_L^D = \frac{K_p^D}{1+Sb_p} V$$

At $t = 5^-$ sec

$$V = 1 \text{ pu}; P_L = 0.9 \text{ pu}$$

$$P_{L0} + M_p + G_p + K_p^D = 0.9 \quad (1a)$$

At $t = 5^+$ sec

$$V = 0.9 \text{ pu}; P_L = 0.842 \text{ pu}$$

$$P_{L0} + 0.9M_p + 0.81G_p + K_p^D = 0.842 \quad (2a)$$

At $t = 20^-$ sec

$$V = 0.9 \text{ pu}; P_L = 0.792$$

$$P_{L0} + 0.9M_p + 0.81G_p + 0.9K_p^D = 0.792 \quad (3a)$$

$$(2a) - (3a) \Rightarrow 0.1K_p^D = 0.05$$

$$\underline{\underline{K_p^D = 0.5}}$$

At $t = 20^+$ sec

$$V = 1.1 \text{ pu}; P_L = 0.912 \text{ pu}$$

$$P_{L0} + 1.1M_p + 1.21G_p + 0.9K_p^D = 0.912 \quad (4a)$$

$$(1a) - (4a) \Rightarrow 0.1M_p + 0.19G_p = 0.058 \quad (5a)$$

$$(4a) - (3a) \Rightarrow 0.2M_p + 0.4G_p = 0.12 \quad (6a)$$

$$2 \times (5a) \Rightarrow 0.2M_p + 0.38G_p = 0.116 \quad (7a)$$

$$(6a) - (7a) \Rightarrow 0.02G_p = 0.004$$

$$\underline{\underline{G_p = 0.2}}$$

 $G_p = 0.2 \text{ in } (5a)$

$$0.1M_p + 0.19(0.2) = 0.058$$

$$Q_L^S = Q_{L0} + M_q V + G_q V^2; Q_L^D = \frac{K_q^D}{1+Sb_q} V$$

At $t = 5^-$ sec

$$V = 1 \text{ pu}; Q_L = 0.3 \text{ pu}$$

$$Q_{L0} + M_q + G_q + K_q^D = 0.3 \quad (1b)$$

At $t = 5^+$ sec

$$V = 0.9 \text{ pu}; Q_L = 0.29 \text{ pu}$$

$$Q_{L0} + 0.9M_q + 0.81G_q + K_q^D = 0.29 \text{ pu} \quad (2b)$$

At $t = 20^-$ sec

$$V = 0.9 \text{ pu}; Q_L = 0.27$$

$$Q_{L0} + 0.9M_q + 0.81G_q + 0.9K_q^D = 0.27 \quad (3b)$$

$$(2b) - (3b) \Rightarrow 0.1K_q^D = 0.02$$

$$\underline{\underline{K_q^D = 0.2}}$$

At $t = 20^+$ sec

$$V = 1.1 \text{ pu}; Q_L = 0.29 \text{ pu}$$

$$Q_{L0} + 1.1M_q + 1.21G_q^2 + 0.9K_q^D = 0.29 \quad (4b)$$

$$(1b) - (4b) \Rightarrow 0.1M_q + 0.19G_q = 0.01 \quad (5b)$$

$$(4b) - (3b) \Rightarrow 0.2M_q + 0.4G_q = 0.02 \quad (6b)$$

$$2 \times (5b) \Rightarrow 0.2M_q + 0.38G_q = 0.02 \quad (7b)$$

$$(6b) - (7b) \Rightarrow 0.02G_q = 0$$

$$\underline{\underline{G_q = 0}}$$

 $G_q = 0 \text{ in } (5b)$

$$0.1M_q = 0.01$$

$$0.1 M_p = 0.02$$

$$\underline{\underline{M_p = 0.2}}$$

$$M_p = 0.2, G_p = 0.2, K_p^D = 0.5 \text{ in } (1a)$$

$$P_{L0} + 0.2 + 0.2 + 0.5 = 0.9$$

$$\underline{\underline{P_{L0} = 0}}$$

$$\underline{\underline{P_L^S = 0.2 V + 0.2 V^2}}$$

From graph, $b_p = 24 - 20 = 4 \text{ sec}$

$$\underline{\underline{P_L^D = \frac{0.5}{1+5.4} V}}$$

$$\underline{\underline{M_Q = 0.1}}$$

$$M_Q = 0.1, G_Q = 0, K_Q^D = 0.2 \text{ in } (1b)$$

$$Q_{L0} + 0.1 + 0 + 0.2 = 0.3$$

$$\underline{\underline{Q_{L0} = 0}}$$

$$\underline{\underline{Q_L^S = 0.1 V}}$$

From graph, $b_Q = 22 - 2 = 2 \text{ sec}$

$$\underline{\underline{Q_L^D = \frac{0.2}{1+5.2} V}}$$