EECS 545: Machine Learning

Lecture 14. Markov Networks

Honglak Lee 2/23/2011





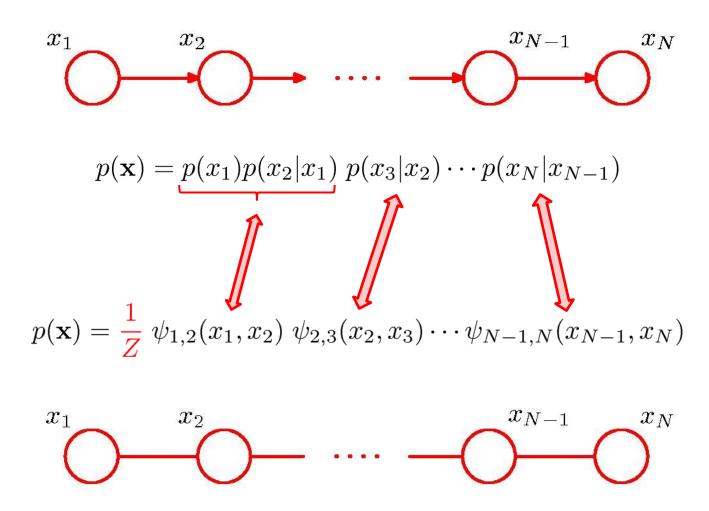
Midterm Student Feedback

- Ending classes on time!
- More high-level intuitions and applications
 - I will try to incorporate as much as possible.
 However, it is important to point out that the goal of this course is to provide you sufficient depth.
- More interactions
 - I will try to incorporate some short (1 min) quizes that include discussions between pair of students and the instructor.

Outline

- Directed vs Undirected graphical models
- Inference in graphical models

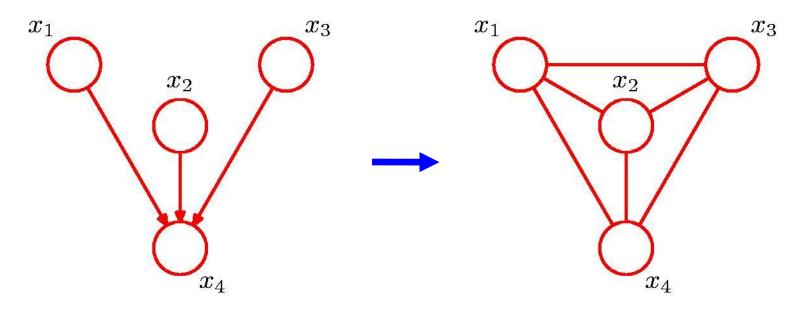
Converting Directed to Undirected Graphs (1)



Converting Directed to Undirected Graphs (2)

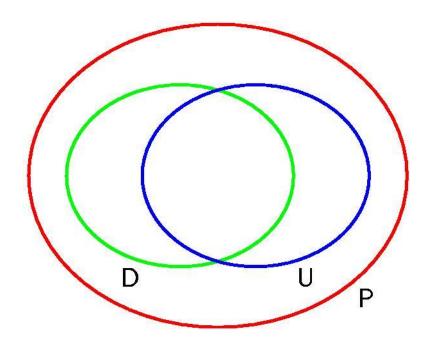
Additional links

Moralizing: "Moral Graph"



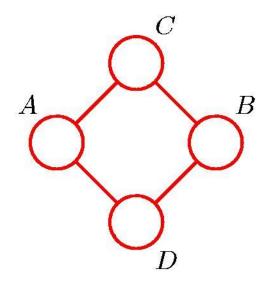
$$p(\mathbf{x}) = p(x_1)p(x_2)p(x_3)p(x_4|x_1, x_2, x_3)$$
$$= \frac{1}{Z}\psi_A(x_1, x_2, x_3)\psi_B(x_2, x_3, x_4)\psi_C(x_1, x_2, x_4)$$

Directed vs. Undirected Graphs (1)



Directed vs. Undirected Graphs (2)

E.g., Markov Network, but cannot be represented by Bayesian Network



Q. Can this graph be converted into an equivalent directed graph? If not, why?

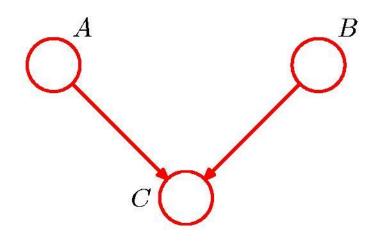
$$A \not\perp\!\!\!\perp B \mid \emptyset$$

$$A \perp\!\!\!\perp B \mid C \cup D$$

$$C \perp\!\!\!\perp D \mid A \cup B$$

Directed vs. Undirected Graphs (3)

E.g., Bayesian Network, but cannot be represented by Markov Network

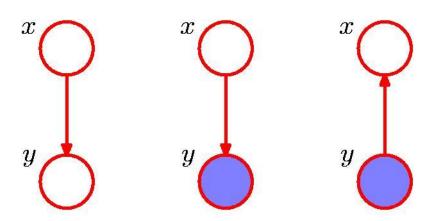


Q. Can this graph be converted into an equivalent undirected graph? If not, why?

$$A \perp \!\!\!\perp B \mid \emptyset$$
 $A \not\perp \!\!\!\perp B \mid C$

Inference in graphical models

Inference in Graphical Models



Marginal probability

$$p(y) = \sum_{x'} p(y|x')p(x')$$
 $p(x|y) = \frac{p(y|x)p(x)}{p(y)}$

Posterior probability

$$p(x|y) = \frac{p(y|x)p(x)}{p(y)}$$

$$x_1 \qquad x_2 \qquad x_{N-1} \qquad x_N$$

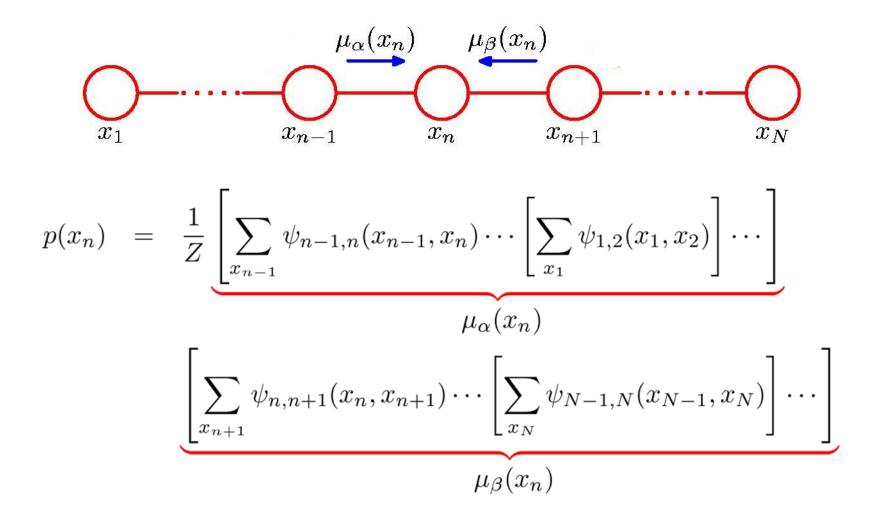
$$p(\mathbf{x}) = \frac{1}{Z} \psi_{1,2}(x_1, x_2) \psi_{2,3}(x_2, x_3) \cdots \psi_{N-1,N}(x_{N-1}, x_N)$$

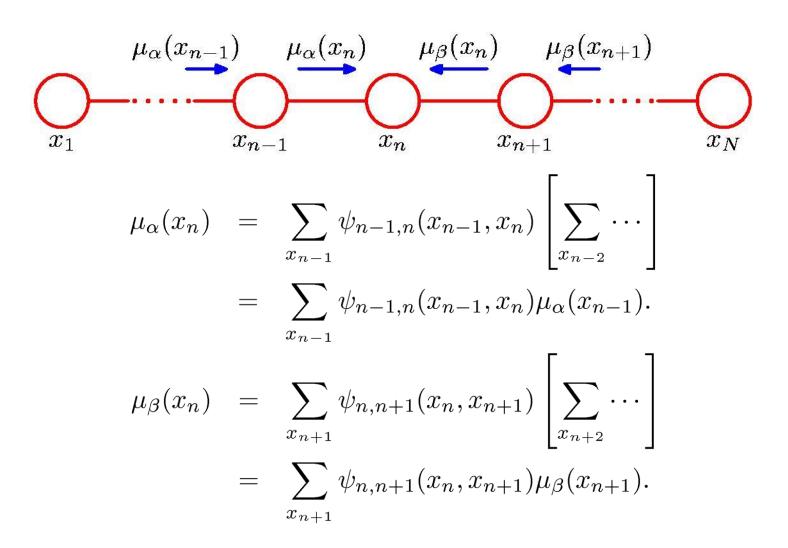
$$p(x_n) = \sum_{x_1} \cdots \sum_{x_{n-1}} \sum_{x_{n+1}} \cdots \sum_{x_N} p(\mathbf{x})$$

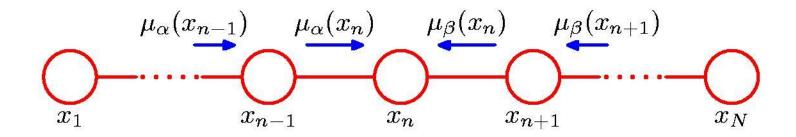
$$\frac{1}{Z} \psi_{1,2}(x_1, x_2) \psi_{2,3}(x_2, x_3) \cdots \psi_{N-1,N}(x_{N-1}, x_N)$$

$$p(x_n) = \sum_{x_1} \cdots \sum_{x_{n-1}} \sum_{x_{n+1}} \cdots \sum_{x_N} p(\mathbf{x})$$

$$\sum_{x_N} \frac{1}{Z} \psi_{1,2}(x_1, x_2) \psi_{2,3}(x_2, x_3) \cdots \psi_{N-1,N}(x_{N-1}, x_N)$$







$$\mu_{\alpha}(x_2) = \sum_{x_1} \psi_{1,2}(x_1, x_2)$$

$$\mu_{\beta}(x_{N-1}) = \sum_{x_N} \psi_{N-1,N}(x_{N-1}, x_N)$$

$$Z = \sum_{x_n} \mu_{\alpha}(x_n) \mu_{\beta}(x_n)$$

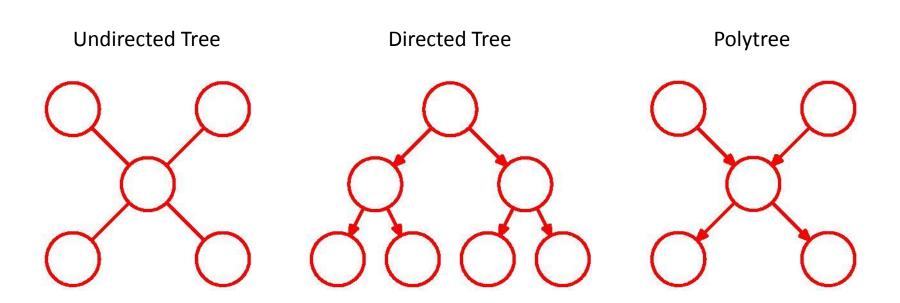
Q. Can you understand why three recursion rules hold?

- To compute local marginals:
 - Compute and store all forward messages, $\mu_{\alpha}(x_n)$.
 - Compute and store all backward messages, $\mu_{\beta}(x_n)$.
 - Compute Z at any node X_m
 - Compute

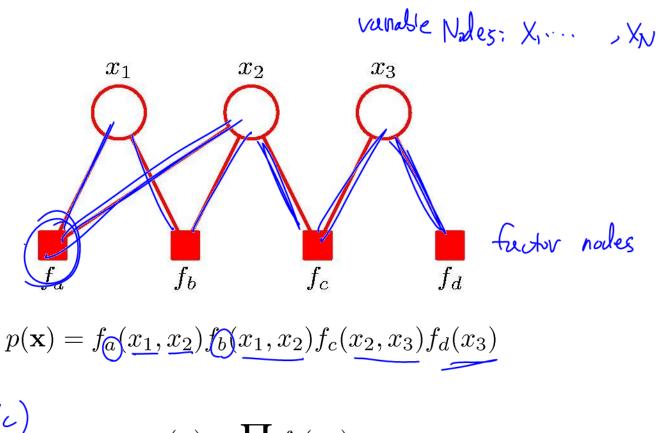
$$p(x_n) = \frac{1}{Z} \mu_{\alpha}(x_n) \mu_{\beta}(x_n)$$

for all variables required.

Trees

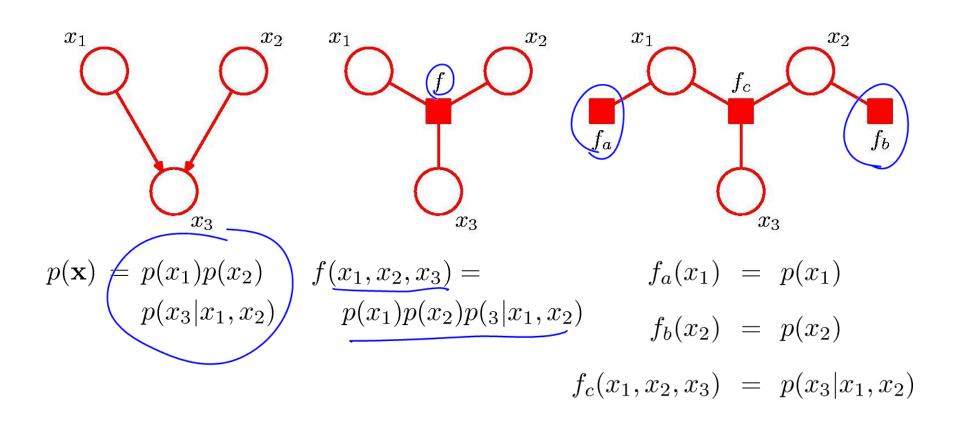


Factor Graphs

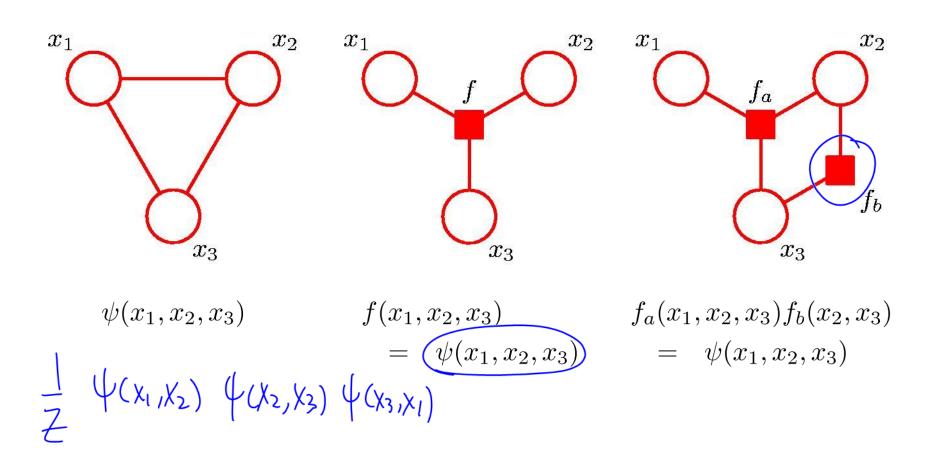


$$p(\mathbf{x}) = \prod_{s} f_s(\mathbf{x}_s)$$

Factor Graphs from Directed Graphs



Factor Graphs from Undirected Graphs

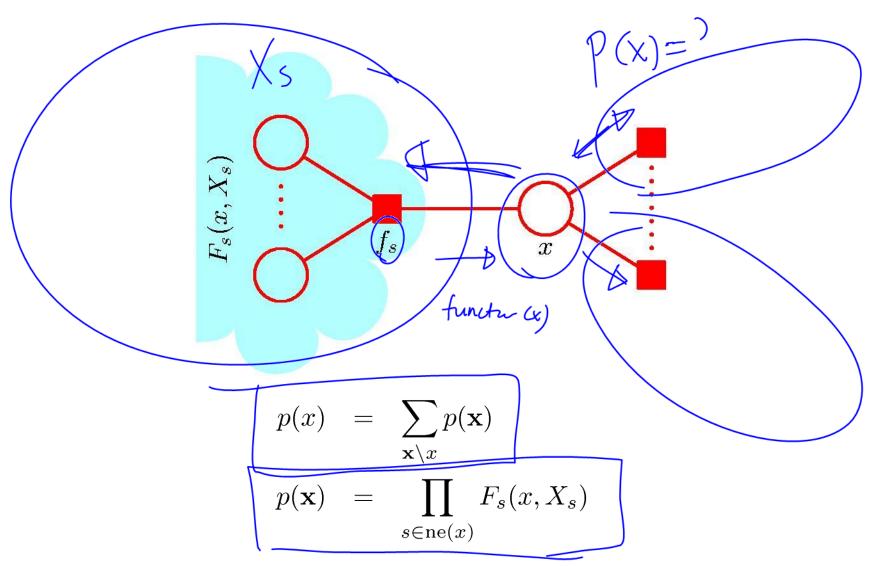


The Sum-Product Algorithm (1)

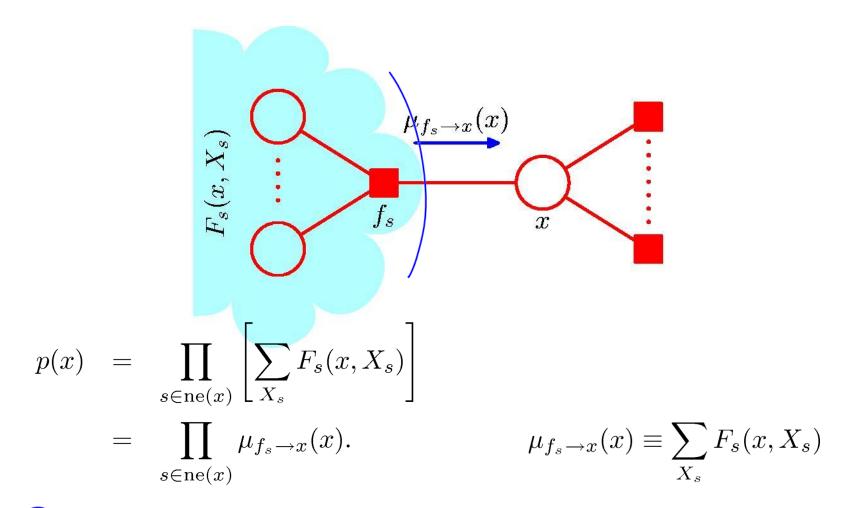
- Objective:
 - to obtain an efficient, exact inference algorithm for finding marginals;
 - ii. in situations where several marginals are required, to allow computations to be shared efficiently.
- Key idea: Distributive Law

$$ab + ac = a(b+c)$$

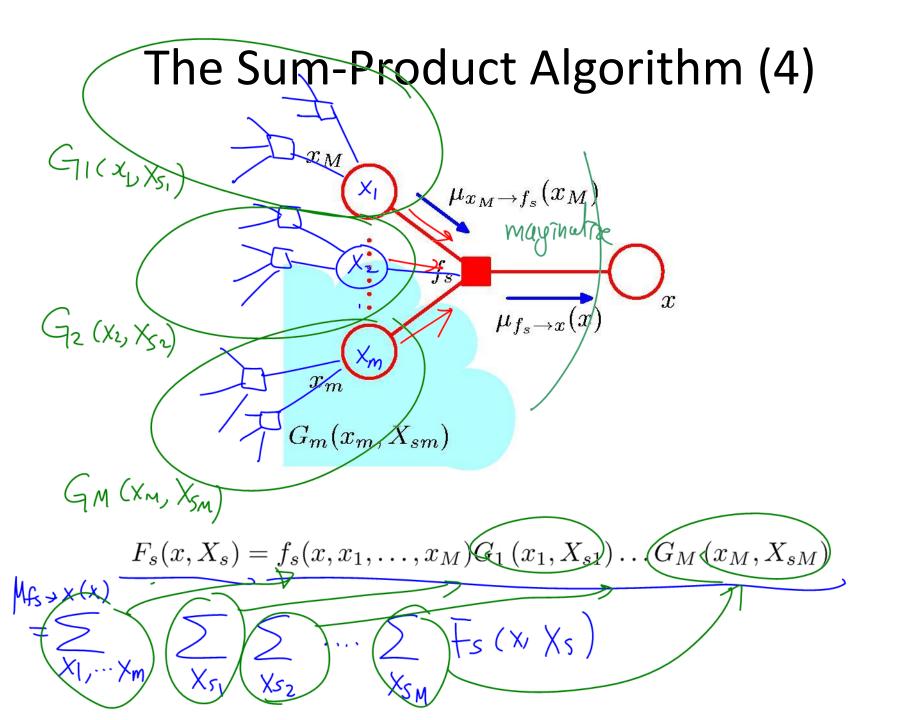
The Sum-Product Algorithm (2)



The Sum-Product Algorithm (3)

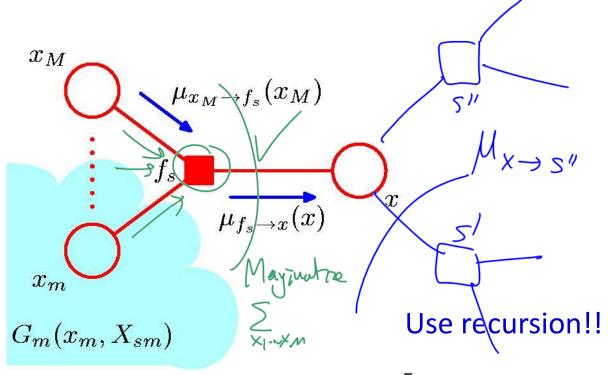


 X_s : the set of all variables in the subtree (connected to x via the factor node f_s) $F_s(x,X_s)$: the product of all the factors in the group associated with factor fs.



$$\begin{array}{lll}
M_{f_{S} \to X}(X) &=& \sum_{X_{1}, \dots, X_{M}} \sum_{X_{S_{2}}} & \dots & \sum_{X_{S_{M}}} \overline{f_{S}}(X_{1} X_{1} X_{2}) & \dots & \sum_{X_{S_{M}}} \overline{f_{S}}(X_{1} X_{2} X_{3}) & \dots & G_{M}(X_{M} X_{M}) \\
&=& \sum_{X_{1} \dots X_{M}} f_{S}(X_{1} \dots X_{M}) & \sum_{X_{S_{1}}} G_{1}(X_{1} X_{S_{1}}) & \sum_{X_{S_{2}}} G_{2}(X_{2}, X_{S_{2}}) & \dots & \sum_{X_{S_{M}}} G_{1}(X_{M} X_{S_{M}}) \\
&=& \sum_{X_{1} \dots X_{M}} f_{S}(X_{1} \dots X_{M}) & \sum_{X_{S_{1}}} G_{1}(X_{1} X_{S_{1}}) & \sum_{X_{S_{2}}} G_{2}(X_{2}, X_{S_{2}}) & \dots & \sum_{X_{S_{M}}} G_{1}(X_{M} X_{S_{M}}) \\
&=& \sum_{X_{1} \dots X_{M}} f_{S}(X_{1} \dots X_{M}) & \sum_{X_{S_{1}}} G_{1}(X_{1} X_{S_{1}}) & \sum_{X_{S_{2}}} G_{2}(X_{2}, X_{S_{2}}) & \dots & \sum_{X_{S_{M}}} G_{1}(X_{M} X_{S_{M}}) \\
&=& \sum_{X_{1} \dots X_{M}} f_{S}(X_{1} \dots X_{M}) & \sum_{X_{S_{1}}} G_{1}(X_{1} X_{S_{1}}) & \sum_{X_{S_{1}}} G_{2}(X_{2} X_{S_{2}}) & \dots & \sum_{X_{S_{M}}} G_{1}(X_{M} X_{S_{M}}) \\
&=& \sum_{X_{1} \dots X_{M}} f_{S}(X_{1} \dots X_{M}) & \sum_{X_{1} \dots X_{M}} G_{1}(X_{M} X_{S_{M}}) & \sum_{X_{1} \dots X_{M}} G_{1}(X_{M} X_{S_{M}}) & \sum_{X_{1} \dots X_{M}} G_{1}(X_{M} X_{S_{M}}) \\
&=& \sum_{X_{1} \dots X_{M}} f_{S}(X_{1} \dots X_{M}) & \sum_{X_{1} \dots X_{M}} G_{1}(X_{M} X_{S_{M}}) & \sum_{X_{2} \dots X_{M}} G_{1}(X_{M} X_{S_{M}}) & \sum_{X_{2} \dots X_{M}} G_{1}(X_{M} X_{S_{M}}) \\
&=& \sum_{X_{1} \dots X_{M}} f_{S}(X_{1} \dots X_{M}) & \sum_{X_{1} \dots X_{M}} G_{1}(X_{M} X_{S_{M}}) & \sum_{X_{2} \dots X_{M}} G_{2}(X_{M} X_{M} X_{M}) & \sum_{X_{2} \dots X_{M}} G_{2}(X_{M} X_{M} X_{M} X_{M}) & \sum_{X_{2} \dots X_{M}} G_{2}(X_{M} X_{M} X_{M} X_{M} X_{M}) & \sum_{X_{2} \dots X_{M}} G_{2}(X_{M} X_{M} X_{M} X_{M}) & \sum_{X_{2} \dots X_{M}} G_{2}$$

The Sum-Product Algorithm (5)



$$\mu_{f_s \to x}(x) = \sum_{x_1} \dots \sum_{x_M} f_s(x, x_1, \dots, x_M) \prod_{m \in \text{ne}(f_s) \setminus x} \left[\sum_{X_{sm}} G_m(x_m, X_{sm}) \right]$$

$$= \sum_{x_1} \dots \sum_{x_M} f_s(x, x_1, \dots, x_M) \prod_{m \in \text{ne}(f_s) \setminus x} \mu_{x_m \to f_s}(x_m)$$

$$\mathcal{M}_{X \to S''(X)} = \mathcal{M}_{f_s \to X} (X) \cdot \mathcal{M}_{f_{S'} \to X} (X) = \mathcal{M}_{f_s \to X} (X)$$

$$M_{fs\rightarrow x} = \int_{s} f_{s}(x_{N(x)}) \prod_{j \in N(t_{s}) \setminus x} \mu_{x_{j}\rightarrow f_{s}}(x_{j})$$

$$= \int_{x_{t}} f_{s}(x_{N(x)}) \prod_{j \in N(t_{s}) \setminus x} \mu_{x_{j}\rightarrow f_{s}}(x_{j})$$

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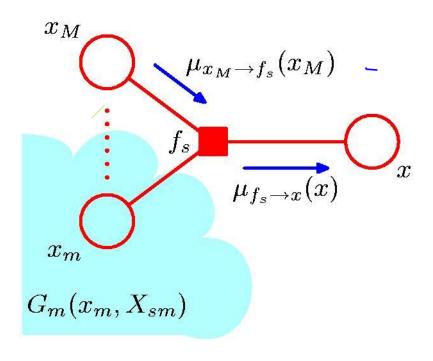
$$= \int_{x_{t}} f_{s}(x_{N(x)}) \prod_{j \in N(t_{s}) \setminus x} \mu_{x_{j}\rightarrow f_{s}}(x_{j})$$

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The Sum-Product Algorithm (6)

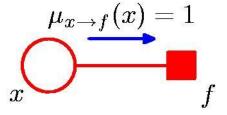


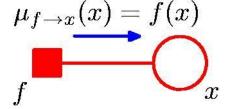
$$\mu_{x_m \to f_s}(x_m) \equiv \sum_{X_{sm}} G_m(x_m, X_{sm}) = \sum_{X_{sm}} \prod_{l \in \text{ne}(x_m) \setminus f_s} F_l(x_m, X_{ml})$$

$$= \prod_{l \in \text{ne}(x_m) \setminus f_s} \mu_{f_l \to x_m}(x_m)$$

The Sum-Product Algorithm (7)

Initialization

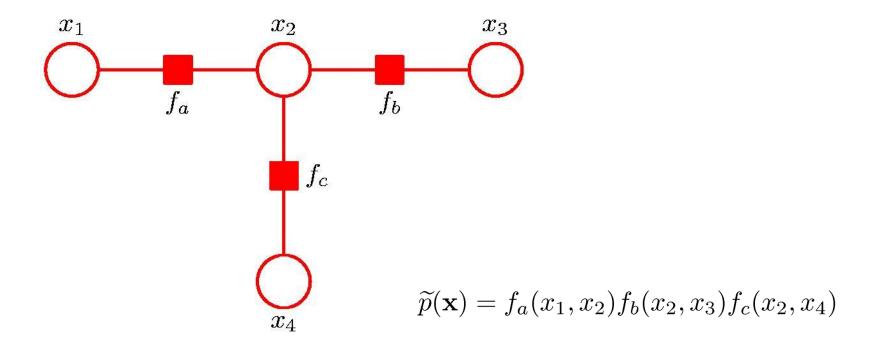




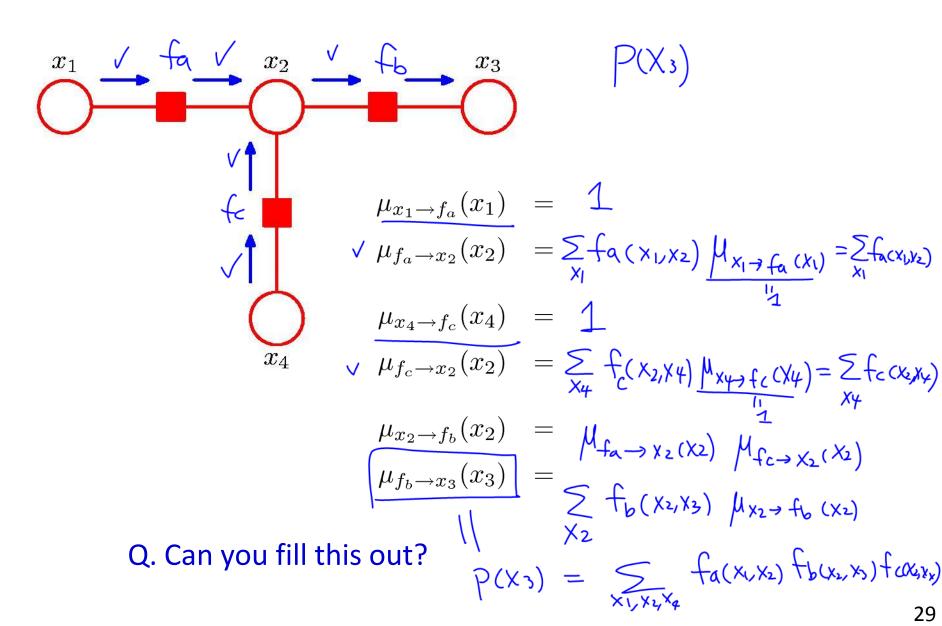
The Sum-Product Algorithm (8)

- To compute local marginals:
 - Pick an arbitrary node as root
 - Compute and propagate messages from the leaf nodes to the root, storing received messages at every node.
 - Compute and propagate messages from the root to the leaf nodes, storing received messages at every node.
 - Compute the product of received messages at each node for which the marginal is required, and normalize if necessary.

Sum-Product: Example (1)

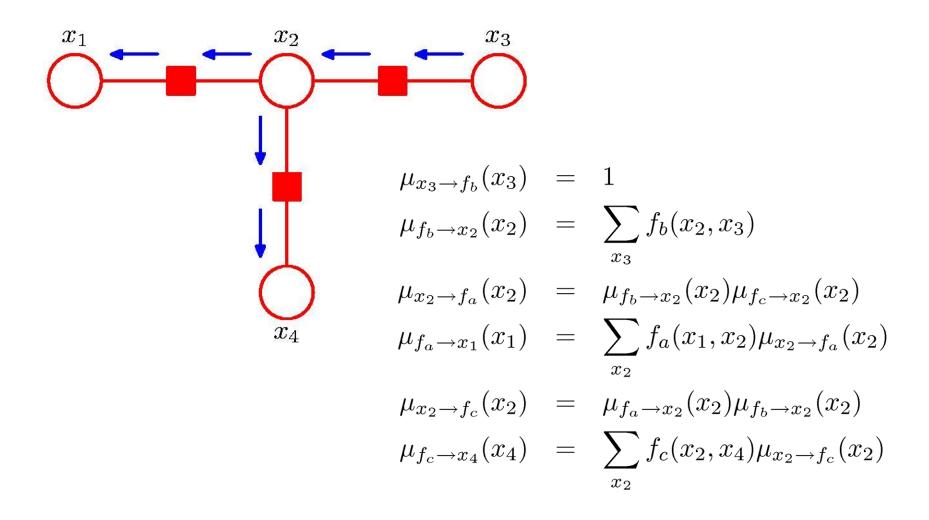


Sum-Product: Example (2)



Sum-Product: Example (2)

Sum-Product: Example (3)



Sum-Product: Example (4)

The Max-Sum Algorithm (1)

- Objective: an efficient algorithm for finding
 - i. the value X^{max} that maximises p(X);
 - ii. the value of $p(x^{max})$.
- In general, maximum marginals ≠ joint maximum.

$$\underset{x}{\operatorname{arg\,max}} p(x,y) = 1 \qquad \underset{x}{\operatorname{arg\,max}} p(x) = 0$$

The Max-Sum Algorithm (2)

Maximizing over a chain (max-product)



$$p(\mathbf{x}^{\max}) = \max_{\mathbf{x}} p(\mathbf{x}) = \max_{x_1} \dots \max_{x_M} p(\mathbf{x})$$

$$= \frac{1}{Z} \max_{x_1} \dots \max_{x_N} \left[\psi_{1,2}(x_1, x_2) \dots \psi_{N-1,N}(x_{N-1}, x_N) \right]$$

$$= \frac{1}{Z} \max_{x_1} \left[\max_{x_2} \left[\psi_{1,2}(x_1, x_2) \left[\dots \max_{x_N} \psi_{N-1,N}(x_{N-1}, x_N) \right] \dots \right] \right]$$

The Max-Sum Algorithm (3)

Generalizes to tree-structured factor graph

$$\max_{\mathbf{x}} p(\mathbf{x}) = \max_{x_n} \prod_{f_s \in ne(x_n)} \max_{X_s} f_s(x_n, X_s)$$

maximizing as close to the leaf nodes as possible

The Max-Sum Algorithm (4)

- Max-Product → Max-Sum
 - For numerical reasons, use

$$\ln\left(\max_{\mathbf{x}} p(\mathbf{x})\right) = \max_{\mathbf{x}} \ln p(\mathbf{x}).$$

Again, use distributive law

$$\max(a+b, a+c) = a + \max(b, c).$$

The Max-Sum Algorithm (5)

Initialization (leaf nodes)

$$\mu_{x \to f}(x) = 0 \qquad \qquad \mu_{f \to x}(x) = \ln f(x)$$

Recursion

$$\mu_{f \to x}(x) = \max_{x_1, \dots, x_M} \left[\ln f(x, x_1, \dots, x_M) + \sum_{m \in \text{ne}(f_s) \setminus x} \mu_{x_m \to f}(x_m) \right]$$

$$\phi(x) = \arg \max_{x_1, \dots, x_M} \left[\ln f(x, x_1, \dots, x_M) + \sum_{m \in \text{ne}(f_s) \setminus x} \mu_{x_m \to f}(x_m) \right]$$

$$\mu_{x \to f}(x) = \sum_{l \in \text{ne}(x) \setminus f} \mu_{f_l \to x}(x)$$

The Max-Sum Algorithm (6)

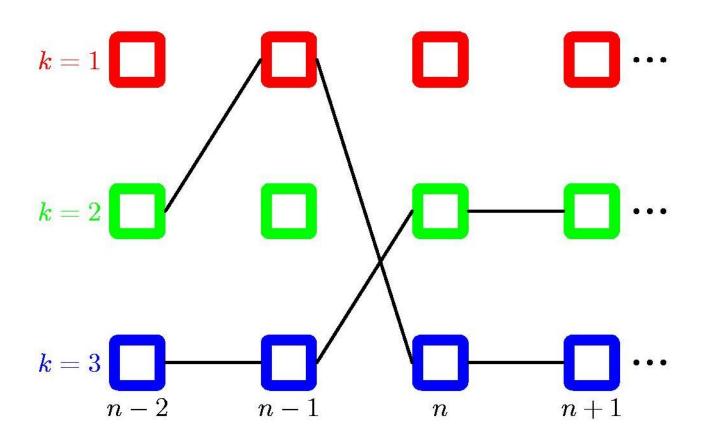
Termination (root node)

$$p^{\max} = \max_{x} \left[\sum_{s \in ne(x)} \mu_{f_s \to x}(x) \right]$$
 $x^{\max} = \arg\max_{x} \left[\sum_{s \in ne(x)} \mu_{f_s \to x}(x) \right]$

Back-tracking to get the full assignment.

The Max-Sum Algorithm (7)

Example: Markov chain



The Junction Tree Algorithm (sketch)

- Exact inference on general graphs.
- Works by turning the initial graph into a junction tree and then running a sum-productlike algorithm.
 - 1. Convert to undirected graph
 - 2. Triangulate the graph
 - 3. Construct a junction tree (where the nodes are cliques of the triangulated graph)
 - 4. Run belief propagation (e.g., sum-product)
- Intractable on graphs with large cliques.

Loopy Belief Propagation (sketch)

- Sum-Product on general graphs.
- Initial unit messages passed across all links, after which messages are passed around until convergence (not guaranteed!).
- Approximate but tractable for large graphs.
- Sometime works well, sometimes not at all.
- Read the Bishop book.

Next class

- Learning in graphical models
 - Maximum likelihood for fully observed variables
 - EM for partially observed variables