

UNIT 5

- ⇒ Define parent and child process with eg (3)
- ⇒ Differentiate between `sock-stream()` & `sock-dgram()` (3)
- ⇒ Define the concept of elementary socket-system call (10)
- ⇒ Explain in detail the IPC programming — with eg (10)
- ⇒ Define Interprocess Communication with eg (5)
- ⇒ `listen()` `accept()` system call (3)
- ⇒ Define Socket. Discuss the connection oriented and connectionless socket system calls briefly (10) (10)
- ⇒ Client server prog with socketable eg. (10)

Interprocess Communication (IPC)

UNIT-5

⇒ Interprocess Communication is the mechanism which allows processes to communicate with each other and to synchronize their actions.

⇒ ~~IPC is an important~~ so be causes,

~~information sharing~~ why IPC?

⇒ IPC is an important concept.

Suppose process may be present with in-
own system or within another system
with the help of networking they will be
communicated. In IPC information sharing will
be there and resource sharing. It means
cpu can share resource also with in-
own system or within another system.

⇒ with the help of IPC computer speed-
will be increased, if cpu use limited-
resources, if these resources will be sharing
by other process also, ^{IPC} then here -
plays important role

⇒ it having the modularity & convenience

⇒ The IPC this allows a program to handle
many tasks request at same time.

Basically the ^{ipc} is process to process communication ^{without} or with an OS system. The process is nothing but it is a series of actions or steps needed to achieve a particular end.

Process can be two types:

- * Independent process
- * Cooperative process

An independent process, it means it is not affected by the execution of other processes, while cooperative, it can be affected by other executing program.

⇒ In interprocess communication, the process can be communicated with each other by using two ways.

- * Shared memory
- * Message passing

D) Shared memory

Shared memory is memory shared between two or more ~~comp~~ process.



In fig(a) here process A generate information about certain resources and keep it as a ~~resource~~ record in shared memory. In that record the resources that will be used by the process A will be saved in the shared memory. Suppose the process B ~~needs~~ wanted to use the shared memory, ~~first~~ by firstly it check the record for identity what type of ~~data~~ resources are sharing by the process A. So, process B check the information and make a notes of information ^{and} generated by process A. If process A take a resources listed of that resources process B have another resources, so this is the cooperation between the two process.

In fig(b) each process, having the shared memory, whenever the process A use some shared memory it sends the information to the OS, then the OS storing the ~~process~~ information of process A. Whenever the process B wanted to ~~find~~ some operators performs some operation it first check the OS, ~~if~~ if any other device is using the resources or not.

if it is long, other
- Another instance.

Message passing

There is no use of shared memory. The process communicates with each other without using any kind of shared memory.

eg: Suppose two processes are there P1 & P2 want to be communicate

- 1) First establish a communication line
- 2) Start exchanging msg using basic primitives functions like send and receive.

The msg passing may be direct or indirect communication

IPC Methods

pipe: Communicate between two related process. This mechanism is half duplex, meaning - The first process communicates with second process. To achieve a full duplex i.e. - the second process communicate with the first process another pipe is required.

FIFO: Communicate between two unrelated process. FIFO is full duplex, meaning first process can communicate with the second process and vice versa.

Message passing

Message Queues: Communication between two or more process with full duplex capacity. The process will communicate with each other by putting a message and receiving it out of the queue. Once received, the message is not longer available in the queue.

Shared memory: Communication between two or more process is achieved through shared piece of memory among all process.

Semaphores: more than process can communicate. Synchronise the process.

When one process wanted process the memory (for reading or writing), it needs to be lock (or protected) and released when the access is removed.

Signal: Communicate multiple process by the way of signaling. This means a source process will send a signal and other process will handle it.

Process Creation & Termination

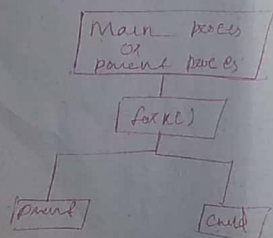
Process is a series of actions / step -
in order to achieve a particular end.

When ever we execute a program -
then a process is created and would
be terminated after the ~~time~~ completion of
the execution. Each process is identified
with a ~~unique~~ unique positive integer -
called p as process ID or simple PID.

The process creation is achieved
through the ~~fork~~ fork() system call.

The newly created process is the
child process and the process where
execution is started is called parent process.

After the system call we have two
process parent and child.



~~fork~~

The fork() system call returns either
3 values.

- 1) Negative value to indicate an error,
i.e., unsuccessful when creating the
child process.
- 2) Returns a zero for child process.
- 3) Returns a positive value for the parent
process.

eg: #include <stdio.h>
#include <sys/types.h>
#include <unistd.h>
int main()

{

fork();
printf("Hello world\n");
return 0;

}

o/p

Hello world
Hello world

```

#include <stdio.h>
#include <sys/types.h>

int main()
{
    fork();
    fork();
    fork();
    printf("hello\n");
    return 0;
}

```

```

hello
hello
hello
hello
hello
hello
hello
hello

```

Total no. of process = 2^n

where n is the ~~fork~~ ^{fork} systems call.

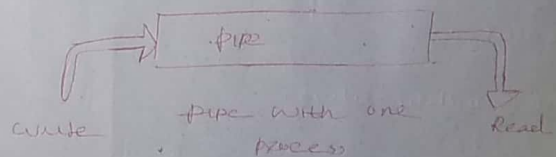
So,
 $n=3 \Rightarrow 2^3=8$

PIPE

⇒ pipe one way communication only
 ⇒ In pipe communication two related process. It is half duplex. It is achieved that means the first process is communicated with the second process, it is achieved full duplex, that means second process communicated with the first process by ^{using} ~~using~~ another pipe.

⇒ pipe is one way communication only. we can use [^] pipe such that one process to write ~~to~~ to pipe.

⇒ pipe is one way communication only
 ⇒ To achieve pipe system and create two file one file create into the file another is read from the file.



There is two descriptors.

First one is connected to the Read End -
~~the~~ pipe and another is connected to -
write end of pipe.

Descriptor `pipefds[0]` is for Reading

Descriptor `pipefds[1]` is for writing.

⇒ The `pipe()` create a pipe

⇒ The `pclose()` closed a pipe

Message Queue

Communication between two process -
between full duplex Capacity. The

full duplex means first process is -
communicated with second process vice versa.

The process will communicate with each -
other while passing a message and

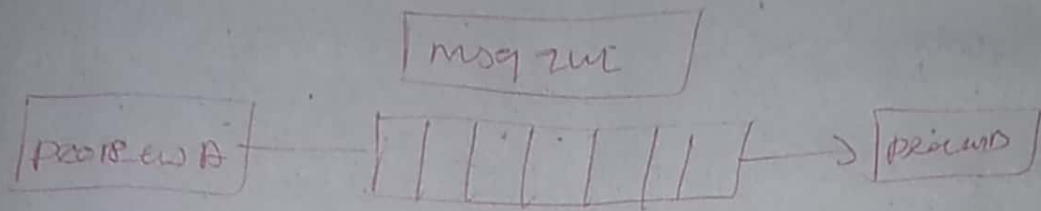
received it out of queue. once the -
msg is received it has no longer available

in the queue.

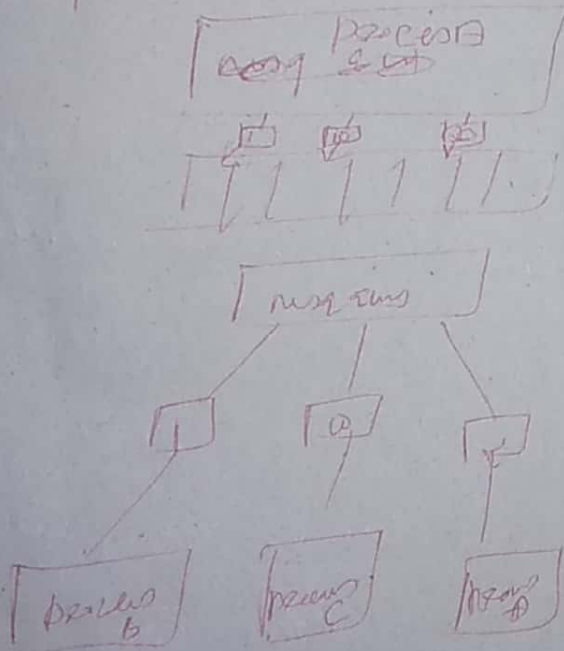
⇒ There is no synchronization.

Message Queue

write into the shared memory one process
and reading from the shared memory -
another process



writing into shared memory by one process
with different data packet and
from by multiple processes



data packets are at a time only one
process can read.

To perform Communication using msgz -
there

- 1) Create a msg queue or connect into an already existing msg (msgget())
- 2) write into the msg queue (msgsnd())
- 3) read from the msg queue (msgrcv())

3) perform Gate operations on the msg queue (msgctl())

Semaphore

There are two types

- Binary Semaphore: It is special form of Semaphore used for implementing mutual exclusion, hence it uses a single mutex. A binary semaphore is initialized to 1 and only allows the value to 0 during execution of P/PV.

Counting Semaphore

These are used to implement bounded-concurrency

Socket

⇒ Socket allow communication between two different process on the same or different machine.

⇒ The communication done ~~with~~ the help of by using standard unix file descriptor.

⇒ In unix, every ~~opened~~ / opened action done by creating and or reading a file descriptor.

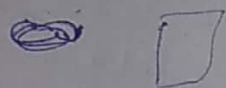
⇒ The socket is a low level file descriptor

⇒ This is because Command such as read() & write() work with socket in the same way they do with files and pipes.

⇒ Socket is a end point of communication between 2 device.

eg: when we have two persons at different places and they want to communicate with each other. Each of them have mobile phones, one of them will have to initiate the communication.

Callion by dialing the other person's number and after the other person accepts the call then connection will be established. Once the connection is established they can start talking to each other by sending and receiving msg's, now in this case each of these mobile phone acts like a socket, which simply is an end point of communication.



Where Socket Used?

* \Rightarrow Unix socket is used in client-server application frame. A server is process, client request is processed by server.

\Rightarrow Most of the application level protocols like FTP, POP3, SMTP these are used in socket, to establish connection between client and server and exchanging data.

Types of Sockets

There are four types of Sockets available to the user. The first two are most commonly used and the last two rarely used.

1) Stream Socket :-

The Stream Sockets are provided ~~guar~~ guaranteed ~~data~~ delivery. In stream-socket, what ever the ^{order} ~~data~~ you send through the stream socket then it reach at the destination at the

same order ~~when~~ you

i.e., if stream socket through sent three items "A, B, C" then they reach at the destination in the same order "A, B, C"

⇒ This socket TCP for data transmission

⇒ if delivery is impossible, the sender receives an error indicator

~~Data gram Socket~~

In data

Data gram Socket

- In data gram socket delivery of is not guaranteed. It is connectionless there is no any connection between the socket.
- They use UDP (User Datagram packet).

Raw Socket

These provide user access to the underlying communication protocol, which support socket abstraction. These socket are normally data gram oriented.

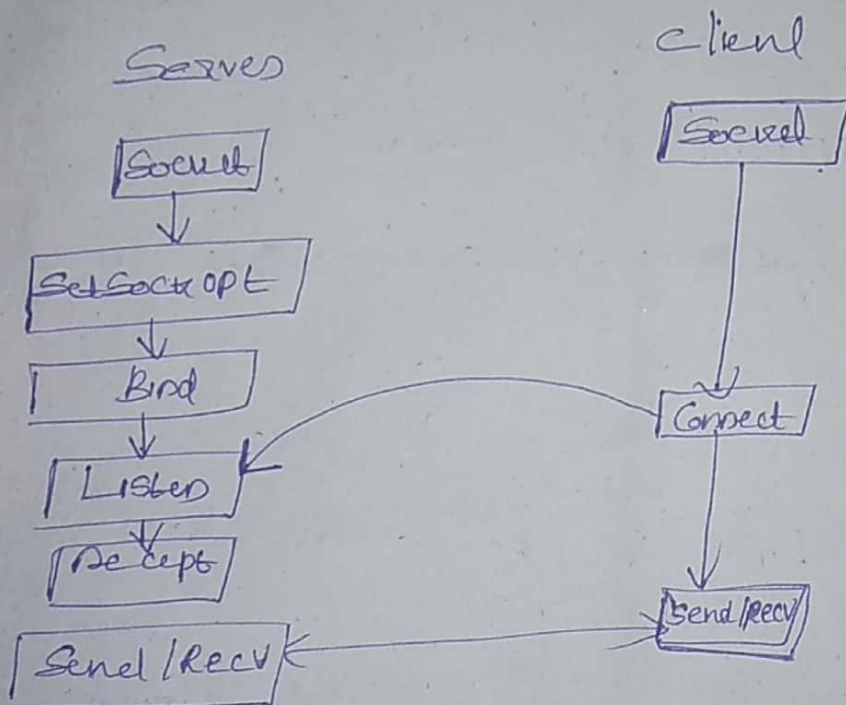
Sequenced packet socket

- This similar to stream socket, here in sequence packet data boundaries are preserved, in the case of stream socket the data receives do not have any bound that is only the sequence is there.

Socket programming

⇒ Socket programming is a way of connecting two nodes on network to communicate with each other

⇒ one Socket (node) listen to a particular port of a ip. while other Socket try to get a connection. Server listen to all client but client reaches out to server



Stages for Server

Socket Creation:

`int sockfd = socket(domain, type, protocol)`

`sockfd`: Socket descriptor

domain: Communication domain

Eg: AF_INET (IPv4 protocol)
AF_INET6 (IPv6 protocol)

type: Communication type

SOCK_STREAM: TCP (reliable, connection oriented)

SOCK_DGRAM: UDP (unreliable, connectionless)

protocol: value for IP

Socket options

Socket options are defined

int setsockopt (int sockfd, int level, int optname,

Bind

Bind function bind to the server client

Socket

int bind (int sockfd, struct sockaddr *addr,
socklen_t addrlen)

Listen

Listen the server and client
int listen (sockfd, int backlog)

Accept

To accept the connection, the new connection can accept

Stage for client

Socket connect: Closely similar to server socket creation

connect (int

connected

int connect (int sockfd, struct sockaddr *addr,
socklen_t addrlen);

here first create the socket and then set the option then bind to the client socket, then listen to the client and server. Then client can connect to listen, and listen server accepts and the send/receive

Elementary System call for Socket

Socket

The Create an end point between Client & Server.

Bind

Binding assigning an IP address

Listen

Waiting for Connection

=> Listen basically done Server only.
Connection oriented Server ready to receive.

(End socket, end has to)

Accept

It waiting for someone to connect

=> Accept new Connection

int accept (int socket, (struct sockaddr*
addr, socklen_t *addrlen);

Send / Recv

Send / Recv

Sending data receiving data

Tcp Chat program

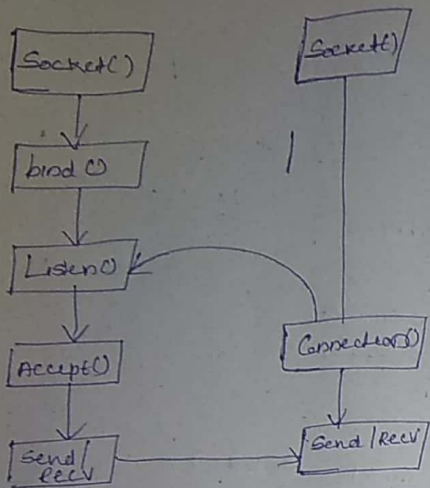
Transmission Control Protocol Connection oriented

Server

- 1) Create a socket with `socket()`
- 2) Bind the socket to an address `bind()`
- 2) Listen the connection with the `listen()`
- 3) Accept the connection with `accept()`
- 4) Send and receive data use `read()` and `write()` system call

Client

- 1) Create the socket with `socket()`
- 2) Connect the socket to the address of the server using `connect()` system call.
- 3) Send and receive data using `read()` and `write()` system



The ~~can~~ TCP means Transmission -
Control protocol, then it is Connection -
oriented. In Connection oriented,
Initially the Connection is established.
~~But server is always~~ First the server
is awake, then at some time client is -
started.

UDP Chat

⇒ User program protocol
Connection ^{less} ~~oriented~~ service

In UDP chat client does not create a
Connection between the server. It -
just send data directly. There is -
no any acknowledgment given

Server

- 1) Create socket with the Socket()
- 2) Bind the socket to an address using -
the bind()
- 3) Send and receive data use the
recvfrom() and sendto() system call.

Client

- ⇒ Create a socket with Socket()
- ⇒ Send and receive data use recvfrom() -
and sendto()

System Calls

Socket Creation

Socket

~~Socket~~ = ~~int~~ ~~socket~~

int sockfd = socket(^{int} domain, ^{int} type, ^{int} protocol);

domain

domain

Communication domain

eg: AF_INET (IPv4)

AF_INET6 (IPv6)

Type \Rightarrow Communication type

Socket - STREAM

Socket - DGRAM

Protocol

value of 0

0 means default protocol

Bind

int bind(int sockfd, ~~struct~~ char ~~server~~ ^{sock} ~~addr~~ ^{len} socklen_t *addr, socklen_t - 1 - addrlen)

Socketfd: File descriptor socket to be bound

addr: address

addrlen: Size of address structure

Recv

Recv

recv(sockfd)

int recvfrom(int sockfd, void *buf, size_t len, int flags, struct sockaddr *src_addr, socklen_t *addrlen)

buf: Application buffers in which to receive data

len: Size of buf

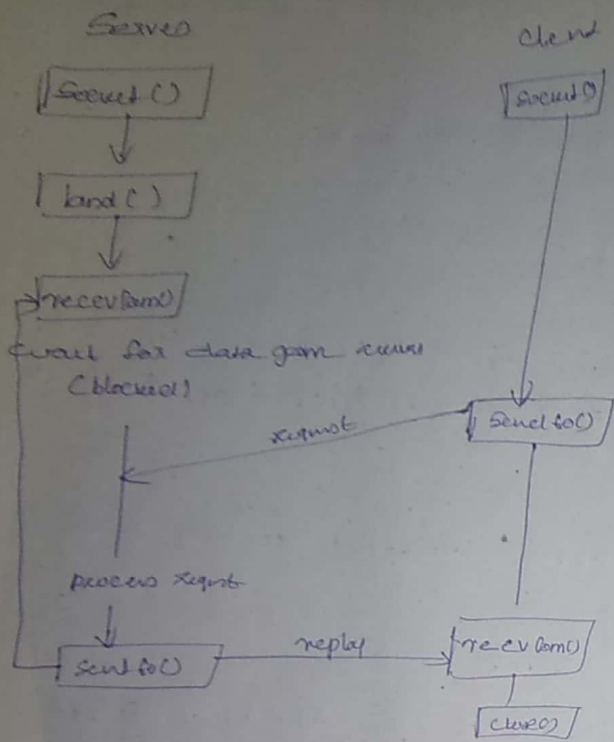
Flags: Bitwise OR of flags to modify socket behavior

src_addr: Structure containing source address is returned

addrlen: Variable in which size

Sendto

int sendto(int sockfd, const void *buf, size_t len, int flags, const struct sockaddr *dest_addr, socklen_t - 1 - addrlen)



Initially the connection is it will be create its own socket, then end point is created. Then address is assigned to end point by using bind() system call. After it ready to receive from anywhere. Assume that client is ready and he is binded to the IP address then he send data directly to request to the server side. Then the server

will process the request then it will basically send to the client - then it received by the client, then this process continues until the requirement. Once the everything is done they will close both the connection using close().

eg:

```

#include <stdio.h>
#include <string.h>
#include <sys/stat.h>
#include <sys/types.h>
#include <sys/socket.h>
#include <netinet/in.h>
#include <arpa/inet.h>
  
```

```

main()
{
    struct sockaddr_in client, server;
    int s, n;
    char b1[100], b2[100];
    s = socket(AF_INET, SOCK_STREAM, 0);
    server.sin_family = AF_INET;
    server.sin_port = 2000;
  
```