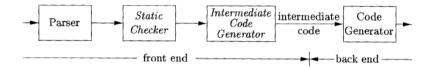
## **Intermediate-Code Generation**

## **Intermediate-Code Generation**



#### **Three-Address Code**

- In three-address code, there is at most one operator on the right side of an instruction
- Thus a source-language expression like x+y\*z might be translated into the sequence of three-address instructions

$$t_1 = y * z$$
  
$$t_2 = x + t_1$$

## **Common three-address instructions**

- 1. Assignment instructions of the form x = y op z, where op is a binary arithmetic or logical operation, and x, y, and z are addresses.
- 2. Assignments of the form x = op y, where op is a unary operation. Essential unary operations include unary minus, logical negation, shift operators, and conversion operators that, for example, convert an integer to a floating-point number.
- 3. Copy instructions of the form x = y, where x is assigned the value of y.
- 4. An unconditional jump goto L. The three-address instruction with label L is the next to be executed.
- 5. Conditional jumps of the form if x goto L and iffalse x goto L. These instructions execute the instruction with label L next if x is true and false, respectively. Otherwise, the following three-address instruction in sequence is executed next, as usual.

- 6. Conditional jumps such as if x relop y goto L, which apply a relational operator (<, ==, >=, etc.) to x and y, and execute the instruction with label L next if x stands in relation relop to y. If not, the three-address instruction following if x relop y goto L is executed next, in sequence.
- 7. Procedure calls and returns are implemented using the following instructions: param x for parameters; call p, n and y = call p, n for procedure and function calls, respectively; and return y, where y, representing a returned value, is optional. Their typical use is as the sequence of three-address instructions

```
\begin{array}{c} \text{param } x_1 \\ \text{param } x_2 \\ \dots \\ \text{param } x_n \\ \text{call } p, n \end{array}
```

generated as part of a call of the procedure  $p(x_1, x_2, \ldots, x_n)$ . The integer n, indicating the number of actual parameters in "call p, n,"

8. Indexed copy instructions of the form x = y[i] and x[i] = y. The instruction x = y[i] sets x to the value in the location i memory units beyond location y. The instruction x[i] = y sets the contents of the location i units beyond x to the value of y.

## **Common three-address instructions**

```
do i = i+1; while (a[i] < v);
```

```
L: t_1 = i + 1

i = t_1

t_2 = i * 8

t_3 = a [t_2]

if t_3 < v goto L
```

## **Data structures for TAC Quadruples**

A quadruple (or just "quad") has four fields, which we call op,  $arg_1$ ,  $arg_2$ , and result. The op field contains an internal code for the operator. For instance, the three-address instruction x = y + z is represented by placing + in op, y in  $arg_1$ , z in  $arg_2$ , and x in result. The following are some exceptions to this rule:

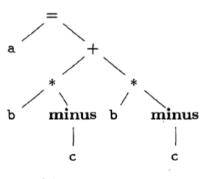
- 1. Instructions with unary operators like  $x = \min y$  or x = y do not use  $arg_2$ . Note that for a copy statement like x = y, op is =, while for most other operations, the assignment operator is implied.
- 2. Operators like param use neither arg<sub>2</sub> nor result.
- 3. Conditional and unconditional jumps put the target label in result.

# Data structures for TAC Quadruples

Three-address code for the assignment a = b \* - c + b \* - c;

$$t_1 = minus c$$
 $t_2 = b * t_1$ 
 $t_3 = minus c$ 
 $t_4 = b * t_3$ 
 $t_5 = t_2 + t_4$ 
 $a = t_5$ 

(a) Three-address code



(a) Syntax tree

# Data structures for TAC Quadruples

Three-address code for the assignment a = b \* - c + b \* - c;

$$t_1 = minus c$$
 $t_2 = b * t_1$ 
 $t_3 = minus c$ 
 $t_4 = b * t_3$ 
 $t_5 = t_2 + t_4$ 
 $a = t_5$ 

	op	$arg_1$	$arg_2$	result
0	minus	С	1	t <sub>1</sub>
1	*	ъ	t <sub>1</sub>	t <sub>2</sub>
2	minus	С	1	t <sub>3</sub>
3	*	b	t <sub>3</sub>	t <sub>4</sub>
4	+	$t_2$	$t_4$	t <sub>5</sub>
5	=	<b>t</b> <sub>5</sub>	1	a

(a) Three-address code

(b) Quadruples

## Data structures for TAC Triples

- A triple has only three fields, which we call op, arg1, and arg2
- Note that the result field in Quad is used primarily for temporary names.
- Using triples, we refer to the result of an operation x op y by its position, rather than by an explicit temporary name.
- Thus, instead of the **temporary t**, a triple representation would refer to **position (0)**.
- Parenthesized numbers represent pointers into the triple structure itself.

# **Data structures for TAC Triples**

Three-address code for the assignment a = b \* - c + b \* - c;

$$t_1 = minus c$$
 $t_2 = b * t_1$ 
 $t_3 = minus c$ 
 $t_4 = b * t_3$ 
 $t_5 = t_2 + t_4$ 
 $a = t_5$ 

(a) Three-address code

op	$arg_1$	$arg_2$
minus	С	ſ
*	b	(0)
minus	С	1
*	b	(2)
+	(1)	(3)
=	a	(4)
	• • • •	
	minus  * minus  * + +	minus   c

(b) Triples

## **Benefit of Quad over Triples**

- A benefit of quadruples over triples can be seen in an optimizing compiler, where instructions are often moved around.
  - With quadruples, if we move an instruction that computes a temporary t, then the instructions that use t require no change.
- With triples, the result of an operation is referred to by its position
- So moving an instruction may require us to change all references to that result.

## **Indirect triples**

- Consist of a listing of pointers to triples,
  - Rather than a listing of triples themselves.
- For example, use an array instruction to list pointers to triples in the desired order.

With indirect triples, an **optimizing compiler** can move an instruction by **reordering the instruction list**, without affecting the triples themselves.

instruction				
35	(0)			
36	(1)			
37	(2)			
38	(3)			
39	(4)			
40	(5)			

	op	$arg_1$	$arg_2$
0	minus	С	1
1	*	b	(0)
2	minus	С	I .
3	*	b	(2)
4	+	(1)	(3)
5	=	a	(4)
		• • •	

## **Static Single-Assignment Form**

Two distinctive aspects distinguish SSA from three-address code.

(a) The first is that **all assignments in SSA** are to **variables with distinct names**; hence the term static single-assignment.

$$p = a + b$$
  $p_1 = a + b$   $q = p - c$   $q_1 = p_1 - c$   $p = q * d$   $p_2 = q_1 * d$   $p_3 = e - p_2$   $q = p + q$   $q_2 = p_3 + q_1$ 

(a) Three-address code. (b) Static single-assignment form.



## **Static Single-Assignment Form**

Two distinctive aspects distinguish SSA from three-address code.

(a) The first is that **all assignments in SSA** are to **variables with distinct names**; hence the term static single-assignment.

(b)

The same variable may be defined in two different control-flow paths in a program. For example, the source program

if ( flag ) 
$$x = -1$$
; else  $x = 1$ ;  $y = x * a$ ;

has two control-flow paths in which the variable x gets defined. If we use different names for x in the true part and the false part of the conditional statement, then which name should we use in the assignment y = x \* a? Here is where the second distinctive aspect of SSA comes into play. SSA uses a notational convention called the  $\phi$ -function to combine the two definitions of x:

```
if (flag) x_1 = -1; else x_2 = 1; x_3 = \phi(x_1, x_2);
```



## **Static Single-Assignment Form**

Here,  $\phi(\mathbf{x}_1, \mathbf{x}_2)$  has the value  $\mathbf{x}_1$  if the control flow passes through the true part of the conditional and the value  $\mathbf{x}_2$  if the control flow passes through the false part. That is to say, the  $\phi$ -function returns the value of its argument that corresponds to the control-flow path that was taken to get to the assignment-statement containing the  $\phi$ -function.

# Major translation classes of Three address code generation

- (a) Declaration statements (+ handling data type and storage)
- (b) Expressions and statements
- (a) Control flow statements

### **Declaration statement**

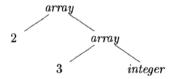
Representing data types: Type Expressions

Types have structure, which we shall represent using type expressions.

- A type expression is either a basic type (boolean, char, integer, float, and void)
   or
- is formed by applying an operator called a type constructor to a type expression.
- A type expression can be formed by applying the array type constructor to a number and a type expression.

## **Declaration statement**

- The array type int [2] [3] can be read as "array of 2 arrays of 3 integers each"
- Can be represented as a type expression array(2, array(3, integer)).
- This type is represented by the tree.



- The operator array takes two parameters, a number and a type.
  - Here the **type expression** can be formed by applying the **array type constructor** to a number and a type expression.

## **Declaration statement Example SDD**

PRODUCTION	SEMANTIC RULES
$T \rightarrow B C$	T.t = C.t
	C.b = B.t
$B \rightarrow \text{int}$	B.t = integer
$B \rightarrow float$	B.t = float
$C \rightarrow [$ num $] C_1$	$C.t = array(\mathbf{num}.val, C_1.t)$
	$C_1.b = C.b$
$C \rightarrow \epsilon$	C.t = C.b



## Type Expressions

- Nonterminal T generates either a basic type or an array type.
- Nonterminal B generates one of the basic types int and float.
- T generates a basic type when C derives €.
- Otherwise, C generates array components consisting of a sequence of integers, each integer surrounded by brackets.

## **Declaration statement** Example SDD

PRODUCTION	SEMANTIC RULES
$T \rightarrow B C$	T.t = C.t
	C.b = B.t
$B \rightarrow \text{int}$	B.t = integer
$B \rightarrow float$	B.t = float
$C \rightarrow [\text{num}] C_1$	$C.t = array(\mathbf{num}.val, C_1.t)$
	$C_1.b = C.b$
$C \rightarrow \epsilon$	C.t = C.b



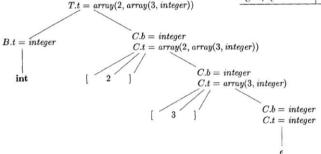
## Type Expressions

- The nonterminals B and T have a synthesized attribute t representing a type.
- The nonterminal C has two attributes: an inherited attribute b and a synthesized attribute t.

# Declaration statement Example SDD

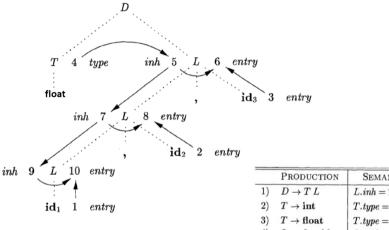
## input string int [2][3]

PRODUCTION	SEMANTIC RULES
$T \rightarrow BC$	T.t = C.t
	C.b = B.t
$B \rightarrow \text{int}$	B.t = integer
$B \rightarrow \text{float}$	B.t = float
$C \rightarrow [$ <b>num</b> $] C_1$	$C.t = array(\mathbf{num}.val, C_1.t)$
	$C_1.b = C.b$
$C \rightarrow \epsilon$	C.t = C.b



- The nonterminal *C* has two attributes: an inherited attribute *b* and a synthesized attribute *t*.
- The inherited *b* attributes pass a basic type down the tree, and the synthesized *t* attributes accumulate the result.

# Declaration statement: Example SDD float $id_1$ , $id_2$ , $id_3$



	PRODUCTION	SEMANTIC RULES
1)	$D \to T  L$	L.inh = T.type
2)	$T  o \mathbf{int}$	T.type = integer
3)	$T  o \mathbf{float}$	T.type = float
4)	$L \to L_1$ , id	$L_1.inh = L.inh$
		addType(id.entry, L.inh)
5)	$L \to \mathbf{id}$	addType(id.entry, L.inh)

## Symbol table

ST(global)

This is the Symbol Table for global symbols

Name	Type	Initial	Size	Offset	Nested
		Value			Table
d	float	2.3	8	0	null
i	$_{ m int}$	null	4	8	null
W	array(10, int)	null	40	12	null
a	$_{ m int}$	4	4	52	null
p	ptr(int)	null	4	56	null
b	$_{ m int}$	null	4	60	null
func	function	null	0	64	ptr-to-ST(func)
С	char	null	1	64	null

## Find the storage for each variable

## **More on Declaration statement**

## Data type + Storage layout

- Simplified grammar that declares just one name at a time;
- We already explored the declarations with lists of names

#### **Storage layout:**

- Relative address of all the variables
- From the type of a name, we can determine the amount of storage that will be needed for the name at run time.
- At compile time, we can use these amounts to assign each name a relative address.
- The type and relative address are saved in the symbol-table entry for the name.



### **More on Declaration statement**

## Data type + Storage layout

- The width of a type is the number of storage units needed for objects of that type (offset).
- A basic type, such as a character, integer, or float, requires an integral number of bytes.
- Arrays allocated in one contiguous block of bytes

```
T 
ightarrow B \ C { t = B.type; w = B.width; } Computes data types and their widths for basic and their widths for basic and array types <math>B 
ightarrow {\rm float} \ B 
ightarrow {\rm float} \ B 
ightarrow {\rm float} \ B.type = {\rm float}; B.width = 4; } C 
ightarrow {\rm float} \ C.type = t; C.width = w; } C 
ightarrow {\rm function} \ C.width = {\rm num.} value \times C_1.type; C.width; }
```

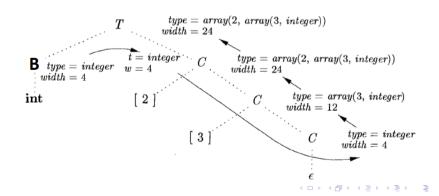
The width of an array is obtained by multiplying the width of an element by the number of elements in the array.

### More on Declaration statement

## Data type + Storage layout

```
int[2][3]
```

```
\begin{array}{lll} T \rightarrow B & \left\{ \begin{array}{ll} t = B.type; \ w = B.width; \right\} \\ C & \\ B \rightarrow & \text{int} & \left\{ \begin{array}{ll} B.type = integer; B.width = 4; \right\} \\ B \rightarrow & \text{float} & \left\{ \begin{array}{ll} B.type = float; B.width = 8; \right\} \\ C \rightarrow & \epsilon & \left\{ \begin{array}{ll} C.type = t; C.width = w; \right\} \\ C.width = & \text{num. value. } C.t.type); \\ C.width = & \text{num. value. } C.t.width : \end{array} \end{array} \right\} \end{array}
```



## **Relative address**

Name	Data type
d	float
i	int
W	array(10, int)

## **Relative address**

	0
	8
	12
П	~~

## **Sequences of Declarations**

int x; float y;

- Relative address: offset
- Keeps track of the next available relative address

```
P \rightarrow \{ offset = 0; \} D D \rightarrow T id ; \{ top.put(id.lexeme, T.type, offset); \\ offset = offset + T.width; \} D_1 D \rightarrow \epsilon
```

- The translation scheme deals with a sequence of declarations of the form T id, where T generates a data type
- Before the first declaration is considered, offset is set to 0.
- As each new name x is seen, x is entered into the symbol table with its relative address = current value of offset,
  - which is **then incremented** by the width of the type of x.



## **Sequences of Declarations**

- Relative address: offset
- Keeps track of the next available relative address

```
P \rightarrow \{ offset = 0; \} D
D \rightarrow T id ; \{ top.put(id.lexeme, T.type, offset); \\ offset = offset + T.width; \}
D_1
D \rightarrow \epsilon
```

The semantic action within the production  $D \to T$  id;  $D_1$  creates a symboltable entry by executing top.put(id.lexeme, T.type, offset). Here top denotes the current symbol table. The method top.put creates a symbol-table entry for id.lexeme, with type T.type and relative address offset in its data area.

# Major translation classes of Three address code generation

(a) Declaration statements (+ handling data type and storage)

## (b) Expressions and statements

(a) Control flow statements

### statement a = b + - c

#### Three-address code for an assignment statement

PRODUCTION	SEMANTIC RULES
$S \rightarrow id = E$ ;	$S.code = E.code \mid \mid$
	gen(top.get(id.lexeme)'='E.addr)
$E \rightarrow E_1 + E_2$	$E.addr = \mathbf{new} \ Temp()$
	$E.addr = \mathbf{new} \ Temp()$ $E.code = E_1.code \mid\mid E_2.code \mid\mid$
	$gen(E.addr'='E_1.addr'+'E_2.addr)$
$\mid -E_1$	$E.addr = \mathbf{new} \ Temp()$
	$E.code = E_1.code \mid   $ $qen(E.addr'=''minus' E_1.addr)$
	gen(D. wwn = minus D1. www)
$\mid$ ( $E_1$ )	$E.addr = E_1.addr \ E.code = E_1.code$
	$E.code = E_1.code$
id	E.addr = top.get(id.lexeme) E.code = ''
	E.code = ''

Attribute code for S

attributes addr and code for an expression E.

Attributes **S.code and E.code denote the three-address code** for S and E, respectively.

Attribute **E.addr denotes the address** that will hold the **value of E.** 

#### Three-address code for an assignment statement

PRODUCTION	SEMANTIC RULES	
$S \rightarrow id = E$ ;	$S.code = E.code \mid\mid$	
	gen(top.get(id.lexeme) '=' E.addr)	
$E \rightarrow E_1 + E_2$	$E.addr = \mathbf{new} \ Temp () \ E.code = E_1 \cdot code \mid \mid E_2 \cdot code \mid \mid \ gen(E.addr'='E_1.addr'+'E_2.addr)$	
\ - E <sub>1</sub>	$E.addr = \mathbf{new} \ Temp()$ $E.code = E_1.code \mid \mid gen(E.addr'=' '\mathbf{minus'} \ E_1.addr)$	
$\mid$ ( $E_1$ )	$E.addr = E_1.addr \ E.code = E_1.code$	
<b>i</b> d	$E.addr = top.get(\mathbf{id}.lexeme)$ When an expression is a <b>single identifier</b> , say x, then x itself holds the value of the expression.	

The semantic rules for this production define **E.addr to point to the symbol-table entry** 



Three-address code for an assignment statement

PRODUCTION	SEMANTIC RULES
$S \to \mathrm{id} = E$ ;	$S.code = E.code \mid \mid$ $gen(top.get(id.lexeme)'='E.addr)$
$E \rightarrow E_1 + E_2$	$E.addr = \mathbf{new} \ Temp()$ $E.code = E_1.code \mid\mid E_2.code \mid\mid$ $gen(E.addr'='E_1.addr'+'E_2.addr)$

The semantic rules for  $E \to E_1 + E_2$ , generate code to compute the value of E from the values of  $E_1$  and  $E_2$ . Values are computed into newly generated temporary names. If  $E_1$  is computed into  $E_1$  addr and  $E_2$  into  $E_2$  addr, then  $E_1 + E_2$  translates into  $t = E_1$  add $r + E_2$  addr, where t is a new temporary name. E addr is set to t. A sequence of distinct temporary names  $t_1, t_2, \ldots$  is created by successively executing  $\mathbf{new}$  Temp().

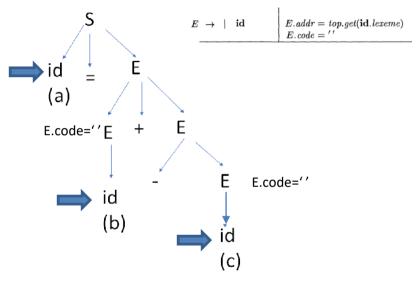
Three-address code for an assignment statement

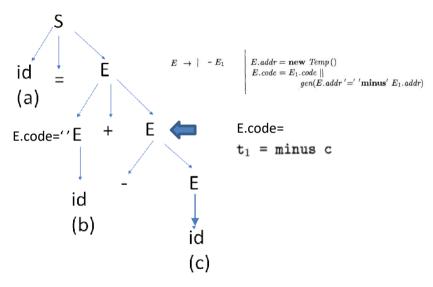
PRODUCTION	SEMANTIC RULES
$S \rightarrow id = E$ ;	$S.code = E.code \mid \mid$ $gen(top.get(id.lexeme) '=' E.addr)$
$E \rightarrow E_1 + E_2$	$E.addr = \mathbf{new} \; Temp() \ E.code = E_1.code \mid\mid E_2.code \mid\mid \ gen(E.addr'='E_1.addr'+'E_2.addr)$

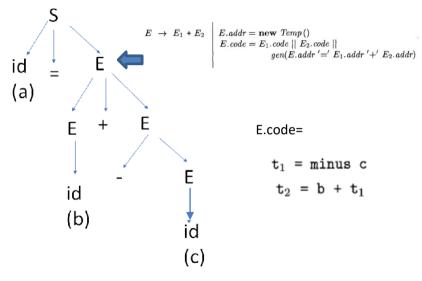
Finally, the production  $S \to \mathbf{id} = E$ ; generates instructions that assign the value of expression E to the identifier  $\mathbf{id}$ . The semantic rule for this production uses function top.get to determine the address of the identifier represented by  $\mathbf{id}$ , as in the rules for  $E \to \mathbf{id}$ . S.code consists of the instructions to compute the value of E into an address given by E.addr, followed by an assignment to the address  $top.get(\mathbf{id}.lexeme)$  for this instance of  $\mathbf{id}$ .

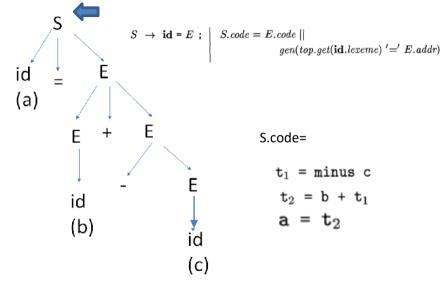
#### Three-address code for an assignment statement

PRODUCTION	SEMANTIC RULES
$S \rightarrow id = E$ ;	$S.code = E.code \mid\mid$
	gen(top.get(id.lexeme)'='E.addr)
$E \rightarrow E_1 + E_2$	$E.addr = \mathbf{new} \ Temp()$
	$ E.code = E_1.code \mid\mid E_2.code \mid\mid \\ gen(E.addr'='E_1.addr'+'E_2.addr) $
	$gen(E.uur = E_1.uur + E_2.uur)$
$-E_1$	E.addr = new Temp()
	$E.code = E_1.code \mid\mid \\ qen(E.addr'=''minus' E_1.addr)$
	$gen(E.aaar = minus E_1.aaar)$
$\mid$ ( $E_1$ )	$E.addr = E_1.addr$
	$E.code = E_1.code$
id	E.addr = top.get(id.lexeme)
	E.code = ''









#### Three-address code for an assignment statement

PRODUCTION	SEMANTIC RULES
$S \rightarrow id = E$ ;	$S.code = E.code \mid  $ $gen(top.get(id.lexeme) '=' E.addr)$
$E \rightarrow E_1 + E_2$	$E.addr = \mathbf{new} \ Temp ()$ $E.code = E_1.code \mid\mid E_2.code \mid\mid$ $gen(E.addr'='E_1.addr'+'E_2.addr)$
- E <sub>1</sub>	$E.addr = \mathbf{new} \ Temp\ ()$ $E.code = E_1.code\   $ $gen(E.addr'='\mathbf{minus'}\ E_1.addr)$
( E <sub>1</sub> )	$E.addr = E_1.addr$ $E.code = E_1.code$
id	E.addr = top.get(id.lexeme) E.code = ''

statement 
$$a = b + - c$$

$$t_1 = minus c$$
  
 $t_2 = b + t_1$   
 $a = t_2$ 

### **Incremental Translation**

- So far, *E.Code* attributes were long strings
  - Generated incrementally
- In incremental translation, generate only the new threeaddress instructions
- Past sequence may either be retained in memory for further processing, or it may be output incrementally.
- In the incremental approach, gen() not only constructs a three-address instruction,
  - it appends the instruction to the sequence of instructions generated so far.

### **Incremental Translation**

```
S \rightarrow id = E; { gen(top.get(id.lexeme)'='E.addr); }
E \rightarrow E_1 + E_2 \quad \{ E.addr = new Temp(); \}
                   gen(E.addr'='E_1.addr'+'E_2.addr); \}
   -E_1 { E.addr = new Temp();
                   gen(E.addr'=''minus' E_1.addr); 
     (E_1) { E.addr = E_1.addr; }
       id
                 \{E.addr = top.get(id.lexeme);\}
```

- This translation scheme generates the same code as the previous syntax directed definition.
- With the incremental approach, the E.code attribute is not used,
  - Since there is a **single sequence of instructions** that is created by **successive calls to gen()**.