

Single-Source Shortest Path Algorithm

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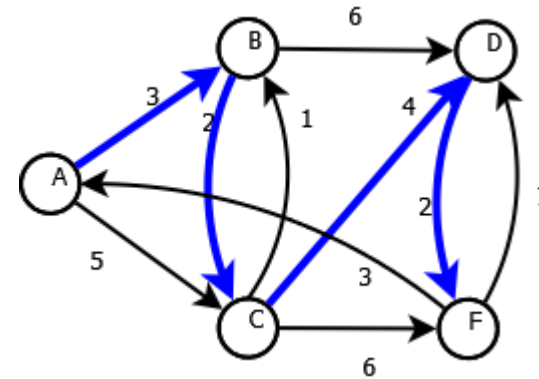
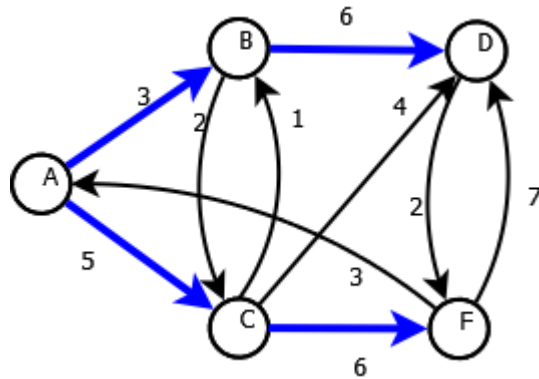
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Single-Source Shortest Path Problem

Single-Source Shortest Path Problem - The problem of finding shortest paths from a source vertex v to all other vertices in the graph.

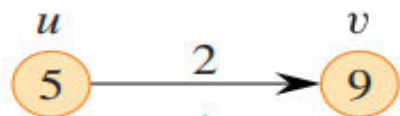


Relaxation

For an edge (u, v) with weight w , relaxation checks if the known shortest path to v can be improved by going through u .

RELAX(u, v, w)

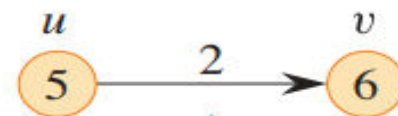
```
1  if  $v.d > u.d + w(u, v)$   
2     $v.d = u.d + w(u, v)$   
3     $v.\pi = u$ 
```



RELAX(u, v, w)



(a)



RELAX(u, v, w)



(b)

Introduction

Dijkstra's algorithm - is a solution to the single-source shortest path problem in graph theory.

Works on both directed and undirected graphs. However, all edges must have nonnegative weights.

Input: Weighted graph $G=\{E,V\}$ and source vertex $v\in V$, such that all edge weights are nonnegative

Output: Lengths of shortest paths (or the shortest paths themselves) from a given source vertex $v\in V$ to all other vertices

Applications of Dijkstra's Algorithm

1. Network Routing Protocols:

- ✓ Used in **OSPF (Open Shortest Path First)** and **IS-IS** routing algorithms to compute the shortest path tree for routing packets.

2. Mapping and GPS Systems:

- ✓ Calculating the quickest route between two locations using road network data.

3. Game Development:

- ✓ Pathfinding for characters or AI agents (though A* is often preferred for efficiency in certain cases).

4. Telecommunications:

- ✓ Optimizing data flow through networks by finding the least-cost path.

5. Compiler Design:

- ✓ Used in **data-flow analysis** and **code optimization** to calculate the shortest distance in control flow graphs.

6. Robot Motion Planning:

- ✓ In robotics, Dijkstra helps robots find the shortest path in a known environment.

7. Dependency Resolution:

- ✓ Used in systems like **package managers** to resolve dependency chains efficiently.

Dijkstra's Algorithm

1. Initialize distances from the source to all nodes as infinity, except the source (0).
2. Use a priority queue (min-heap) to repeatedly select the node with the smallest tentative distance.
3. Update the distances to neighboring nodes if a shorter path is found.
4. Repeat until all nodes are visited or the destination is reached.

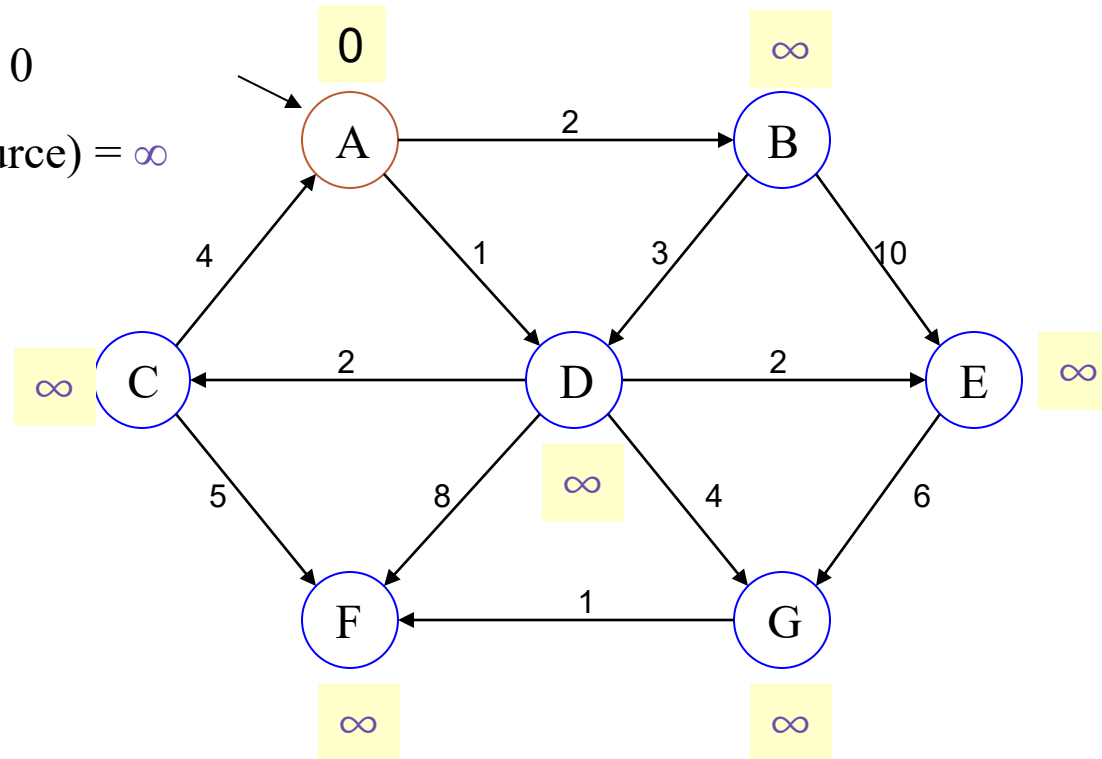
```
function Dijkstra(Graph, source):  
  create a priority queue Q  
  for each vertex v in Graph:  
    dist[v] := infinity  
    prev[v] := undefined  
  add source to Q  
  dist[source] := 0
```

```
  while Q is not empty:  
    u := vertex in Q with smallest dist[u]  
    remove u from Q  
    for each neighbor v of u:  
      alt := dist[u] + length(u, v)  
      if alt < dist[v]:  
        dist[v] := alt  
        prev[v] := u  
  return dist, prev
```

Example: Initialization

Distance(source) = 0

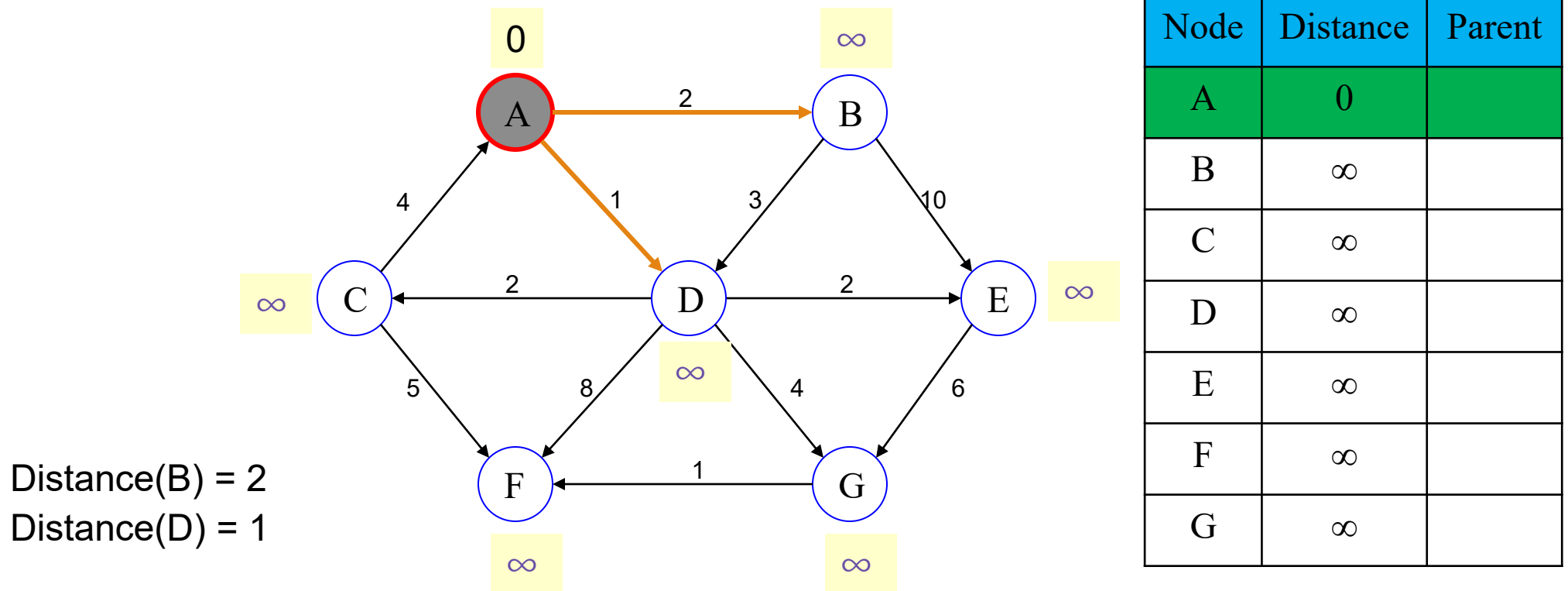
Distance (all vertices but source) = ∞



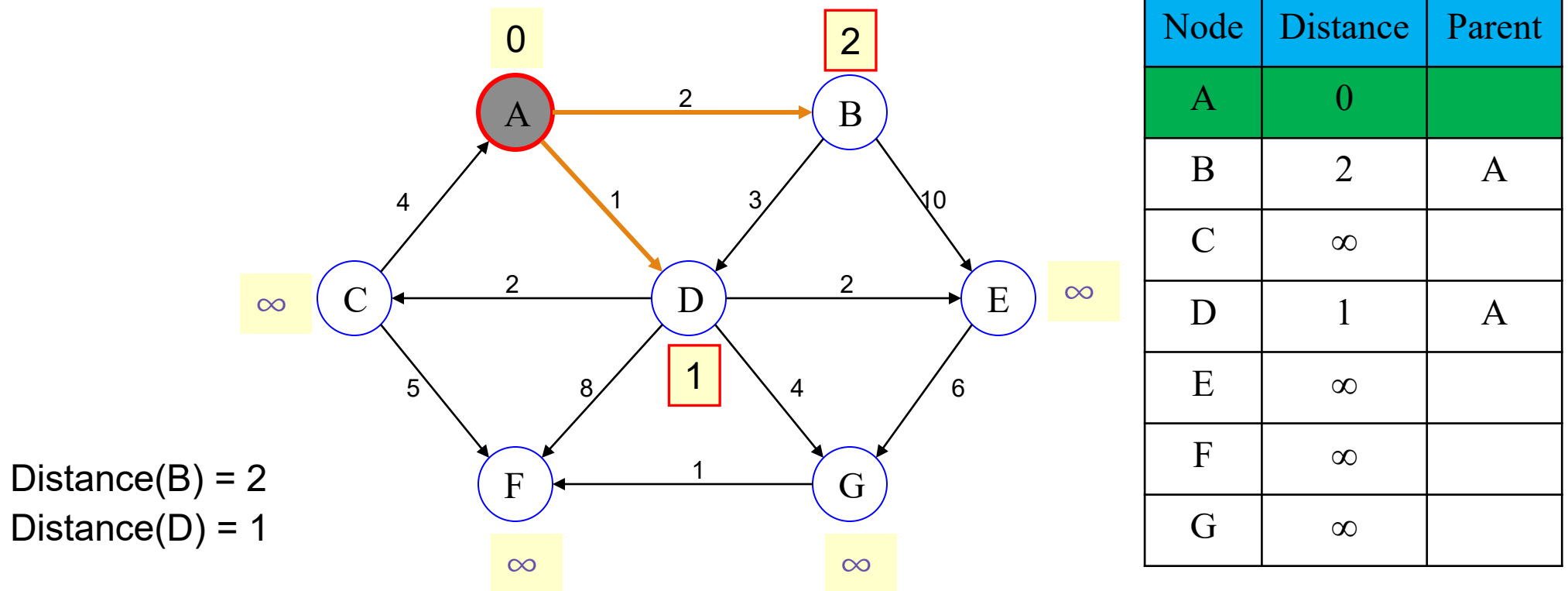
| Node | Distance | Parent |
|------|----------|--------|
| A | 0 | |
| B | ∞ | |
| C | ∞ | |
| D | ∞ | |
| E | ∞ | |
| F | ∞ | |
| G | ∞ | |

Pick vertex in List with minimum distance.

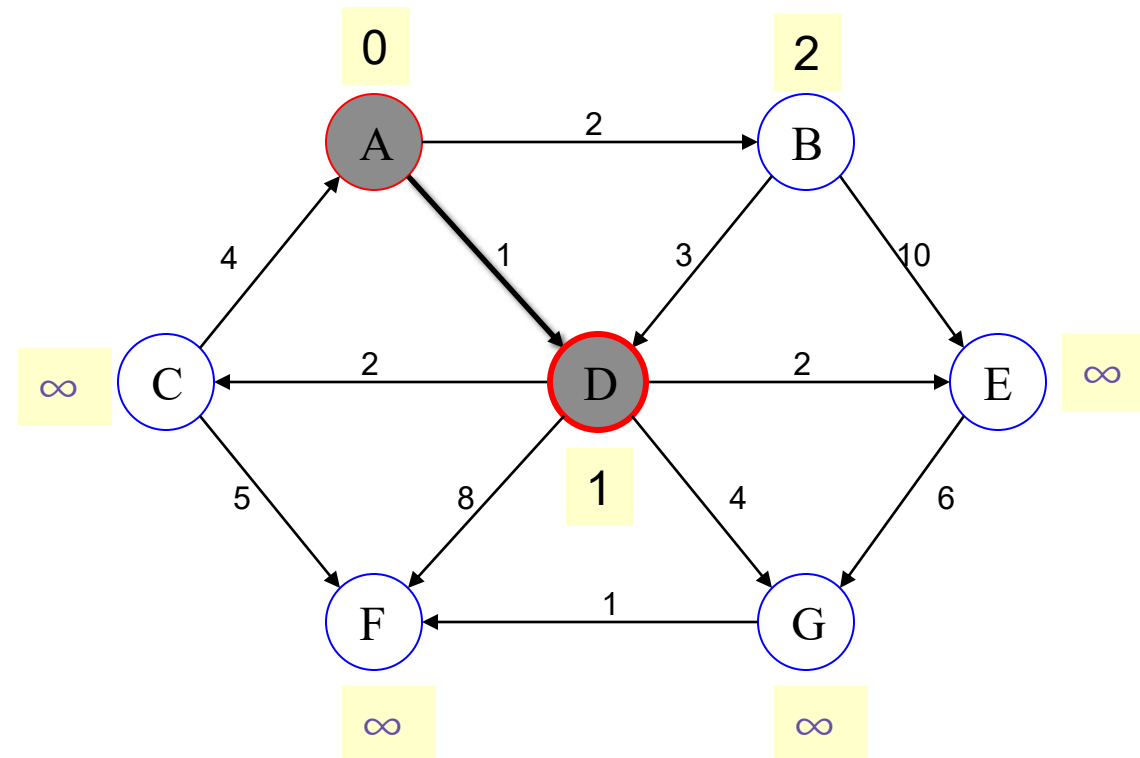
Example: Update neighbors' distance



Example: Update neighbors' distance



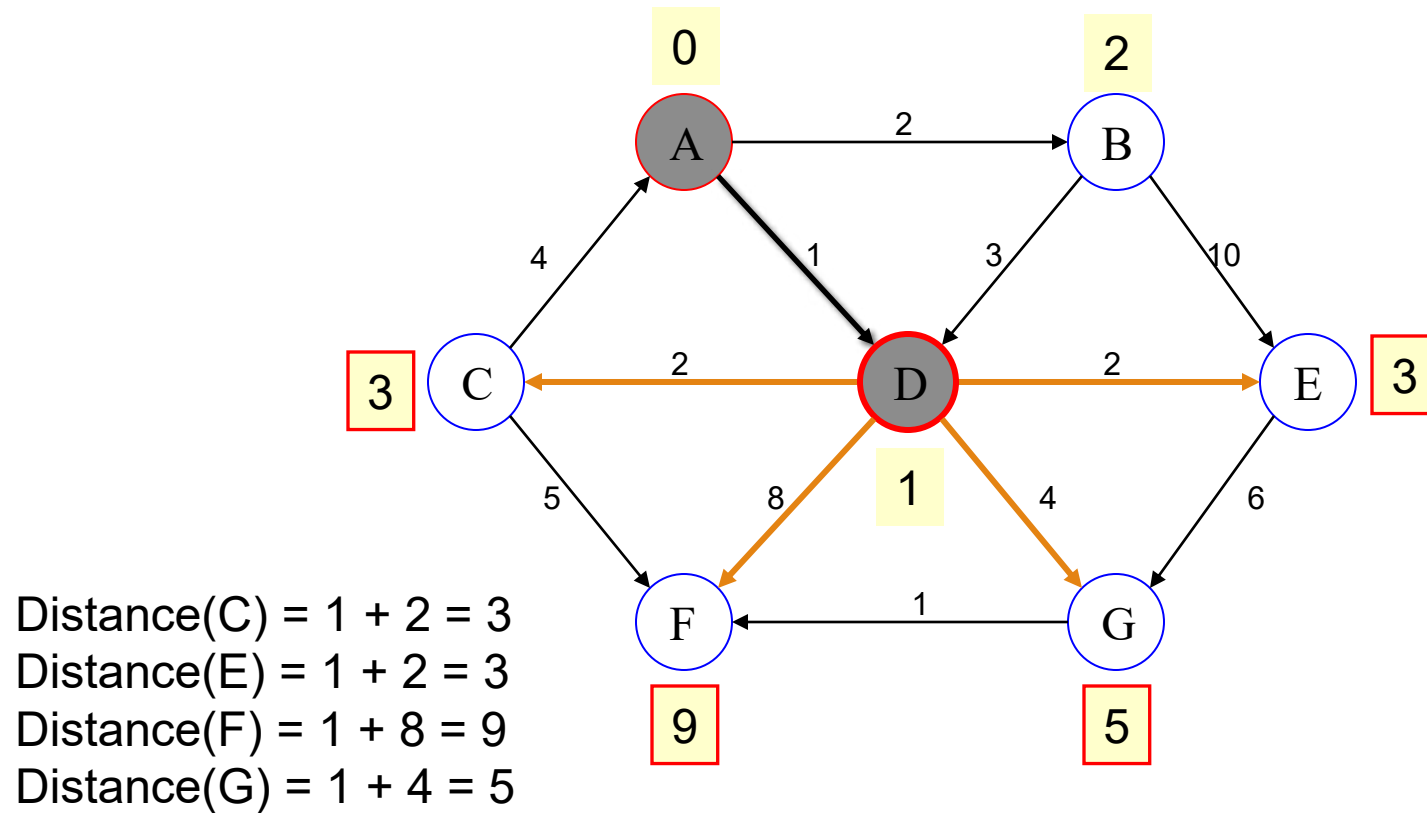
Example: Pick vertex with minimum distance



| Node | Distance | Parent |
|------|----------|--------|
| A | 0 | |
| B | 2 | A |
| C | ∞ | |
| D | 1 | A |
| E | ∞ | |
| F | ∞ | |
| G | ∞ | |

Pick vertex in List with minimum distance, i.e., D

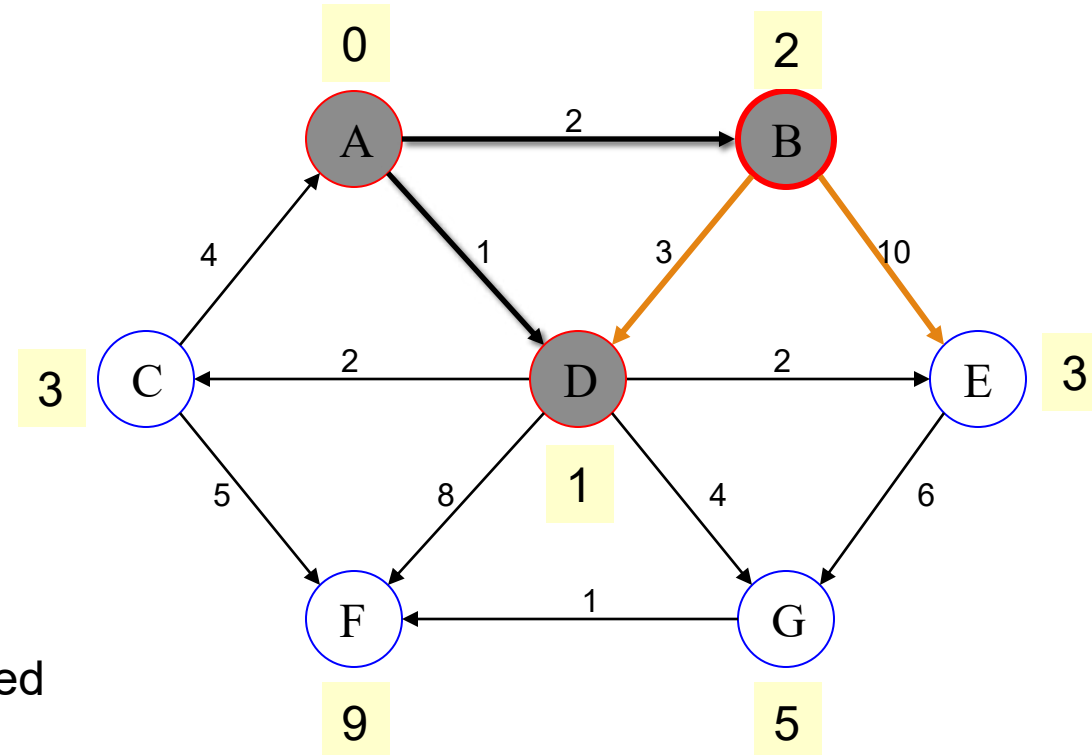
Example: Update neighbors



| Node | Distance | Parent |
|------|----------|--------|
| A | 0 | |
| B | 2 | A |
| C | 3 | D |
| D | 1 | A |
| E | 3 | D |
| F | 9 | D |
| G | 5 | D |

Example: Continued...

Pick vertex in List with minimum distance (B) and update neighbors

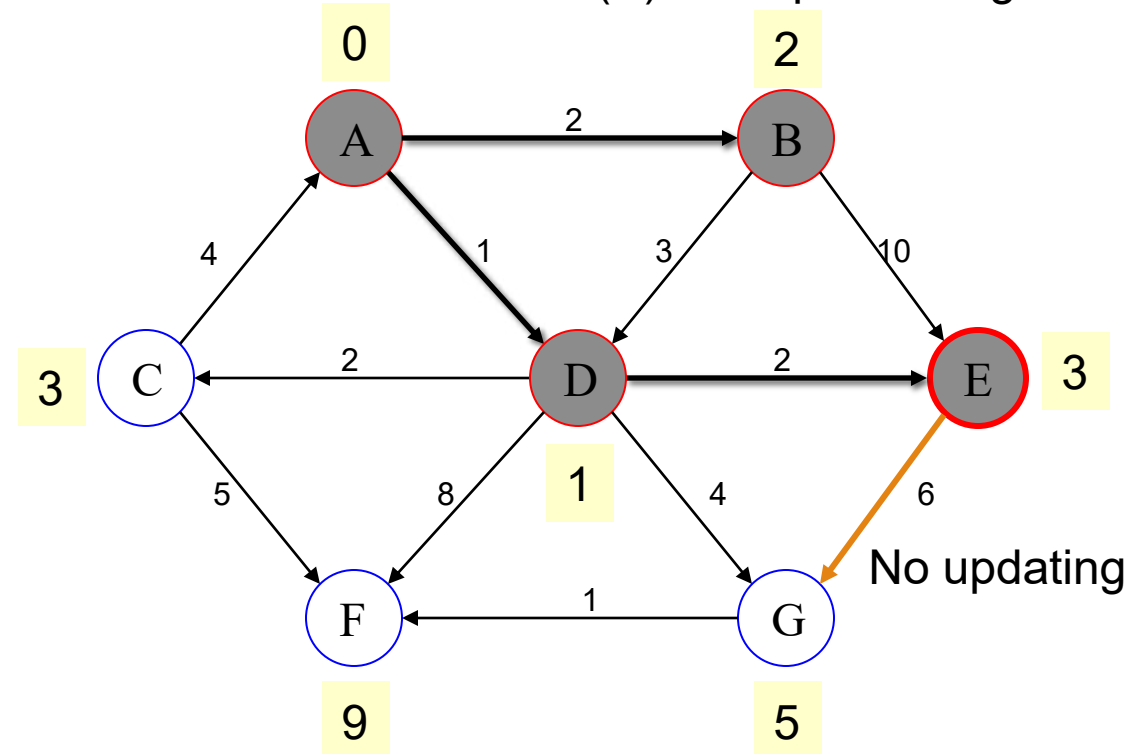


Note : distance(D) not updated since D is already known and distance(E) not updated since it is larger than previously computed

| Node | Distance | Parent |
|------|----------|--------|
| A | 0 | |
| B | 2 | A |
| C | 3 | D |
| D | 1 | A |
| E | 3 | D |
| F | 9 | D |
| G | 5 | D |

Example: Continued...

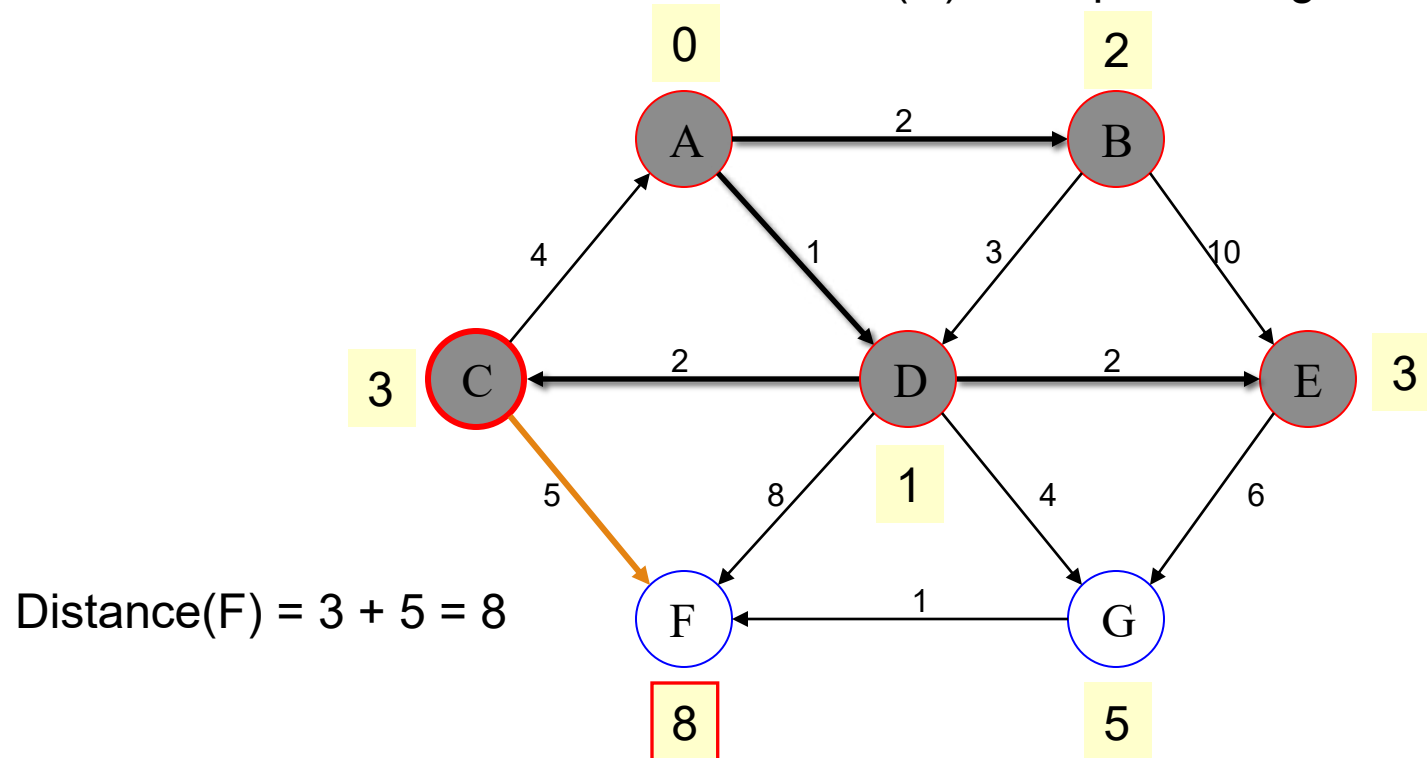
Pick vertex List with minimum distance (E) and update neighbors



| Node | Distance | Parent |
|------|----------|--------|
| A | 0 | |
| B | 2 | A |
| C | 3 | D |
| D | 1 | A |
| E | 3 | D |
| F | 9 | D |
| G | 5 | D |

Example: Continued...

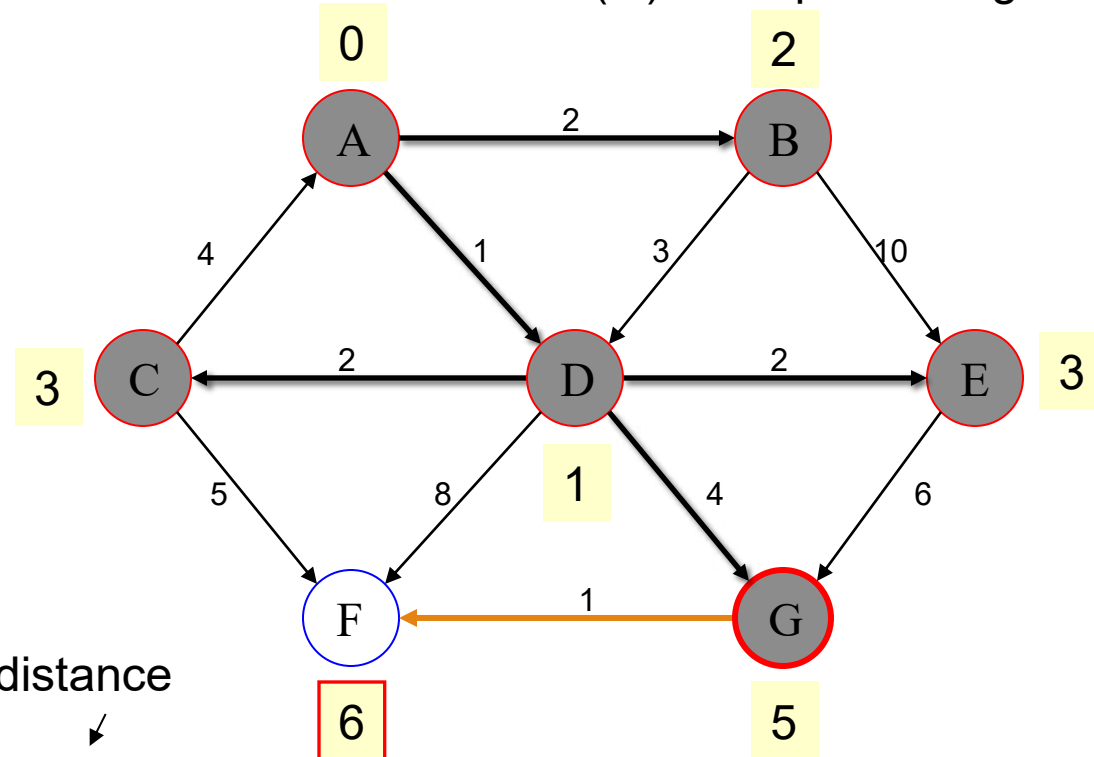
Pick vertex List with minimum distance (C) and update neighbors



| Node | Distance | Parent |
|------|----------|--------|
| A | 0 | |
| B | 2 | A |
| C | 3 | D |
| D | 1 | A |
| E | 3 | D |
| F | 8 | C |
| G | 5 | D |

Example: Continued...

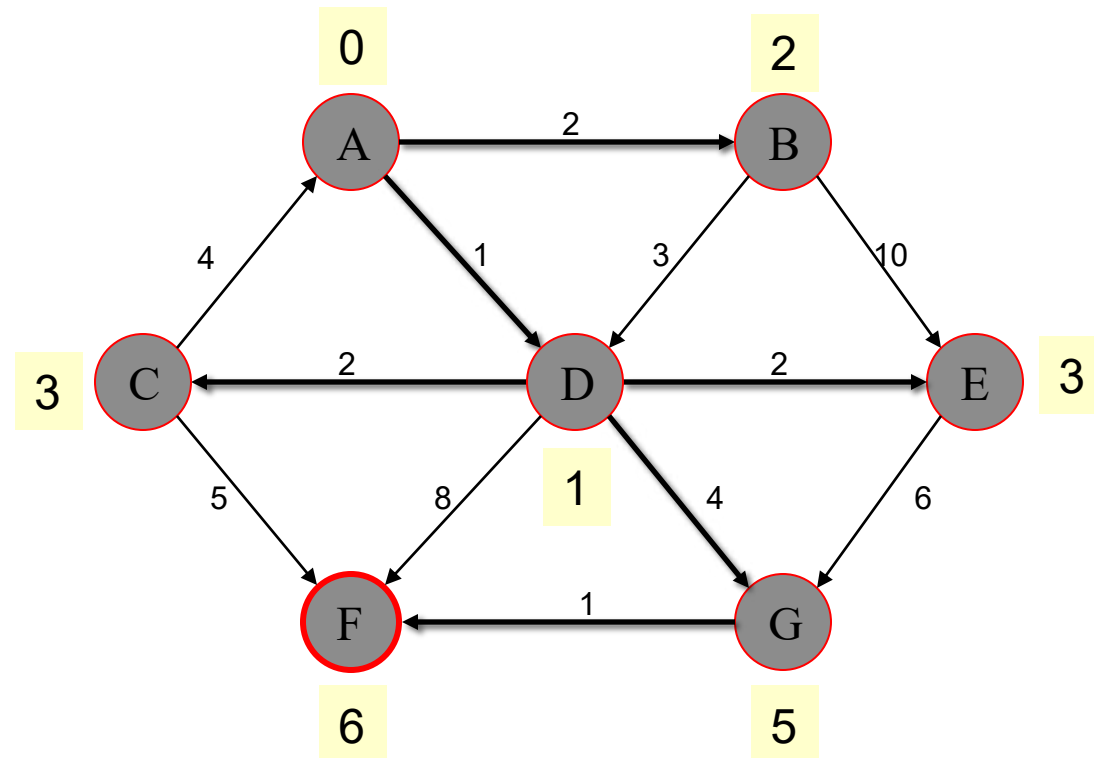
Pick vertex List with minimum distance (G) and update neighbors



$$\text{Distance}(F) = \min(8, 5+1) = 6$$

| Node | Distance | Parent |
|------|----------|--------|
| A | 0 | |
| B | 2 | A |
| C | 3 | D |
| D | 1 | A |
| E | 3 | D |
| F | 6 | G |
| G | 5 | D |

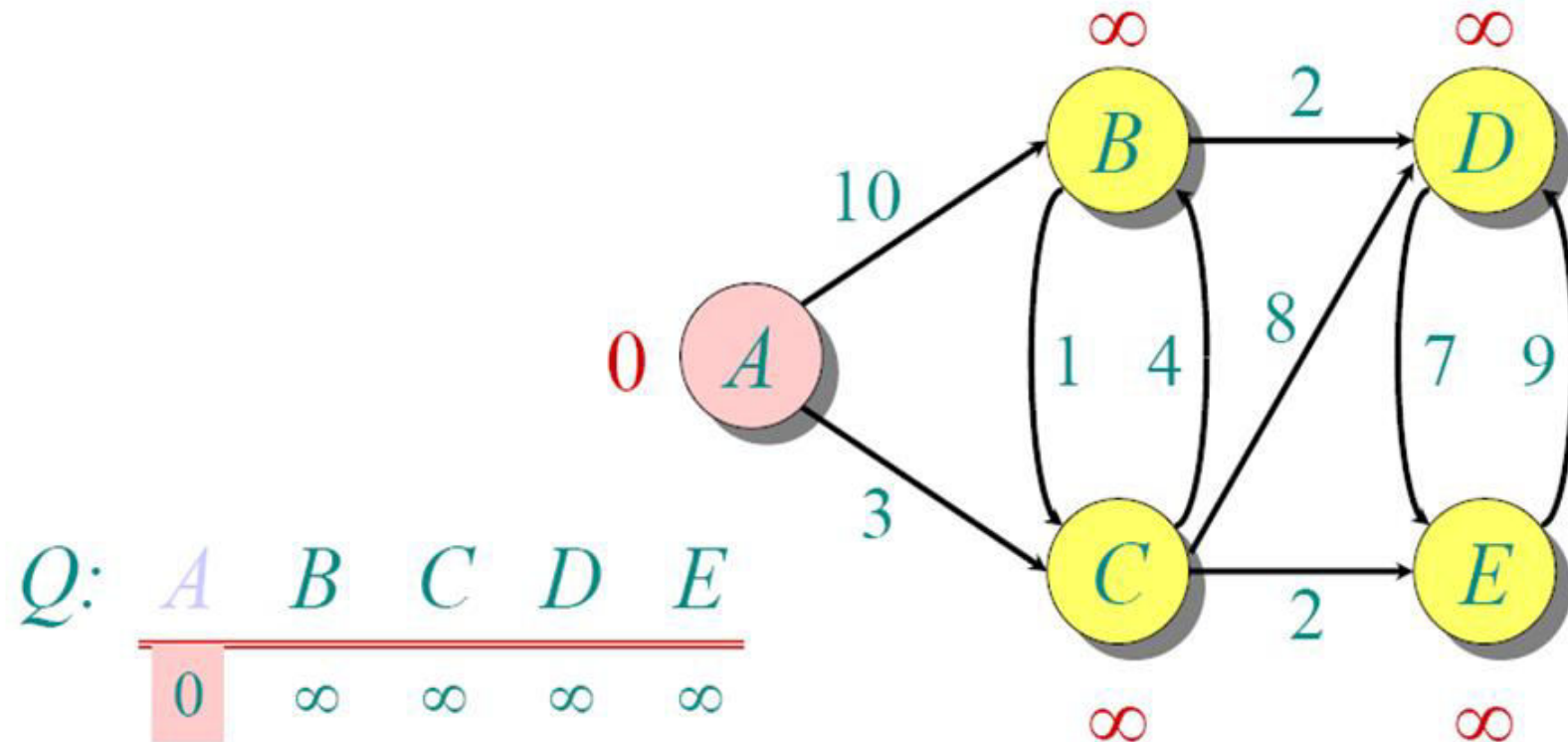
Example (end)



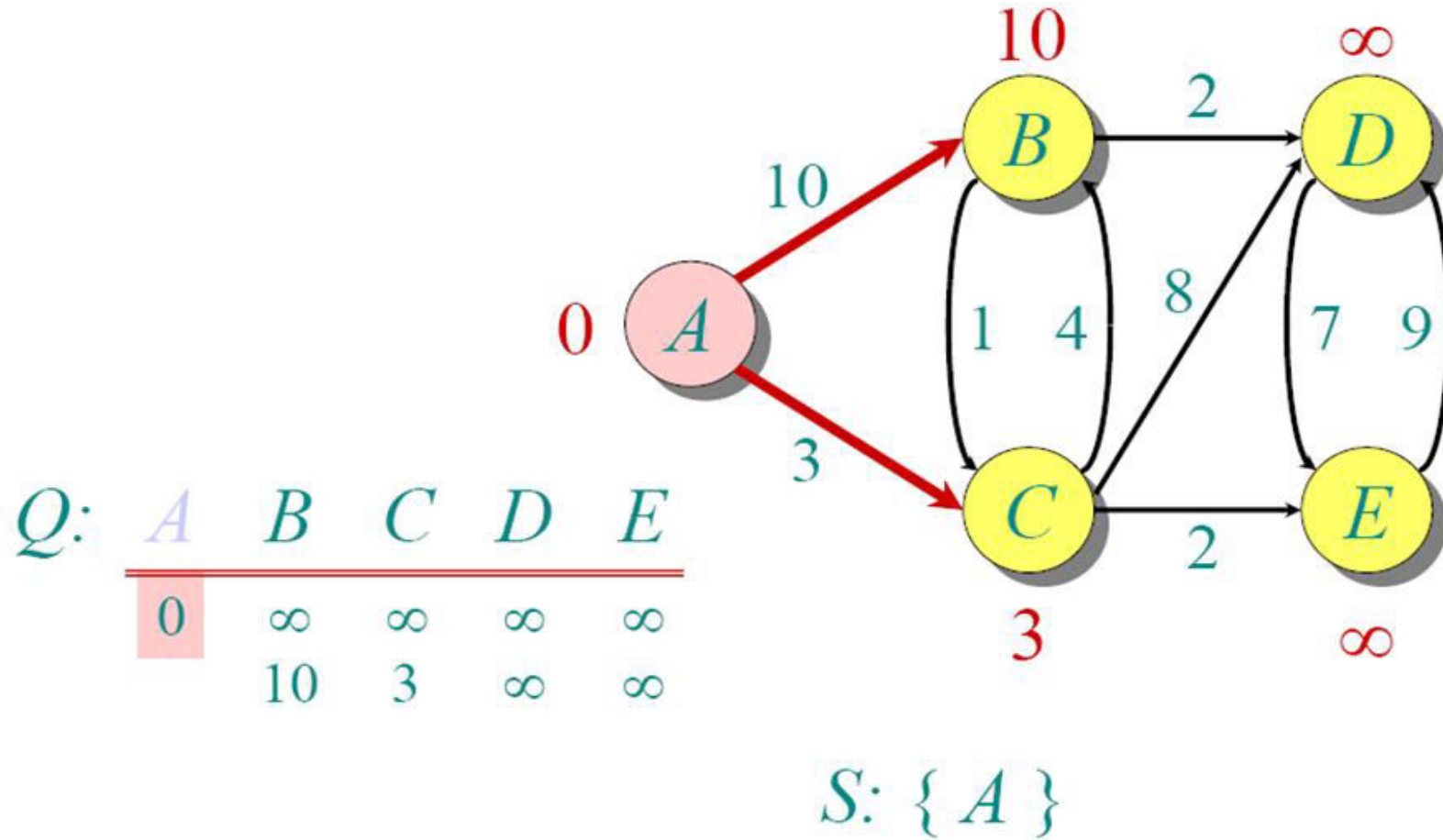
| Node | Distance | Parent |
|------|----------|--------|
| A | 0 | |
| B | 2 | A |
| C | 3 | D |
| D | 1 | A |
| E | 3 | D |
| F | 6 | G |
| G | 5 | D |

Pick vertex not in S with lowest cost (F) and update neighbors

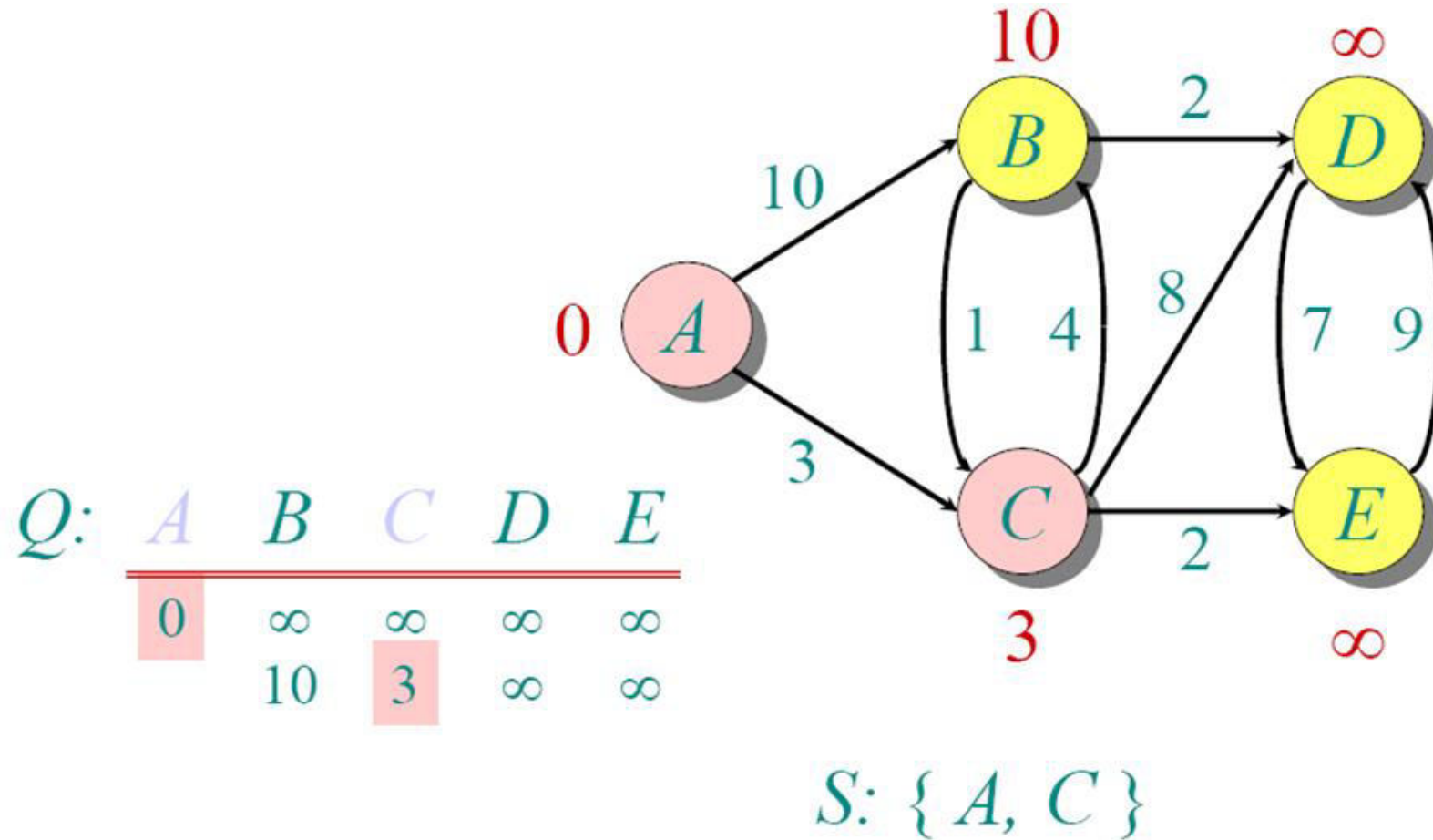
Another Example



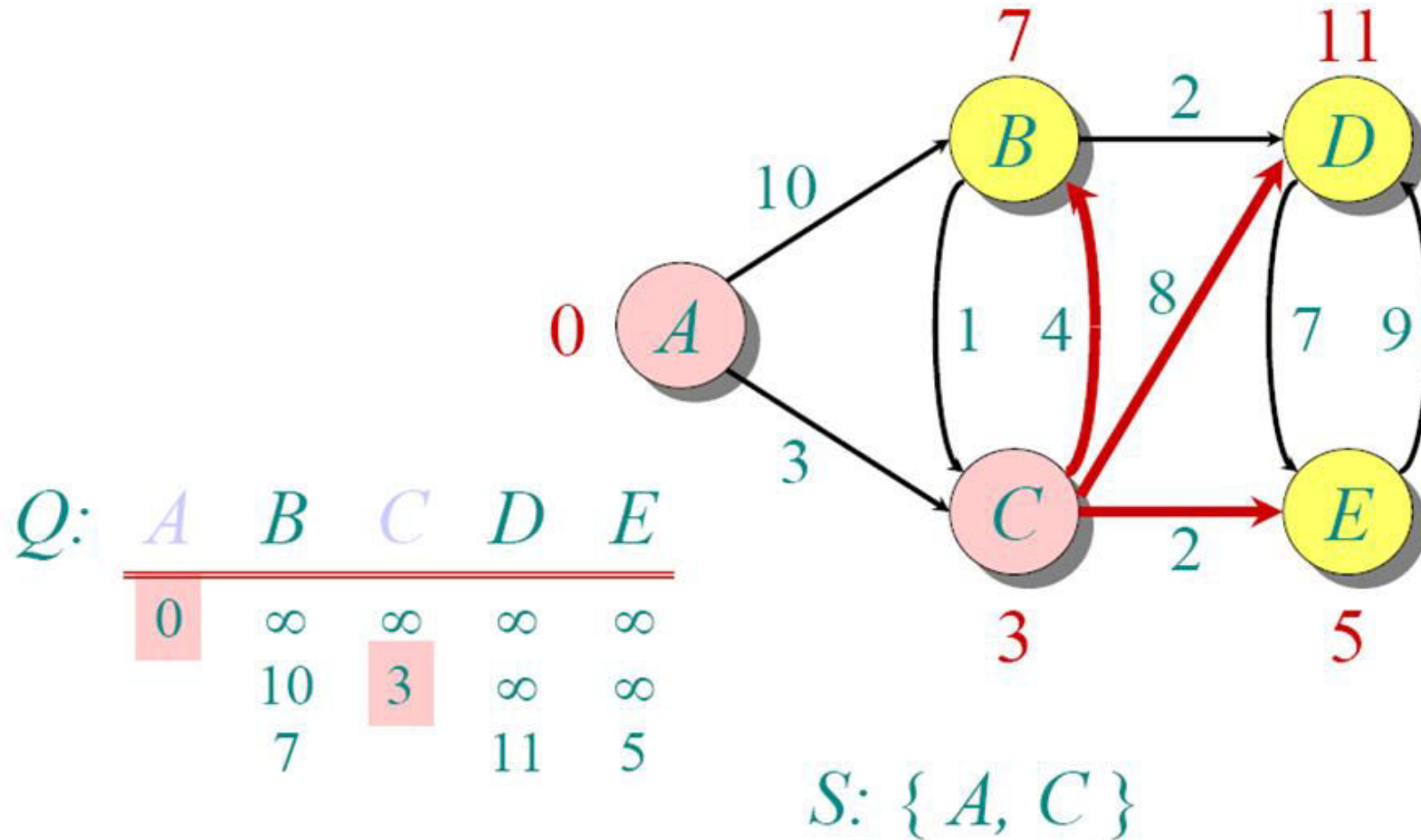
Example: Continued...



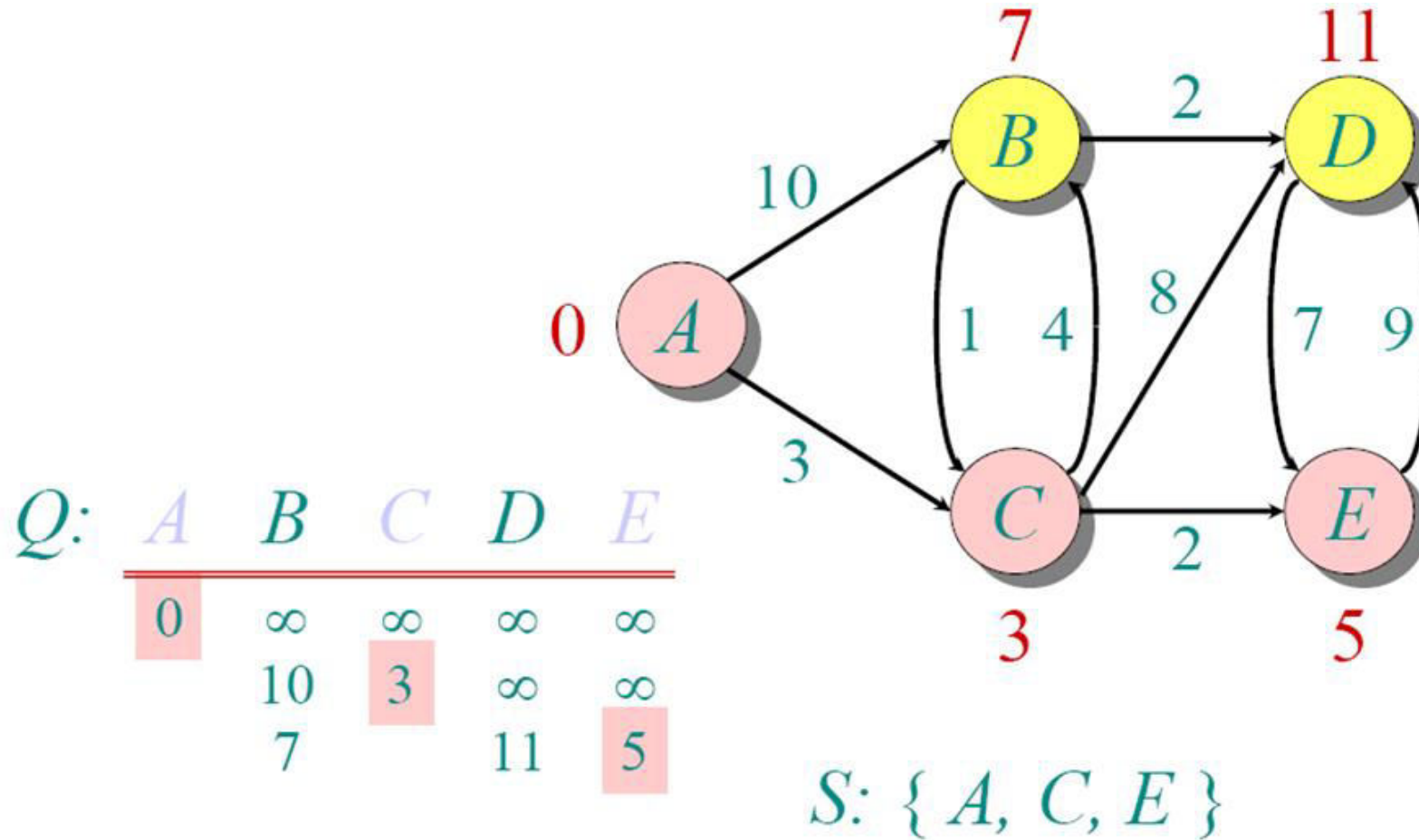
Example: Continued...



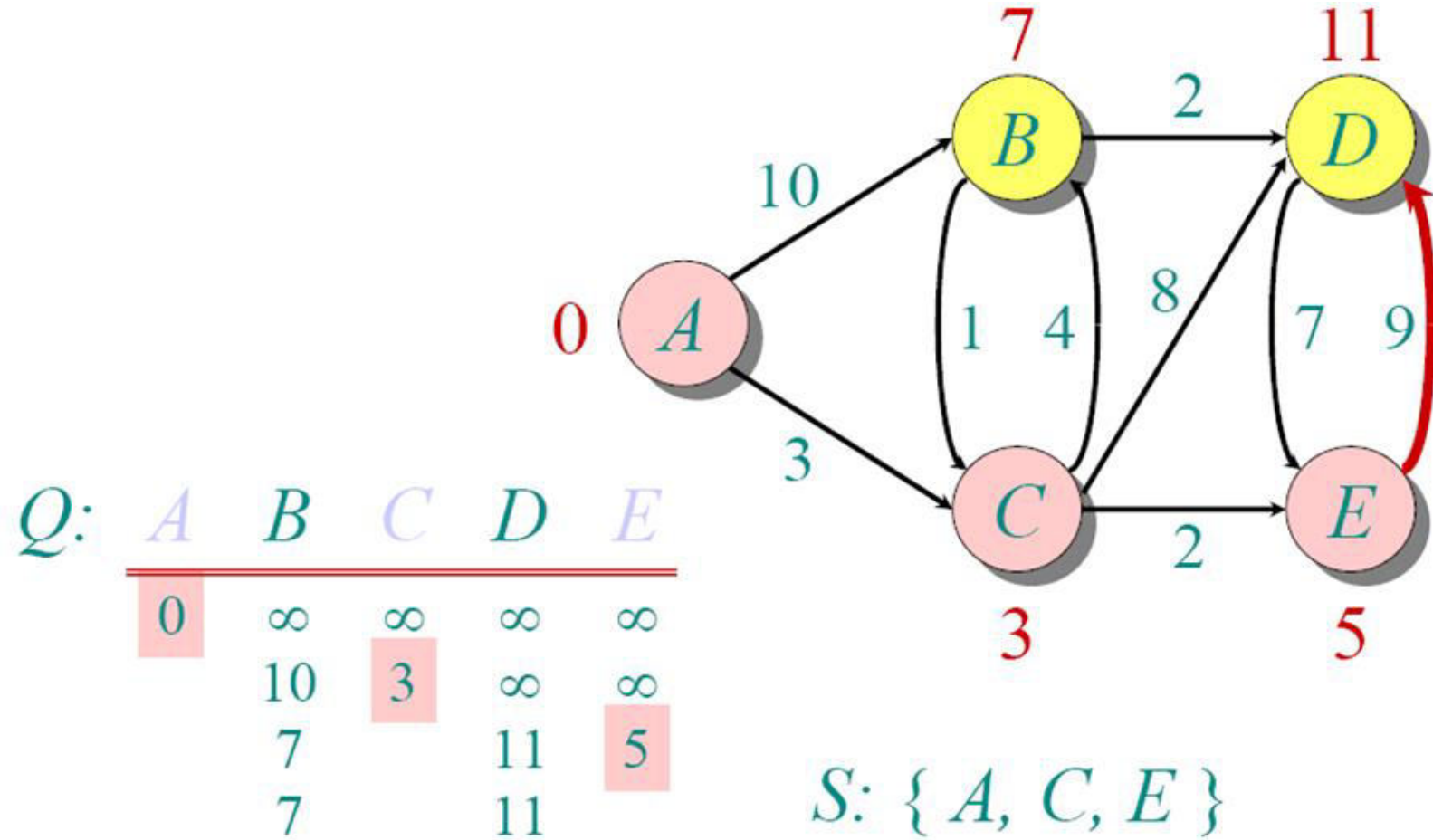
Example: Continued...



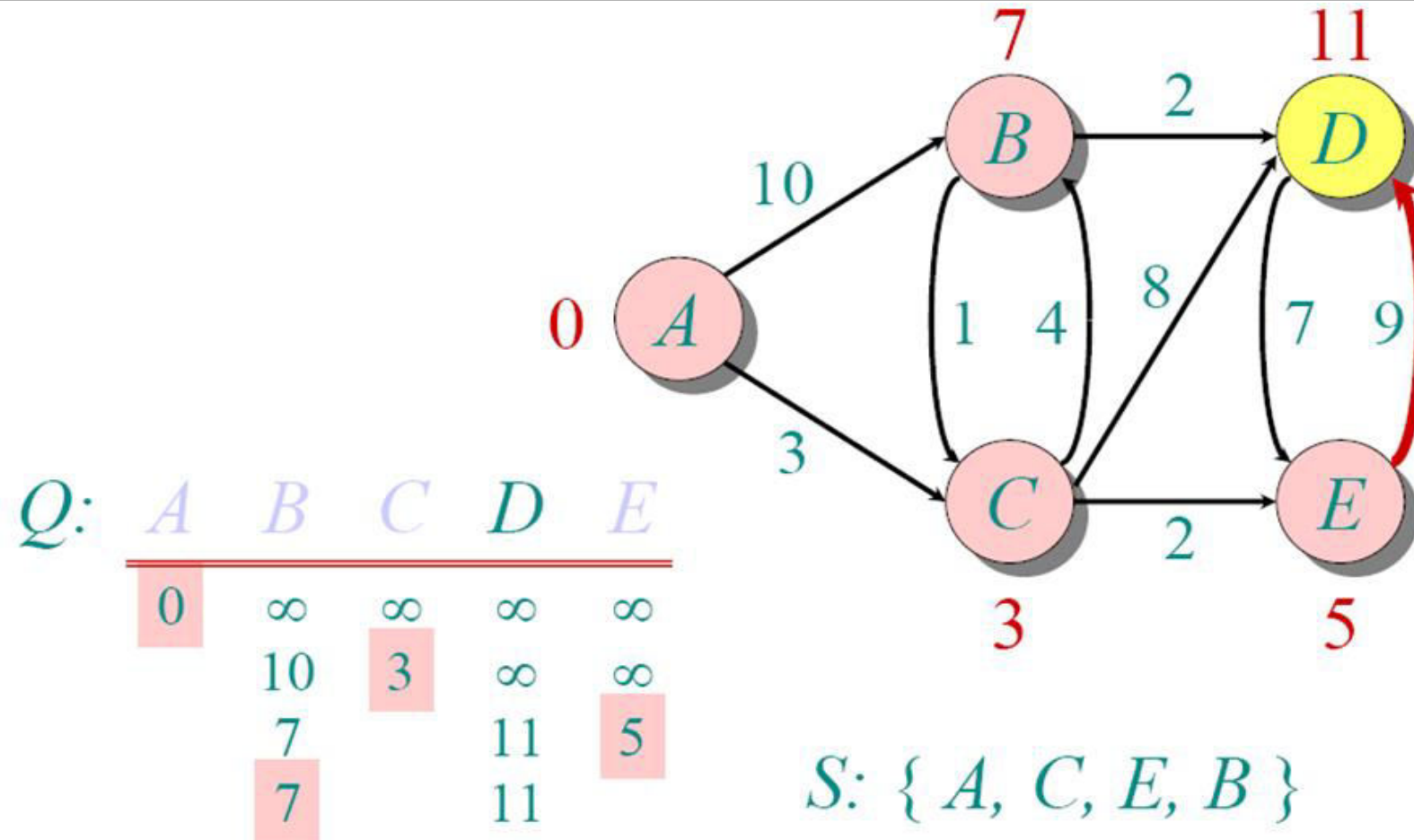
Example: Continued...



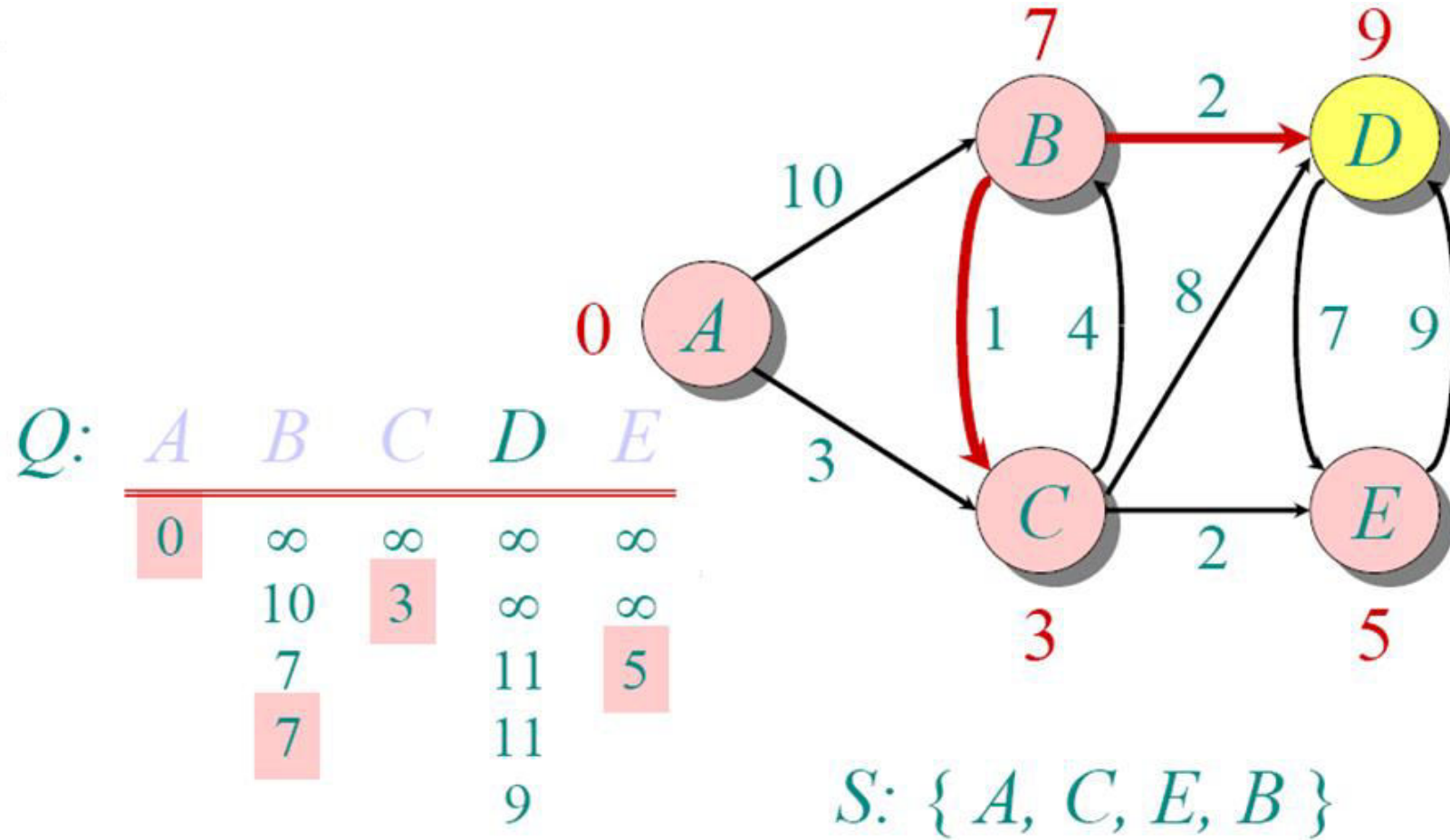
Example: Continued...



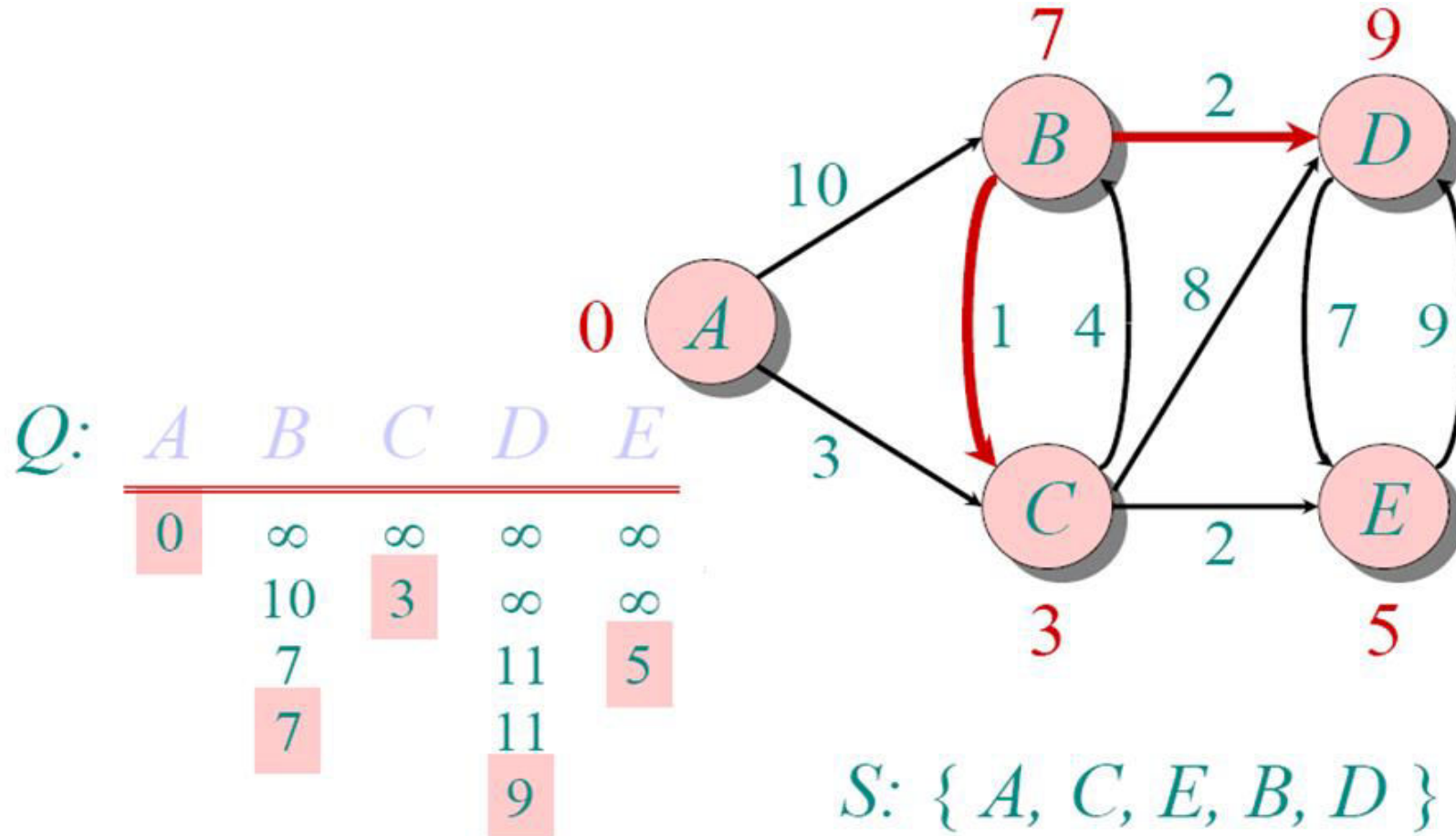
Example: Continued...



Example: Continued...



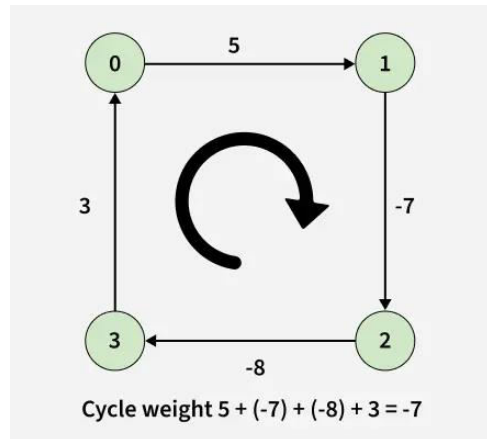
Example: Continued...



What if Negative Edge/Cycle??

Dijkstra is not suitable when the graph consists of negative edges. The reason is, it doesn't revisit those nodes which have already been marked as visited. If a shorter path exists through a longer route with negative edges, Dijkstra's algorithm will fail to handle it.

A negative weight cycle is a cycle in a graph, whose sum of edge weights is negative. If you traverse the cycle, the total weight accumulated would be less than zero.



In the presence of negative weight cycle in the graph, the shortest path doesn't exist because with each traversal of the cycle shortest path keeps decreasing.

Bellman–Ford Algorithm

Bellman-Ford is a **single source** shortest path algorithm. It effectively works in the cases of negative edges and is able to detect negative cycles as well. It works on the principle of **relaxation of the edge**

```
function BellmanFord(G, source):
```

```
    for each vertex v in G:
```

```
        distance[v] =  $\infty$ 
```

```
    distance[source] = 0
```

```
    for i from 1 to |V| - 1:
```

```
        for each edge (u, v) with weight w in G:
```

```
            if distance[u] + w < distance[v]:
```

```
                distance[v] = distance[u] + w
```

```
    for each edge (u, v) with weight w in G:
```

```
        if distance[u] + w < distance[v]:
```

```
            report "Negative-weight cycle detected"
```

```
            return
```

```
    return distance
```

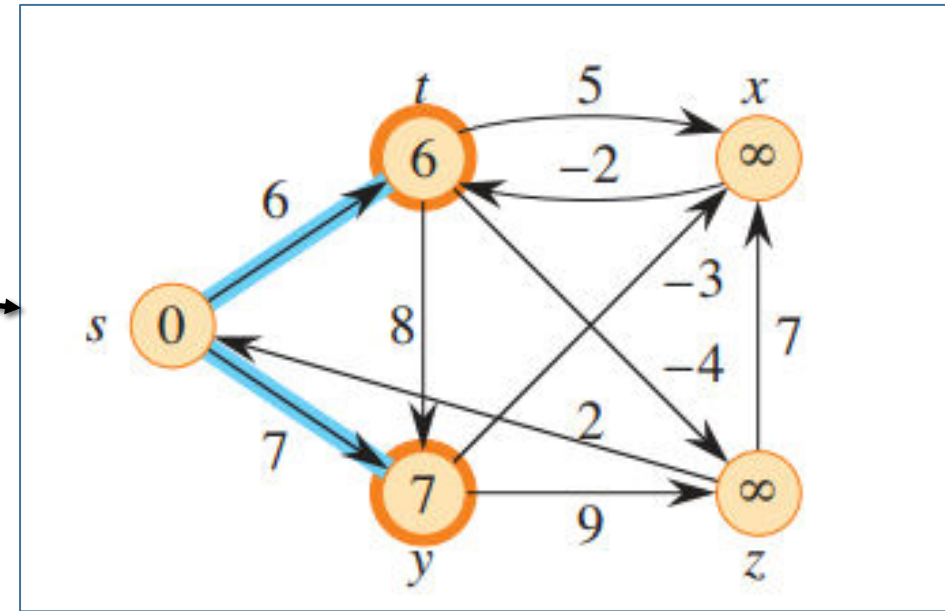
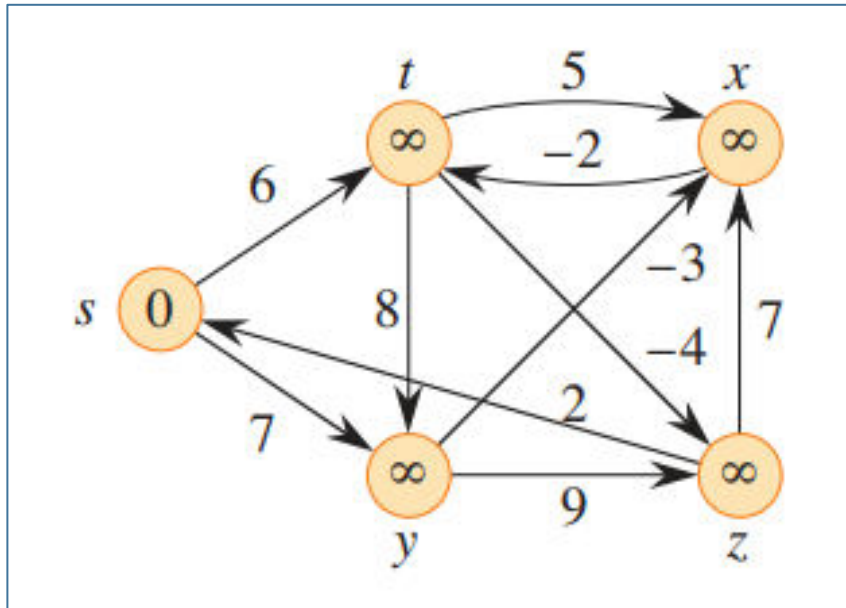
Set the distance to all other nodes as ∞ (infinity).

Set the distance to the source node as 0.

Relax all edges (V - 1) times

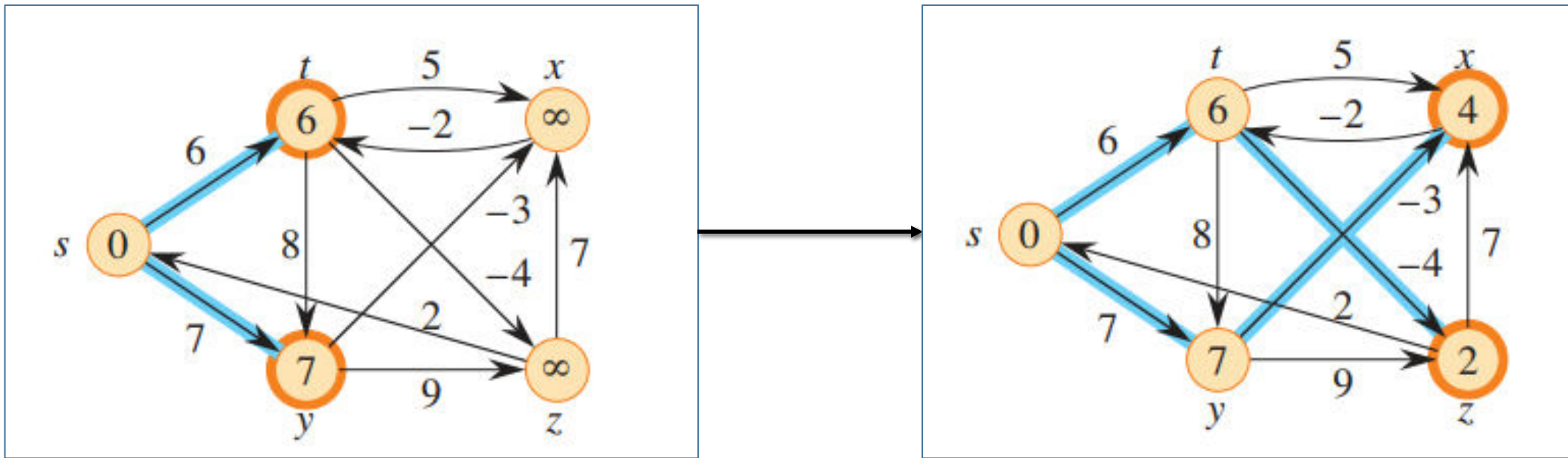
Check for negative-weight cycles (optional but important)

Bellman–Ford Algorithm - Example



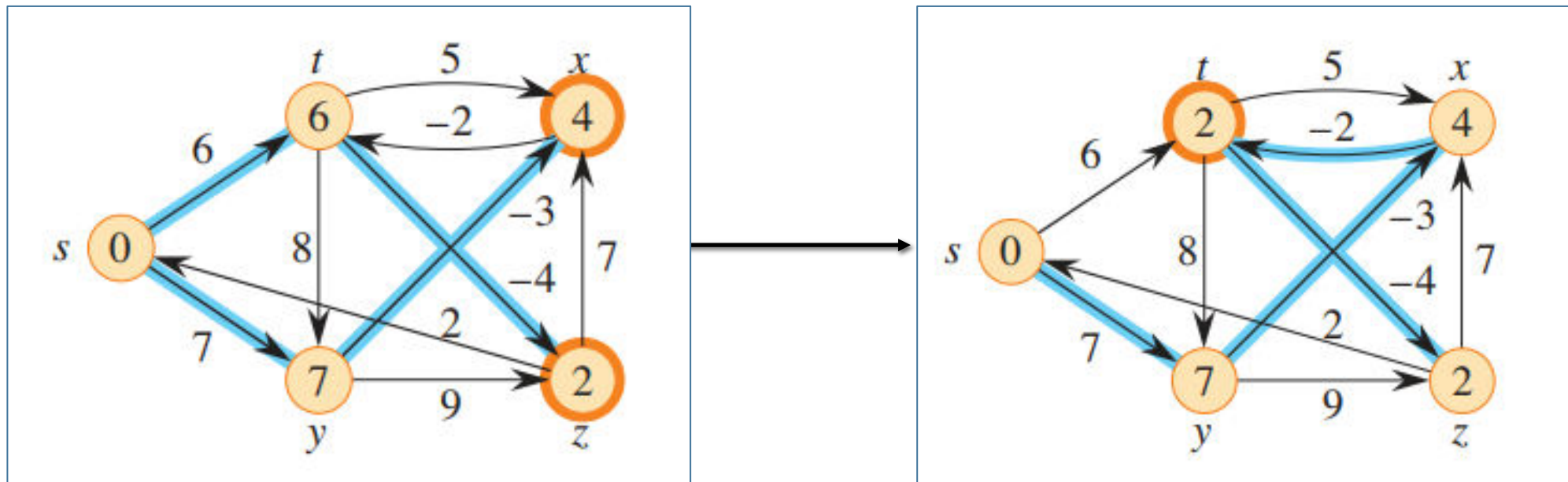
**First
Relaxation**

Example Continued...



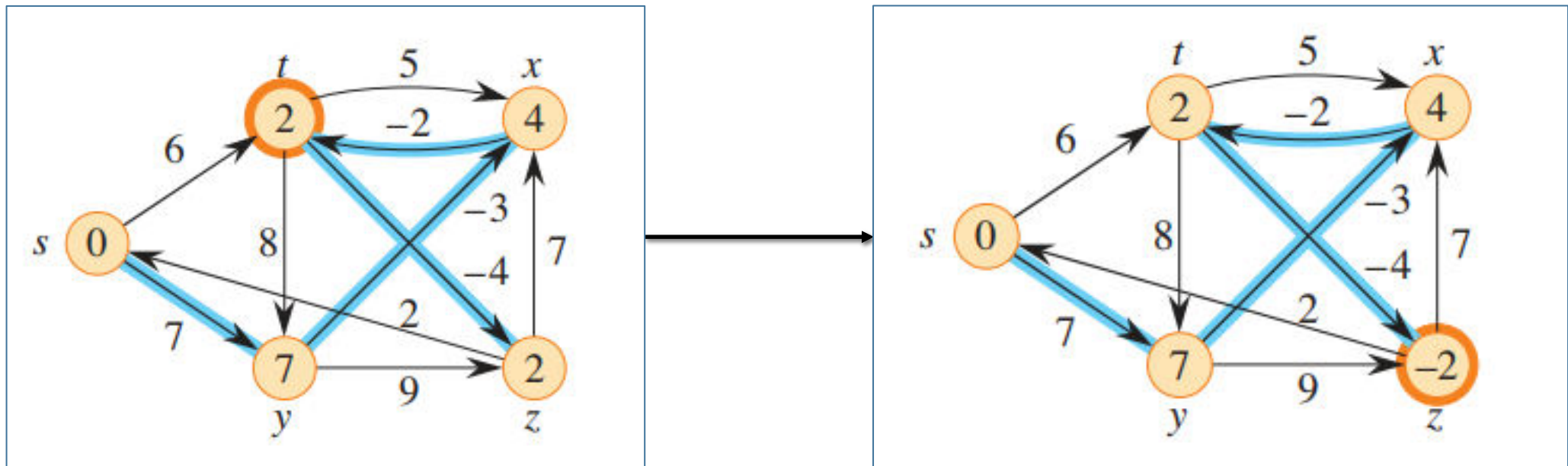
Second
Relaxation

Example Continued...



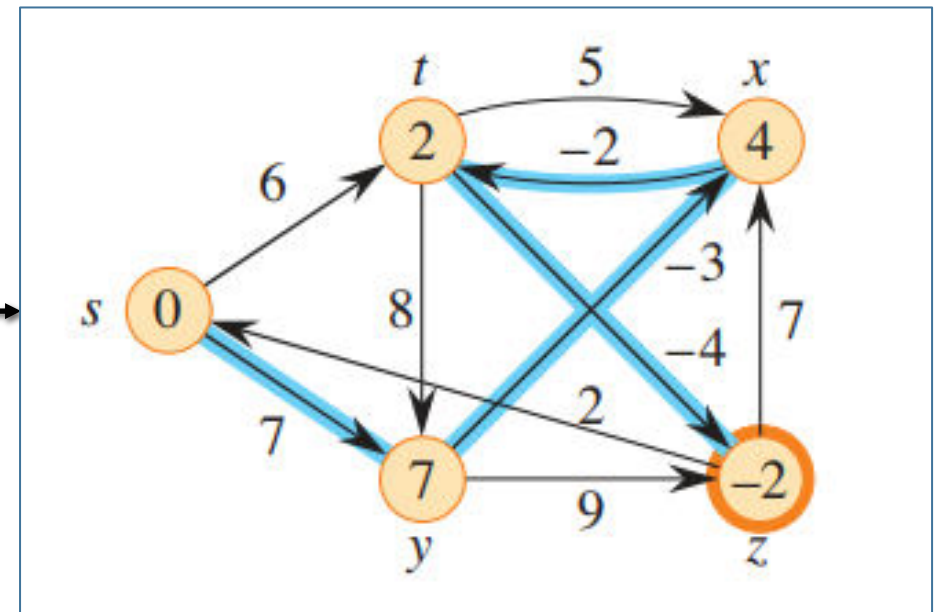
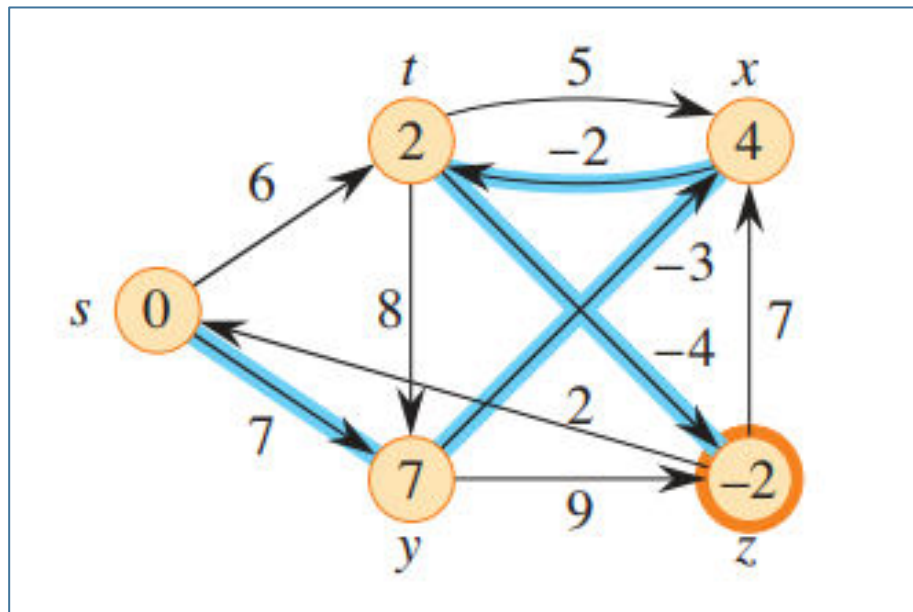
**Third
Relaxation**

Example Continued...



**Fourth
Relaxation**

Example Continued...

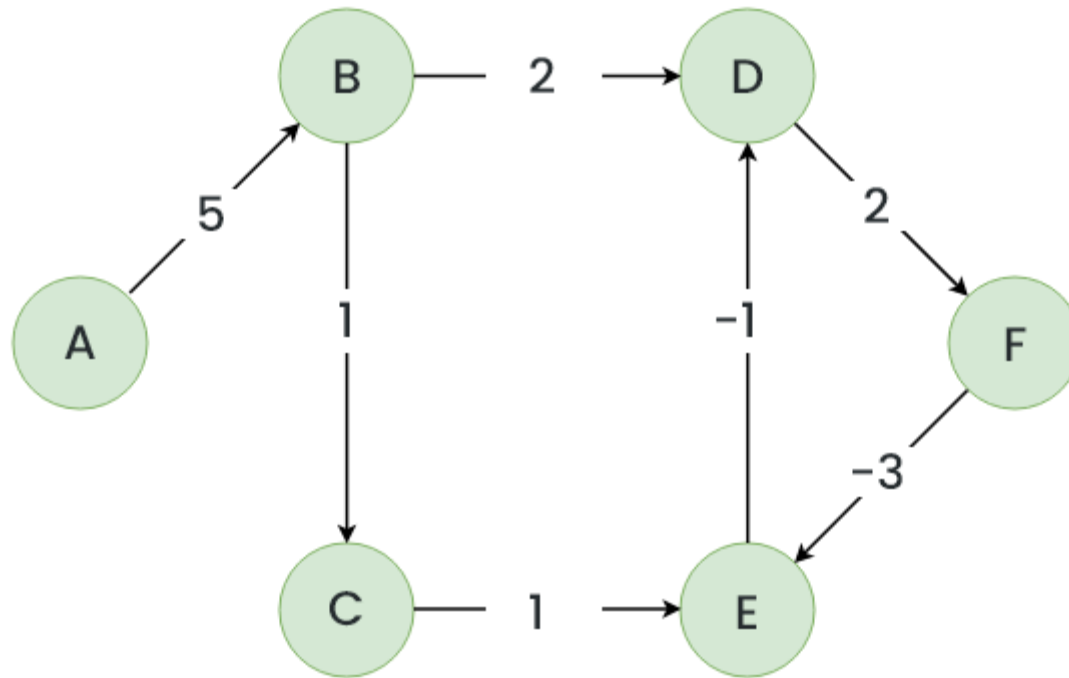


**Fifth
Relaxation**

No updates found. Hence, no negative edge cycle present in the graph.

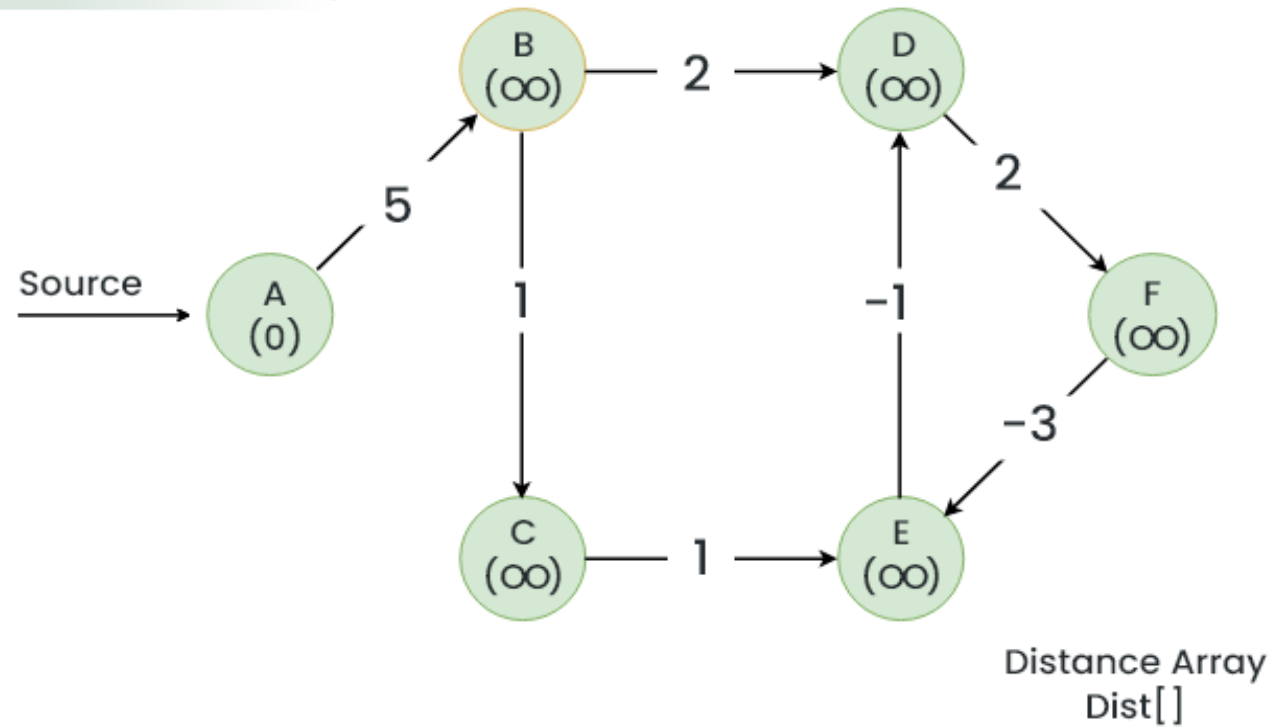
Another Example

Let's suppose we have a graph which is given below and we want to find whether there exists a negative cycle or not using Bellman-Ford.



Example Continued...

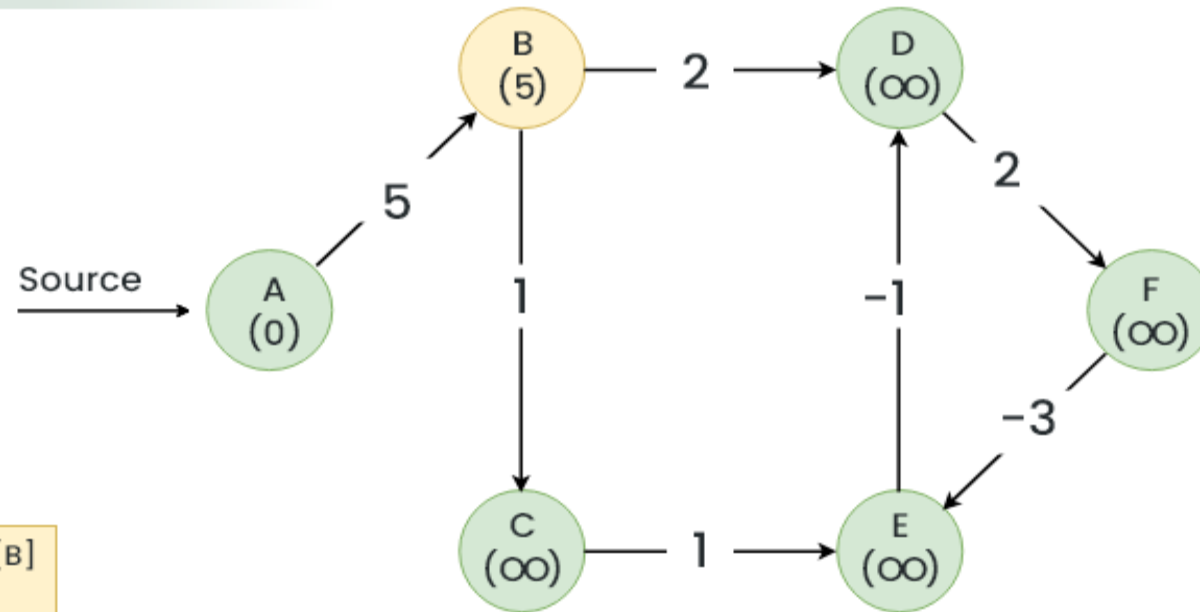
Initialize The Distance Array



| A | B | C | D | E | F |
|---|---|---|---|---|---|
| 0 | ∞ | ∞ | ∞ | ∞ | ∞ |

Example Continued...

1st Relaxation Of Edges



$\text{Dist}[A] + 5 < \text{Dist}[B]$
 $0 + 5 < (\infty)$
 $\text{Dist}[B] = 5$

Distance Array

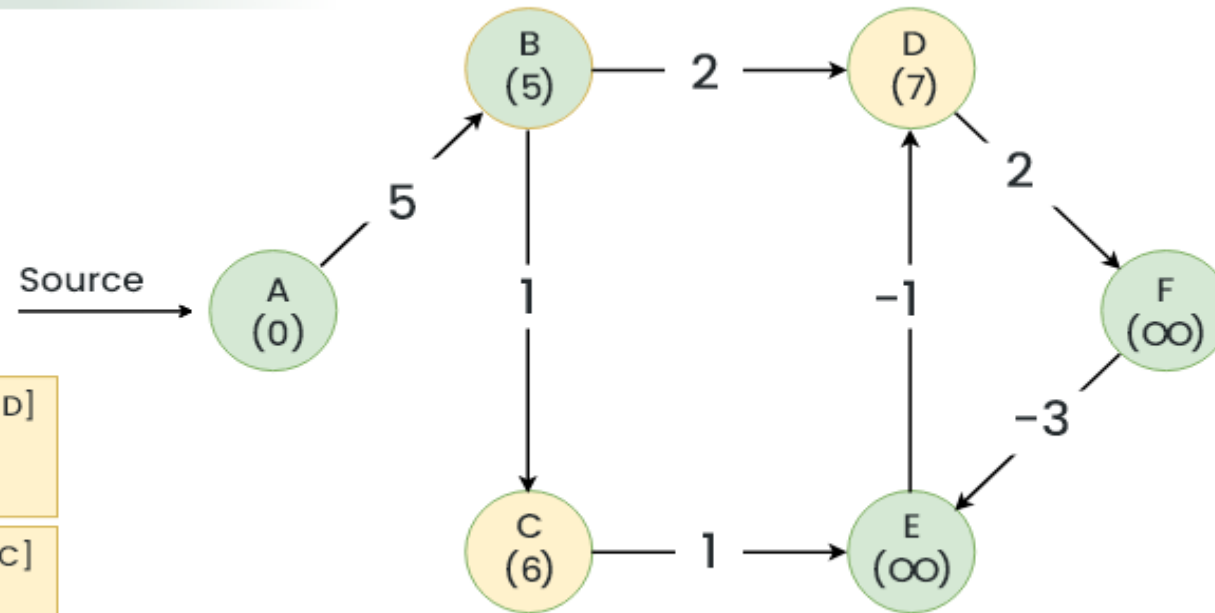
| A | B | C | D | E | F |
|---|----------|----------|----------|----------|----------|
| 0 | ∞ | ∞ | ∞ | ∞ | ∞ |



| A | B | C | D | E | F |
|---|---|----------|----------|----------|----------|
| 0 | 5 | ∞ | ∞ | ∞ | ∞ |

Example Continued...

2nd Relaxation Of Edges



$\text{Dist}[B] + 2 < \text{Dist}[D]$
 $5 + 2 < (\infty)$
 $\text{Dist}[D] = 7$

$\text{Dist}[B] + 1 < \text{Dist}[C]$
 $5 + 1 < (\infty)$
 $\text{Dist}[C] = 6$

Distance Array

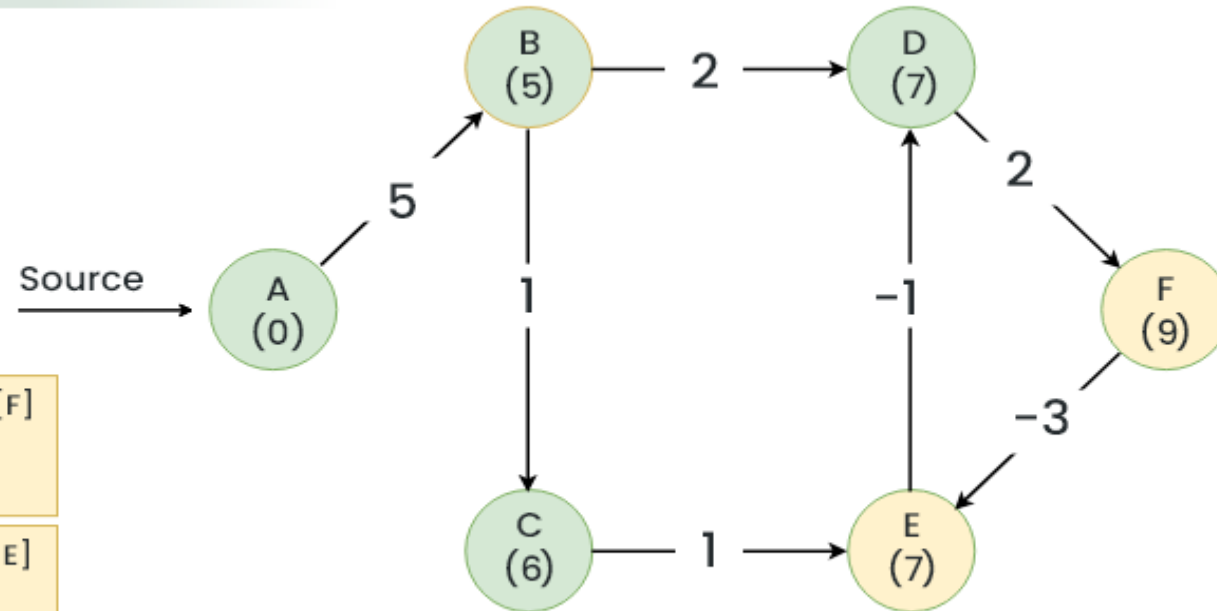
| A | B | C | D | E | F |
|---|---|----------|----------|----------|----------|
| 0 | 5 | ∞ | ∞ | ∞ | ∞ |



| A | B | C | D | E | F |
|---|---|---|---|----------|----------|
| 0 | 5 | 6 | 7 | ∞ | ∞ |

Example Continued...

3rd Relaxation Of Edges



$\text{Dist}[D] + 2 < \text{Dist}[F]$
 $7 + 2 < (\infty)$
 $\text{Dist}[F] = 9$

$\text{Dist}[C] + 1 < \text{Dist}[E]$
 $6 + 1 < (\infty)$
 $\text{Dist}[E] = 7$

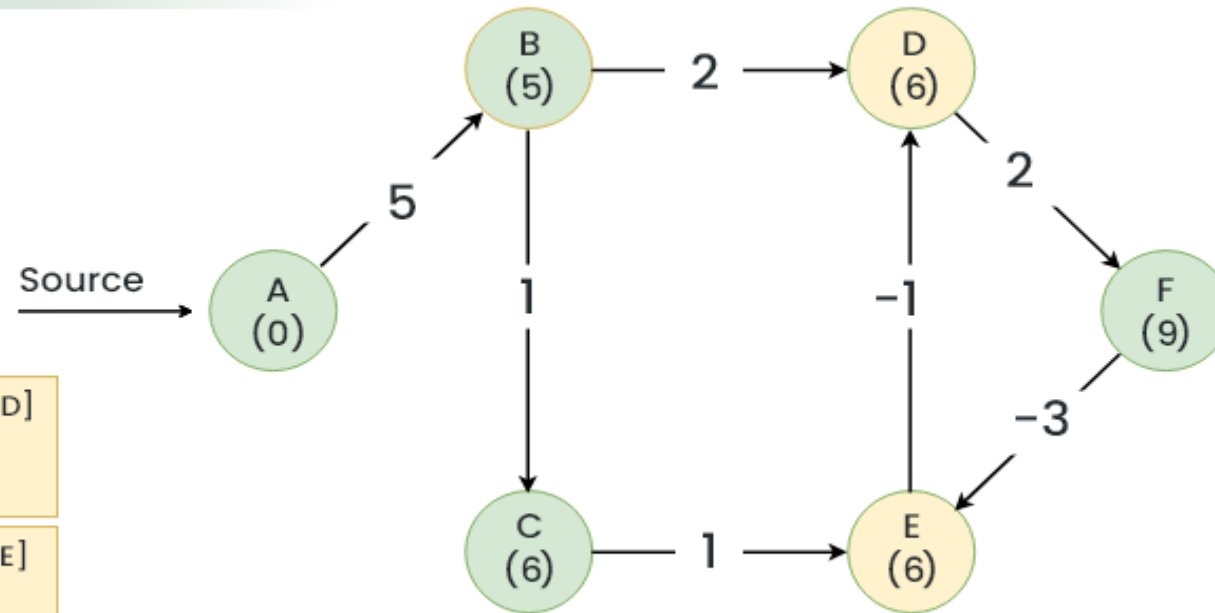
Distance Array

| A | B | C | D | E | F |
|---|---|---|---|----------|----------|
| 0 | 5 | 6 | 7 | ∞ | ∞ |

| A | B | C | D | E | F |
|---|---|---|---|---|---|
| 0 | 5 | 6 | 7 | 7 | 9 |

Example Continued...

4th Relaxation Of Edges



$\text{Dist}[E] + 2 < \text{Dist}[D]$
 $7 + (-1) < 7$
 $\text{Dist}[D] = 6$

$\text{Dist}[F] + 1 < \text{Dist}[E]$
 $9 + (-3) < 6$
 $\text{Dist}[E] = 6$

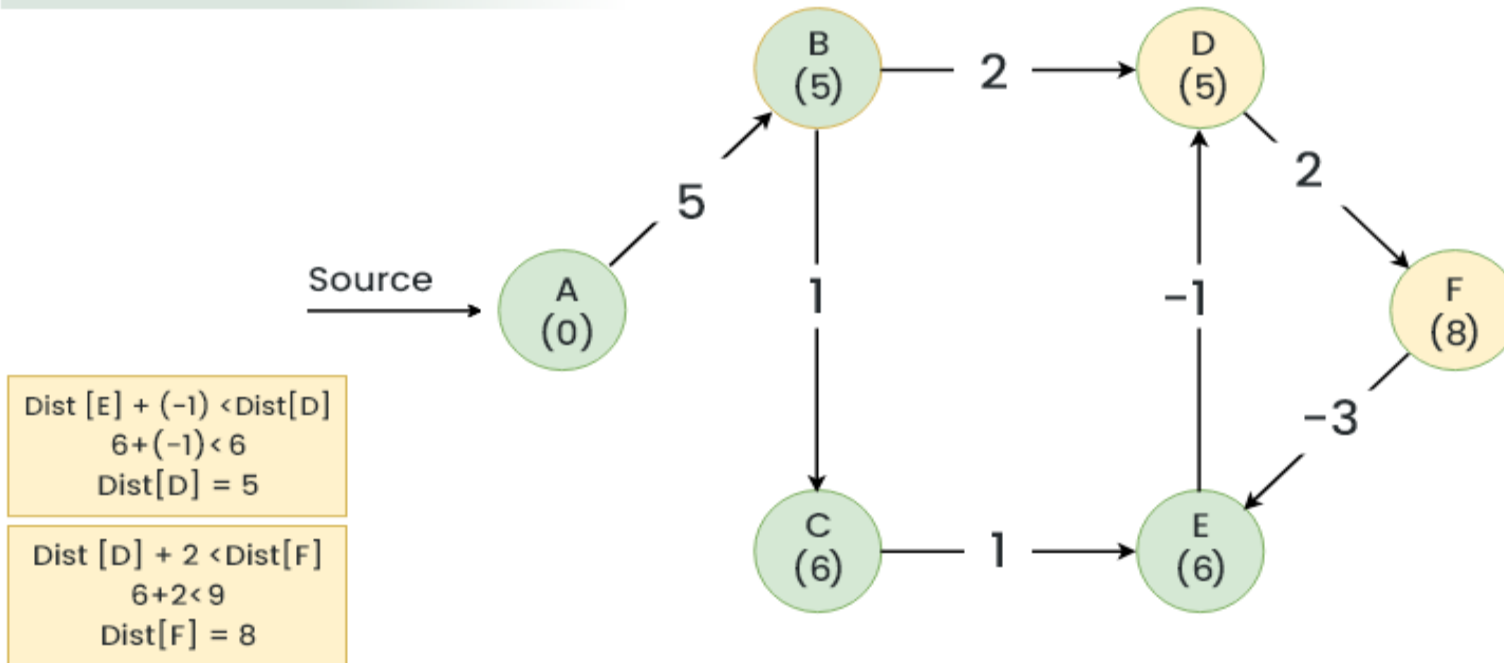
Distance Array

| A | B | C | D | E | F |
|---|---|---|---|---|---|
| 0 | 5 | 6 | 7 | 7 | 9 |

| A | B | C | D | E | F |
|---|---|---|---|---|---|
| 0 | 5 | 6 | 6 | 6 | 9 |

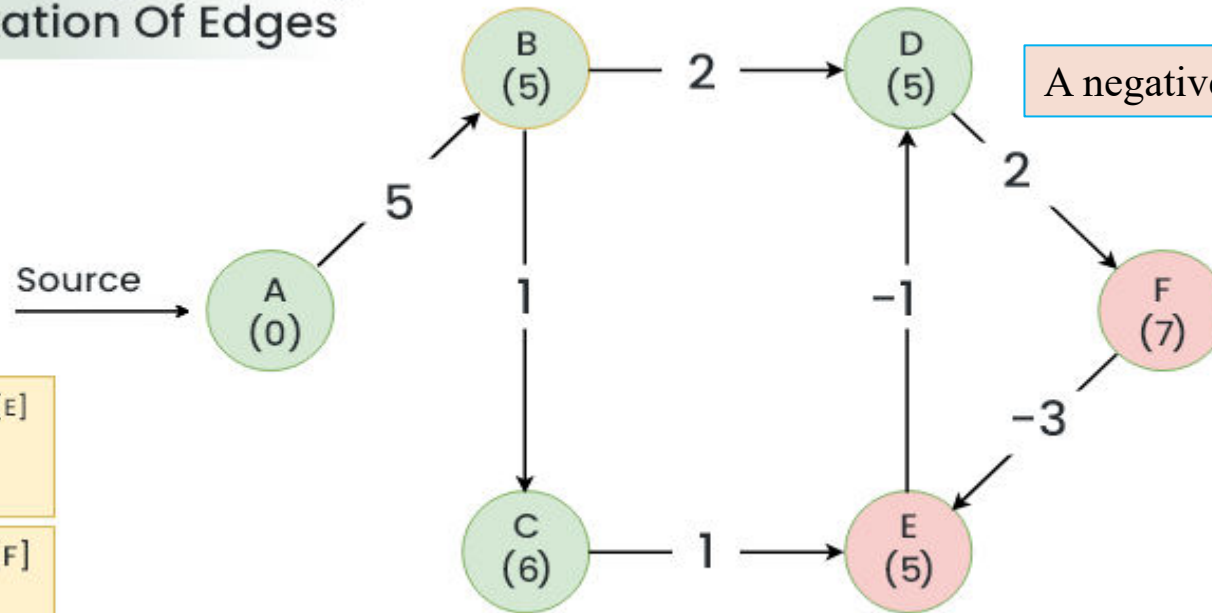
Example Continued...

5th Relaxation Of Edges



Example Continued...

Detecting The Negative Edge
By 6Th Relaxation Of Edges



A negative cycle (D→F→E) exists in the graph.

$\text{Dist}[F] + (-3) < \text{Dist}[E]$
 $8 + (-3) < 6$
 $\text{Dist}[E] = 5$

$\text{Dist}[D] + 2 < \text{Dist}[F]$
 $6 + 2 < 8$
 $\text{Dist}[F] = 7$

Distance Array

| A | B | C | D | E | F |
|---|---|---|---|---|---|
| 0 | 5 | 6 | 5 | 6 | 8 |



| A | B | C | D | E | F |
|---|---|---|---|---|---|
| 0 | 5 | 6 | 4 | 4 | 6 |

THANK YOU
