

# CSE 2103

## (Data Structures)

### Lecture on

## Chapter-7: Tree

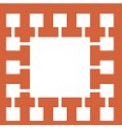
By

**Dr. M. Golam Rashed**

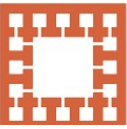
(golamrashed@ru.ac.bd)



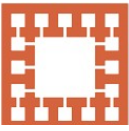
Department of Computer Science and Engineering(CSE)  
Varendra University, Rajshahi, Bangladesh



**Trees and Graphs:** Basic terminology, Binary trees, Binary tree representation, Tree traversal algorithms, Extended binary tree, Huffman codes/algorithm, Graphs, Graph representation, Shortest path algorithm and transitive closure, Traversing a graph.

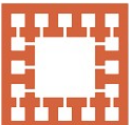


- Linear Data Structures
  - ✓ Strings
  - ✓ Arrays
  - ✓ Linked Lists
  - ✓ Stacks, and
  - ✓ Queues
- Nonlinear Data Structures
  - ✓ Tree,
  - ✓ Graphs



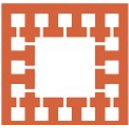
# Tree Data Structure

- Tree structure is mainly used to represent data containing a hierarchical relationship between elements. For example....
  - Records,
  - Family tress, and
  - Tables of contents.
- In this chapter, we investigate a special kind of tree, called a *binary tree*
  - It can be maintained in the computer easily



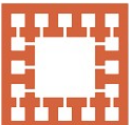
# Binary Tree

- $T$  is a finite set of elements, called *Nodes*, such that
  - $T$  is empty (called null tree or empty tree), or
  - $T$  contains a distinguished node  $R$ , called a **root** of  $T$ , and the remaining nodes form an ordered pair of disjoint binary trees  $T_1$ , and  $T_2$
- Any node of  $T$  has 0, 1, or 2 children.



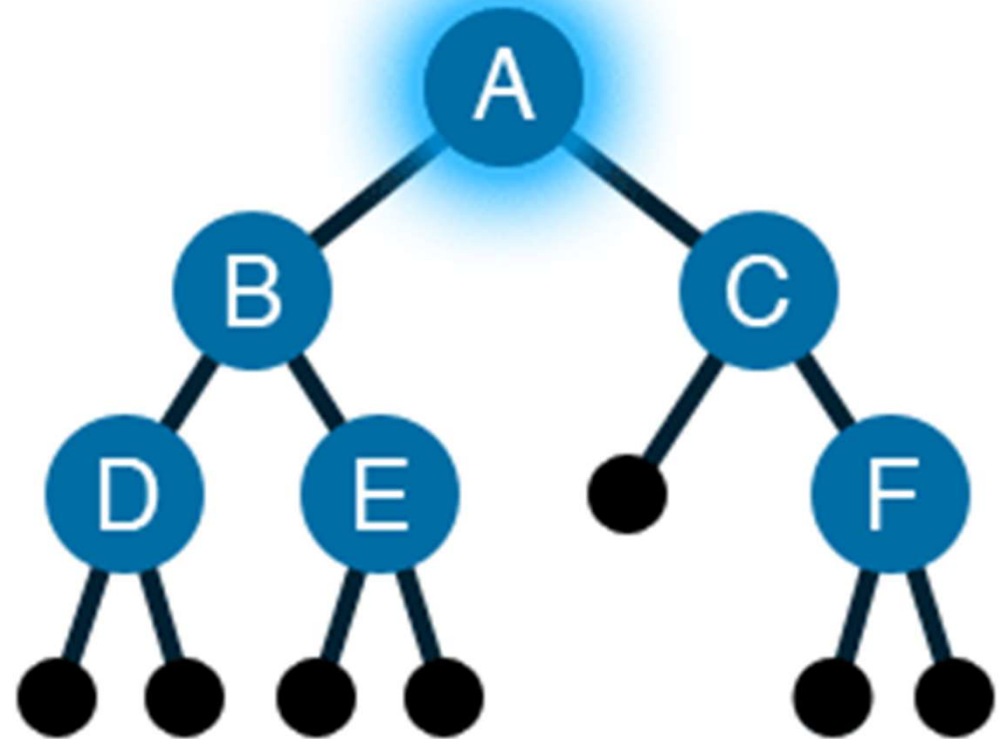
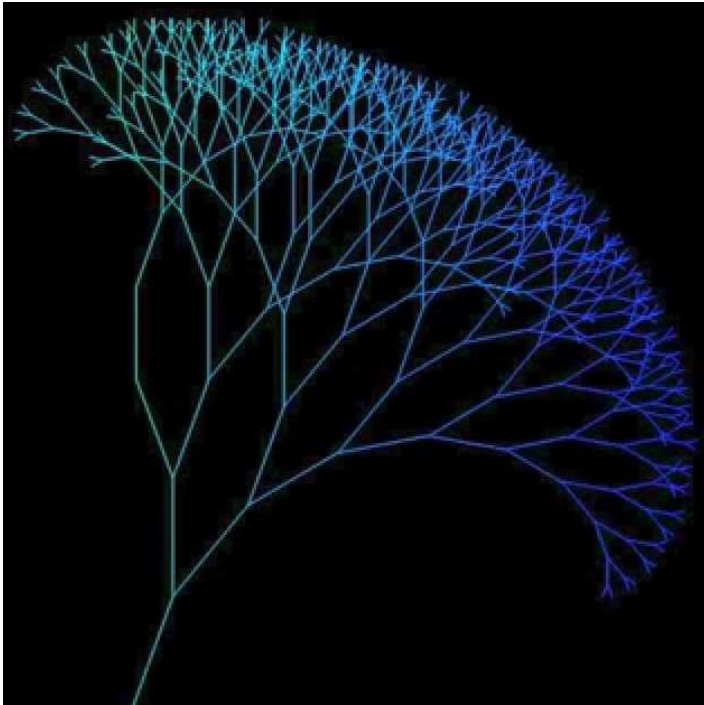
# Basic Binary Tree Concept

- If  $T$  does contain a Root  $R$ , then the two trees  $T_1$  and  $T_2$  are called, respectively, the left and right subtrees of  $R$ .
- If  $T_1$  is nonempty, then its root is called the left successor of  $R$ ; similarly,
- If  $T_2$  is nonempty, then its root is called the right successor of  $R$ ;



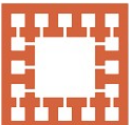
# Binary Tree Illustration

- A Binary Tree  $T$  is frequently presented by mean of a diagram



Output:

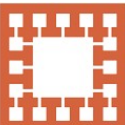
See Example 7.1 and 7.2 for understanding



# Tree Terminology

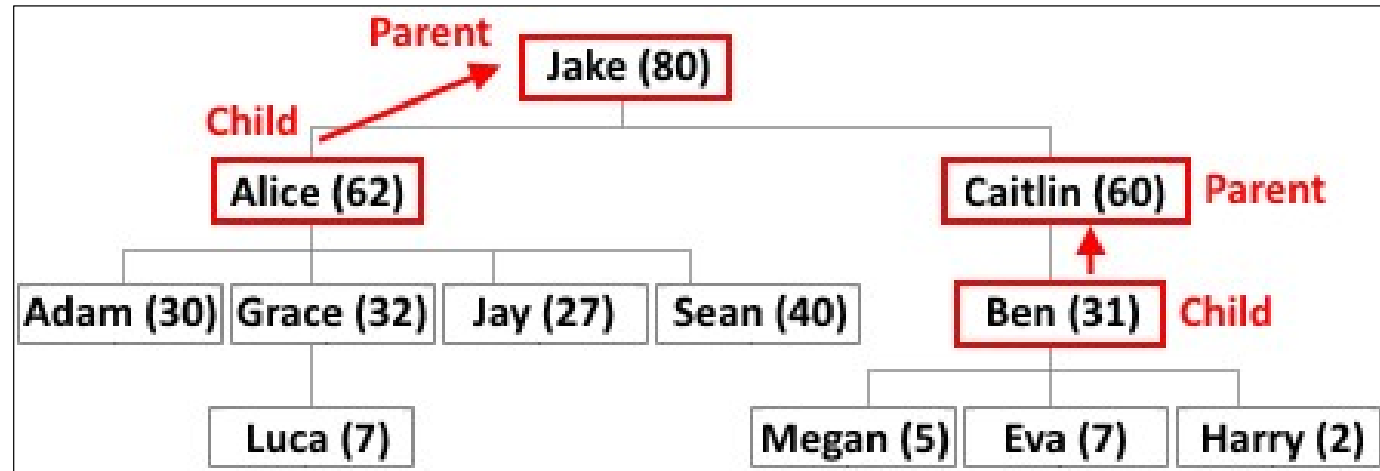
- Suppose  $N$  is a node in  $T$  with left successor  $S1$  and right successor  $S2$ .
  - $N$  is called the parent (or father) of  $S1$  and  $S2$ .
- Analogously,  $S1$  is called the left child (or son) of  $N$ , and  $S2$  is called the right child (or son) of  $N$
- $S1$  and  $S2$  are said to be siblings (or brothers)
- Two or more nodes with the same parents are called siblings.



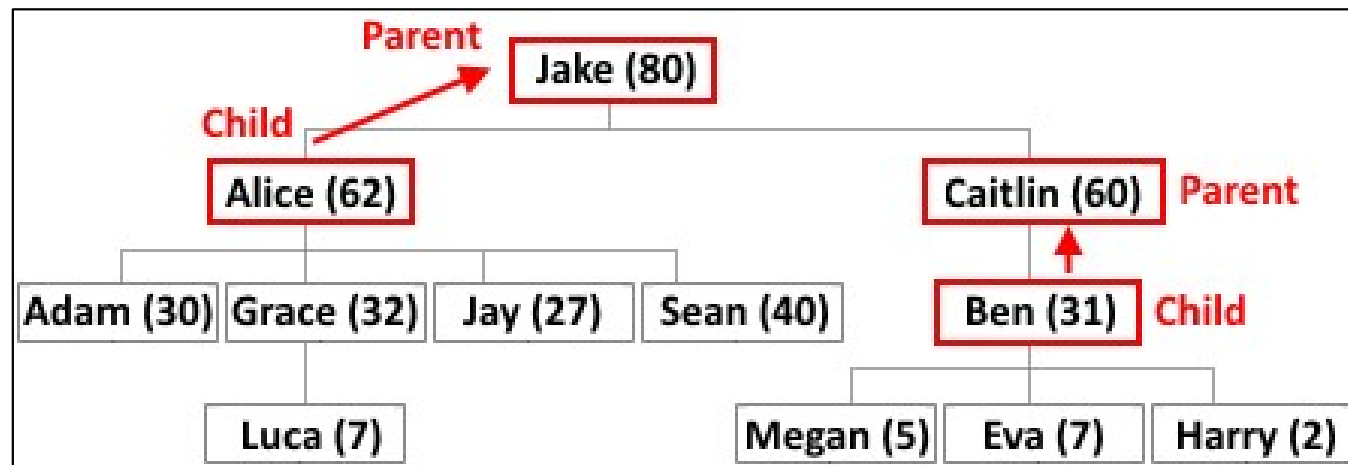


# Tree Terminology

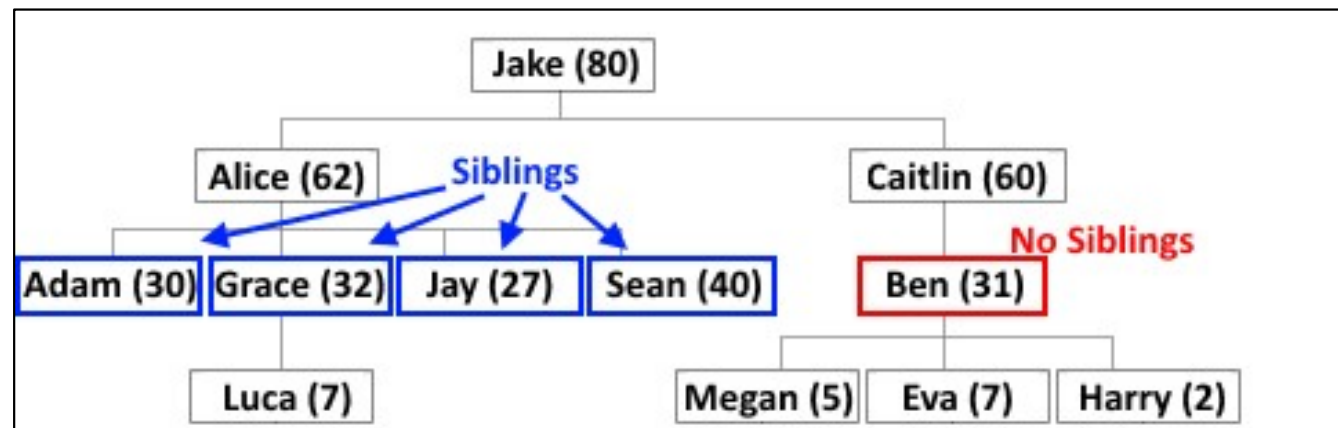
Parent

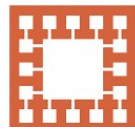


Child



Sibling

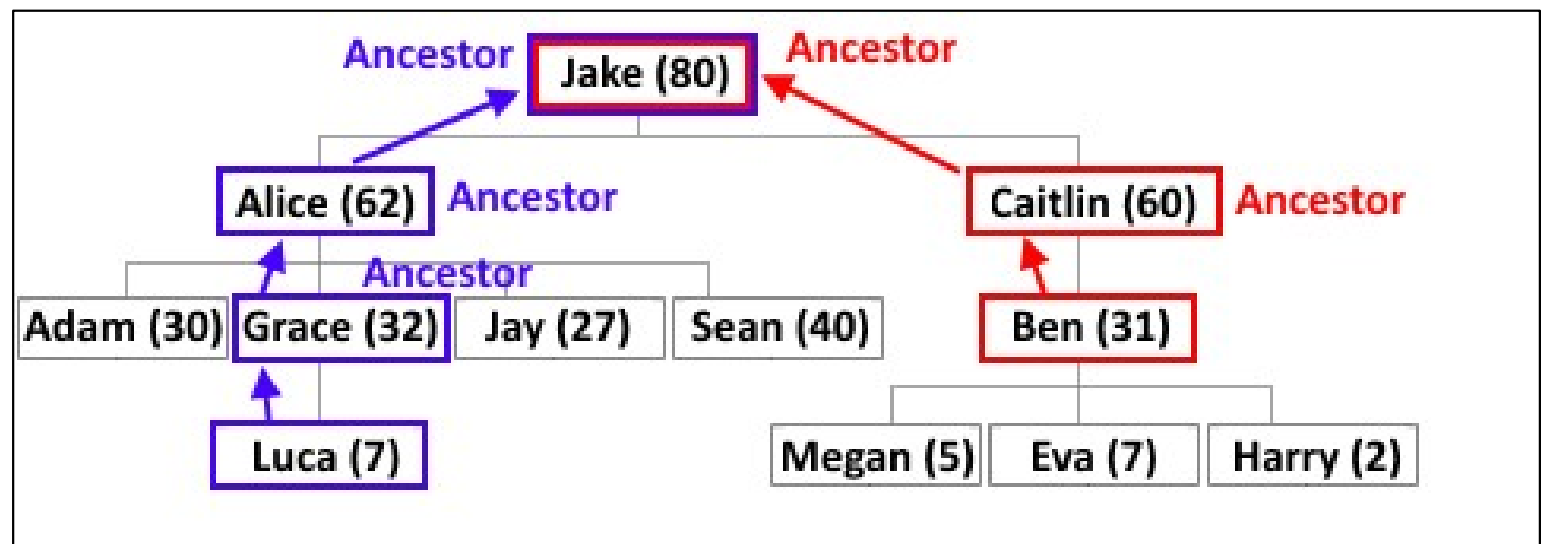


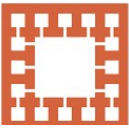


# Tree Terminology

- An **ancestor** is any node in the path from the root to the node.

**Ancestor**

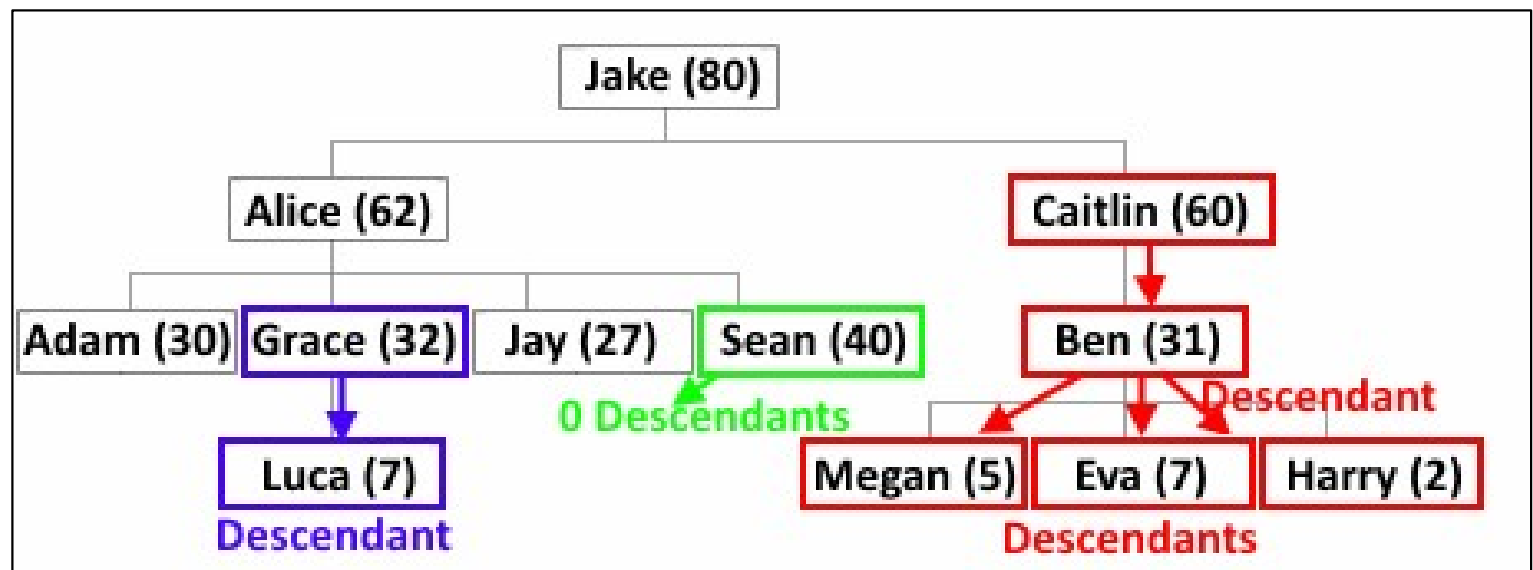


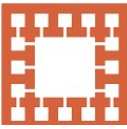


# Tree Terminology

- A **descendant** is any node in the path below the parent node; that is, all nodes in the paths from a given node to a leaf are descendants of that node.

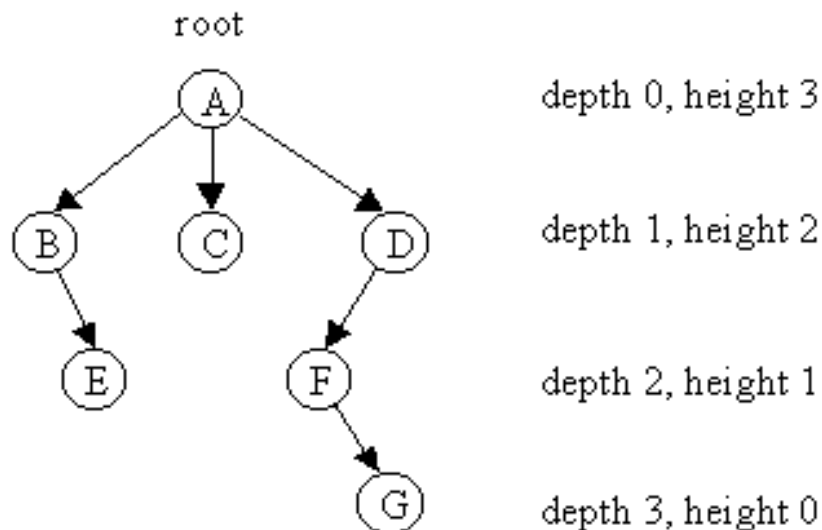
## Descendant





# Tree Terminology

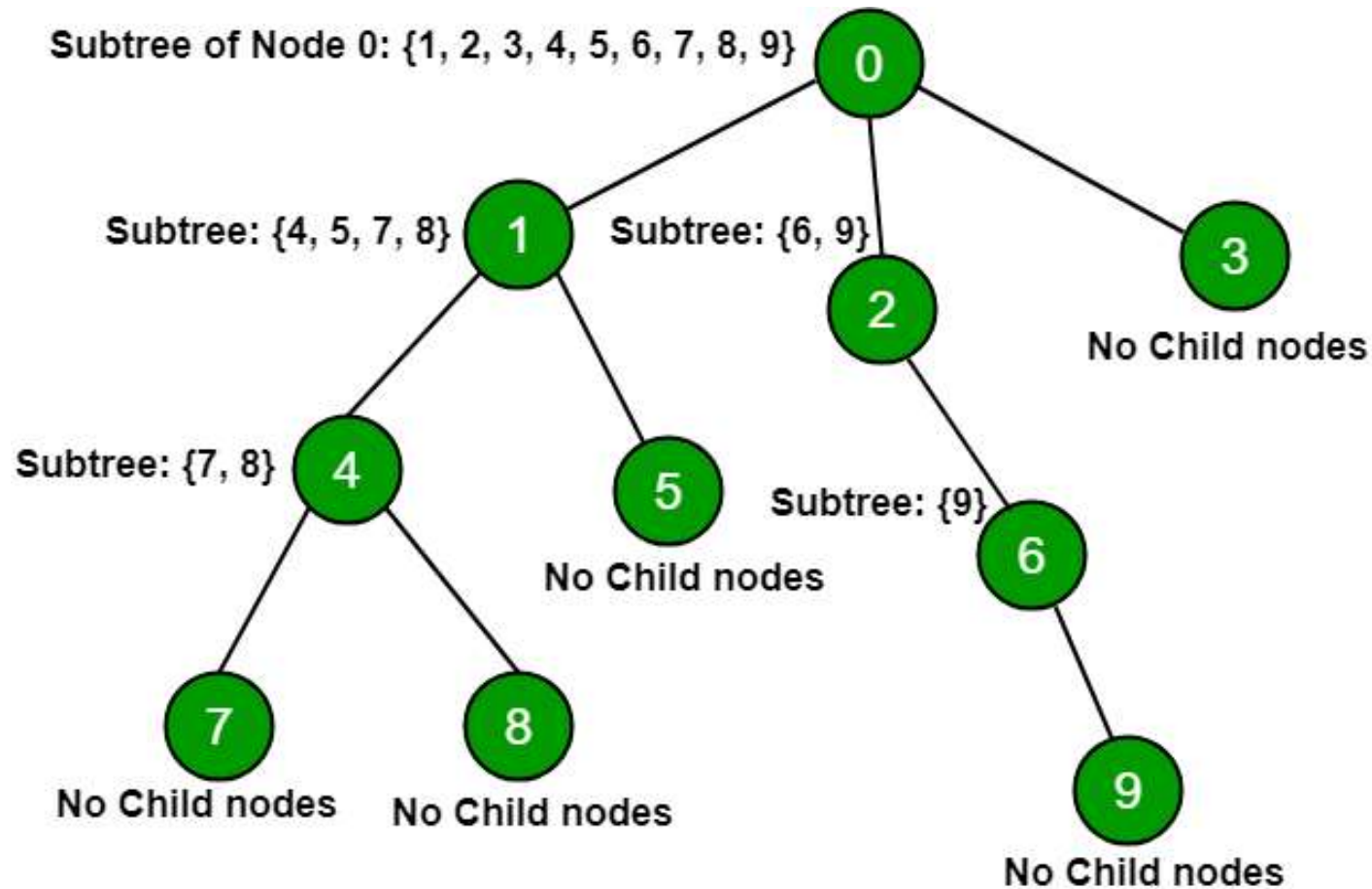
- A **path** is a sequence of nodes in which each node is adjacent to the next node.
- The **level or depth** of a node is its distance from the root. The root is at level 0, its children are at level 1, etc.
- The **height** of the tree is the level of the leaf in the longest path from the root.

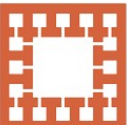


A tree of height 3

# Tree Terminology

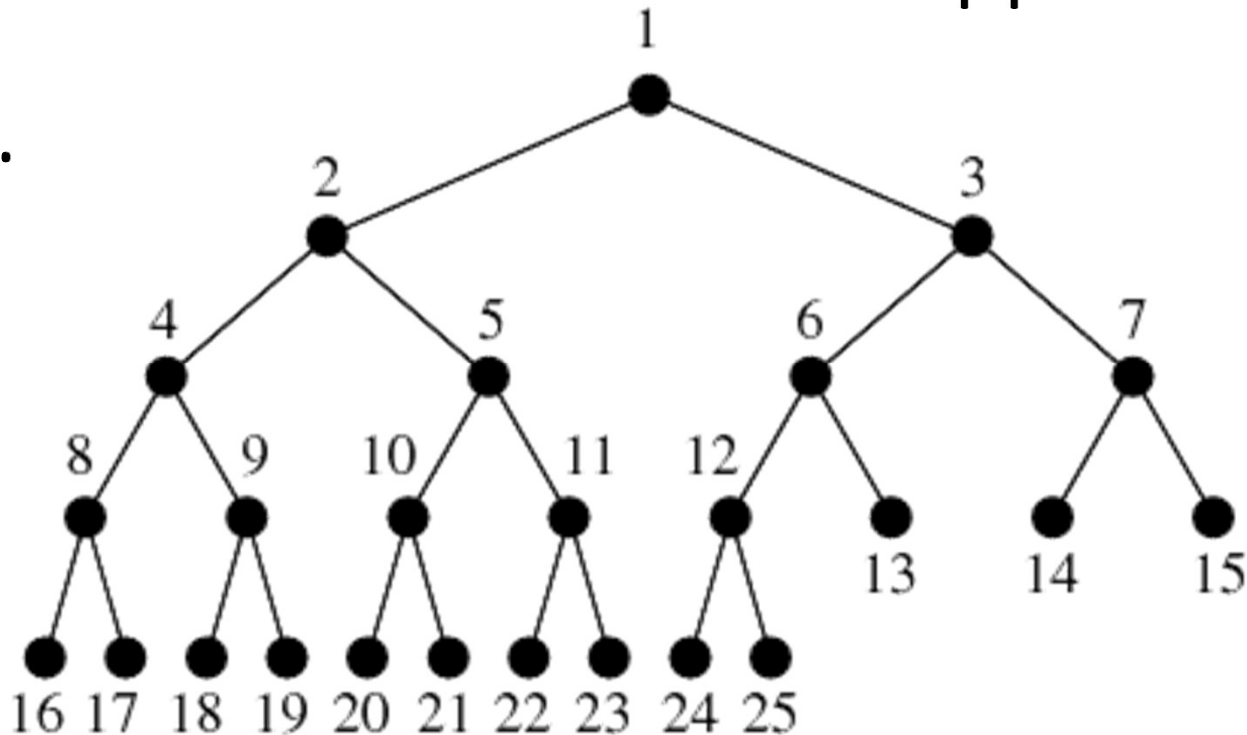
- A **subtree** is any connected structure below the root.
- The first node in the subtree is known as the root of the subtree.





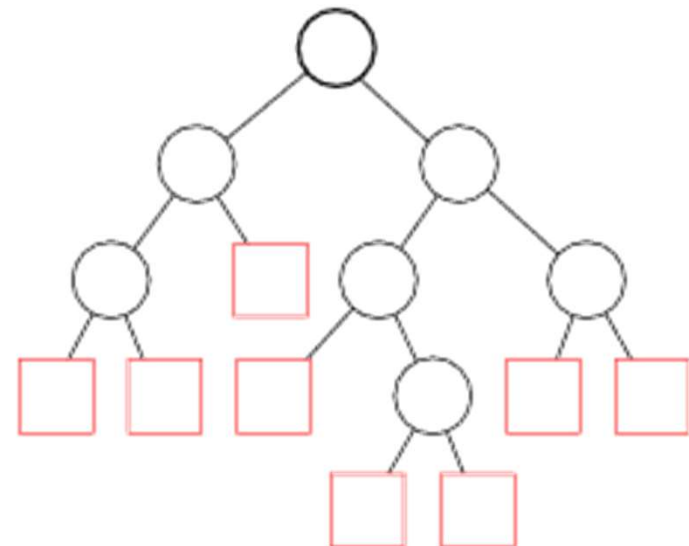
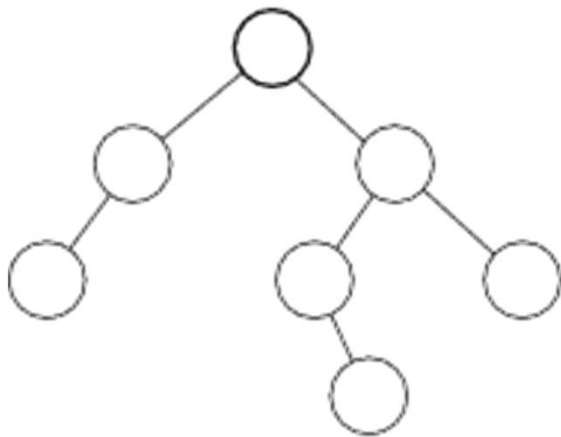
# Complete Tree

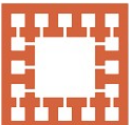
- A tree is said to be **complete** if all its levels, except possibly the last have the maximum number of possible nodes, and
- if all the nodes at the last level appear as far left as possible.



# Extended Binary Tree: 2-Tree

- A binary tree **T** is said to be a **2-tree or an extended binary tree** if each node **N** has either 0 or 2 children.
- In such a case, the nodes, with 2 children are called internal nodes, and the node with 0 children are called external node.

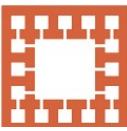




# Representing Binary Tree in Memory

- Let  $T$  be a binary tree.
- There are two ways of representing  $T$  in memory:
  - First and usual way is called link representation of  $T$
  - The second way uses a single array, called the sequential representation of  $T$
- The main requirement of any representation of  $T$  is that one should have direct access to the root  $R$  of  $T$  and, given any node  $N$  of  $T$ , one should have direct access to the children of  $N$ .

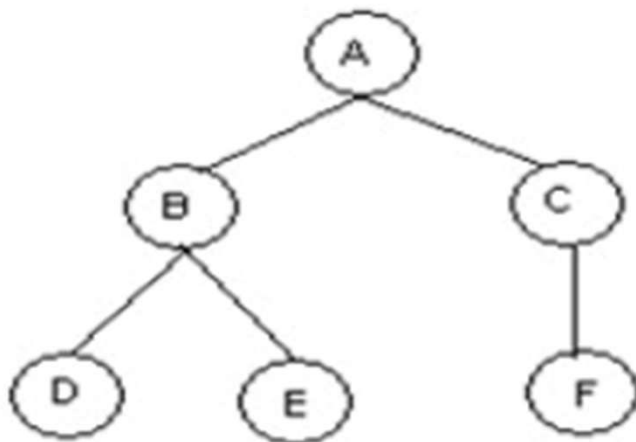




# Linked Representation of Binary Trees

## Linked Representation of Binary Tree

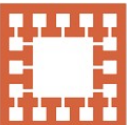
- Use Three parallel arrays Info, Left and Right and a pointer variable Root.
- Info[K]: Contains data at node N.
- Left[K]: Contains location of left child of N
- Right[K]: Contains location of right child of N
- Root: Contains location of Root
- Example:



Root

	Info	Left	Right
1	C	0	10
2	D	0	0
3			
4	E	0	0
5	A	7	1
6			
7	B	2	4
8			
9			
10	F	0	0

Figure: Binary Tree T and its linked representation.



# Sequential Representation of Binary Trees

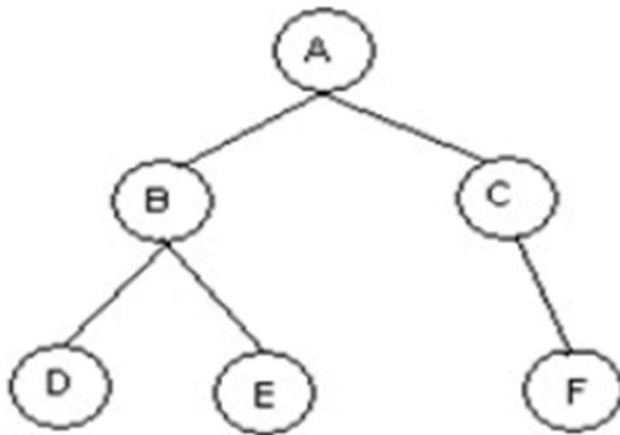
- Use only a single linear array Tree.

(a) Tree[1] represents the Root of T.

(b) If node N is in Tree[K], then its left child is in Tree[2K] and right child is in Tree[2K+1].

(c) Tree[1] = NULL indicates T is empty.

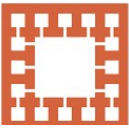
- Example:



Tree =

1	2	3	4	5	6	7	8	9	10
A	B	C	D	E		F			

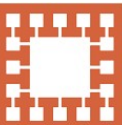
Figure: Binary Tree T and its sequential representation.



# Binary Tree Traversal Methods

- In a traversal of a binary tree, each element of the binary tree is **visited** exactly once.
- During the **visit** of an element, all action (display, evaluate the operator, etc.) with respect to this element is taken.

# Binary Tree Traversal Methods



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• There are three standard ways of traversing a binary tree  $T$  with Root  $R$ :

- **Preorder**

- Process the Root  $R$
- Traverse the left subtree of  $R$  in preorder
- Traverse the right subtree of  $R$  in preorder

- **Inorder**

- Traverse the left subtree of  $R$  in preorder
- Process the root  $R$
- Traverse the right subtree of  $R$  in inorder

- **Postorder**

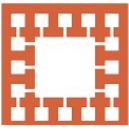
- Traverse the left subtree of  $R$  in postorder
- Traverse the right subtree of  $R$  in postorder
- Process the root  $R$

# Binary Tree Traversal Methods

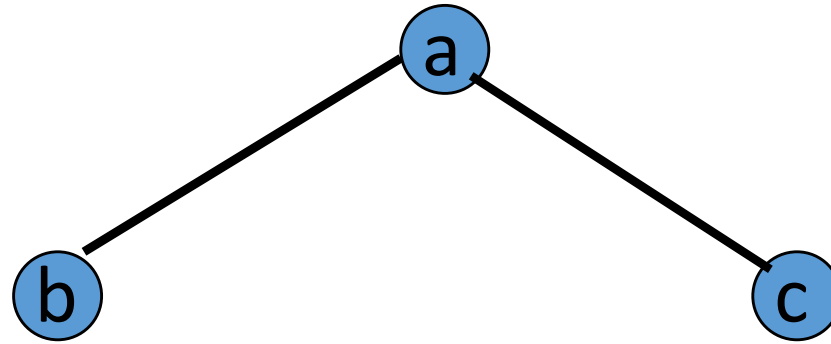
## Preorder Traversal

```
preOrder (treePointer ptr)
{
    (ptr != NULL)
    {
        visit(ptr) ;
        preOrder (ptr->leftChild) ;
        preOrder (ptr->rightChild) ;
    }
}
```

# Preorder Example (Visit = print)

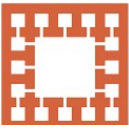


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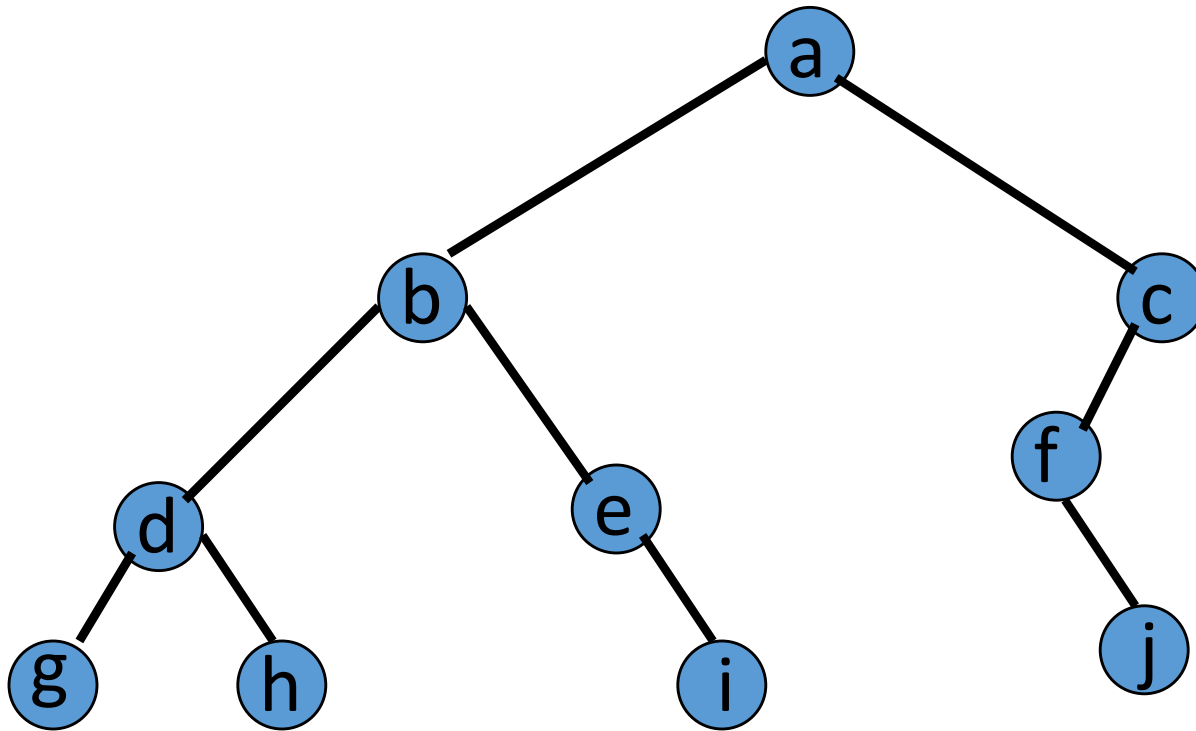


a b c

# Preorder Example (Visit = print)

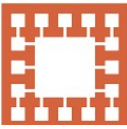


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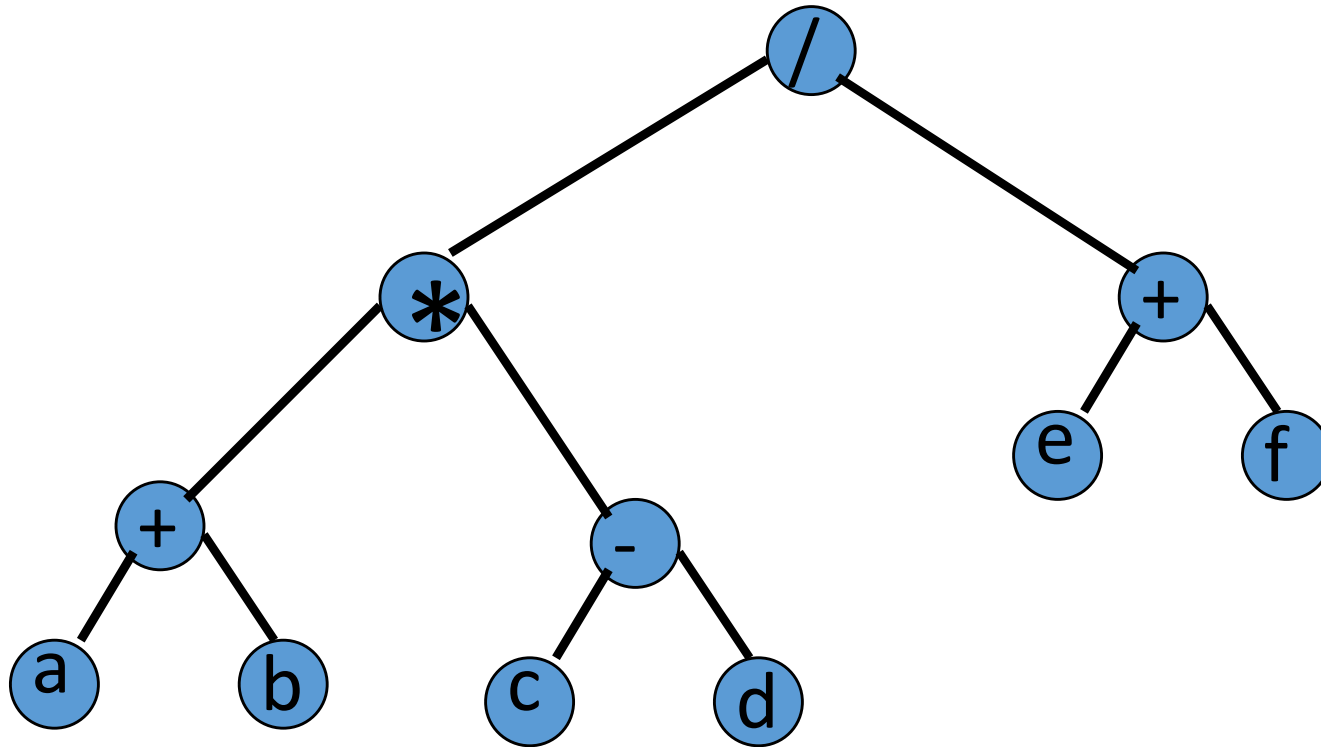


a b d g h e i c f j

# Preorder Of Expression Tree



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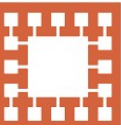


$/ * + a b - c d + e f$

Gives prefix form of expression!



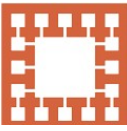
# Inorder Traversal



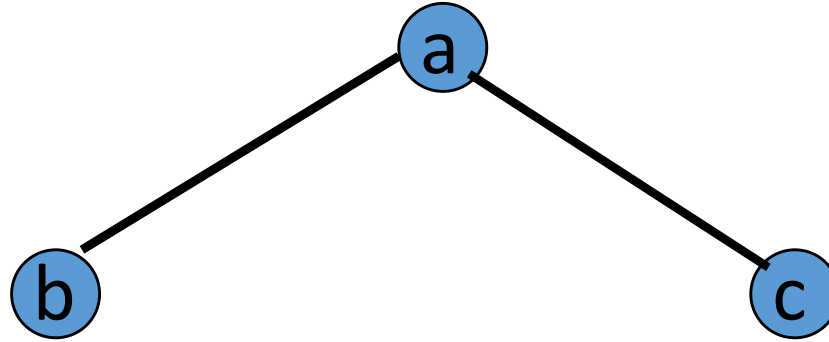
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```
inOrder (treePointer ptr)
{
    (ptr != NULL)
    {
        inOrder (ptr->leftChild) ;
        visit (ptr) ;
        inOrder (ptr->rightChild) ;
    }
}
```

# Inorder Example (Visit = print)

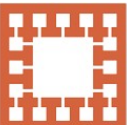


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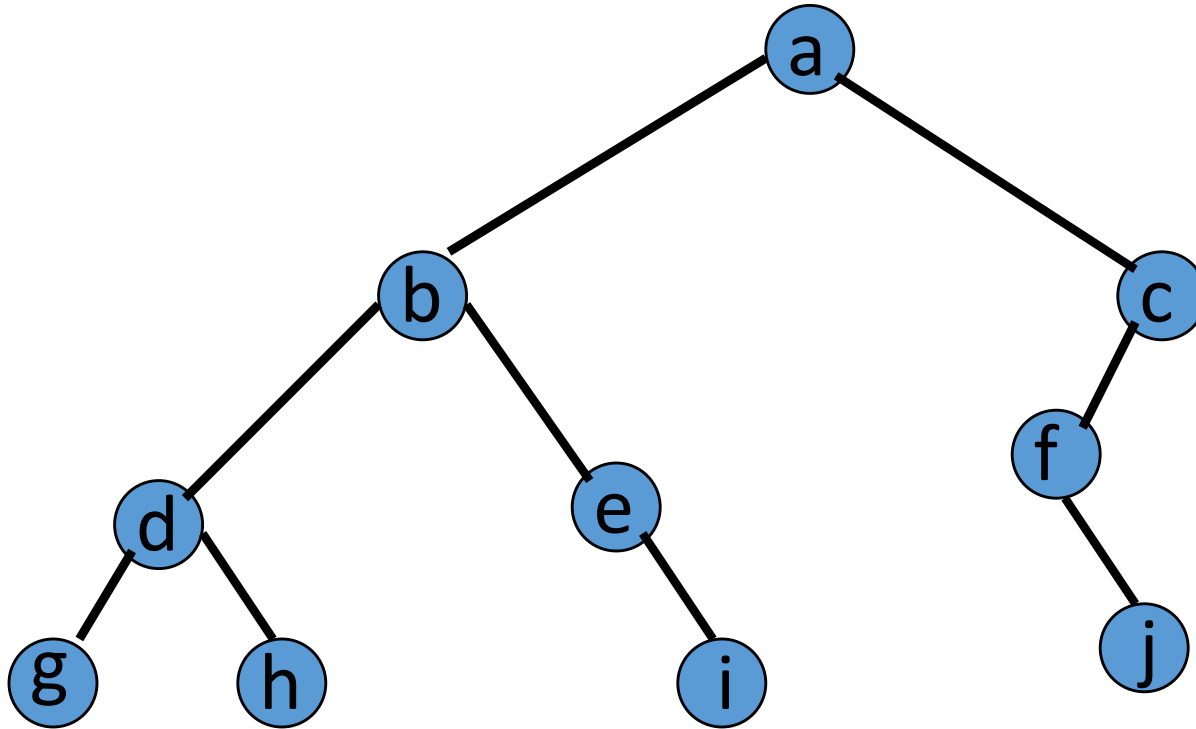


b a c

# Inorder Example (Visit = print)

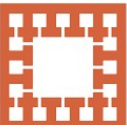


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g d h b e i a f j c

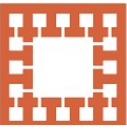
# Postorder Traversal



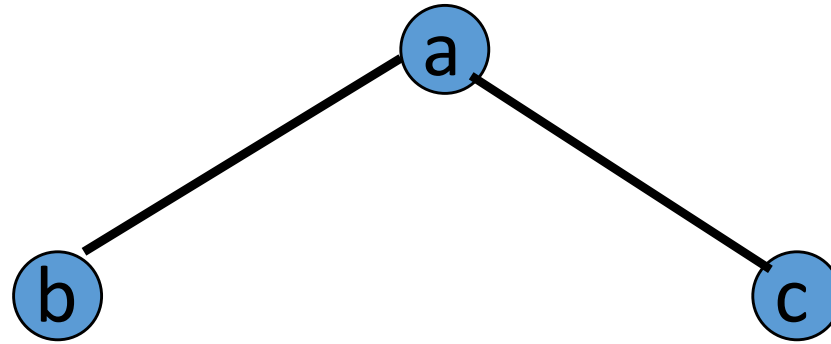
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```
postOrder (treePointer ptr)
{
    (ptr != NULL)
    {
        postOrder (ptr->leftChild) ;
        postOrder (ptr->rightChild) ;
        visit (ptr) ;
    }
}
```

# Postorder Example (Visit = print)

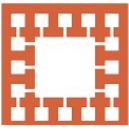


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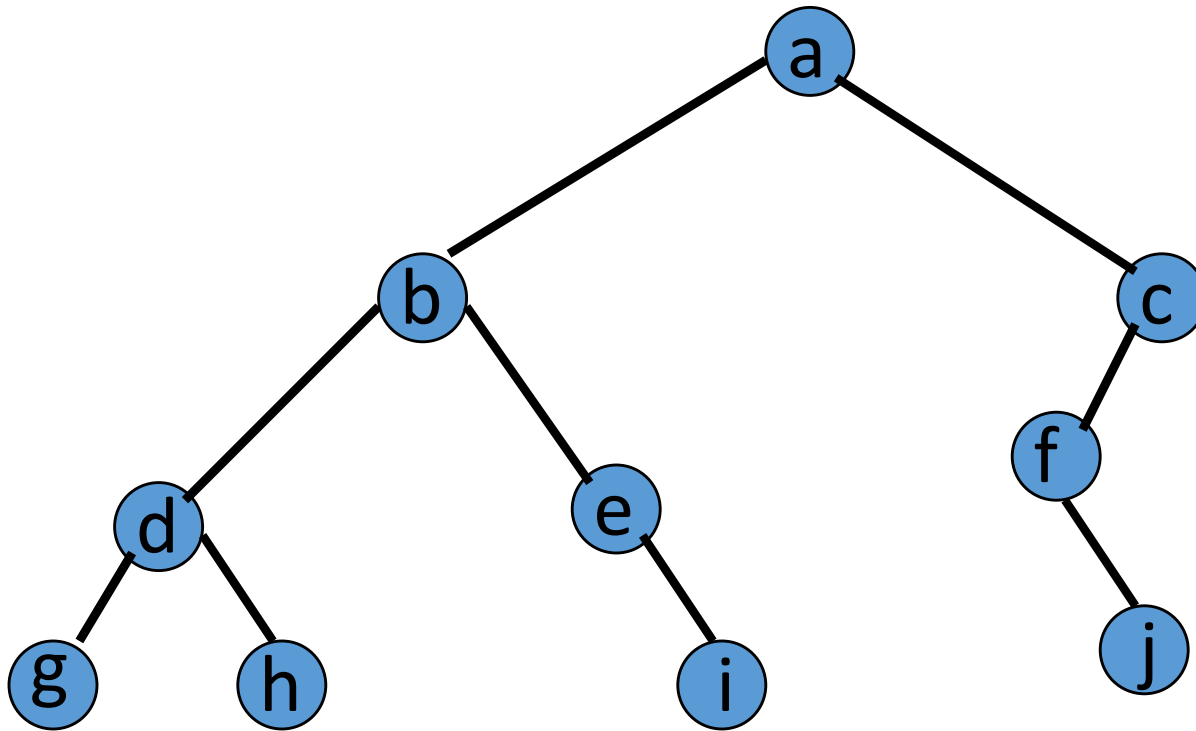


b c a

# Postorder Example (Visit = print)

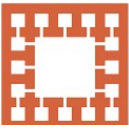


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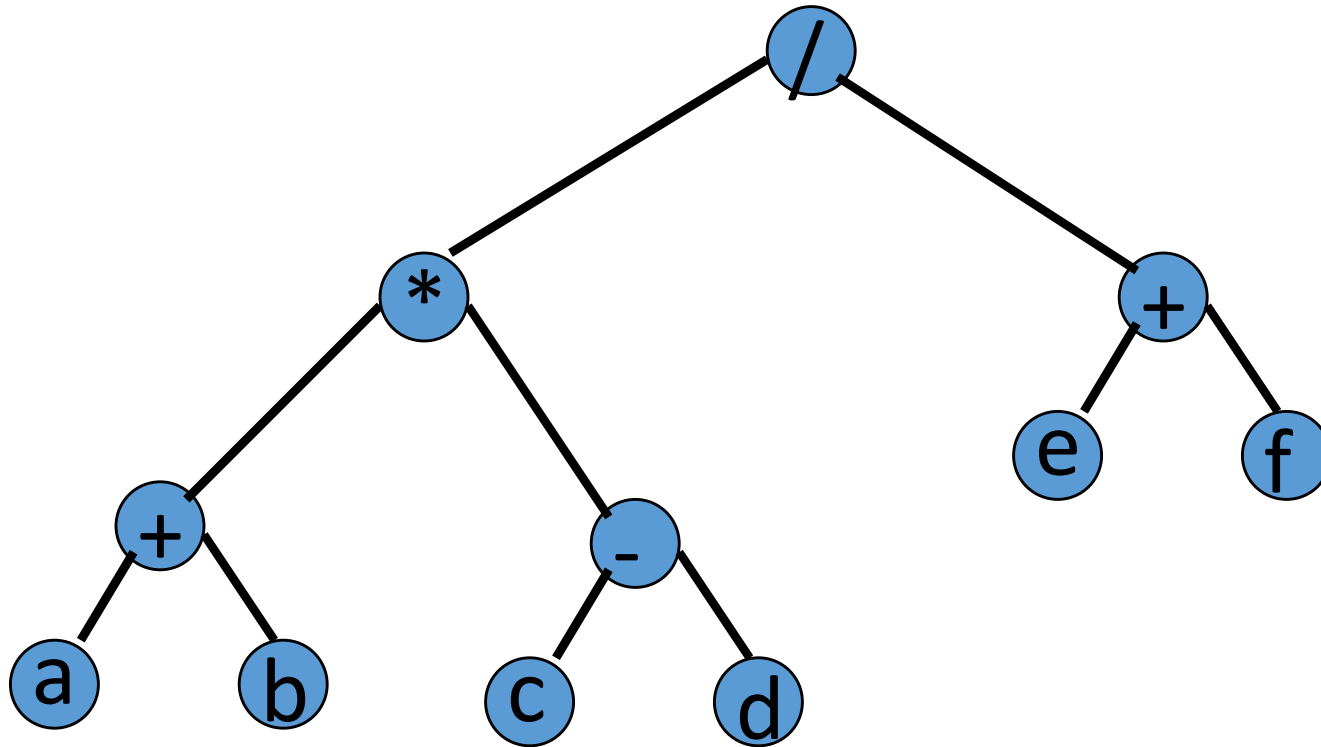


ghdi e b j f c a

# Postorder Of Expression Tree



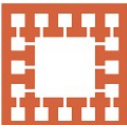
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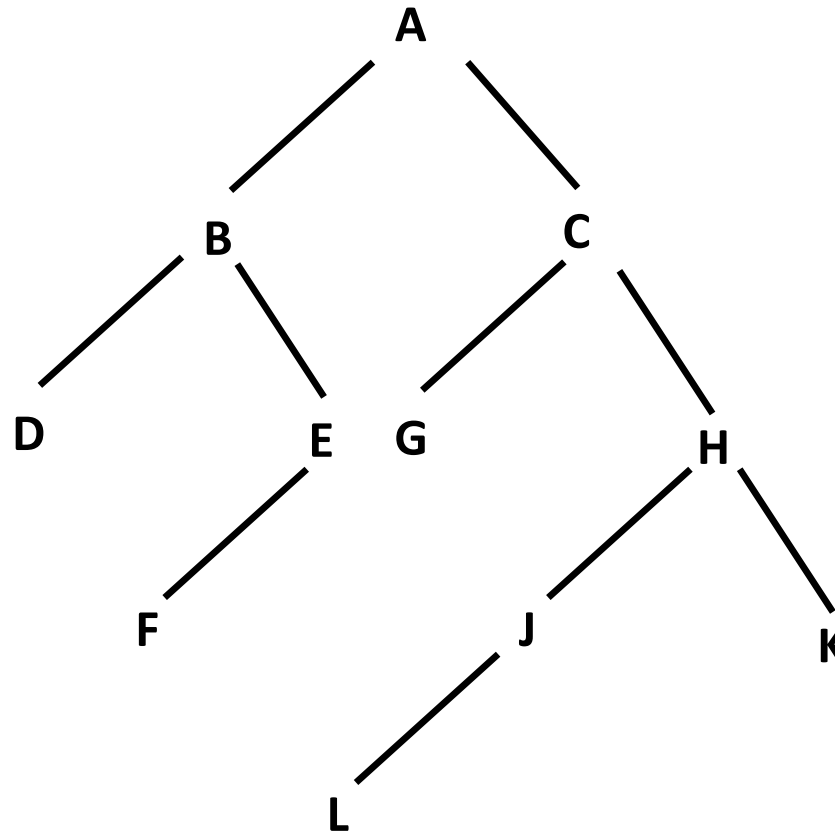
a b + c d - \* e f + /

Gives postfix form of expression!

# Traversal Applications



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The Preorder traversal of T:

**A B D E F C G H J L K**

The Inorder traversal of T:

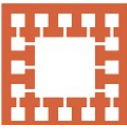
**D B F E A G C L J H K**

The Postorder traversal of T:

**D F E B G L J K H C A**

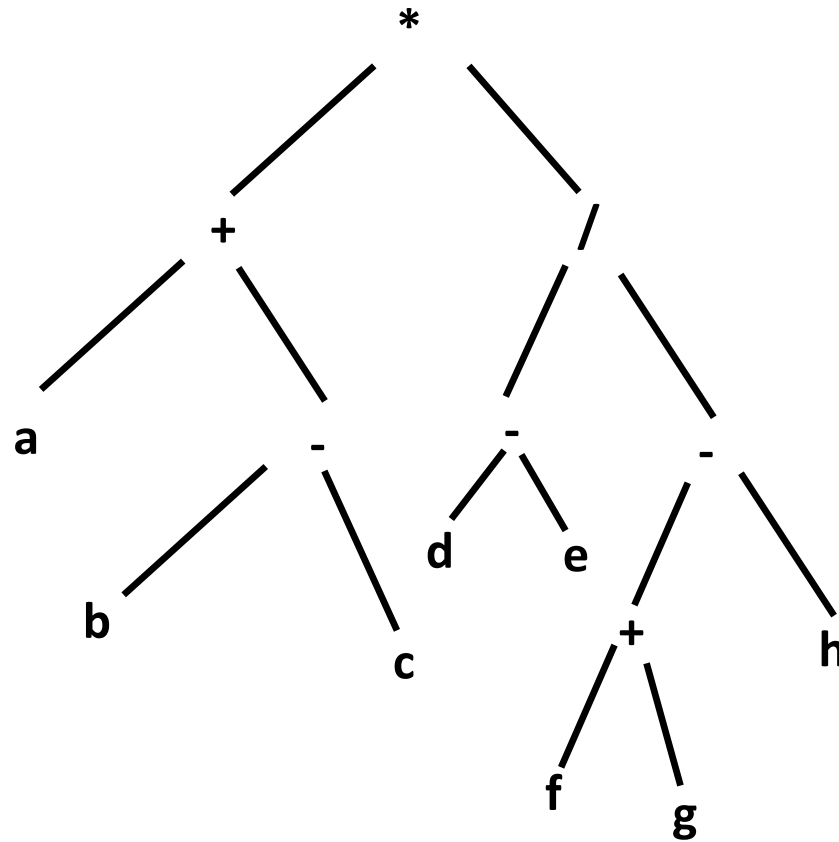


# Traversal Applications



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$$[a+(b-c)]*[(d-e)/(f+g-h)]$$



The Preorder traversal of T:

**\* + a - b c / - d e - + f g h**

The Postorder traversal of T:

**a b c - + d e - f g + h - / \***