Multi-Layered Dictionary Learning for Face Spoofing Detection

Atif Ahmed (aa3931)

Srinidhi Srinivas (ss5145)

Thejaswi Muniyappa (tm2848)

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Introduction

- ☐ Ease of availability of silicone masks has increased the crime related to face spoofing.
- Spoofing is difficult to be identified by single-layered pre-defined dictionaries.
- Adaptive multi-layered dictionaries for sparse approximation provide a superior performance for such applications.
- ☐ Motivation: Improve the face spoofing detection using multi-layered dictionaries.





Problem Statement

"Face Spoofing Detection in unconstrained environment"

- \Box Given an image, compute the sparse approximation and classify if the image is spoofed.
- How to compute the sparse approximation?
 Learn the dictionary and sparse approximation of the input dataset of images.
- ☐ How to classify?Train the classifier using the sparse representation of the input data.

Literature Survey

- ☐ Presentation Attack Detection (PAD) algorithms rely on domain knowledge.
- Properties like Motion, Texture, Reflectance and Image Quality are considered by PAD.
- Image Spoofing is difficult to incorporate texture in Boltzmann machines.
- ☐ Regularized Sparse Coding is also used for Image Representation

Multi-layered Dictionary Learning

 \square Let D_1 be the Dictionary at the first level, X be the input data and Z be the sparse representation.

$$X = D_1 Z$$

This is similar to the shallow one-level dictionary learning problem

☐ Extending the shallow set-up to the second layer, we get

$$X = D_1 \varphi(D_2 Z)$$

Here, ϕ is the activation function

 \Box The full optimization for the N layers can be written as:

$$X = D_1 \varphi(D_2 \varphi(\dots(D_N Z)))$$

Hence, the minimization problem becomes

$$\min_{D_{1},D_{2},...D_{N}} ||X - D_{1}\varphi(D_{2}\varphi(...(D_{N}Z)))||_{F}^{2}$$

Multi-layered Dictionary Learning via Greedy Algorithm – 1st Layer

- ☐ The entire problem can be divided into a smaller bunch of greedy problems.
- For the first layer,

$$Z_1 = \varphi(D_2\varphi(\dots(D_NZ)))$$

$$\min_{D_1,Z_1} ||X - D_1 Z_1||_F^2$$

☐ This can be solved by Method of Alternating Directions

$$Z_k \leftarrow \min_{Z} ||X - D_{k-1}Z||_F^2$$

$$D_k \leftarrow \min_{D} ||X - DZ_k||_F^2$$

Multi-layered Dictionary Learning via Greedy Algorithm – Continuing it with other layers

After formulating the coefficients for the first layer, we formulate that of second layer as:

$$\varphi^{-1}(Z_1) = D_2 Z_2$$

$$Z_1 = \varphi(D_3\varphi(...(D_NZ)))$$

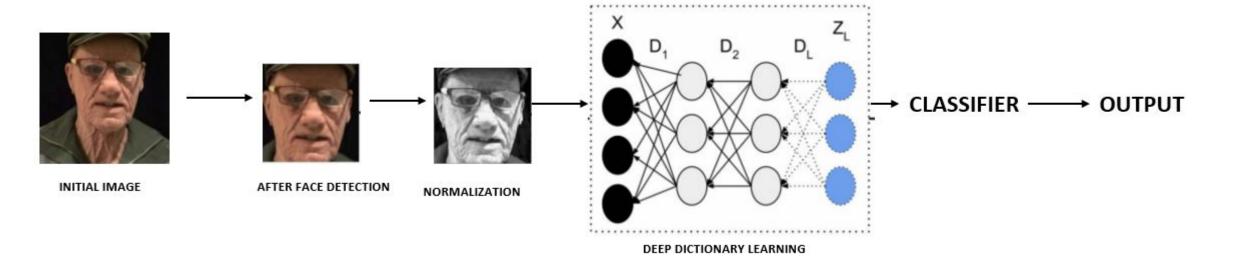
- ☐ Method of alternating directions is invoked again to find to solve the optimization at every level
- Sparsity can be introduced to this optimization problem by re-writing it as:

$$\min_{D_1,D_2,...D_N} ||X - D_1 \varphi(D_2 \varphi(...(D_N Z)))||_F^2 + \lambda ||Z||_1$$

☐ This can be imposed at the final layer as:

$$\min_{\mathbf{D}_{N},\mathbf{Z}} \left| \left| \varphi^{-1}(\mathbf{Z}_{N-1}) - \mathbf{D}_{N}\mathbf{Z} \right| \right|_{F}^{2} + \lambda \left| |\mathbf{Z}| \right|_{1}$$

Architecture

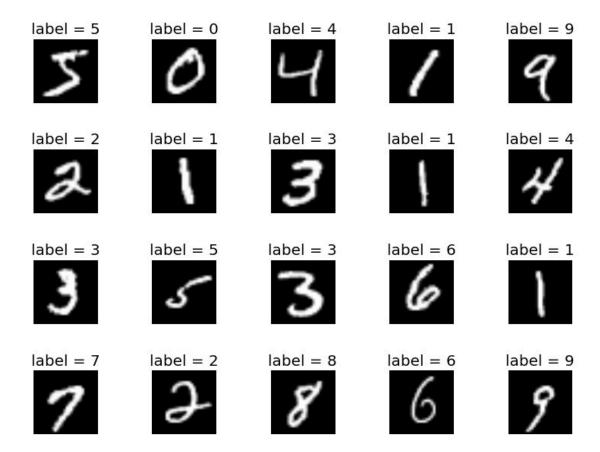


Dataset - Evaluation on MNIST

■ Dataset of handwritten digits provided by Yann Lecun*.

28 x 28 images for 10 class	es
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Training	Test
40,000	8,000



^{*} http://yann.lecun.com/exdb/mnist/

Dataset - Training on MNIST

First we tried with all features.

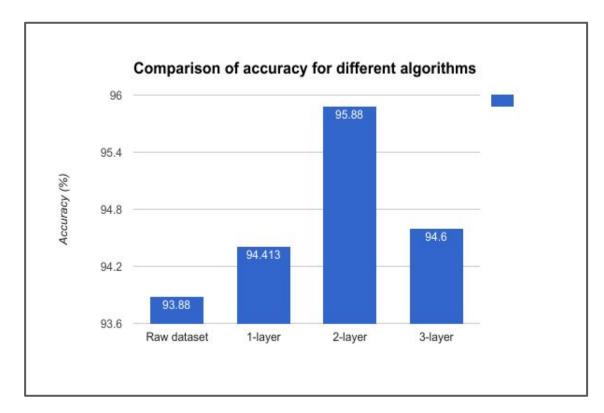
Dataset	Feature Size	Training Size	Test Size
MNIST	784	40,000	8,000

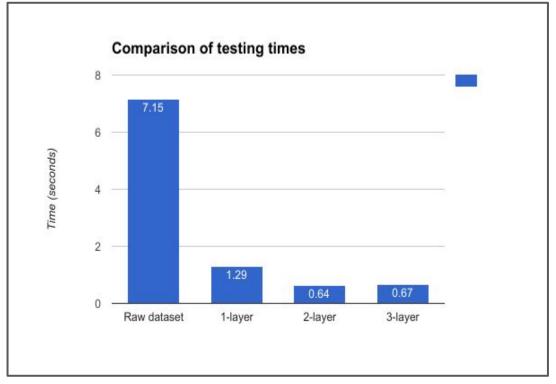
☐ Dimensionality Reduction with **Dictionary learning.**

Dataset	Feature Size (1 Layer)	Feature Size (2 Layer)	Feature Size (3 Layer)	Training Size	Test Size
MNIST	100	200 - 100	400 - 200 - 100	40,000	8,000

Testing and Results on MNIST

MNIST Dataset	Raw Dataset	Shallow (1-layer)	2-layer	3-layer
Accuracy (%)	93.58	94.413	95.88	94.6
Testing Time (sec.)	7.15	1.29	0.64	0.67

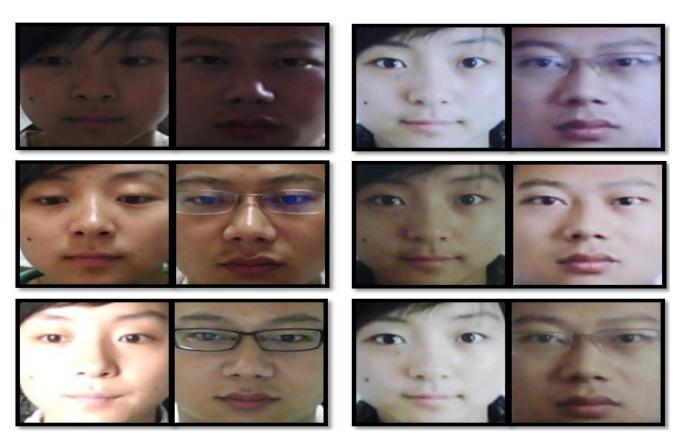




Dataset - NUAA

- ☐ Database of photograph imposters collected with cheap webcams.
- ☐ 64 x 64 images of 2 classes (client or impostor).

Training	Test
3491	9123



Preprocessing - NUAA

■ We extract the face using Viola Jones face detection algorithm.



Original Image



Gray scale and normalization



- After detecting the face, the image is converted to grayscale and is normalized
- \Box All the cropped images are 64 x 64. Hence, every image is represented as a vector of length 4096

Training on NUAA

First we tried with all features.

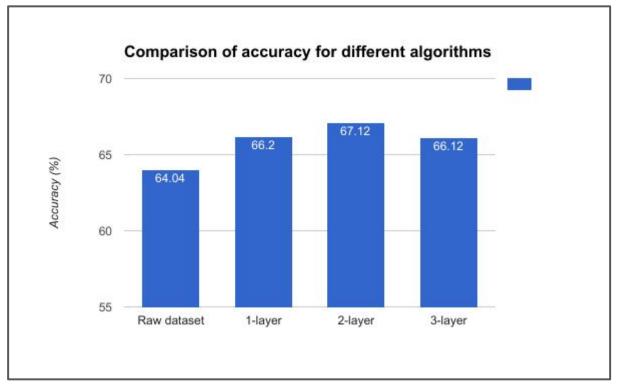
Dataset	Feature Size	Training Size	Test Size
MNIST	784	40,000	8,000
NUAA	4096	3,491	9123

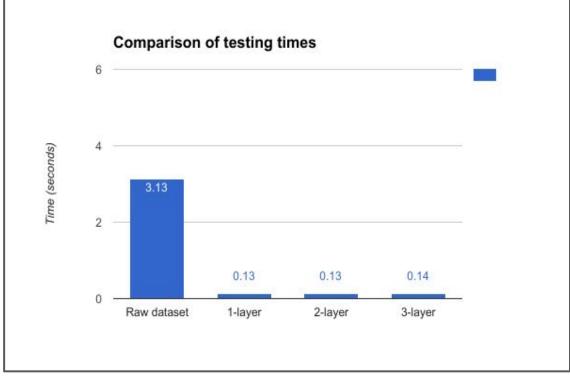
☐ Dimensionality Reduction with **Dictionary learning.**

Dataset	Feature Size (1 Layer)	Feature Size (2 Layer)	Feature Size (3 Layer)	Training Size	Test Size
MNIST	100	200 - 100	400 - 200 - 100	40,000	8,000
NUAA	512	1024 - 512	1024 - 512 - 256	3,491	9123

Testing and Results on NUAA

MNIST Dataset	Raw Dataset	Shallow (1-layer)	2-layer	3-layer
Accuracy (%)	64.04	66.2	67.12	66.12
Testing Time (sec.)	3.13	0.13	0.13	0.14





Effect of various activation functions

- ☐ The reference paper [2] uses only linear activation functions in all the layers.
- We tried with other activation functions also like tanh and sigmoid.
- In the algorithm, inverse of the activation functions have to be used.
- \Box At each layer we project the values to a specified interval (e.g. [-1, +1] for arctanh).

Layers	200, 100	400, 200	50, 25
Accuracy	63.86	51.31	60.61

Challenges for multi-layered dictionary learning

- ☐ Studies have proven the convergence guarantees for single level dictionary learning. These proofs are very hard to replicate for multiple layers.
- The number of parameters required to be solved increases when multiple layers of dictionaries are learned simultaneously. With limited training data, this could lead to overfitting.

Conclusion

Multi-layered dictionary gives better results and testing times than shallow dictionary learning.
 Learning different levels of dictionaries along with the coefficients is not the same as learning a single (collapsed) dictionary and its corresponding features (even with linear activation functions).
 The single-level problem (single level) is a bi-linear problem and 2-level problem is a tri-linear problem
 Greedy approach for layer-wise learning ensures the convergence of each layer.
 Regularization at final layer can be used to control sparsity and prevent overfitting.

Future Work

- ☐ Using images in 2D format instead of a vector. The data will then become multi-dimensional which calls for multi-dimensional dictionary learning.
- Using other kind of sparsity measures and comparing performance.
- Improving performance for nonlinear activation functions.

References

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Thank You!