딥러닝 (Deep Learning)

딥러닝은 머신러닝 알고리즘의 한 종류입니다.

데이터 처리 유닛의 층을 여러 개 쌓아 구조적이지 않은 데이터로부터 고수준 표현을 학습합니다.

더 많은 층 ... 가중치 가중치 가중치 가중치 입력 첫 번째 층 두번째층 출력 N 번째 층

그림 2-2 딥러닝의 개념도

먼저 책에 나와 있는 예제를 따라 해보고

어떻게 하면 딥러닝 모델의 성능을 향상 할 수 있는지 고민해 보겠습니다.



첫 번째 심층 신경망

라이브러리 임포트

```
In [3]: import numpy as no
                                              import matplotlib.pvplot as plt
                                            from keras layers import Input, Flatten, Dense, Conv2D
                                            from keras.models import Model
                                            from keras.optimizers import Adam
                                            from kerasutils import to categorical
                                            from keras.datasets import cifar10
                                            Using TensorFlow backend.
                                            e' as a synonym of type is deprecated; in a future version of numpy, it will be understood as (type, (1,)) / '(1,)type'.
                                                       _{np\_qint8} = np.dtype([("qint8", np.int8, 1)])
                                            C:\Users\User\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\unda
                                            e' as a synonym of type is deprecated; in a future version of numpy, it will be understood as (type, (1,)) / '(1,)type'.
                                                        _np_quint8 = np.dtype([("quint8", np.uint8, 1)])
                                            C:\Users\User\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\unda
                                            e' as a synonym of type is deprecated; in a future version of numpy, it will be understood as (type, (1,)) / '(1,)type'.
                                                        _np_gint16 = np.dtype([("gint16", np.int16, 1)])
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                                            e' as a synonym of type is deprecated; in a future version of numpy, it will be understood as (type, (1,)) / '(1,)type'.
                                                        np quint16 = np.dtvpe([("quint16", np.uint16, 1)])
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                                            e' as a synonym of type is deprecated; in a future version of numpy, it will be understood as (type, (1,)) / '(1,)type'.
                                                       np gint32 = np.dtvpe([("gint32", np.int32, 1)])
                                            C:\Users\User\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\undamaconda3\unda
                                            e' as a synonym of type is deprecated; in a future version of numpy, it will be understood as (type, (1,)) / '(1,)type'.
                                                      np resource = np.dtvpe([("resource", np.ubvte, 1)])
```

데이터 적재

```
In [2]: NUM_CLASSES = 10
In [3]: (x_train, y_train), (x_test, y_test) = cifar10.load_data()
ln [4]: x_{train} = x_{train.astype}('float32') / 255.0
       x_{test} = x_{test.astype}('float32') / 255.0
       y_train = to_categorical(y_train, NUM_CLASSES)
       y_test = to_categorical(y_test, NUM_CLASSES)
In [5]: # 색 채널 R : 빨간색(0) , G : 초록색 (1) , B : 파란색 (2)
In [6]: x_train[54, 12, 13, 1] # 인덱스 54의 이미지에서 (12, 13)에 해당하는 픽셀의 초록색 채널(1)의 값
Out[6]: 0.36862746
In [7]: x_train[2050, 12, 16, 0] # 인덱스 2050의 이미지에서 (12, 16)에 해당하는 픽셀의 빨간색 채널(0)의 값
Out[7]: 0.1254902
```

여기서는 Sequential 모델보다 함수형 API를 사용하여 유연성을 높입니다.

```
In [8]: input_layer = Input((32,32,3))
    x = Flatten()(input_layer)
    x = Dense(200, activation = 'relu')(x)
    x = Dense(150, activation = 'relu')(x)
    output_layer = Dense(NUM_CLASSES, activation = 'softmax')(x)
    model = Model(input_layer, output_layer)
```

WARNING: tensorflow: From C: \u00edUsers\u00edUsers\u00edusers\u00edusers\u00edusers\u00edusers\u00edusers\u00edusers\u00eduser\u00edusers\u00eduser\u00edusers\u00eduser\u00edusers\u00eduser\u00ed

Instructions for updating:

Colocations handled automatically by placer.

In [9]: model.summary()

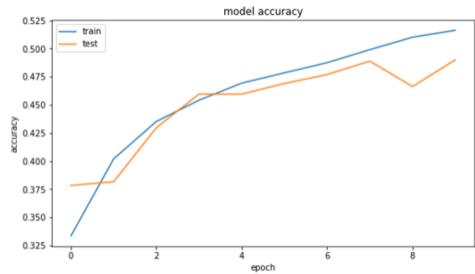
Layer (type)	Output Shape	Param #
input_1 (InputLayer)	(None, 32, 32, 3)	0
flatten_1 (Flatten)	(None, 3072)	0
dense_1 (Dense)	(None, 200)	614600
dense_2 (Dense)	(None, 150)	30150
dense_3 (Dense)	(None, 10)	1510

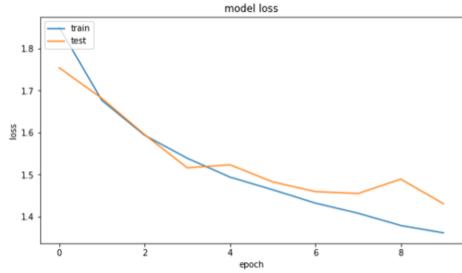
Total params: 646,260 Trainable params: 646,260 Non-trainable params: 0

모델 훈련

```
In [11]: history = model.fit(x train
          . v_train
          . batch size=50
          , epochs=10
          . shuffle=True
          , validation_data = (x_test, v_test))
   WARNING:tensorflow:From C:\Users\User\anaconda3\underchangconda3\underchen\s\User\langle at GAN\underchentibusite-packages\underchensorflow\underchensorflow\underchen\underchensors.pv:3066:to_int32 (from tenso
   rflow.python.ops.math_ops) is deprecated and will be removed in a future version.
   Instructions for updating:
   Use tf.cast instead.
   Train on 50000 samples, validate on 10000 samples
   Epoch 1/10
   Epoch 2/10
   Epoch 3/10
   Epoch 4/10
   Epoch 5/10
   Epoch 6/10
   Epoch 7/10
   Epoch 8/10
   Epoch 9/10
   Epoch 10/10
```

```
In [12]: plt.figure(figsize=(20, 5))
         # summarize history for accuracy
         plt.subplot(121)
         plt.plot(history.history['acc'])
         plt.plot(history.history['val_acc'])
         plt.title('model accuracy')
         plt.ylabel('accuracy')
         plt.xlabel('epoch')
         plt.legend(['train', 'test'], loc='upper left')
         # summarize history for loss
         plt.subplot(122)
         plt.plot(history.history['loss'])
         plt.plot(history.history['val_loss'])
         plt.title('model loss')
         plt.ylabel('loss')
         plt.xlabel('epoch')
         plt.legend(['train', 'test'], loc='upper left')
         plt.show()
```





```
In [13]: fig, loss_ax = plt.subplots()
acc_ax = loss_ax.twinx()

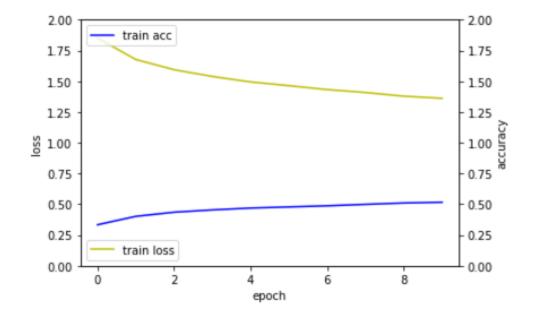
loss_ax.set_ylim([0.0, 2.0])
acc_ax.set_ylim([0.0, 2.0])

loss_ax.plot(history.history['loss'], 'y', label = 'train loss')
acc_ax.plot(history.history['acc'], 'b', label = 'train acc')

loss_ax.set_xlabel('epoch')
loss_ax.set_ylabel('loss')
acc_ax.set_ylabel('accuracy')

loss_ax.legend(loc = 'lower left')
acc_ax.legend(loc = 'upper left')
```

Out[13]: <matplotlib.legend.Legend at 0x1eb028a6208>



모델 평가

```
In [14]: |model.evaluate(x_test, y_test)
         10000/10000 [============= ] - 1s 120us/step
Out[14]: [1.426109185218811, 0.4985] acc = 49.8%
In [15]: CLASSES = np.array(['airplane', 'automobile', 'bird', 'cat', 'deer', 'dog', 'frog', 'horse', 'ship', 'truck'])
         preds = model.predict(x test)
         preds_single = CLASSES[np.argmax(preds, axis = -1)]
         actual_single = CLASSES[np.argmax(y_test, axis = -1)]
In [16]: In to show = 10
         indices = np.random.choice(range(len(x test)), n to show)
         fig = plt.figure(figsize=(15, 3))
         fig.subplots_adjust(hspace=0.4, wspace=0.4)
         for i. idx in enumerate(indices):
             ima = x test[idx]
             ax = fig.add_subplot(1, n_to_show, i+1)
             ax.axis('off')
             ax.text(0.5, -0.35, 'pred = ' + str(preds_single[idx]), fontsize=10, ha='center', transform=ax.transAxes)
             ax.text(0.5, -0.7, 'act = ' + str(actual_single[idx]), fontsize=10, ha='center', transform=ax.transAxes)
             ax.imshow(img)
```



act = horse



















pred = horse pred = automobile pred = truck pred = automobile pred = automobile pred = bird pred = automobile pred = truck pred = airplane act = truck act = automobile act = truck act = truck

act = horse act = automobileact = automobile act = cat act = automobile

어떻게 하면 정확도를 끌어 올릴 수 있을까요?

여러 방법이 있지만 책에 나와있는 방법으로는

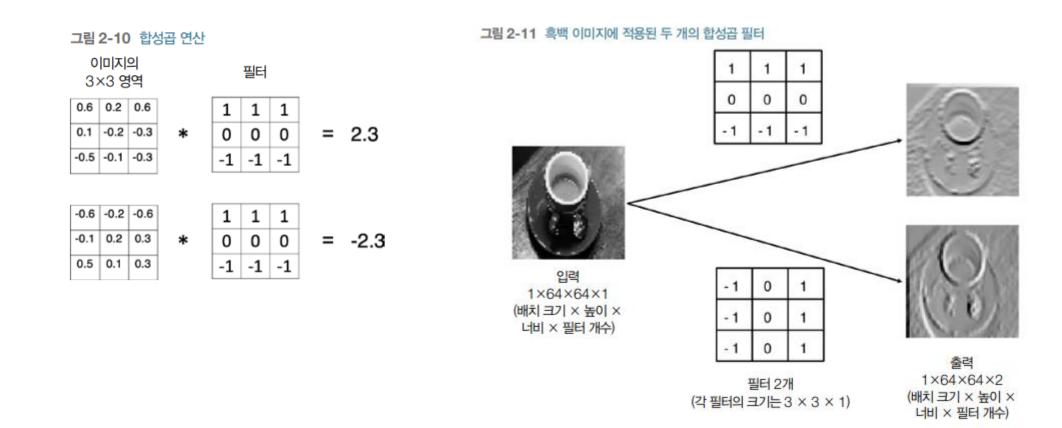
- 1. 합성곱 층(Convolution Layer)
- 2. 배치의 정규화 (Batch Normalization)
- 3. 드롭아웃 (Drop Out)

의 사용을 예로 들고 있습니다.

먼저 합성곱 층이 무엇인지 가시적(visualize)으로 확인해 보고 이것들을 적용해보고 정말로 정확도가 올라가는지 확인해 봅니다.



이미지의 특징을 잘 나타내기 위해 합성곱 층(convolution layer) 을 사용합니다. 합성곱은 필터를 이미지의 일부분과 픽셀끼리 곱한 후 결과를 더하는 것입니다. 이미지의 영역이 필터와 비슷할수록 큰 양수가 출력되고 필터와 반대일 수록 큰 음수가 출력됩니다.



합성곱

라이브러리 임포트

```
In [1]: %matplotlib inline
import matplotlib.pyplot as plt
from scipy.ndimage import correlate
import numpy as np
from skimage import data
from skimage.color import rgb2gray
from skimage.transform import rescale,resize
```

원본 이미지

```
In [2]: im = rgb2gray(data.coffee())
im = resize(im, (64,64))
print(im.shape)

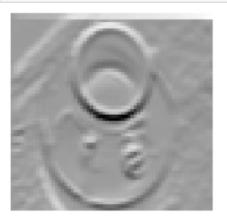
plt.axis('off')
plt.imshow(im, cmap = 'gray');

(64, 64)
```



수평 모서리 필터

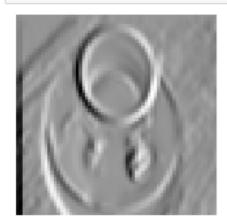
```
In [3]: filter1 = np.array([
             [ 1, 1, 1],
            [0, 0, 0],
            [-1, -1, -1]
        ])
        new_image = np.zeros(im.shape)
        im_pad = np.pad(im, 1, 'constant')
        for i in range(im.shape[0]):
            for j in range(im.shape[1]):
                 try:
                     new_image[i,j] = ₩
                     im_pad[i-1,j-1] * filter1[0,0] + \( \pi \)
                     im_pad[i-1,j] * filter1[0,1] + \
                     im_pad[i-1,j+1] * filter1[0,2] + \
                     im_pad[i,j-1] * filter1[1,0] + \( \)
                     im_pad[i,j] * filter1[1,1] + \footnotemath{\psi}
                     im_pad[i,j+1] * filter1[1,2] +#
                     im_pad[i+1,j-1] * filter1[2,0] + #
                     im_pad[i+1,j] * filter1[2,1] + \footnotemath{\psi}
                     im_pad[i+1,j+1] * filter1[2,2]
                 except:
                     pass
        plt.axis('off')
        plt.imshow(new_image, cmap='Greys');
```



수평 부분의 모서리가 강조됩니다.

수직 모서리 필터

```
In [4]: filter2 = np.array([
            [ -1, 0, 1],
            [ -1, 0, 1],
            [ -1, 0, 1]
        new_image = np.zeros(im.shape)
        im_pad = np.pad(im,1, 'constant')
        for i in range(im.shape[0]):
            for j in range(im.shape[1]):
                try:
                    new_image[i,j] = ₩
                    im_pad[i-1,j-1] * filter2[0,0] + \#
                    im_pad[i-1,j] * filter2[0,1] + \
                    im_pad[i-1,j+1] * filter2[0,2] + \#
                    im_pad[i,j-1] * filter2[1,0] + #
                    im_pad[i,j] * filter2[1,1] + #
                    im_pad[i,j+1] * filter2[1,2] +\(\pi\)
                    im_pad[i+1,j-1] * filter2[2,0] + #
                    im_pad[i+1,j] * filter2[2,1] + \#
                    im_pad[i+1,j+1] * filter2[2,2]
                except:
                    pass
        plt.axis('off')
        plt.imshow(new_image, cmap='Greys');
```



수직 부분의 모서리가 강조됩니다.

첫 번째 합성곱 신경망 (모델 성능 향상 ver.)

라이브러리 임포트

```
In [1]: import numby as no
        from keras.lavers import Input. Flatten. Dense. Conv2D. BatchNormalization. LeakvReLU. Dropout. Activation
        from keras models import Model
        from keras.optimizers import Adam
        from kerasutils import to categorical
         import keras backend as K
        from keras datasets import cifar10
        Hsing TensorFlow backend.
        C:\Users\User\anaconda3\envs\testGAN\lib\site-packages\tensorflow\pvthon\framework\dtypes.pv:526: Future\arning: Passing (type, 1) or '1typ
        e' as a synonym of type is deprecated; in a future version of numpy, it will be understood as (type, (1,)) / '(1,)type'.
           np gint8 = np.dtvpe([("gint8", np.int8, 1)])
        C:\Users\User\anaconda3\envs\testGAN\lib\site-packages\tensorflow\pvthon\framework\dtypes.py:527: Future\arning: Passing (type, 1) or '1typ
        e' as a synonym of type is deprecated; in a future version of numpy, it will be understood as (type, (1,)) / '(1,) type'.
          _np_quint8 = np.dtvpe([("quint8", np.uint8, 1)])
        C:\Users\Users\User\undersanaconda3\undervs\undervs\undertestGAN\underpackages\undertensorflow\underpython\underframework\underdtypes.py:528: Future\underning: Passing (type, 1) or '1typ
        e' as a synonym of type is deprecated; in a future version of numpy, it will be understood as (type, (1,)) / '(1,)type'.
          np aint16 = np.dtvpe([("aint16", np.int16, 1)])
        C:\Users\Users\User\undagmanacondag\undagmanvs\undagmatestGAN\undagmalib\undagmaite-packages\undagmatensorflow\undagmaython\undagmarkutypes.py:529: Future\undagmarning: Passing (type, 1) or '1typ
        e' as a synonym of type is deprecated; in a future version of numpy, it will be understood as (type, (1,)) / '(1,)type'.
           np quint16 = np.dtvpe([("quint16", np.uint16, 1)])
        C:\Users\User\anaconda3\envs\testGAN\lib\site-packages\tensorflow\pvthon\framework\dtvpes.pv:530: Future\arning: Passing (tvpe. 1) or '1tvp
        e' as a synonym of type is deprecated; in a future version of numpy, it will be understood as (type, (1,)) / '(1,)type'.
           _{np\_qint32} = np.dtype([("qint32", np.int32, 1)])
        C:\Users\User\anaconda3\envs\testGAN\lib\site-packages\tensorflow\pvthon\framework\dtvpes.pv:535: Future\arning: Passing (tvpe. 1) or '1tvp
        e' as a synonym of type is deprecated; in a future version of numpy, it will be understood as (type, (1,)) / '(1,)type'.
          np resource = np.dtvpe([("resource", np.ubvte, 1)])
```

데이터 적재

```
In [2]: NUM_CLASSES = 10
In [3]: (x_train, y_train), (x_test, y_test) = cifar10.load_data()
In [4]: x_train = x_train.astype('float32') / 255.0
    x_test = x_test.astype('float32') / 255.0
    y_train = to_categorical(y_train, NUM_CLASSES)
    y_test = to_categorical(y_test, NUM_CLASSES)
```

모델 만들기

```
In [5]: input_layer = Input((32,32,3))
        x = Conv2D(filters = 32, kernel_size = 3, strides = 1, padding = 'same')(input_layer)
        x = BatchNormalization()(x)
        x = LeakyReLU()(x)
        x = Conv2D(filters = 32, kernel_size = 3, strides = 2, padding = 'same')(x)
        x = BatchNormalization()(x)
        x = LeakyReLU()(x)
        x = Conv2D(filters = 64, kernel size = 3, strides = 1, padding = 'same')(x)
        lx = BatchNormalization()(x)
        x = LeakyReLU()(x)
        x = Conv2D(filters = 64, kernel_size = 3, strides = 2, padding = 'same')(x)
        x = BatchNormalization()(x)
        \times = LeakyReLU()(x)
        x = Flatten()(x)
        x = Dense(128)(x)
        \times = BatchNormalization()(x)
        x = LeakyReLU()(x)
        x = Dropout(rate = 0.5)(x)
        \times = Dense(NUM CLASSES)(\times)
        output_layer = Activation('softmax')(x)
        model = Model(input_layer, output_layer)
```

WARNING: tensorflow: From C:\u00e4Users\u00fallers\u00fallers\u00faller\u00e4\u00e4naconda3\u00faenvs\u00fatestGAN\u00faller\u00e4lib\u00fasite=\u00fackages\u00fatensorflow\u00fapython\u00faramework\u00fap_def_library.py: 263: colocate_with (from tensorflow.python.framework.ops) is deprecated and will be removed in a future version.

Instructions for updating:

Colocations handled automatically by placer.

WARNING: tensorflow: From C:\u00e4Users\u00fallers\u00fallers\u00fallers\u00fallers\u00fallers\u00fallers\u00fallers\u00faller\u00e4unaconda\u00e3\u00faenvs\u00fatestGAN\u00faller\u00eantieste -packages\u00fakeras\u00fabackend\u00faters\u00farorflow_backend.py: 3445: calling dropout (from tensorflow.python.ops.nn_ops) with keep_prob is deprecated and will be removed in a future version.

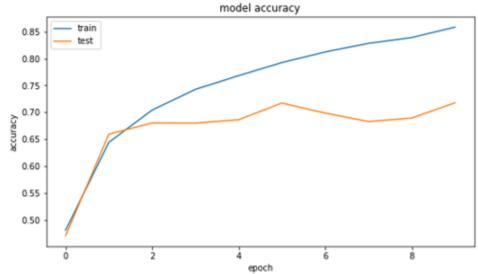
Instructions for updating:
Please use `rate` instead of `keep_prob`. Rate should be set to `rate = 1 - keep_prob`.

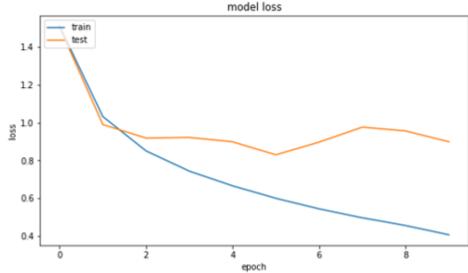
Layer (type)	Output Shape	Param #
input_1 (InputLayer)	(None, 32, 32, 3)	0
conv2d_1 (Conv2D)	(None, 32, 32, 32)	896
batch_normalization_1 (Batch	(None, 32, 32, 32)	128
leaky_re_lu_1 (LeakyReLU)	(None, 32, 32, 32)	0
conv2d_2 (Conv2D)	(None, 16, 16, 32)	9248
batch_normalization_2 (Batch	(None, 16, 16, 32)	128
leaky_re_lu_2 (LeakyReLU)	(None, 16, 16, 32)	0
conv2d_3 (Conv2D)	(None, 16, 16, 64)	18496
batch_normalization_3 (Batch	(None, 16, 16, 64)	256
leaky_re_lu_3 (LeakyReLU)	(None, 16, 16, 64)	0
conv2d_4 (Conv2D)	(None, 8, 8, 64)	36928
batch_normalization_4 (Batch	(None, 8, 8, 64)	256
leaky_re_lu_4 (LeakyReLU)	(None, 8, 8, 64)	0
flatten_1 (Flatten)	(None, 4096)	0
dense_1 (Dense)	(None, 128)	524416
batch_normalization_5 (Batch	(None, 128)	512
leaky_re_lu_5 (LeakyReLU)	(None, 128)	0
dropout_1 (Dropout)	(None, 128)	0
dense_2 (Dense)	(None, 10)	1290
activation_1 (Activation)	(None, 10)	0

모델 훈련

```
In [7]: opt = Adam(Ir=0.0005)
  model.compile(loss='categorical crossentropy', optimizer=opt, metrics=['accuracy'])
In [8]: history = model.fit(x train
         , y_train
         , batch_size=50
         . epochs=10
         . shuffle=True
         , validation_data = (x_test, y_test))
  WARNING: tensorflow: From C: \Users\Users\User\undanaconda3\undercy\undanaconda3\undanaconda3\undanaconda3\undanacondao.
  rflow.python.ops.math_ops) is deprecated and will be removed in a future version.
  Instructions for updating:
  Use tf.cast instead.
  Train on 50000 samples, validate on 10000 samples
  Epoch 1/10
  Epoch 2/10
  Epoch 3/10
  Epoch 4/10
  Epoch 5/10
  Epoch 6/10
  Epoch 7/10
  Epoch 8/10
  Epoch 9/10
  Epoch 10/10
```

```
In [9]: plt.figure(figsize=(20, 5))
         # summarize history for accuracy
        plt.subplot(121)
        plt.plot(history.history['acc'])
        plt.plot(history.history['val_acc'])
        plt.title('model accuracy')
        plt.ylabel('accuracy')
        plt.xlabel('epoch')
        plt.legend(['train', 'test'], loc='upper left')
        # summarize history for loss
        plt.subplot(122)
        plt.plot(history.history['loss'])
        plt.plot(history.history['val_loss'])
        plt.title('model loss')
        plt.ylabel('loss')
        plt.xlabel('epoch')
        plt.legend(['train', 'test'], loc='upper left')
        plt.show()
                                                                                                                 model loss
```





```
In [10]: fig, loss_ax = plt.subplots()
acc_ax = loss_ax.twinx()

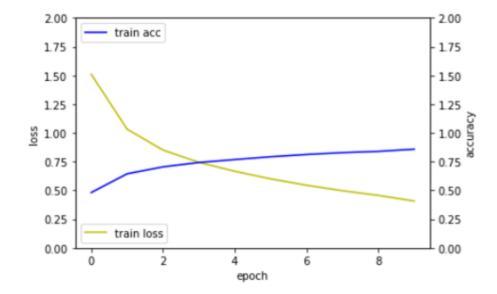
loss_ax.set_ylim([0.0, 2.0])
acc_ax.set_ylim([0.0, 2.0])

loss_ax.plot(history.history['loss'], 'y', label = 'train loss')
acc_ax.plot(history.history['acc'], 'b', label = 'train acc')

loss_ax.set_xlabel('epoch')
loss_ax.set_ylabel('loss')
acc_ax.set_ylabel('accuracy')

loss_ax.legend(loc = 'lower left')
acc_ax.legend(loc = 'upper left')
```

Out[10]: <matplotlib.legend.Legend at 0x21605aff438>



모델 평가

```
In [11]: | model.evaluate(x_test, y_test, batch_size=1000)
         10000/10000 [============= - - 130s 13ms/step
                                                  acc = 71.7\%
Out[11]: [0.8988511860370636, 0.7176999986171723]
In [12]: CLASSES = np.array(['airplane', 'automobile', 'bird', 'cat', 'deer', 'dog', 'frog', 'horse', 'ship', 'truck'])
         preds = model.predict(x_test)
         preds_single = CLASSES[np.argmax(preds, axis = -1)]
         actual single = CLASSES[np.argmax(v_test, axis = -1)]
         import matplotlib.pyplot as plt
In [13]:
         n_{to\_show} = 10
         indices = np.random.choice(range(len(x_test)), n_to_show)
         fig = plt.figure(figsize=(15, 3))
         fig.subplots_adjust(hspace=0.5, wspace=0.5)
         for i, idx in enumerate(indices):
             ima = x_test[idx]
             ax = fig.add_subplot(1, n_to_show, i+1)
             ax.axis('off')
             ax.text(0.5, -0.35, 'pred = ' + str(preds_single[idx]), fontsize=10, ha='center', transform=ax.transAxes)
             ax.text(0.5, -0.7, 'act = ' + str(actual_single[idx]), fontsize=10, ha='center', transform=ax.transAxes)
             ax.imshow(img)
```



act = dog

pred = frog

act = bird



pred = horse

act = horse



pred = airplane

act = airplane



pred = dog

act = dog



pred = cat

act = frog



pred = airplane

act = airplane







pred = truck pred = automobile pred = frog act = truck act = airplane act = frog

사실 파라미터는 어느 한 개의 변수에 종속되어 변하는 것이 아니어서 어떤 변수를 변경하면 무조건 정확도가 올라간다는 것이 보장 되지 않습니다. 그 이유는 신경망이 어떤 원리로 특징을 찾아내는지 알 수 없는 것에서 찾아 볼 수 있습니다. 따라서 스무고개를 하듯이 파라미터를 변경을 하며 최적을 상태를 찾아갑니다.

이제 본인이 나름대로 파라미터를 변경 해 보았습니다.



모델 만들기

```
In [5]: input_layer = Input((32,32,3))
        x = Conv2D(filters = 32, kernel_size = 3, strides = 1, padding = 'same')(input_layer)
        x = BatchNormalization()(x)
        \times = LeakyReLU()(\times)
        x = Conv2D(filters = 32, kernel_size = 3, strides = 2, padding = 'same')(x)
        x = BatchNormalization()(x)
        x = LeakyReLU()(x)
        x = Conv2D(filters = 64, kernel_size = 3, strides = 1, padding = 'same')(x)
        x = BatchNormalization()(x)
        x = LeakyReLU()(x)
        x = Conv2D(filters = 64, kernel_size = 3, strides = 2, padding = 'same')(x)
        x = BatchNormalization()(x)
        x = LeakyReLU()(x)
        x = Flatten()(x)
        x = Dense(128)(x)
        x = BatchNormalization()(x)
        x = LeakyReLU()(x)
        \times = Dense(NUM CLASSES)(\times)
        output_layer = Activation('softmax')(x)
        model = Model(input_layer, output_layer)
```

WARNING: tensorflow: From C: \u03c8Users\u03c8User\u03c8anaconda3\u03c8envs\u00c4testGAN\u00c8lib\u00ffsite-packages\u00c8tensorflow\u00c8python\u00c4framework\u00c4pp_def_library.py: 263: colocate_with (from tensorflow.python.framework.ops) is deprecated and will be removed in a future version.

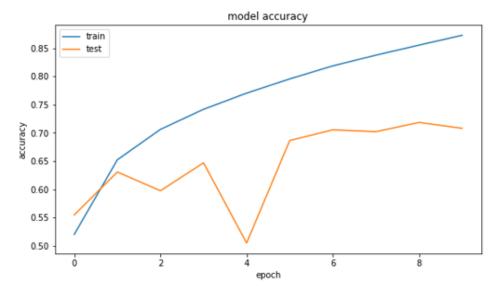
Instructions for updating:

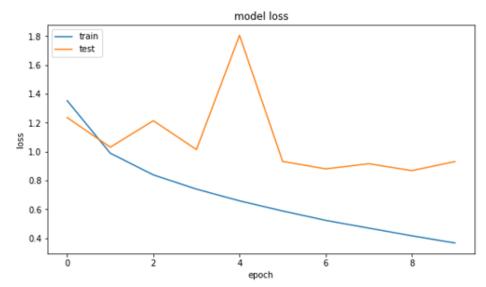
Colocations handled automatically by placer.

모델 훈련

```
opt = Adam(Ir=0.0005)
In [7]:
          |model.compile(loss='categorical_crossentropy', optimizer=opt, metrics=['accuracy'])
In [8]: history = model.fit(x_train
                                     . v train
                                     . batch size=50
                                     . epochs=10
                                     , shuffle=True
                                     , validation_data = (x_test, y_test))
           WARNING: tensorflow: From C: \unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\unders\
           rflow.python.ops.math_ops) is deprecated and will be removed in a future version.
           Instructions for updating:
          Use tf.cast instead.
           Train on 50000 samples, validate on 10000 samples
           Epoch 1/10
           Epoch 2/10
           Epoch 3/10
           Epoch 4/10
           Epoch 5/10
           Epoch 6/10
           Epoch 7/10
           Epoch 8/10
           Epoch 9/10
           Epoch 10/10
```

```
In [9]: plt.figure(figsize=(20, 5))
        # summarize history for accuracy
        plt.subplot(121)
        plt.plot(history.history['acc'])
        plt.plot(history.history['val_acc'])
        plt.title('model accuracy')
        plt.ylabel('accuracy')
        plt.xlabel('epoch')
        plt.legend(['train', 'test'], loc='upper left')
        # summarize history for loss
        plt.subplot(122)
        plt.plot(history.history['loss'])
        plt.plot(history.history['val_loss'])
        plt.title('model loss')
        plt.ylabel('loss')
        plt.xlabel('epoch')
        plt.legend(['train', 'test'], loc='upper left')
        plt.show()
```





```
In [10]: fig, loss_ax = plt.subplots()
acc_ax = loss_ax.twinx()

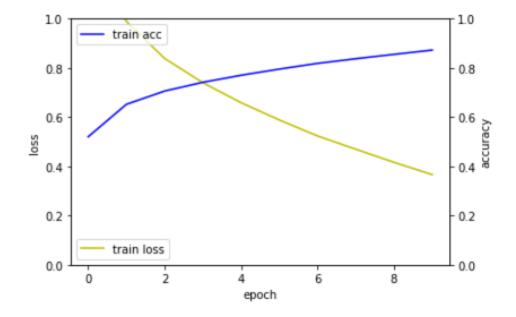
loss_ax.set_ylim([0.0, 1.0])
acc_ax.set_ylim([0.0, 1.0])

loss_ax.plot(history.history['loss'], 'y', label = 'train loss')
acc_ax.plot(history.history['acc'], 'b', label = 'train acc')

loss_ax.set_xlabel('epoch')
loss_ax.set_ylabel('loss')
acc_ax.set_ylabel('accuracy')

loss_ax.legend(loc = 'lower left')
acc_ax.legend(loc = 'upper left')
```

Out[10]: <matplotlib.legend.Legend at 0x27585555240>



모델 평가

```
In [11]: model.evaluate(x_test, v_test, batch_size=1000)
         Out[11]: [0,930810272693634, 0.7080000042915344]
                                                acc = 70.8\%
In [12]: CLASSES = np.array(['airplane', 'automobile', 'bird', 'cat', 'deer', 'dog', 'frog', 'horse', 'ship', 'truck'])
        |preds = model.predict(x test)
        preds_single = CLASSES[np.argmax(preds, axis = -1)]
        actual_single = CLASSES[np.argmax(y_test. axis = -1)]
In [13]: import matplotlib.pyplot as plt
        In to show = 10
        lindices = np.random.choice(range(len(x_test)), n_to_show)
        fig = plt.figure(figsize=(15, 3))
        fig.subplots_adjust(hspace=0.5, wspace=0.5)
        for i. idx in enumerate(indices):
            img = x_test[idx]
            ax = fig.add_subplot(1, n_to_show, i+1)
            ax.axis('off')
            ax.text(0.5, -0.35, 'pred = ' + str(preds_single[idx]), fontsize=10, ha='center', transform=ax.transAxes)
            ax.text(0.5, -0.7, 'act = ' + str(actual_single[idx]), fontsize=10, ha='center', transform=ax.transAxes)
            ax.imshow(img)
```



pred = cat

act = cat











pred = ship



pred = dog



pred = dog







pred = deer act = deer

pred = horse pred = truck act = horse

act = truck

pred = dogact = dog

act = ship

act = deer

act = dog

위와 같은 상황(과대 적합; loss = 93%)을 피하기 위하여 드랍 아웃(Drop out)을 사용하기도 합니다. 실제 모델을 사용시에 새로운 이미지를 판별하는 일이 대부분이므로 그다지 좋은 모델이 아닙니다.



모델 만들기

```
In [5]: input layer = Input((32.32.3))
         x = Conv2D(filters = 32, kernel_size = 3, strides = 1, padding = 'same')(input_layer)
         x = BatchNormalization()(x)
         x = ReLU()(x)
         x = Conv2D(filters = 32, kernel_size = 3, strides = 2, padding = 'same')(x)
         x = BatchNormalization()(x)
         x = ReLU()(x)
         \times = Conv2D(filters = 64, kernel_size = 3, strides = 1, padding = 'same')(x)
         \times = BatchNormalization()(x)
         x = ReLU()(x)
         x = \text{Conv2D}(\text{filters} = 64. \text{ kernel size} = 3. \text{ strides} = 2. \text{ padding} = 'same')(x)
         lx = BatchNormalization()(x)
         x = ReLU()(x)
         x = Flatten()(x)
         \times = Dense(128)(\times)
         x = BatchNormalization()(x)
         x = ReLU()(x)
         x = Dropout(rate = 0.5)(x)
         \times = Dense(NUM CLASSES)(\times)
         output_layer = Activation('softmax')(x)
         model = Model(input_layer, output_layer)
```

WARNING: tensorflow: From C: \u03c4Users\u03c4Users\u03c4unaconda3\u03c4envs\u00c4testGAN\u00fclib\u00fcsite-packages\u00c4tensorflow\u00c4python\u00c4framework\u00c4op_def_library.py: 263: colocate_with (from tensorflow.python.framework.ops) is deprecated and will be removed in a future version.

Instructions for updating:

Colocations handled automatically by placer.

WARNING: tensorflow: From C: \u00fcUsers\u00fcUsers\u00fcUsers\u00fcUsers\u00fc\u00e4naconda3\u00fcenvs\u00fctestGAN\u00fclib\u00fcsite-packages\u00fckeras\u00fcbackend\u00fctensorflow_backend.py: 3445: calling dropout (from tensorflow.python.ops.nn_ops) with keep_prob is deprecated and will be removed in a future version.

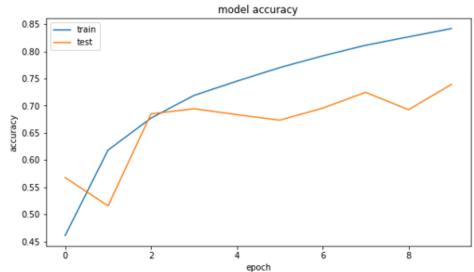
Instructions for updating:

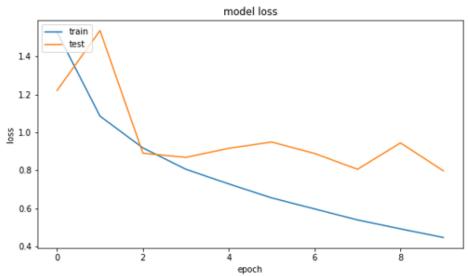
Please use `rate` instead of `keep_prob`. Rate should be set to `rate = 1 - keep_prob`.

모델 훈련

```
In [7]: |opt = Adam(Ir=0.0005)|
  model.compile(loss='categorical crossentropy', optimizer=opt, metrics=['accuracy'])
In [R]: history = model.fit(x train
       . v train
       , batch_size=50
       . epochs=10
       . shuffle=True
       , validation_data = (x_test, y_test))
  rflow.python.ops.math_ops) is deprecated and will be removed in a future version.
  Instructions for updating:
  Use tf.cast instead.
  Train on 50000 samples, validate on 10000 samples
  Epoch 1/10
  Epoch 2/10
  Epoch 3/10
  Epoch 4/10
  Epoch 5/10
  Epoch 6/10
  Epoch 7/10
  Epoch 8/10
  Epoch 9/10
  Epoch 10/10
```

```
In [9]: plt.figure(figsize=(20, 5))
        # summarize history for accuracy
        plt.subplot(121)
        plt.plot(history.history['acc'])
        plt.plot(history.history['val_acc'])
        plt.title('model accuracy')
        plt.ylabel('accuracy')
        plt.xlabel('epoch')
        plt.legend(['train', 'test'], loc='upper left')
        # summarize history for loss
        plt.subplot(122)
        plt.plot(history.history['loss'])
        plt.plot(history.history['val_loss'])
        plt.title('model loss')
        plt.ylabel('loss')
        plt.xlabel('epoch')
        plt.legend(['train', 'test'], loc='upper left')
        plt.show()
```





```
In [10]: fig, loss_ax = plt.subplots()
acc_ax = loss_ax.twinx()

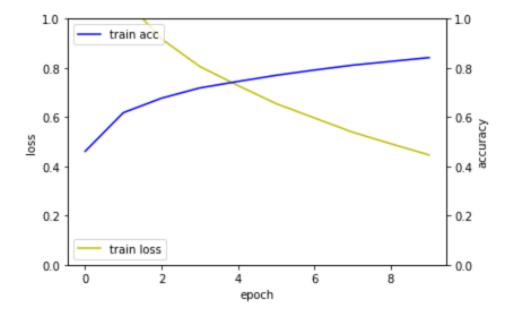
loss_ax.set_ylim([0.0, 1.0])
acc_ax.set_ylim([0.0, 1.0])

loss_ax.plot(history.history['loss'], 'y', label = 'train loss')
acc_ax.plot(history.history['acc'], 'b', label = 'train acc')

loss_ax.set_xlabel('epoch')
loss_ax.set_ylabel('loss')
acc_ax.set_ylabel('accuracy')

loss_ax.legend(loc = 'lower left')
acc_ax.legend(loc = 'upper left')
```

Out[10]: <matplotlib.legend.Legend at 0x242855ad4a8>



모델 평가

```
In [11]: model.evaluate(x test. v test. batch size=1000)
         10000/10000 [============ ] - 31s 3ms/step
Out[11]: [0.7973899841308594. 0.7390999972820282]
                                                   acc = 73.9\%
In [12]: CLASSES = np.array(['airplane', 'automobile', 'bird', 'cat', 'deer', 'dog', 'frog', 'horse', 'ship', 'truck'])
         preds = model.predict(x_test)
         preds_single = CLASSES[np.argmax(preds, axis = -1)]
         actual_single = CLASSES[np.argmax(y_test, axis = -1)]
In [13]: import matplotlib.pyplot as plt
         n to show = 10
         indices = np.random.choice(range(len(x_test)), n_to_show)
         fig = plt.figure(figsize=(15, 3))
         fig.subplots_adjust(hspace=0.5, wspace=0.5)
         for i. idx in enumerate(indices):
             img = x_test[idx]
             ax = fig.add_subplot(1, n_to_show, i+1)
             ax.axis('off')
             ax.text(0.5, -0.35, 'pred = ' + str(preds_single[idx]), fontsize=10, ha='center', transform=ax.transAxes)
             ax.text(0.5, -0.7, 'act = ' + str(actual_single[idx]), fontsize=10, ha='center', transform=ax.transAxes)
             ax.imshow(img)
```



pred = horse

act = horse



act = frog



pred = frog

act = frog



pred = bird

act = bird



pred = frog

act = frog



pred = airplane

act = airplane



pred = ship

act = ship

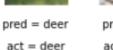




pred = bird

act = bird





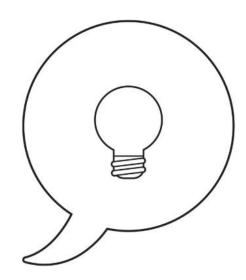


pred = catact = ship

드랍 아웃(Drop out)을 적용하고 활성화 함수(Activate Function)을 ReLU로 바꾸었습니다.

loss = 79.7% accuracy = 73.9 % 로

과적합도 피할 수 있고 새로운 이미지에 대한 정확도는 73.9%로 여태 실험해 본 모델 중 가장 뛰어납니다. 여러 파라미터를 변경하다 보면 73.9%보다 높아질 지도 모릅니다.



수고하셨습니다.