

SOUTHEAST UNIVERSITY

School of Science & Engineering/Department of CSE, Final Exam

Semester: Summer 2019

Program: BSc in CSE

Course Title: Computer Graphics & Animation

Course Code: CSE4013

Sec: 2, 4

Time: 120 Minutes

Full Marks: 40

[You have to answer all of the questions given below. ☺]

No.	QUESTION	Marks
1.	<p>a) We want to align a vector, $\bar{V} = \frac{1}{7}\mathbf{i} - 3\mathbf{j} + 6\mathbf{k}$ with the vector \mathbf{i} along the positive X-axis by performing two rotations about the principal axes.</p> <p>i) First we rotate by an angle α about the Y axis and then by an angle β about the Z axis. Find α and β.</p> <p>ii) Find the composite transformation matrix to rotate all 3D objects by an angle of 30 degree with respect to \bar{V}. You don't need to multiply the matrices. Use homogeneous coordinates. You can use data from part one.</p>	1+3
	<p>b) Suppose you have some 3D homogeneous points A (3, -9, 7, -1), B (0, -3, -7, 2) and C (4, 4, 4, 4).</p> <p>1. Find ($3\overline{AB} - 2\overline{CB} + 5\overline{AC}$).</p> <p>2. Find ($\overline{AB} \cdot \overline{CA}$).</p>	2+2 2
	c) What does mean the value of w in homogeneous co-ordinate? Draw necessary figures.	
2.	<p>a) Find the transformation matrix of mirror reflection about the line $2x - 3y + 3 = 0$. You don't need to multiply the matrices. Use homogenous coordinates.</p> <p>b) Consider two straight lines L1 and L2, which are represented by the equations $x+y-6=0$ and $x-y+4=0$ respectively. You want to align L1 with L2 by performing 2D translation(s) and rotation(s). Write down the corresponding composite transformation matrix. You don't need to multiply the matrices. Use homogenous coordinates.</p> <p>c) Consider a 3D plane P, which is defined by the equation $y-z=0$. Determine the transformation matrix for reflection with respect to P. You don't need to multiply the matrices.</p>	4 3 3

3.

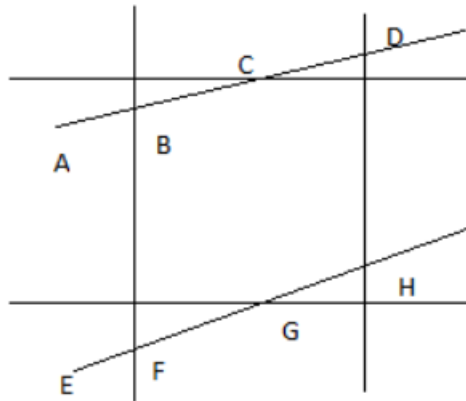


Fig-1

a) Inspect Fig-1 and answer the questions below.

5

i) Which portion will be selected to draw from line AD?

ii) Which portion will be selected to draw from line EH?

Use **Cohen-Sutherland** line clipping algorithm.

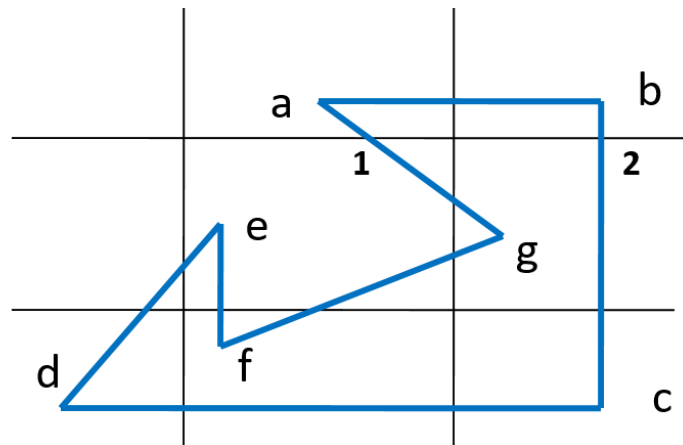


Fig-2

b) Inspect Fig-2 and find the resultant portion when clip on bottom, clip on right and clip on top have occurred. You have to use **Sutherland-Hodgman** polygon clipping algorithm.

5

4.

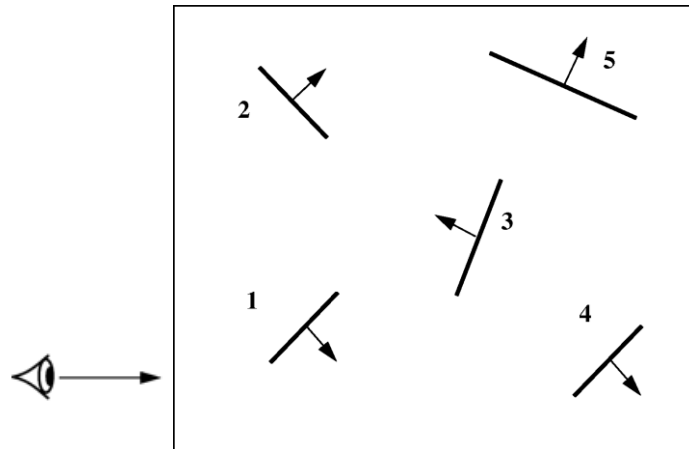


Fig-3

a) Inspect Fig-3 and answer the questions below.

4+1

i) Draw the BSP tree and take object 3 as root. Then display the BSP tree.

ii) Draw the BSP tree if you take object 5 as root.

b) Write down the invisible primitives for a polygon.

1

c) Write the advantages and disadvantages of Back-Face Culling algorithm. Draw figures if necessary.

2

d) Compare Image precision and Object precision algorithm.

2