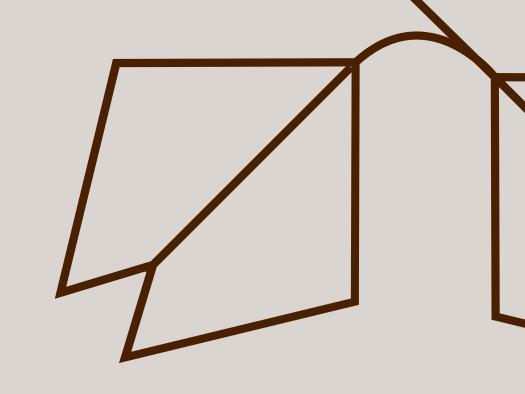
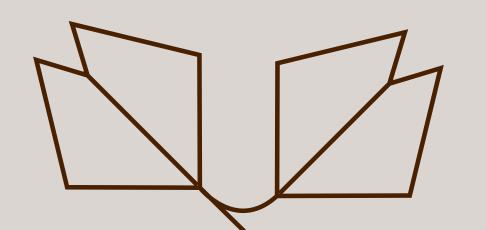
Kharagpur Open Source Society

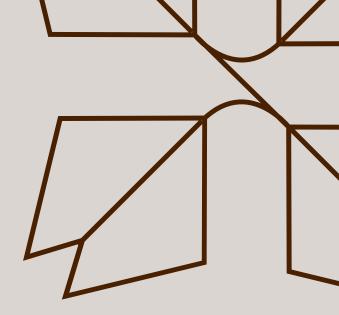
THE INNER WORKINGS OF COMPILERS





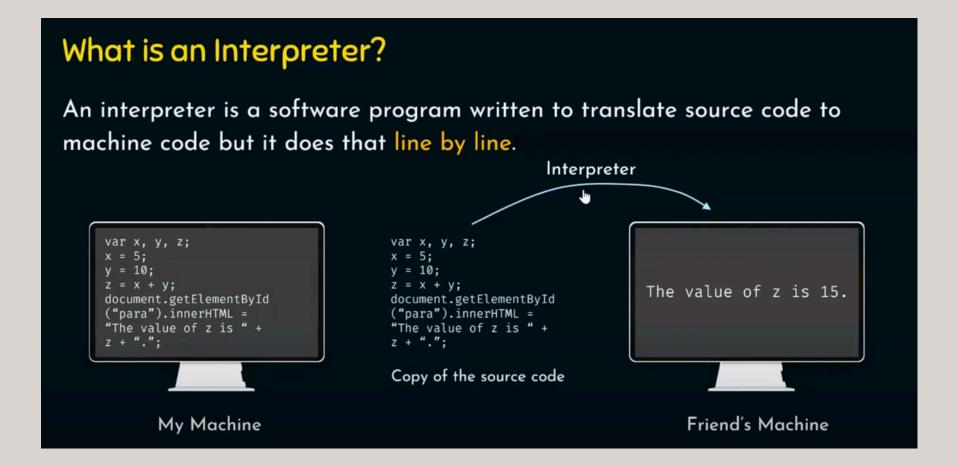
By-ABHINAV TIWARI

COMPILERS vs INTERPRETERS

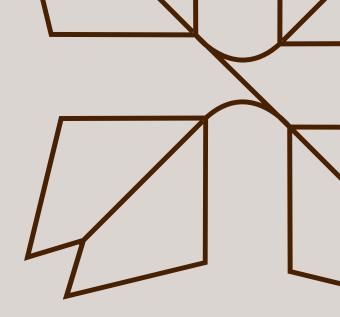


Convert the entire source code into machine code before execution. The resulting executable file runs independently of the source code.

Process and execute code line by line, translating it into machine instructions at runtime.



COMPILERS



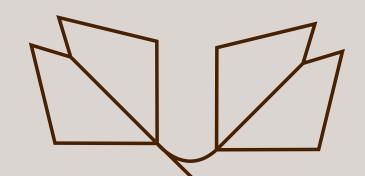
intermediate representation (IR).

FRONT-END MIDDLE-END

front end takes The middle end optimizes source code as input and the IR for performance, transforms it into an reducing execution time and memory usage.

BACK-END

The back end converts the optimized IR into machine code (assembly code) and prepares it for execution.



COMPILERS - FRONT END

1. Lexical Analysis: Breaks code into tokens

For Example:

int a = 10;

This gets tokenised as:

[int] [a] [=] [10] [;]

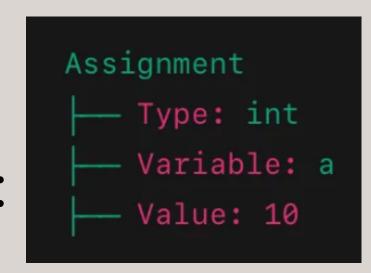
2. Syntax analysis: Verifies code structure and constructs a parse tree using grammar rules



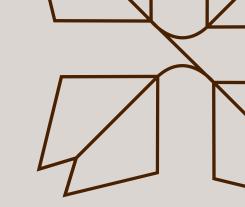
For Example:

int a = 10;

Corresponding tree:



COMPILERS - FRONT END



3. Semantic analysis: Checks for logical errors and type consistency

For Example:

int
$$x = "hello"; \rightarrow Type error$$

4. Intermediate Code Generation : Converts code to low-level representation.

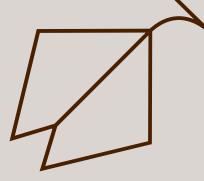
For Example:

Intermediate

$$t1 = b + c$$

 $a = t1$





What is an Intermediate Representation (IR)?

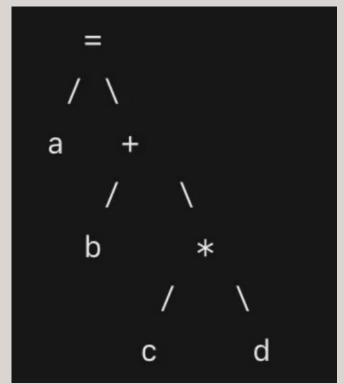
- IR is a low-level representation of the source code, but it is not yet machine code.
- It makes optimisation easier before final machine code generation.
- It is independent of the source language and target machine.





Types of Intermediate Representations

- 1. Abstract Syntax Tree (AST):
 - a. A tree representation of the parsed source code.
 - b. Example for a = b + c * d

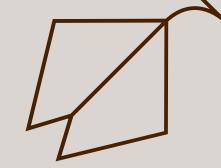


- 2. Three-Address Code (TAC):
 - a. Breaks down complex expressions into simpler three-operand statements.
 - b. Example for a = b + c * d

$$t1 = c * d$$

 $t2 = b + t1$
 $a = t2$



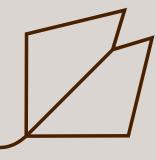


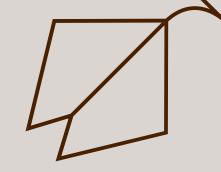
Code Optimisation: Improves efficiency independent of target architecture

- 1. Constant Folding:
 - a. Replaces constant expressions at compile time
 - b. Example for int x = 5 * 4 // Becomes: int x = 20
 - c. Compiler precomputes 5 * 4 instead of computing it at runtime.
- 2. Dead Code Elimination:
 - a. Removes unreachable or unnecessary code.
 - b. The compiler removes x = 10; as it's overwritten immediately.

```
int x = 10;

x = 20; // x = 10 is never used, so it's removed.
```





Example: Unoptimized C Code

```
int compute(int x) {
   int y = x * 2; // Used
   int z = x * 5; // Unused (dead code)
   return y;
}
```

```
assembly
CopyEdit
imul eax, edi, 2 ; y = x * 2
imul ecx, edi, 5 ; z = x * 5 (DEAD CODE)
mov eax, eax ; return y
```

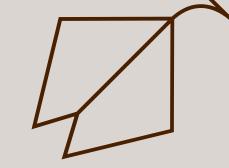
Optimized Code after Dead Code Elimination

```
int compute(int x) {
    return x * 2; // Removed 'z' since it's never used
}
```

```
After Dead Code Elimination

Plain Text >

assembly
CopyEdit
imul eax, edi, 2 ; Only y = x * 2 is kept
```



3. Loop Unrolling:

- a. Expands loops to reduce branching overhead.
- b. The compiler removes x = 10; as it's overwritten immediately.

for
$$(i = 0; i < 4; i++) \{arr[i] = 0; \}$$

Converts to:

$$arr[0] = 0;$$

$$arr[1] = 0;$$

$$arr[2] = 0;$$

$$arr[3] = 0;$$

4. Strength Reduction:

- a. Replaces expensive operations with cheaper ones.
- b. Eg : $x = y * 2 \Rightarrow x = y << 1$ // Bitwise is faster than multplication

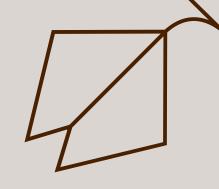


- 5. Common Subexpression Elimination (CSE)
 - a. Removes redundant calculations.

```
int x = (a + b) * c + (a + b) * d;
```



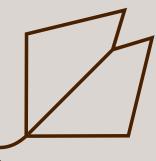
COMPILERS - BACK END



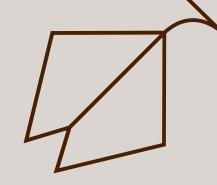
The back end of a compiler is responsible for converting optimised intermediate representation (IR) into assembly code or machine code for execution. It consists of code selection, register allocation, instruction scheduling, and final assembly generation.

Steps in the Back End:

- 1. Instruction Selection
 - Converts IR into target CPU instructions.
 - Example: x = a + b; \rightarrow ADD R1, R2, R3.
- 2. Instruction Scheduling
 - Reorders instructions to improve execution speed (pipelining).
- 3. Register Allocation
 - Assigns variables to CPU registers to minimize memory access.
- 4. Code Generation
 - Produces final assembly or machine code for execution.
- 5. Code Linking & Relocation
 - Combines object files, resolves function calls, and loads the program into memory.



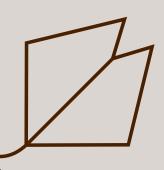
INTERPRETERS



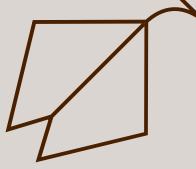
Interpreters execute source code line by line, translating and running each instruction sequentially.

The process typically involves:

- 1. Parsing the source code
- 2. Executing each instruction immediately



How an Interpreter Works

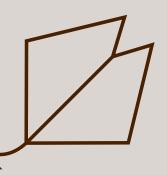


When you run a script using an interpreter (like Python or JavaScript), it follows these steps:

- Reads a statement from the source code => The Python interpreter reads the first line and moves to execution immediately.
- Checks for syntax errors => If there is a syntax error, Python stops immediately and does not execute the next lines.
- Converts the statement into an intermediate form => When you run a Python program, it does not execute the source code directly. Instead, Python first translates the human-readable source code into an intermediate representation called bytecode before executing it.

Bytecode

Bytecode is a **low-level** representation of your Python program, which is **not human-readable** but still not machine code. It is a set of instructions that the **Python Virtual Machine** can understand and execute.

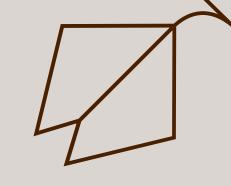


Why Bytecode?

- 1. Portability: Bytecode can run on any system with a Python interpreter, unlike machine code, which is system-dependent.
- 2. Faster Execution: Parsing source code every time would be slow; bytecode speeds up execution.
- 3. Intermediate Representation: Acts as a bridge between source code and machine execution.

Let's take a simple Python function:

Bytecode output



```
import dis

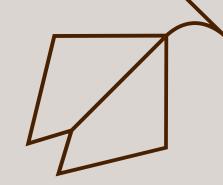
def example():
    x = 5
    y = x * 2
    print(y)

dis.dis(example)
```

```
0 LOAD_CONST
                                       1 (5)
                                       0 (x)
           2 STORE_FAST
           4 LOAD_FAST
                                       0 (x)
3
           6 LOAD_CONST
                                       2 (2)
           8 BINARY_MULTIPLY
           10 STORE_FAST
                                       1 (y)
                                       0 (print)
           12 LOAD GLOBAL
4
                                       1 (y)
          14 LOAD_FAST
           16 CALL_FUNCTION
           18 POP_TOP
           20 RETURN_VALUE
```



Breaking down the Bytecode:



1. $x=5 \rightarrow$ Bytecode Representation

1.7		
2	0 LOAD_CONST	1 (5)
	2 STORE_FAST	0 (x)

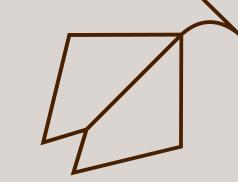
- LOAD_CONST 1 (5) → Loads the constant value 5 onto the stack.
- STORE_FAST $0 (x) \rightarrow$ Stores the value from the stack into the variable x.

2. $y = x * 2 \rightarrow Bytecode Representation$

3	4	LOAD_FAST	0	(x)
	6	LOAD_CONST	2	(2)
	8	BINARY_MULTIPLY		
	10	STORE_FAST	1	(y)

- LOAD_FAST 0 (x) → Loads the value of x onto the stack.
- LOAD_CONST 2 (2) → Loads the constant 2 onto the stack.
- BINARY_MULTIPLY → Multiplies x and 2, leaving the result on the stack.
- STORE_FAST 1 (y) → Stores the result into variable y.

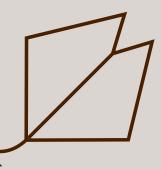
Breaking down the Bytecode:



3. $print(y) \rightarrow Bytecode Representation$

```
4 12 LOAD_GLOBAL 0 (print)
14 LOAD_FAST 1 (y)
16 CALL_FUNCTION 1
18 POP_TOP
20 RETURN_VALUE
```

- LOAD_GLOBAL 0 (print) → Loads the function print from global scope.
- LOAD_FAST 1 (y) \rightarrow Loads the value of y onto the stack.
- CALL_FUNCTION 1 → Calls the print function with 1 argument (y).
- POP_TOP → Removes the function's return value (since print() returns None).
- RETURN_VALUE → Ends the function execution.



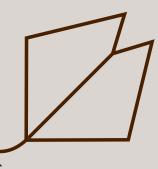
Challenges Encountered during the Development of Compilers and Interpreters

Problem:

- Different platforms (Windows, Linux, macOS) and hardware architectures (x86, ARM, RISC-V) have different instruction sets.
- A compiler must generate code that works across multiple platforms.

Solution:

- Use an Intermediate Representation (IR)
- To achieve platform independence, compilers use an Intermediate Representation (IR). IR is a machine-independent representation that can be later converted into target-specific machine code.



Challenges Encountered during the Development of Compilers and Interpreters

• Understanding the LLVM IR Code

```
define i32 @add(i32 %a, i32 %b) {
  %1 = add i32 %a, %b
  ret i32 %1
}
```

```
    Function Definition ( define i32 @add(i32 %a, i32 %b) )
    define i32 @add → Defines a function named add that returns an i32 (32-bit integer).
    (i32 %a, i32 %b) → The function takes two 32-bit integer arguments, %a and %b.
    Addition (%1 = add i32 %a, %b)
    %1 is a temporary variable (SSA register).
    add i32 %a, %b → Adds %a and %b and stores the result in %1.
    Return Statement ( ret i32 %1 )
    ret i32 %1 → Returns the result stored in %1.
```



Challenges Encountered during the Development of Compilers and Interpreters

Problem:

- Different CPUs have unique features like:
 - Vectorized Instructions (SIMD)
 - Parallel Execution (Multi-core Processing)
 - Different Register Sizes (32-bit vs. 64-bit)
- A compiler must optimize the generated code to fully utilize hardware capabilities.

```
int square(int x) {
    return x * x;
}
```

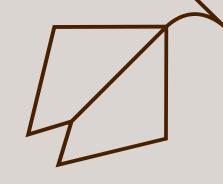
• Generated x86 Assembly (Optimized for Intel Processors)

```
imul eax, eax ; Uses the efficient "imul" multiplication instruction
```

• Generated ARM Assembly (Optimized for ARM Processors)

```
mul r0, r0, r0 ; Uses ARM's multiplication instruction
```

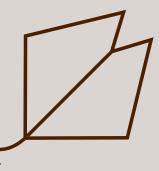


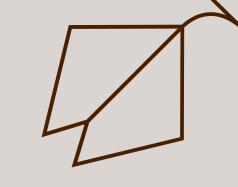


To demonstrate how a compiler optimises register allocation using a disassembler, we will:

- 1. Write a simple C function and compile it.
- 2. Generate unoptimised (O0) and optimised (O3) assembly code using clang or GCC.
- 3. Analyse the differences using a disassembler (objdump).

```
#include <stdio.h>
int compute(int a, int b) {
    int x = a + b; // x is stored in memory at -00
    int y = x * 2; // y is stored in memory at -00
    return y;
}
int main() {
    printf("%d\n", compute(3, 5));
    return 0;
}
```





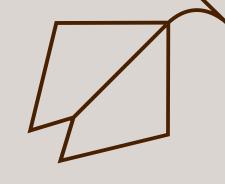
Compile with Different Optimization Levels

We will compile this with no optimizations (-O0) and maximum optimizations (-O3).

```
gcc -00 -S -masm=intel test.c -o test_00.s # No optimization gcc -03 -S -masm=intel test.c -o test_03.s # High optimization
```

- $OO \rightarrow No$ optimization, keeps variables in memory.
- O3 \rightarrow Aggressive optimization, stores values in registers instead of memory.
- $S \rightarrow$ Generates assembly code.
- masm=intel \rightarrow Uses Intel syntax (easier to read than AT&T syntax).





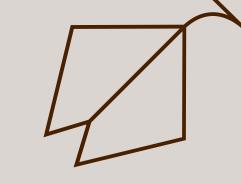
Disassemble and Compare the Assembly Code

Assembly Output with O0 (No Optimization)

```
compute:
           rbp
   push
           rbp, rsp
   mov
           DWORD PTR [rbp-4], edi ; Store a in memory
   mov
           DWORD PTR [rbp-8], esi ; Store b in memory
   mov
           eax, DWORD PTR [rbp-4]; Load a from memory
   mov
           eax, DWORD PTR [rbp-8]; Add b (memory access)
   add
           DWORD PTR [rbp-12], eax; Store x in memory
   mov
           eax, DWORD PTR [rbp-12]; Load x from memory
   mov
                                  ; Multiply by 2
   imul
           eax, eax, 2
           DWORD PTR [rbp-16], eax; Store y in memory
   mov
           eax, DWORD PTR [rbp-16]; Load y from memory
   mov
           rbp
   pop
   ret
```

Analysis (Unoptimized Code)

- Memory-heavy: Stores and loads every variable (a, b, x, y) from memory.
- Performance issue: CPU registers are not used efficiently.
- Multiple redundant memory accesses slow down execution.



Disassemble and Compare the Assembly Code

Assembly Output with O3 (Optimized Code)

```
compute:
   lea   eax, [rdi + rsi] ; Compute x = a + b directly into a register
   add   eax, eax ; Multiply by 2 (y = x * 2)
   ret
```

Analysis (Optimized Code)

- No memory access: Everything is kept in registers (eax, rdi, rsi), eliminating slow memory reads/writes.
- Optimized arithmetic:
 - lea eax, [rdi + rsi] replaces mov and add (faster instruction).
 - add eax, eax replaces multiplication (cheaper operation).
- Shorter, more efficient assembly:
 - O3 eliminates redundant instructions.
 - Faster execution and better CPU utilization.



Thank You