

# 15-411 Compiler Design, Fall 2013

## Lab 3

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Test Programs Due: 11:59pm, Tuesday, October 8, 2013

Compilers Due: 11:59pm, Tuesday, October 15, 2013

### 1 Introduction

The goal of the lab is to implement a complete compiler for the language L3. This language extends L2 with the ability to define functions and call them. This means you will have to change all phases of the compiler from the second lab. One can write some interesting recursive and iterative functions over integers in this language. Correctness is still paramount, but performance starts to become a bit more of an issue as we may slightly tighten the time-bounds for the compiler.

### 2 L3 Syntax

The lexical specification of L3 remains unchanged from that of L2, except that comma (,) is now a lexical token. The syntax of L3 is a superset of L2, as presented in Figure 1. Ambiguities in this grammar are resolved according to the same rules of precedence as in L2. The main extension is to allow definitions of functions and transparent definitions of types. We also have function calls as expressions, as well as a new statement `assert(e)` with its meaning from C0 and C, aborting the program if *e* evaluates to `false`. Finally, we have the new type `void`, used only as the return type for functions not intended to return a value.

Ambiguities in the grammar are resolved according to the operator precedence table in Figure 2 and the rule that an `else` provides the alternative for the most recent eligible `if`.

$\langle \text{program} \rangle$	$::= \epsilon \mid \langle \text{gdecl} \rangle \langle \text{program} \rangle$
$\langle \text{gdecl} \rangle$	$::= \langle \text{fdecl} \rangle \mid \langle \text{fdefn} \rangle \mid \langle \text{typedef} \rangle$
$\langle \text{fdecl} \rangle$	$::= \langle \text{type} \rangle \textbf{ident} \langle \text{param-list} \rangle ;$
$\langle \text{fdefn} \rangle$	$::= \langle \text{type} \rangle \textbf{ident} \langle \text{param-list} \rangle \langle \text{block} \rangle$
$\langle \text{param} \rangle$	$::= \langle \text{type} \rangle \textbf{ident}$
$\langle \text{param-list-follow} \rangle$	$::= \epsilon \mid , \langle \text{param} \rangle \langle \text{param-list-follow} \rangle$
$\langle \text{param-list} \rangle$	$::= ( ) \mid ( \langle \text{param} \rangle \langle \text{param-list-follow} \rangle )$
$\langle \text{typedef} \rangle$	$::= \textbf{typedef} \langle \text{type} \rangle \textbf{ident} ;$
$\langle \text{type} \rangle$	$::= \textbf{int} \mid \textbf{bool} \mid \textbf{ident} \mid \textbf{void}$
$\langle \text{block} \rangle$	$::= \{ \langle \text{stmts} \rangle \}$
$\langle \text{decl} \rangle$	$::= \langle \text{type} \rangle \textbf{ident} \mid \langle \text{type} \rangle \textbf{ident} = \langle \text{exp} \rangle$
$\langle \text{stmts} \rangle$	$::= \epsilon \mid \langle \text{stmt} \rangle \langle \text{stmts} \rangle$
$\langle \text{stmt} \rangle$	$::= \langle \text{simp} \rangle ; \mid \langle \text{control} \rangle \mid \langle \text{block} \rangle$
$\langle \text{simp} \rangle$	$::= \langle \text{lvalue} \rangle \langle \text{asop} \rangle \langle \text{exp} \rangle \mid \langle \text{lvalue} \rangle \langle \text{postop} \rangle \mid \langle \text{decl} \rangle \mid \langle \text{exp} \rangle$
$\langle \text{simpopt} \rangle$	$::= \epsilon \mid \langle \text{simp} \rangle$
$\langle \text{lvalue} \rangle$	$::= \textbf{ident} \mid ( \langle \text{lvalue} \rangle )$
$\langle \text{elseopt} \rangle$	$::= \epsilon \mid \textbf{else} \langle \text{stmt} \rangle$
$\langle \text{control} \rangle$	$::= \textbf{if} ( \langle \text{exp} \rangle ) \langle \text{stmt} \rangle \langle \text{elseopt} \rangle$ $\mid \textbf{while} ( \langle \text{exp} \rangle ) \langle \text{stmt} \rangle$ $\mid \textbf{for} ( \langle \text{simpopt} \rangle ; \langle \text{exp} \rangle ; \langle \text{simpopt} \rangle ) \langle \text{stmt} \rangle$ $\mid \textbf{return} \langle \text{exp} \rangle ; \mid \textbf{return} ;$ $\mid \textbf{assert} ( \langle \text{exp} \rangle ) ;$
$\langle \text{arg-list-follow} \rangle$	$::= \epsilon \mid , \langle \text{exp} \rangle \langle \text{arg-list-follow} \rangle$
$\langle \text{arg-list} \rangle$	$::= ( ) \mid ( \langle \text{exp} \rangle \langle \text{arg-list-follow} \rangle )$
$\langle \text{exp} \rangle$	$::= ( \langle \text{exp} \rangle ) \mid \textbf{num} \mid \textbf{true} \mid \textbf{false} \mid \textbf{ident}$ $\mid \langle \text{unop} \rangle \langle \text{exp} \rangle \mid \langle \text{exp} \rangle \langle \text{binop} \rangle \langle \text{exp} \rangle$ $\mid \langle \text{exp} \rangle ? \langle \text{exp} \rangle : \langle \text{exp} \rangle \mid \textbf{ident} \langle \text{arg-list} \rangle$
$\langle \text{asop} \rangle$	$::= = \mid += \mid -= \mid *= \mid /= \mid \% = \mid \& = \mid \wedge = \mid \mid = \mid \ll = \mid \gg =$
$\langle \text{binop} \rangle$	$::= + \mid - \mid * \mid / \mid \% \mid < \mid \leq \mid > \mid \geq \mid == \mid !=$ $\mid \&\& \mid \mid \mid \& \mid \wedge \mid \mid \mid \ll \mid \gg$
$\langle \text{unop} \rangle$	$::= ! \mid \sim \mid -$
$\langle \text{postop} \rangle$	$::= ++ \mid --$

The precedence of unary and binary operators is given in Figure 2. Non-terminals are in  $\langle \text{angle brackets} \rangle$ . Terminals are in **bold**. The absence of tokens is denoted by  $\epsilon$ .

Figure 1: Grammar of L3

Operator	Associates	Meaning
()	n/a	explicit parentheses
! ~ - ++ --	right	logical not, bitwise not, unary minus, increment, decrement
* / %	left	integer times, divide, modulo
+ -	left	integer plus, minus
<< >>	left	(arithmetic) shift left, right
< <= > >=	left	integer comparison
== !=	left	overloaded equality, disequality
&	left	bitwise and
^	left	bitwise exclusive or
	left	bitwise or
&&	left	logical and
	left	logical or
? :	right	conditional expression
= += -= *= /= %=		
&= ^=  = <<= >>=	right	assignment operators

Figure 2: Precedence of operators, from highest to lowest

### 3 L3 Elaboration

Each kind of global declaration (`gdecl`) is based on a closely corresponding construct in C.

- `fdecl`: declares a function; like a function prototype in C.
- `fdefn`: defines a function; like a function definition in C.
- `typedef`: defines an alias for a type that is transparent to the type system, just as in C.

The semantics is complicated because the language also intrinsically supports a foreign function interface through a mechanism of headers. Consult the section on the compile-time environment for details on how headers are supplied. For now, it is sufficient to know that a header is a list of `gdecls` that satisfy the following conditions:

- They are treated as if they are available to the L3 program *before* the `gdecls` in the L3 sources proper.
- They can contain type definitions and function declarations, but *not* function definitions. These are instead supplied by the runtime environment in the linking phase.
- The fact that a function declaration was supplied in a header is an essential distinguishing factor that is preserved for the purpose of the static semantics.

To expeditiously capture the similarity and differences between global declarations in headers and in L3 sources, we assume that the the header is parsed with the same rules as for sources, and the resulting declarations are tagged as external.

A program is now simply a list of global declarations and definitions. It must elaborate and then store the elaborated (internal) form of function declarations, definitions, and type definitions.

For each function declaration

$$\tau \ f(\tau_1 \ x_1, \dots, \tau_n \ x_n);$$

or function definition

$$\tau \ f(\tau_1 \ x_1, \dots, \tau_n \ x_n)\{s\}$$

we obtain a declaration  $f : (\tau_1, \dots, \tau_n) \rightarrow \tau$  and, in addition, a corresponding definition of  $f$  in the second case.

For each type definition

$$\text{typedef } \tau \ \alpha$$

which defines the type name  $\alpha$  as a transparent synonym for  $\tau$ , we obtain a definition  $\alpha = \tau$ .

A context  $\Gamma$  that we can use for type checking, therefore now contains:

$$\Gamma ::= \cdot \mid \Gamma, f:(\tau_1, \dots, \tau_n) \rightarrow \tau, \mid \Gamma, \alpha = \tau \mid \Gamma, x:\tau$$

While elaborating a program, we must obey the following scoping rules:

- A function may be declared several times, in which case the declarations must be compatible (same argument and return types). External functions may not be defined, while other functions must be defined exactly once and be compatible with their declaration (if there is one).

- The name of a function is visible after its first declaration, and within and after its definition. This means a single recursive function does not require a declaration, but two mutually recursive functions require at least one forward declaration.
- The name of a defined type is visible after its definition. Type names may be defined only once.
- Names of functions and variables may not collide with defined type names.

## 4 L3 Static Semantics

Due to the presence of functions and defined type names, type checking is more complex than in L2. We refer to function parameters or variables declared in the body of functions as *local variables*. As noted in the previous section, the typing context  $\Gamma$  contains declarations for functions  $f : (\tau_1, \dots, \tau_n) \rightarrow \tau$ , type names  $\alpha = \tau$ , and local variables  $x : \tau$ .

- Function parameters and locally declared variables with overlapping scopes may not have the same name. Among other things, this means that for a given function, all function parameters must have distinct names. However, local variables are allowed to shadow function names. This is similar to the behavior of C. You can emulate this specification, for example, by extending the rules for declarations from L2 as follows:

$$\frac{x \notin \text{Dom}(\Gamma) \quad \Gamma, x : \tau \vdash s \text{ valid}}{\Gamma \vdash \text{declare}(x, \tau, s) \text{ valid}}$$

$$\frac{\Gamma(x) = (\tau_1, \dots, \tau_n) \rightarrow \tau' \quad \Gamma, x : \tau \vdash s \text{ valid}}{\Gamma \vdash \text{declare}(x, \tau, s) \text{ valid}}$$

- A function must be called with the correct number of arguments, and with compatible types. The whole expression has the corresponding return type.

$$\frac{\Gamma(f) = (\tau_1, \dots, \tau_n) \rightarrow \tau \quad \Gamma \vdash e_1 : \tau_1 \quad \dots \quad \Gamma \vdash e_n : \tau_n}{\Gamma \vdash f(e_1, \dots, e_n) : \tau}$$

- The new type `void` is allowed only as the return type of a function. It expresses that the function returns no value. Such a function can not be called *inside* an expression, but only directly as a statement.
- A function returning `void` does not require an explicit `return` statement at the end of each control flow path starting from the beginning of the function. Any explicit return that happens to be present must have the form “`return;`” with no argument.
- The new statement `assert(e)` is typed by

$$\frac{\Gamma \vdash e : \text{bool}}{\Gamma \vdash \text{assert}(e) \text{ valid}}$$

As you can probably observe, we have imported a lot of the non-uniform behavior of C to L3, especially with respect to name collisions and shadowing. It is plausible to handle these inconsistencies to varying extents in the elaborator and the type checker. You are free to make design decisions that suit your compiler. However, wherever you draw your module boundaries (if at all), think carefully about why your implementation is equivalent to this specification.

The static check that there is a `return` statement along every control flow path from the beginning of a function is similar to L2, except that we omit this check for functions returning `void`. The check that all local variables are defined before they are used also proceeds as in L2, where function parameters are considered *defined* at the beginning of the function body. This is because they will have values when the execution of the body of a function commences.

Now that we have function calls, we define `main` as an identifier with the special requirement that it can only be defined as a function with no parameters and the return type of `int`. Execution of an L3 program begins in the `main` function. Please refer to the section describing the runtime.

## 5 L3 Dynamic Semantics

The dynamic semantics directly extendeds that from L2.

Function calls  $f(e_1, \dots, e_n)$  are very similar to their counterparts in C with the following significant difference: they must evaluate their arguments from left to right before passing the resulting values to  $f$ . The same is true for other operators that evaluate their arguments. For example, in  $e_1 + e_2$ , we must evaluate  $e_1$  before  $e_2$ . Since L3 has several kinds of effects (arithmetic exception, nontermination, abort, and even output), this specification now becomes significant (when it was not observable in L2).

The new statement `assert( $e$ )` first evaluates  $e$ . If the result is `true`, the assertion succeeds and we just continue with the next statement. If  $e$  is false, it raises the `SIGABRT` exception (6). In your code you can achieve this by calling the function `abort()` which takes no arguments.

We also allow expressions to appear as statements, because we now have the concept of expressions with side-effects. These side-effects are quite simple in L3: arithmetic exceptions, program abort, nontermination, and output done by library functions. A memory reference error can also arise when a program runs out of stack space.

## 6 Project Requirements

For this project, you are required to hand in test cases and a complete working compiler for L3 that produces correct target programs written in Intel x86-64 assembly language.

We also require that you document your code. Documentation includes both inline documentation and a README document which explains the design decisions underlying the implementation along with the general layout of the sources. If you use publicly available libraries, you are required to indicate their use and source in the README file. If you are unsure whether it is appropriate to use external code, please discuss it with course staff.

When we grade your work, we will use the `gcc` compiler to assemble and link the code you generate into executables using the provided runtime environment on the lab machines.

Your compiler and test programs must be formatted and handed in via Autolab as specified below. For this project, you must also write and hand in at least 20 test programs, at least two of

which must fail to compile, at least two of which must generate a runtime exception, and at least two of which must execute correctly and return a value.

## Test Files

Test programs should have extension `.l3` and start with one of the following lines

<code>//test return <i>i</i></code>	program must execute correctly and return <i>i</i>
<code>//test exception <i>n</i></code>	program must compile but raise runtime exception <i>n</i>
<code>//test exception</code>	program must compile but raise <i>some</i> runtime exception
<code>//test error</code>	program must fail to compile due to an L3 source error

followed by the program text. In L3, the exceptions defined are `SIGABRT` (6), `SIGFPE` (8), `SIGALARM` (14). Note that infinitely recursing programs might also raise `SIGSEGV` (11) in case they run out of stack space before they run out of time. Best to avoid such tests, but if you have such a test is should only verify that *some* exception is raised.

Since the language now supports function calls, the runtime environment contains external functions providing output capabilities (see the runtime section for details). The testing framework may decide to take advantage of this. For a file `$test.l3`:

- If a file `$test.l3.out` exists *and the program returns*, the output of the program must be identical to the contents of the file for the test to pass.

Please use this capability sparingly, as the behavior of some library functions may be implementation dependent.

All test files should be collected into a directory `tests/` (containing no other files) and submitted via the Autolab server.

Now that the language we are compiling supports function calls, we would like some fraction of your test programs to compute “interesting” functions on specific values; please briefly describe such examples in a comment in the file. Disallowed are programs which compute Fibonacci numbers, factorials, greatest common divisors, and minor variants thereof. Please use your imagination. We will read your tests!

## Compiler Files

The files comprising the compiler itself should be collected in a directory `compiler/` which should contain a `Makefile`. **Important:** You should also update the `README` file and insert a description of your code and algorithms used at the beginning of this file. Even though your code will not be read for grading purposes, we may still read it to provide you feedback. The `README` will be crucial information for this purpose.

Issuing the shell command

```
% make l3c
```

should generate the appropriate files so that

```
% bin/l3c <args>
```

will run your L3 compiler. The command

```
% make clean
```

should remove all binaries, heaps, and other generated files.

## Runtime Environment

Your compiler should accept a command line argument `-l` which must be given the name of a file as an argument. For instance, we will be calling your compiler using the following command: `bin/l3c -l 15411.h0 $test.l3`. Here, `15411.h0` is the header file mentioned in the elaboration and static semantics sections.

The runtime for this lab contains functions to perform output. The output functions write to `stderr`, while the result of the program is printed to `stdout`. `15411.h0` contains a listing and a small amount of documentation.

The GNU compiler and linker will be used to link your assembly to the implementations of the external functions, so you need not worry much about the details of calling to external functions. You should ensure that the code you generate adheres to the C ABI for Linux on x86-64. In order for the linking to work, you must adhere to the following conventions

- External functions must be called as named.
- Non-external functions with name *name* must be called `_c0_name`. This ensures that non-external function names do not accidentally conflict with names from standard library which could cause assembly or linking to fail.
- Non-external functions must be exported from (declared to be *global* in) the assembly file you generate, so that our test harness can call them and verify your adherence to the calling conventions.

The runtime environment defines a function `main()` which calls a function `_c0_main()` your assembly code should provide and export. Your compiler will be tested in the standard Linux environment on the lab machines; the produced assembly must conform to this environment.

We suggest for booleans to be given an underlying 32 bit integer representation with `false` mapping to 0 and `true` mapping to 1. There might be occasion to reconsider the sizes of representations in Lab 4, but it should not affect this lab.

## Using the Subversion Repository

Handin and handout of material is via the course subversion repository.

The handout files for this course can be checked out from our subversion repository via

```
% svn checkout https://svn.concert.cs.cmu.edu/15411-f13/groups/<team>
```

where `<team>` is the name of your team. You will find materials for this lab in the `lab3` subdirectory. Or, if you have checked out `15411-f13/groups/<team>` directory before, you can issue the command `svn update` in that directory.

After adding and committing your handin directory to the repository with `svn add` and `svn commit` you can hand in your tests or compiler through Autolab.

```
https://autolab.cs.cmu.edu/15411-f13
```

Once logged into Autolab, navigate to the appropriate assignment and select

```
Checkout your work for credit
```



from the menu. It will perform one of

```
% svn checkout https://svn.concert.cs.cmu.edu/15411-f13/groups/<team>/lab3/tests
% svn checkout https://svn.concert.cs.cmu.edu/15411-f13/groups/<team>/lab3/compiler
```

to obtain the files directories to autograde, depending on whether you are handing in your test files or your compiler.

If you are submitting multiple versions, please remember to commit your changes to the repository before asking the Autolab server to grade them! And please do not include any compiled files or binaries in the repository!

## What to Turn In

Hand in on the Autolab server:

- At least 20 test cases, at least two of which generate an error, at least two of which raise a runtime exception, and at least two of which return a value. The directory `tests/` should only contain your test files and be submitted via subversion as described above. The server will test your test files and notify you if there is a discrepancy between your answer and the outcome of the reference implementation. You may hand in as many times as you like before the deadline without penalty. If you feel the reference implementation is in error, please notify the instructors on Piazza. The compiled binary for each test case should run in 5 seconds with the reference compiler on the lab machines; we will use a 5 second limit for testing compilers.

Test cases are due **11:59pm on Tuesday, October 8, 2013.**

- The complete compiler. The directory `compiler/` should contain only the sources for your compiler and be submitted via subversion. The Autolab server will build your compiler, run it on all extant test files, link the resulting assembly files against our runtime system (if compilation is successful), execute the binaries (each with a 5 second time limit), and finally compare the actual with the expected results. You may hand in as many times as you like before the deadline without penalty.

Compilers are due **11:59pm on Tuesday, October 15, 2013.**

## 7 Notes and Hints

### Elaboration

Please take the recommended elaboration strategy seriously. It significantly streamlines your compiler and reducing the amount of work you do in each remaining pass of a multi-pass compiler. Isolating elaboration also makes your source code more portable.

We again *highly* recommend using an explicit elaboration pass, rather than transforming source code on the fly during parsing. This will make the next lab a significantly smoother experience.

### Static Checking

The specification of static checking should be implemented on abstract syntax trees, translating the rules into code. You should take some care to produce useful error messages.

## Compiling Functions

It is not a strict requirement, but we recommend compiling functions completely independently from each other, taking care to respect the calling conventions but making no other assumptions. Interprocedural program analysis and optimization is difficult and, if you do it at all, is better left to a later lab.

## Calling Conventions

Your code must strictly adhere to the x86-64 calling conventions. Please refer to the course webpage for resources on the ABI and calling conventions. Two points of note: `%rsp` must be 16-byte aligned. GCC often ignores this rule when it isn't actively using floating point numbers, because the requirement is only consequential when the floating point stack is in use. Also, `%al` (the lowest 8 bits of `%rax`) is used as a hidden argument to specify the number of vector registers passed to certain functions.