

# **Divide and Conquer Optimization**

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- Compute and store all values of S(0,j) for all j such that  $0 \le j < N$ .
- Now you can compute S(i,j) = S(0,j) S(0,i-1) in constant time for any i and j.

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- Each jail cell is assigned to exactly one guard.
- Each guard can only watch over a contiguous range of prisoners.
- If the guard watching prisoner i is watching over k cells, then the prisoner's escaping potential is  $kS_i$ .
- Your goal is to assign the cells to guards in a way that minimizes the total escaping potential over all prisoners.

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- $\bullet$  Our state space is  $\mathcal{O}(NG)$  and each state can be computed in  $\mathcal{O}(N)$  time.
- Time complexity is  $\mathcal{O}(N^2G)$ , which is too slow.

#### Implementation - Initial Definitions

```
#include <bits/stdc++.h>
using namespace std;
typedef long long 11;
const 11 INF = 80'000'000'000'000'000LL:
ll arr[8000];
11 prefix_sum[8001];
ll mem[3001][8001];
ll range_sum(int left, int right) {
   return prefix_sum[right] - prefix_sum[left-1];
}
11 cost(ll left, ll right) {
   return range_sum(left, right) * (right - left + 1LL);
```

#### Naive Implementation - Computing Each Layer

### Naive Implementation - Main

```
int main()
{
    int n, g;
    cin >> n >> g;
    prefix_sum[0] = 0;
    for (int i = 0; i < n; i++) {
        cin >> arr[i];
        prefix_sum[i+1] = prefix_sum[i] + arr[i];
    for (int i = 0; i < n; i++) {
        mem[0][i] = cost(0, i);
    for (int guards = 2; guards <= g; guards++) {</pre>
        compute(guards - 1, n);
    cout << mem[g - 1][n - 1] << endl;
    return 0;
}
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- With that value in mind, compute dp(N/4, k) and dp(3N/4, k).

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- First compute dp(N/2, k) and note the value of opt(N/2, k).
- With that value in mind, compute dp(N/4, k) and dp(3N/4, k).
- Repeat this process, computing the left and right side, tracking the minimum and maximum possible value of  $\operatorname{opt}(j,k)$ .

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- At each level we will do  $\mathcal{O}(N)$  work, since there is no overlap for values of j at the same level.
- Note it does not matter how balanced  ${\rm opt}(j,k)$  is, we always do linear work at a level.
- Time complexity is now  $\mathcal{O}(NG \log N)$ , so fast enough.

#### Optimized Implementation - Computing Each Layer

```
void compute(int level, int l, int r, int optl, int optr) {
    if (1 > r) return;
    int mid = (1+r)/2;
    pair<11, int> best = {INF, -1};
    for (int k = optl; k <= min(mid, optr); k++) {</pre>
        best = min(best.
            \{(k ? mem[level - 1][k - 1] : OLL) + cost(k, mid), k\});
    mem[level][mid] = best.first;
    int opt = best.second;
    compute(level, 1, mid-1, optl, opt);
    compute(level, mid+1, r, opt, optr);
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#### Optimized Implementation - Main

```
int main()
{
    int n, g;
    cin >> n >> g;
    prefix_sum[0] = 0;
    for (int i = 0; i < n; i++) {
        cin >> arr[i];
        prefix_sum[i+1] = prefix_sum[i] + arr[i];
    for (int i = 0; i < n; i++) {
        mem[0][i] = cost(0, i);
    for (int guards = 2; guards <= g; guards++) {</pre>
        compute(guards-1, 0, n-1, 0, n-1);
    cout << mem[g-1][n-1] << endl;
    return 0;
}
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- It is usually not that difficult to prove the quadrangle inequality holds when it does.
- Once you've proven it for a DP pattern like shown before, you know you can use this method.
- The Convex Hull Trick can often be used in the same tasks to which this method applies.

# Try on these problems!

- Guards
- Split the Sequences
- Partition Game
- The Bakery