(weak A.I.) M2 (went 42) Reciforement: Supervise 2 Unsupervixe Learning to perform ig classify photos w two focus; ig: face Detection odertification actions in an environment without explicit labbush of number, arenal eg: self-drives can E-commerce-classify Computer Games, etc. Measuring At - Turing Test Robotin. ML initially storted as a quest for AI & minicking borain dynamics, but has now evolved to solving practical poroblem wing algos which have little er no resemblance to brains. Hem or MCH or AI 4 ML j'ust have an overlap. De hate: Goal of ML > Generalisation of learning to new f

whow datasets of scenarios (Ah I).

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Priar-Variance Tradeoff Decomposition - pre-trained

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entirely and learning best way to estimate generalisation error. after requires L'andred & Drian: wrong assumption about training data (underfitting) Variance: High sensitivity to small fluctuation of random raise. (ting overfitting) 7: Learned function y= f(n) + E / : L)

L> Return function. E: Zero mean Bian = ES[] - f 62 variance. Variance = ED[(ED[]) -]] unseen sample: Expected Error Bean + van + 52 van of your e

Supervised Learning: Regression vs. Classification ML is another form of every curve fitting, or function approprintation, but where the functional form of the curve is not explicitly obvious.

[not binary but gray scale] Linear legression --> Linear classification Models sum] Reposition Non-linear classification models Decision (SVM with Kernels), Decision (SVM with Kernels) ANN -> Deep Learning. Model encompassing a broad family of functions of charging parameters helps in navigating this set of functions. Learning = Training + Testing Generalisation overfitting: Low than 4 High Variance

Low training training the fitting fluke

we regularisation

High

Hig Testing Formar Low Underfitting: High frian variance overfitting sdeal Good fit - Naire Bayer's Bayer optimal classifier Manimum propability - Marymum Likelilood Estimator 9 - K- reaves & Neighbours - ANNs. - Linear Regression

- Logistic Regression

- Suppost Vector Machines

- Decision trees

New Print of the

Measure distance from K- rearest preighbours & classify based on najority rule.

Currer of Dinessionality

Consider a D-dimensional unit embe. of we want to do owr KNN estimate based on a traction, t, of date points, we need to take a culs around our test point of edge size, $e_{D}(t) = f'D$

D=3 >> eol#)2 0.215 of f= 1%=:0.01, D=10 => G(A)= 0.63 -> very large D=100 -> ep(A)=0.96 | culse!!

Blessing of Dimersionality 96 Signal to Noise radio is Wigh. High Dimersional date has can have very idercesting & geometric properties which could be emploited for improving Recurracy
Precision =

TP

TP + FP

TP + FP

Recurracy
Precision =

TP

TP + FP

TP + FN

True Positive Rate

Specificity =

TN + FP

TN + FP

TN - True Regative

Rate

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