

Atmadeep Arya

Masters in Computer Sciences with focus on Computer Vision

Dedicated to field of autonomous machines and computer vision.

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EDUCATION

Integrated M.Tech in computer science Central University of Karnataka

07/2015 - 07/2020

8.53

WORK EXPERIENCE

Machine Learning Engineer Bitsilica Pvt Ltd

02/2021 - 04/2021 VLSI and Edge computing startup Hyderabd, Telangana

Achievements/Tasks

- Worked on Applications related to customer face detection and matching using Dlib, opency and django. Converted the app from flask to django.
- Worked on traffic management solution using opency and parallel processing concepts in python.

Contact: Mohd. M. Babji - linkedin.com/in/mdbabji

IEEE Creative Learning chair

IEEE Student branch, Central University of Karnataka

01/2018 - 12/2020

Kalaburagi, Karnataka

Achievements/Tasks

 Conducted various workshops and seminars on topics related to meta learning and interdisciplinary domains

Contact: Sneha Chandran ,SB executive chair, CUK

Image processing Intern Avian Aerospace Pvt Ltd

12/2017 - 03/2018

Bangalore, Karnataka

Achievements/Tasks

- Worked on image processing using opency 3.x and python to extract information related to potholes on various terrains
- Wrote an algorithm for algae detection for underwater ROV

Candidate Volunteer

Harbortech Pvt Ltd, Mumbai

10/2016

Achievements/Tasks

- Volunteered for workshop on android app development and aerial robotics workshop
- Was selected for national level competition held at IIT Kharagpur

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10/2017

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- Volunteered for workshop on android app development and aerial robotics workshop
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SKILLS

Javascript Django 3 Flask C++ 14 Python 3.x

Tensorflow 2.x OpenCV 4.x Linux LaTeX

Jupyter Git Github

PERSONAL AND ACADEMIC PROJECTS

Prototype of a research quad-copter (04/2020 - 10/2020)

 Selected for IEEE SHTPF (financial grant) for year 2020. Proposed a hardware and software stack useful for research in various domains related to MAVs

Master's thesis: Deep learning based navigation for aerial robots (08/2019 - 04/2020)

 Built a CNN with < 1M trainable parameters for MAVs equipped with an onboard SBC.

Inertial methods for navigation of aerial robots (05/2019 - 07/2019)

 Did a study on geometric vision navigation algorithms coupled with inertial sensor values suitable for indoor navigation for MAVs

Bachelor's thesis: 3D vision based methods for navigation of aerial robots. (01/2019 - 04/2019)

 Did a study geometric vision based navigation method suitable for indoor environments for MAVs.

Surveillance copter for campus safety (05/2018 - 07/2018)

 Trained YOLOv3 on custom vehicle classes from Indian vehicle domain for campus traffic detection

ORGANIZATIONS

Avian Aerospace (12/2017 - 02/2018)

Computer vision and robotics intern.

CERTIFICATES

Certificate Name

LANGUAGES

Full Professional Proficiency

English

Full Professional Proficiency

INTERESTS

Autonomous aerial robots

Computer vision

Deep learning

Machine learning