

0.MARKDOWN_TEMPLATE

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色

Red

```
<font color="red">Red</font>
```

blue

```
<font color="blue">blue</font>
```

green

```
<font color="green">green</font>
```

darkPink

```
<font color="darpink">darkPink</font>
```

数式

ギリシャ文字

α : \alpha

ϵ : \epsilon

分数

$$\frac{A}{B}$$

```
\begin{eqnarray}
\frac{A}{B}
\end{eqnarray}
```

微分

$$\frac{\partial y}{\partial x}$$

```
\begin{eqnarray}
\frac{\partial y}{\partial x}
\end{eqnarray}
```

$$\frac{dy}{dx}$$

```
\begin{eqnarray}
\frac{d y}{d x}
\end{eqnarray}
```

積分

$$\overline{A} := \frac{1}{L} \int_0^L A dx$$

```
\begin{eqnarray}
\overline{A} := \frac{1}{L} \int_0^L A dx
\end{eqnarray}
```

$$\text{IVT} := \int_{p_s}^{100hPa} u q_v dp \tag{1}$$

```

\begin{eqnarray}
\text{IVT}:=\int_{p_s}^{100\text{ hPa}} u\,q_v\,dp
\end{eqnarray}
\tag{1}

```

アンダーブレース

$$\underbrace{A}_{\text{実際の値}} = \underbrace{\overline{A}}_{\text{平均}} + \underbrace{A'}_{\text{偏差}}$$

```

\begin{eqnarray}
\underbrace{A}_{\text{実際の値}}=\underbrace{\overline{A}}_{\text{平均}}+\underbrace{A'}_{\text{偏差}}
\end{eqnarray}

```

行列

$$\begin{pmatrix} a & b \\ c & d \end{pmatrix}$$

```

\begin{pmatrix}
a & b \\
c & d
\end{pmatrix}

```

$$A = \begin{bmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{2n} \\ \vdots & \vdots & & \vdots \\ a_{m1} & a_{m2} & \cdots & a_{mn} \end{bmatrix}$$

```

A=
\begin{bmatrix}
a_{11} & a_{12} & \cdots & a_{1n} \\
a_{21} & a_{22} & \cdots & a_{2n} \\
\vdots & \vdots & & \vdots \\
a_{m1} & a_{m2} & \cdots & a_{mn}
\end{bmatrix}

```

<https://mathlandscape.com/latex-matrix/>

$$\left. \begin{bmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{n1} & a_{n2} & \cdots & a_{nn} \end{bmatrix} \right\} = n\text{個}$$

```

\begin{eqnarray}
\left.
\begin{bmatrix}
a_{11} & a_{12} & \dots & a_{1n} \\
a_{21} & a_{22} & \dots & a_{2n} \\
\vdots & \vdots & \ddots & \vdots \\
a_{n1} & a_{n2} & \dots & a_{nn}
\end{bmatrix}
\right.
= n\text{個}
\end{eqnarray}

```

<http://xyoshiki.web.fc2.com/tex/form0121.html>

$$\mathbf{e}_1 := \left[\begin{array}{c} 1 \\ 0 \\ \vdots \\ 0 \end{array} \right] = n\text{個}$$

```

\mathbf{e}_1:=
\left.
\begin{bmatrix}
1 \\
0 \\
\vdots \\
0
\end{bmatrix}
\right.
= n\text{個}

```

$$A = (a_{ij})_{m \times n} = \underbrace{\left[\begin{array}{cccc} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{m1} & a_{m2} & \dots & a_{mn} \end{array} \right]}_{n \text{ columns}} \left. \vphantom{\left[\begin{array}{cccc} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{m1} & a_{m2} & \dots & a_{mn} \end{array} \right]} \right\} m \text{ rows}$$

```

\begin{equation*}
% a disposable command for avoiding repetitions
\newcommand{\zm}{%
\begin{bmatrix}
a_{11} & a_{12} & \dots & a_{1n} \\
a_{21} & a_{22} & \dots & a_{2n} \\
\vdots & \vdots & \ddots & \vdots \\
a_{m1} & a_{m2} & \dots & a_{mn}
\end{bmatrix}
}
A=\underset{m \times n}{(a_{ij})}=
\left.
\right., \smash[b]{\underbrace{\!\!\zm\!}_{\textstyle n \text{ columns}}},
\right\} m \text{ rows}
\vphantom{\underbrace{\zm}_{\textstyle n \text{ columns}}}

```

```
\end{equation*}
```

<https://tex.stackexchange.com/questions/644625/how-can-i-have-both-horizontal-and-vertical-curl-y-braces-in-a-matrix>

$$\begin{bmatrix} \sigma_1 & 0 & \dots & 0 & \dots & 0 \\ 0 & \sigma_2 & \dots & 0 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots & \ddots & \vdots \\ 0 & \dots & \dots & \sigma_N & \dots & 0 \\ 0 & 0 & \dots & 0 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots & \dots & \vdots \\ 0 & 0 & \dots & 0 & \dots & 0 \end{bmatrix}$$

```
\begin{eqnarray}
\begin{bmatrix}
\begin{array}{cccc}
\sigma_1 & 0 & \dots & 0 & \dots & 0 \\
0 & \sigma_2 & \dots & 0 & \dots & 0 \\
\vdots & \vdots & \ddots & \vdots & \ddots & \vdots \\
0 & \dots & \dots & \sigma_N & \dots & 0 \\
0 & 0 & \dots & 0 & \dots & 0 \\
\vdots & \vdots & \ddots & \vdots & \dots & \vdots \\
0 & 0 & \dots & 0 & \dots & 0
\end{array}
\end{bmatrix}
\end{eqnarray}
```

連立方程式

$$\begin{cases} x = a + b \\ y = c + d \end{cases}$$

```
\left\{
\begin{align*}
x &= a + b \\
y &= c + d
\end{align*}
\right.
```

運動方程式

$$m \frac{d\mathbf{v}}{dt} = \mathbf{F}$$

```
\begin{eqnarray}
m \frac{d \mathbf{v}}{dt} = \mathbf{F}
\end{eqnarray}
```

$$\begin{aligned}\rho \frac{du}{dt} &= F_x \\ \rho \frac{dv}{dt} &= F_y \\ \rho \frac{dw}{dt} &= F_z\end{aligned}\tag{1}$$

```
\begin{eqnarray}
\rho \frac{du}{dt} &=& F_x \\ \rho \frac{dv}{dt} &=& F_y \\ \rho \frac{dw}{dt} &=& F_z \\ \end{eqnarray} \tag{1}
```

ブリュームモデル

$$w_c \frac{\partial s_c}{\partial z} = L_v c - \epsilon W_c (s_c - s_e) \tag{1}$$

$$w_c \frac{\partial q_{v,c}}{\partial z} = c - \epsilon W_c (s_{v,c} - s_{v,e}) \tag{2}$$

$$w_c \frac{\partial q_{l,c}}{\partial z} = c - G \epsilon - W_c q_{l,c} \tag{3}$$

```
\begin{eqnarray}
w_c \frac{\partial s_c}{\partial z} &=& L_v c - \epsilon W_c (s_c - s_e) \tag{1} \\ w_c \frac{\partial q_{v,c}}{\partial z} &=& c - \epsilon W_c (s_{v,c} - s_{v,e}) \tag{2} \\ w_c \frac{\partial q_{l,c}}{\partial z} &=& c - G \epsilon - W_c q_{l,c} \tag{3} \\ \end{eqnarray}
```

収支式

$$d \left(\frac{\partial h_b}{\partial t} + \mathbf{V}_h \cdot \nabla h_b \right) = F_h - (M_d + w_e)(h_b - h_m) - \dot{Q}_b d \tag{2}$$

```
\begin{eqnarray}
d \bigg( \frac{\partial h_b}{\partial t} + \mathbf{V}_h \cdot \nabla h_b \bigg) &=& F_h - (M_d + w_e)(h_b - h_m) - \dot{Q}_b d \\ \end{eqnarray} \tag{2}
```

Q1, Q2 of Yanai et al. (1973)

$$Q_1 := -\frac{\partial \overline{q''\omega''}}{\partial p} + Q_R - L(c - e) \quad \left(= \frac{\partial \bar{q}}{\partial t} + \nabla \cdot \overline{s\mathbf{v}} + \frac{\partial \overline{s\omega}}{\partial p} \right) \quad (1)$$

```
\begin{eqnarray}
Q_1:=-\frac{\partial \overline{q'' \omega''}}{\partial p}+Q_R-L(c-e) \quad \text{quad} \quad \text{bigg}(=
\frac{\partial \overline{q}}{\partial t}+\nabla \cdot \overline{s \mathbf{v}}+\frac{\partial \overline{s \omega}}{\partial p} \quad \text{bigg})
\tag{1}
\end{eqnarray}
```

$$Q_2 := L\frac{\partial \overline{q''\omega''}}{\partial p} + L(c - e) \quad \left(= -L\left[\frac{\partial \bar{q}}{\partial t} + \nabla \cdot \overline{q\mathbf{v}} + \frac{\partial \overline{q\omega}}{\partial p}\right] \right) \quad (2)$$

```
\begin{eqnarray}
Q_2:=L\frac{\partial \overline{q'' \omega''}}{\partial p}+L(c-e) \quad \text{quad} \quad \text{bigg}(= -
L\text{bigg}[\frac{\partial \overline{q}}{\partial t}+\nabla \cdot \overline{q \mathbf{v}}+\frac{\partial \overline{q \omega}}{\partial p}
\text{bigg}]\text{bigg})
\tag{2}
\end{eqnarray}
```

移流項

$$u\frac{\partial u}{\partial x} + v\frac{\partial u}{\partial y} = \frac{\partial(uu)}{\partial x} + \frac{\partial(uv)}{\partial y} \quad (3)$$

```
\begin{eqnarray}
u\frac{\partial u}{\partial x}+v\frac{\partial u}{\partial y}
=\frac{\partial (uu)}{\partial x}+\frac{\partial (uv)}{\partial y}\\
\end{eqnarray}
\tag{3}
```

温度風

$$fu = -\partial\phi/\partial y$$

```
fu=-\partial \phi / \partial y
```

$$dp = -\rho g dz$$

```
dp=-\rho g dz
```

$$\partial\phi/\partial p = -\alpha$$

```
\partial \phi/\partial p=-\alpha
```

$$f\frac{\partial u}{\partial p}=-\frac{\partial}{\partial y}\left(\frac{\partial \phi}{\partial p}\right)=\frac{\partial \alpha}{\partial y}$$

```
\begin{eqnarray}
f\frac{\partial u}{\partial p}=-\frac{\partial}{\partial y}\bigg(\frac{\partial \phi}{\partial p}\bigg)=\frac{\partial \alpha}{\partial y}
\end{eqnarray}
```

$y = a\phi$ を用いると,

$$\frac{\partial u}{\partial p} = \frac{1}{af} \frac{\partial \alpha}{\partial \phi}$$

```
\begin{eqnarray}
\frac{\partial u}{\partial p}=\frac{1}{af}\frac{\partial \alpha}{\partial \phi}
\end{eqnarray}
```

レイアウト

改行

```
<\br >
```

改ページ

```
<div class="page-break"></div>
```