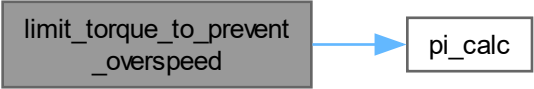


limit\_torque\_to\_prevent  
\_overspeed



```
graph LR; A[limit_torque_to_prevent_overspeed] --> B[pi_calc]
```

pi\_calc