

# **Detector construction**

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Getting Started with Geant4 at CERN, Geneva (Switzerland)





- Material definition
  - The Geant4 material model
  - Material definition
  - The NIST material data base
- Geometry definition
  - The Geant4 geometry description
  - Solid, Logical , Physical volume





## Material definition

## THE GEANT4 MATERIAL MODEL





- The Geant4 material model follows the natural one: materials are made of elements and elements are made of isotopes
- The 3 main classes to describe these objects are
  - G4Isotope: describes the properties of atoms (Z atomic number, N number of nucleons and A molar mass) with unique name and index
  - **G4Element**: describes the properties of elements (Z effective atomic number, N effective number of nucleons and A effective molar mass, number of isotopes, etc.) with unique name, symbol and index
  - G4Material: describes the macroscopic properties of matter (density, state, temperature, pressure, etc.) with unique name and index
- Unique index: a pointer to the created object is automatically stored in global table (isotope, element and material tables)





- The material density must be set (> zero) by the user at definition (except NIST materials)!
- The material temperature and pressure can optionally be set:
  - default: Normal Temperature and Pressure(NTP) 293.15 [k], 1
     [atm] = 101.325 [kPascal]
- The material state can be solid, liquid or gas:
  - default is either solid or gas depending on the density (kGasThreshold = 10 [mg/cm³])
  - non-crystalline (i.e. amorphous) solid by default (special extension for incorporating some information on the crystal structure)
- Special set of pre-defined materials: NIST material composition data base with some frequently used HEP materials
- Geant4 material documentation: Material Documentation





## Material definition

# **MATERIAL DEFINITION**





- Elements and isotopes:
  - G4Element object without specifying the isotope composition:

```
// simple way of Carbon element definition
G4Element* elC = new G4Element(name="Carbon", symbol="C", z = 6., a = 12.01*g/mole)
```

- need to give: name, symbol, Z and A (effective atomic number and molar mass)
- isotopes will be automatically added with natural abundances (A won't be updated)
- G4Element object by specific (non-natural) isotope composition:

```
// Define "enriched uranium" element as 90 % of U235 and 10 % of U 238:
//
// create the isotopes: iz = number of protons and n = number of nucleons
G4Isotope* U5 = new G4Isotope(name="U235", iz=92, n=235);
G4Isotope* U8 = new G4Isotope(name="U238", iz=92, n=238);
// create the element and build up by adding the isotopes with their abundance
G4Element* elU=new G4Element(name="enriched uranium",symbol="U",numisotopes=2);
elU->AddIsotope(U5, abundance= 90.*perCent);
elU->AddIsotope(U8, abundance= 10.*perCent);
```

- element object must be created: name, symbol, number of isotopes
- isotope objects must be created: name, number of protons and nucleons
- isotopes need to be added by their relative abundance





- Simple G4Material object definition:
  - "simple": the material contains only one element and the corresponding G4Element object is not provided:

- the corresponding G4Element object will be automatically created (with natural isotope abundance)
- need to give: name, density of the material, Z and A (effective atomic number and molar mass) of the single G4Element
- what happens if we want the single element to have non-natural isotope abundance e.g. the previously created enriched uranium (see later)





- G4Material object definition as chemical molecule:
  - molecules build up from (several) elements with composition specified by the number of element (e.g. water = H<sub>2</sub>O)
  - accordingly, G4Material object can be created by adding G4Element objects to it together with their composition number:

```
// Create water material as molecule based on its chemical formula (H2O)
// create the necessary H and O elements (natural isotope abundance):
G4Element* elH = new G4Element(name
                                       = "Hydrogen",
                                symbol = "H",
                                       = 1.00.
                                      = 1.01 * q/mole);
                                      = "0xygen",
G4Element* el0 = new G4Element(name
                                symbol = "0",
                                       = 8.00
                                       = 16.00 * q/mole);
// create the water material (name, density, number of components):
G4Material* matH20 = new G4Material(name
                                                = "Water",
                                    density
                                                = 1.0 * g/cm3,
                                    ncomponents = 2);
// add the elements to the material with their composition number
```





- G4Material object definition as mixture:
  - mixture of elements (G4Element), mixture of other materials
     (G4Material) or even mixture of elements and materials
  - similar to molecules with the differences:
    - components can be other materials not only elements
    - the ratio of the components must be given as "fractional mass" not as "number of atoms"
  - mixture of elements example: using the AddElement method



- G4Material object definition as mixture:
  - mixture of element(s) and material(s) example: using the AddElement and AddMaterial methods





## Material definition

## THE NIST MATERIAL DATA BASE





- The data base includes more than 3000 isotopes
- Isotopic composition of elements (Z = [1-108]) with their natural isotopic abundance: using the NIST Atomic Weights and Isotopic Compositions data base
- NIST elements can be obtained easily from the Geant4 NIST data base by using their symbol or Z atomic number:
  - the corresponding G4Isotope objects will be automatically built

```
- "find or build" i.e. avoids duplication of element objects

// get the carbon G4Element object from the NIST data base; by its symbol

G4Element* elC = G4NistManager::Instance()- FindOrBuildElement("C");

// get the silicon G4Element object from the NIST data base; by its Z

G4Element* elSi = G4NistManager::Instance()->FindOrBuildElement(14);
```

- Large collection of pre-defined materials:
  - pre-defined: density, elemental composition (with the pre-defined natural isotopic composition), mean ionization energy, density effect parameters, etc.





- Use these pre-defined materials whenever possible:
  - guaranties high accuracy for many derived parameters (consistency)
- NIST and more pre-defined materials (318 at the moment):
  - **single element NIST** materials with Z = [1-98] and named after the atomic symbol:
    - aluminum ("G4\_A1"), silicon ("G4\_Si"), gold ("G4\_Au"), etc.
  - compound NIST materials:
    - "G4 AIR", "G4 ALUMINUM OXIDE", "G4 MUSCLE SKELETAL ICRP", etc.
  - **HEP** and nuclear materials:
    - liquid argon "G4 lAr", lead tungstate "G4 PbWO4", "G4 STAINLESS-STEEL", etc.
  - **space** materials:
    - "G4 KEVLAR", "G4 NEOPRENE", etc.
  - **bio-chemical** materials:
    - the DNA bases "G4\_ADENINE", "G4\_GUANINE", "G4\_CYTOSINE", "G4\_THYMINE", etc.





- How to access these pre-define materials:
  - can be obtained from the Geant4 NIST data base by using their name
  - their name starts with the "G4" prefix (see in the previous

```
// Use the NIST data base to get predefined materials: carbon, silicon
//
// get the simple pre-defined carbon material from the NIST data base
G4Material* matC = G4NistManager::Instance() >FindOrBuildMaterial("G4_C");
// get the simple pre-defined silicon material from the NIST data base
G4Material* matSi = G4NistManager::Instance()->FindOrBuildMaterial("G4_Si");
```

```
// Use the NIST data base to get pre-defined materials:
//
// get the NIST manager (just to simplify)
G4NISTManager* nistMGR = G4NistManager::Instance();
// get the pre-defined liquid argon ("G4 [Ar") from the NIST DB
G4Material* matLAr = nistMGR->FindOrBuildMaterial("G4_lAr");
// get the pre-defined concerete ("G4_CONCRETE") from the NIST DB
G4Material* matConcr = nistMGR->FindOrBuildMaterial("G4_CONCRETE");
```





- List available pre-define NIST elements, materials from the data base with their composition:
  - user interface command:
    - o /material/nist/printElement <SYMBOL>
    - o /material/nist/listMaterials <CATEGORY>
  - directly from C++ code:

```
// List the pre-defined NIST ELEMENT(S) with its(their) isotope composition:
//
// element name can be: the element SYMBOL i.e. "Al" or "all"
const G4String nistElementName = "Al";
G4NistManager::Instance()->PrintElement(nistElementName);
//
// List the pre-defined NIST MATERIALS with their element composition:
//
// category name can be: "simple", "compound", "hep", "space", "bio", "all"
const G4String nistMatCategoryName = "simple";
G4NistManager::Instance()->ListMaterials(nistMatCategoryName);
```





- List available pre-define NIST elements, materials from the data base with their composition:
  - user interface command:

\_ /matarial/nigt/nrintFlamant < GVMROT.>

# We will keep it simple and use <a href="NIST materials">NIST materials</a> in our application <a href="Try">Try these out with the simple main that we wrote to check the installation!





# THE GEANT4 GEOMETRY DESCRIPTION





- Geant4 detector geometry description is composed of three conceptual layers: Solid, Logical-Volume, Physical-Volume
- users need to construct them directly in their user code
   (Detector Construction) by "new", they get registered at
   construction in the corresponding store (G4SolidStore,
   G4LogicalVolumeStore, G4PhysicalVolumeStore) which
   will take care of deallocation of the corresponding memory at the
   end (if needed)
- geometry description can be rather complex but we will keep it simple now and focus only on the parts that we need
- more information on the detector geometry description can be found in the corresponding documentation: Detector Geometry





# **SOLID**





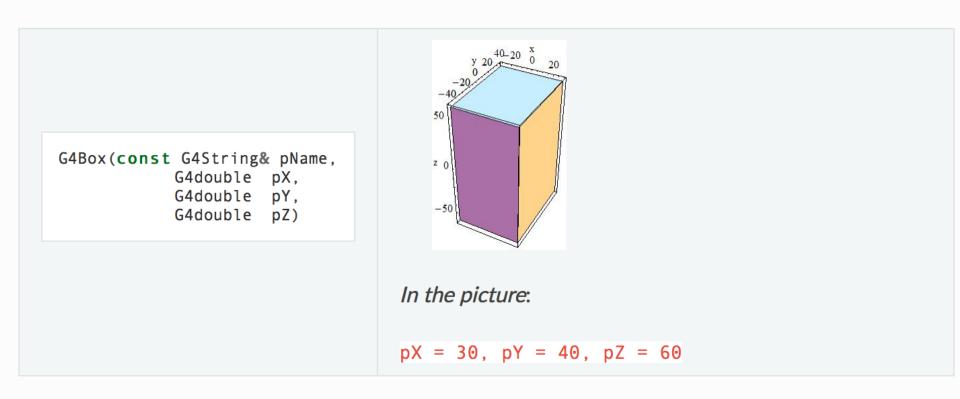
#### G4VSolid:

- the shape of the Geant4 detector geometry builds up from geometrical primitives, all derived from the G4VSolid base class that provides interface to:
  - compute distances between the shape and a given point
  - check whether a point is inside the shape
  - compute the extent of the shape
  - compute the surface normal to the shape at a given point
- Geant4 makes use of Constructed Solid Geometry (CSG) to define these geometrical primitives: G4Box, G4Tubes, G4Trd, G4Para, G4Trap, G4Torus, etc.. (special CSG-like solids e.g. G4Polycone, G4Polyhedra, G4Ellipsoid, etc., tessellated and boolean solids are also available. See the Geometry: Solids documentation).
- these three-dimensional primitives described by a minimal set of parameter to define the dimensions of the corresponding solid e.g. G4Box
- these implement the G4VSolid base class interface methods



#### Box:

To create a **box** one can use the constructor:



by giving the box a name and its half-lengths along the X, Y and Z axis:

pX	half length in X	pY	half length in Y	pΖ	half length in Z
----	------------------	----	------------------	----	------------------

This will create a box that extends from -pX to +pX in X, from -pY to +pY in Y, and from -pZ to +pZ in Z.

Box:

To create a **box** one can use the constructor:

```
50
    G4Box(const G4String& pName,
                                   z 0
              G4double pX,
              G4double pY.
              G4double pZ)
// create solid (box) for the target
G4Box* targetSolid = new G4Box("solid-Target", // name
                                  0.5*targetXSize, // half x-size
                                  0.5*targetYZSize, // half y-size
                                  0.5*targetYZSize); // half z-size
```

by giving the box a name and its half-lengths along the X, Y and Z axis:

pX half length in X pY half len	gth in Y pZ half length in Z
---------------------------------	------------------------------

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# **LOGICAL VOLUME**





#### G4LogicalVolumne:

- encapsulates all information of a detector volume element except its real physical position (position and rotation):
  - the **shape** and dimensions of the volume i.e. a **G4VSolid**
  - the material of the volume i.e. G4Material that is the minimally required additional information beyond the solid
  - additional, optional information such as magnetic field (G4FieldManager) or user defined limits (G4UserLimits), etc.
- it's NOT a base class! Its constructor:

```
G4LogicalVolume( G4VSolid* pSolid, // its Solid G4Material* pMaterial, // its Material const G4String& Name, // its Name G4FieldManager* pFieldMgr=0, G4VSensitiveDetector* pSDetector=0, G4UserLimits* pULimits=0, G4bool Optimise=true)
```





### G4LogicalVolumne:

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```

see the Geometry: Logical Volumes documentation





# **PHYSICAL VOLUME**





## G4VPhysicalVolume:

- the abstract base class for representation of physically positioned volumes
- a volume is positioned in a mother volume relative to its coordinate system
- the positioning can be:
  - placement volume: one positioned volume, i.e. one G4VPhysicalVolume object
     represents one "real" volume
  - repeated volume: one volume positioned many times, i.e. one
     G4VPhysicalVolume object represents multiple copies of "real" volumes
     (reduces memory by exploiting symmetry)
    - Replica volumes: the multiple copies of the volume are all identical
    - Parameterised volumes: the multiple copies of a volume can be different in size, solid type, or material that can all be parameterised as a function of the copy number
- we will have a look only to the placement but see all at the Geometry:
   Physical Volume documentation





## G4VPhysicalVolume - G4PVPlacement:

- represent one positioned G4LogicalVolume
- created by associating a G4LogicalVolume with a Transformation that defines the position of the volume in the mother volume
- the **Transformation** can be given either as a single **G4Transform3d** object or as combination of rotation **G4RotationMatrix** and translation **G4ThreeVector**
- a mother volume must be specified for all volumes except the "world"
- (one of the two) constructor with the rotation matrix and translation vector:

```
G4PVPlacement(
                    G4RotationMatrix*
                                                       // rot.-matrix
                                       pRot,
                                                       // translation
              const G4ThreeVector&
                                      tlate,
                    G4LogicalVolume*
                                      pCurrentLogical, // logical volume
              const G4String&
                                                       // name
                                      pName,
                    G4LogicalVolume*
                                      pMotherLogical,
                                                       // mother logical volume
                    G4bool
                                      pMany,
                    G4int
                                       pCopyNo,
                                                       // unique identifier
                                       pSurfChk=false ) // check overlap ?
                    G4bool
```



Everything has shown that is necessary to write YourDetectorConstruction

# START TO DEVELOP OUR APPLICATION

