

Visualization

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Getting Started with **Geant4** at CERN, Geneva (Switzerland)

- What can be visualized?
- Type of visualization drivers
- Qt GUI with OpenGL driver

Visualization

WHAT CAN BE VISUALIZED?

- **Simulation data:**
 - geometrical components, detector, simulation set-up
 - particle trajectories and their tracking steps
 - hits of particles in the geometry or
 - quantities like energy deposit, dose, etc.
- **User defined objects** (not directly related to the simulation itself):
 - polylines (connected lines as an object): e.g. coordinate axes
 - 3D markers: e.g. eye guides
 - text:
 - descriptive character strings (e.g. some dynamic properties during tracking)
 - comments or titles
- **Geant4 visualization documentation:** [Visualization Documentation](#)

Visualization

TYPE OF VISUALIZATION DRIVERS

A variety of choices depending on the requirements:

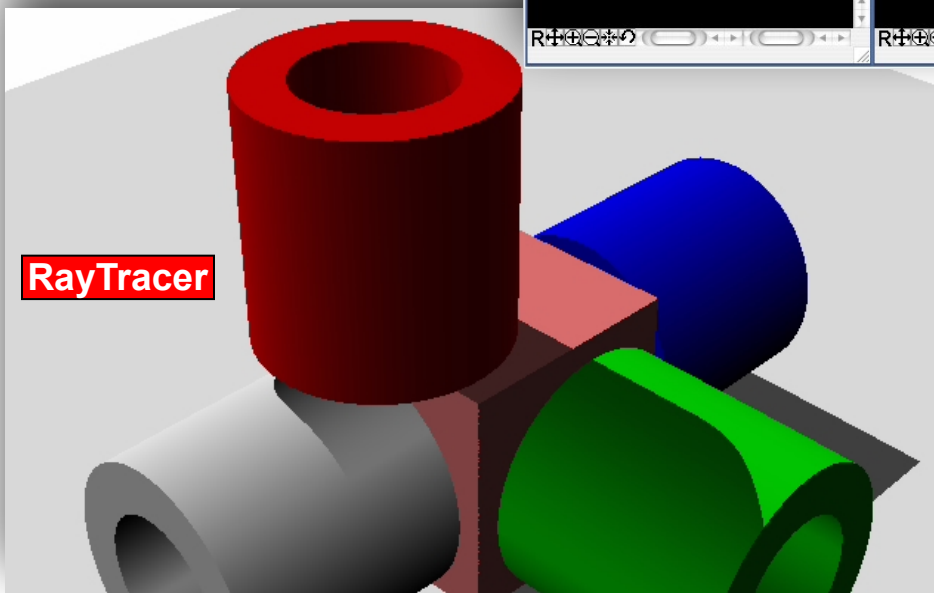
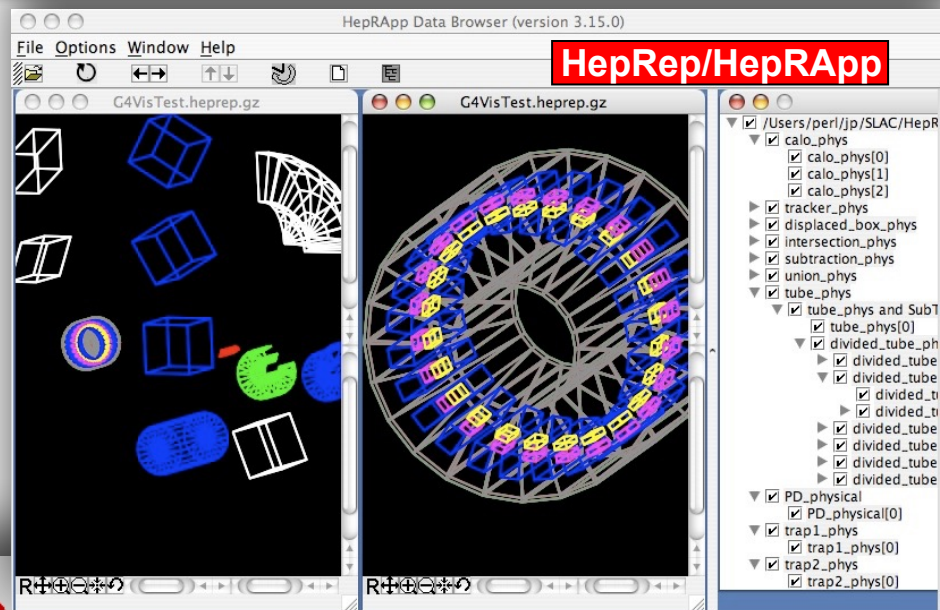
Driver	Variant	Hight quality print	Interactive	browse geometry hierarchies	Direct access to G4 kernel	Make movies	Web
OpenGL	X						
	Xm						
	Qt						
	Win32						
OpenInventor	Xt						
	Win32						
DAWN							
VRML							
HepRep							
gMocren							
RayTracer							
ACSII File							

Comput. Phys. Comm. 178 (2008) 331-365

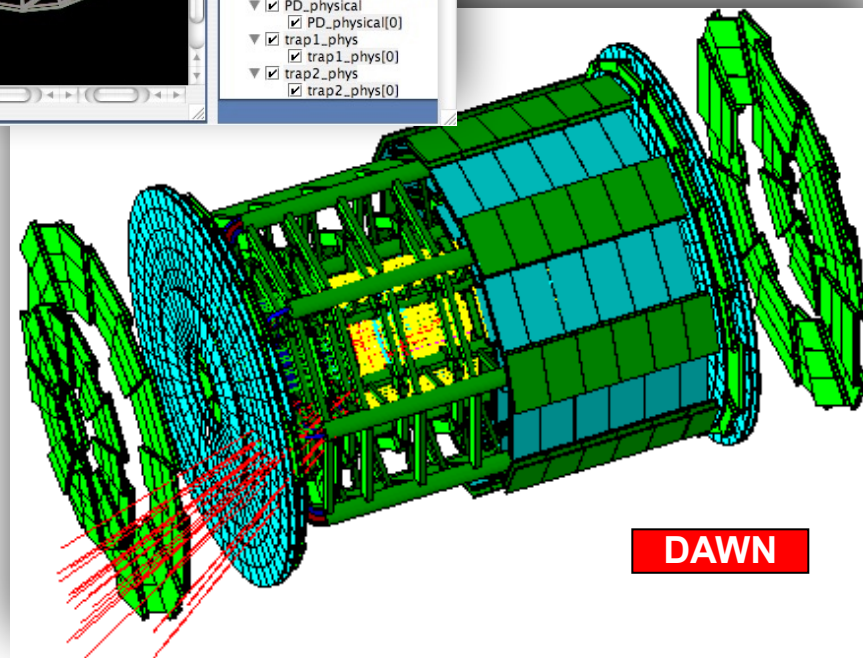
- From **controlling** point of view:
 - some visualization drivers work **directly from Geant4**:
 - OpenGL, OpenInventor, RayTracer, ASCII Tree
 - for other visualization drivers, **a (special) file must be first produced by Geant4** then this file will be **rendered by another application**:
 - HepRep, DAWN, VRML, gMocren
- The **Geant4** code stays basically the same independently from the choice of the driver
- Visualization is performed either with commands or from C++ code
 - for the present tutorial, we confine ourselves to **command-driven** visualization (both in interactive and batch modes)

- Availability of drives:
 - six of the visualization drivers are always included by default (since they require no external libraries):
 - RayTracer, ASCII Tree, HepRep, DAWN, VRML, gMocren
 - other visualization drives (e.g. OpenGL, OpenInventor) will be included only if they were explicitly required during the Geant4 build (through ***cmake*** using the appropriate ***cmake option***):
 - `-DGEANT4_USE_OPENGL_X11=ON` OpenGL visualization driver with X11 window
 - `-DGEANT4_USE_QT=ON` Qt GUI with OpenGL visualization driver
 - in all cases some headers and libraries (X11, Qt, OpenGL or MesaGL) need to be available on the system
 - on your virtual machine, Geant4 is available with Qt GUI and OpenGL support

Type of visualization drivers

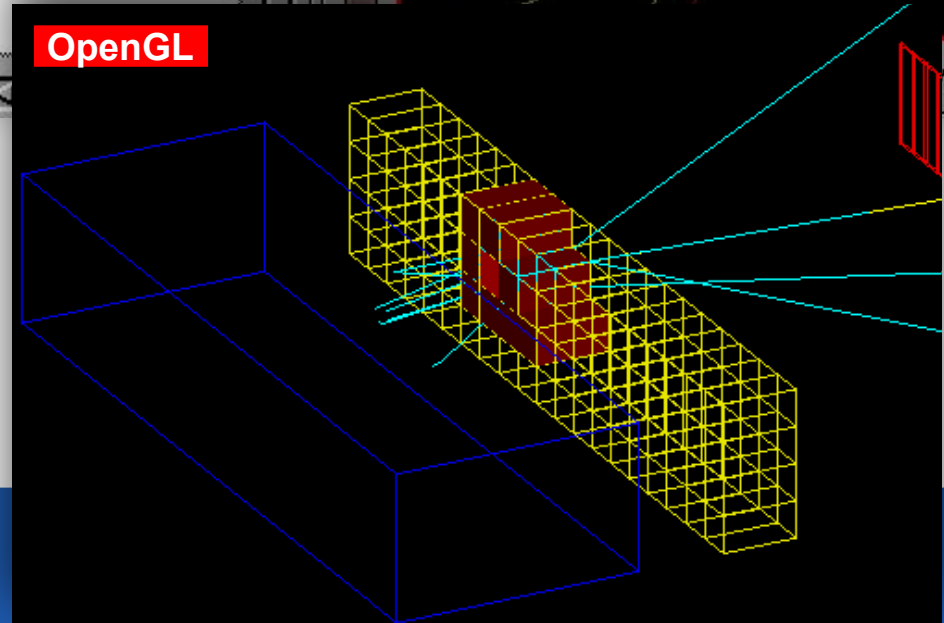
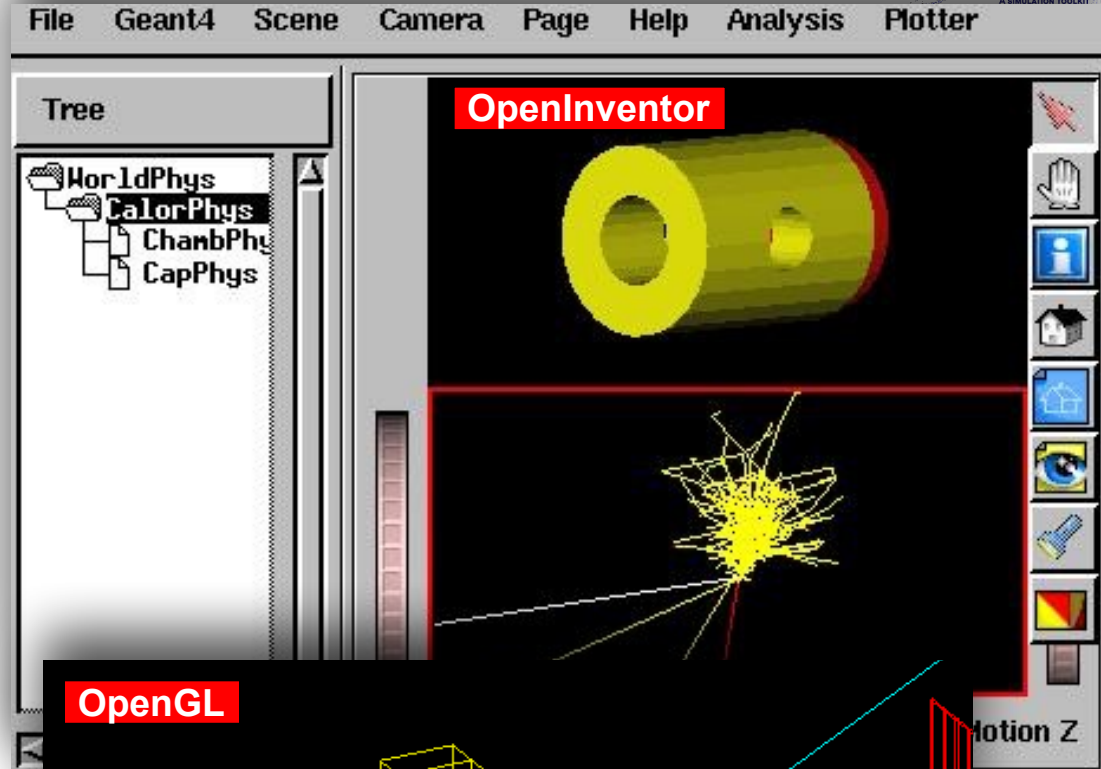
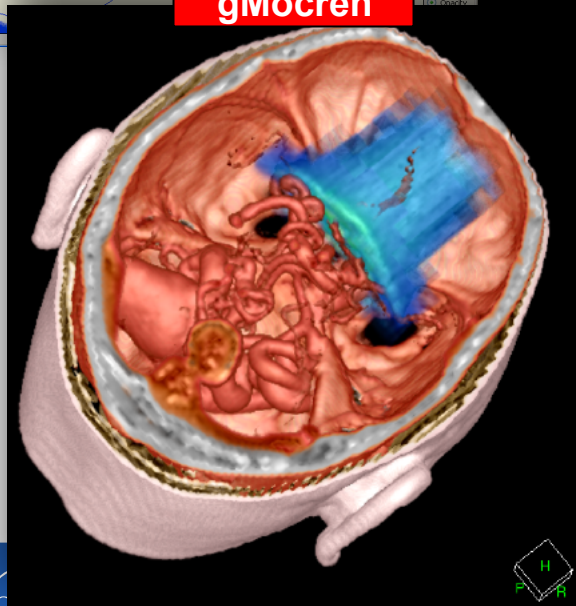
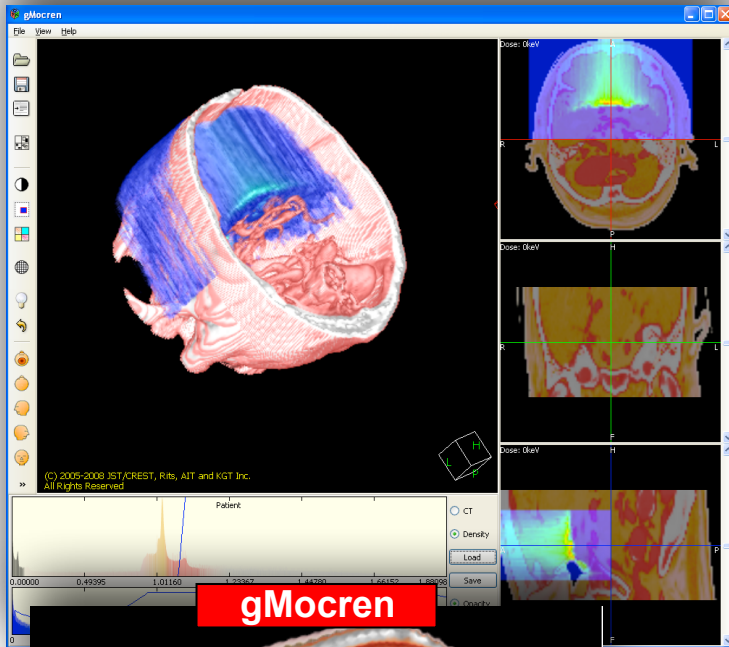


RayTracer

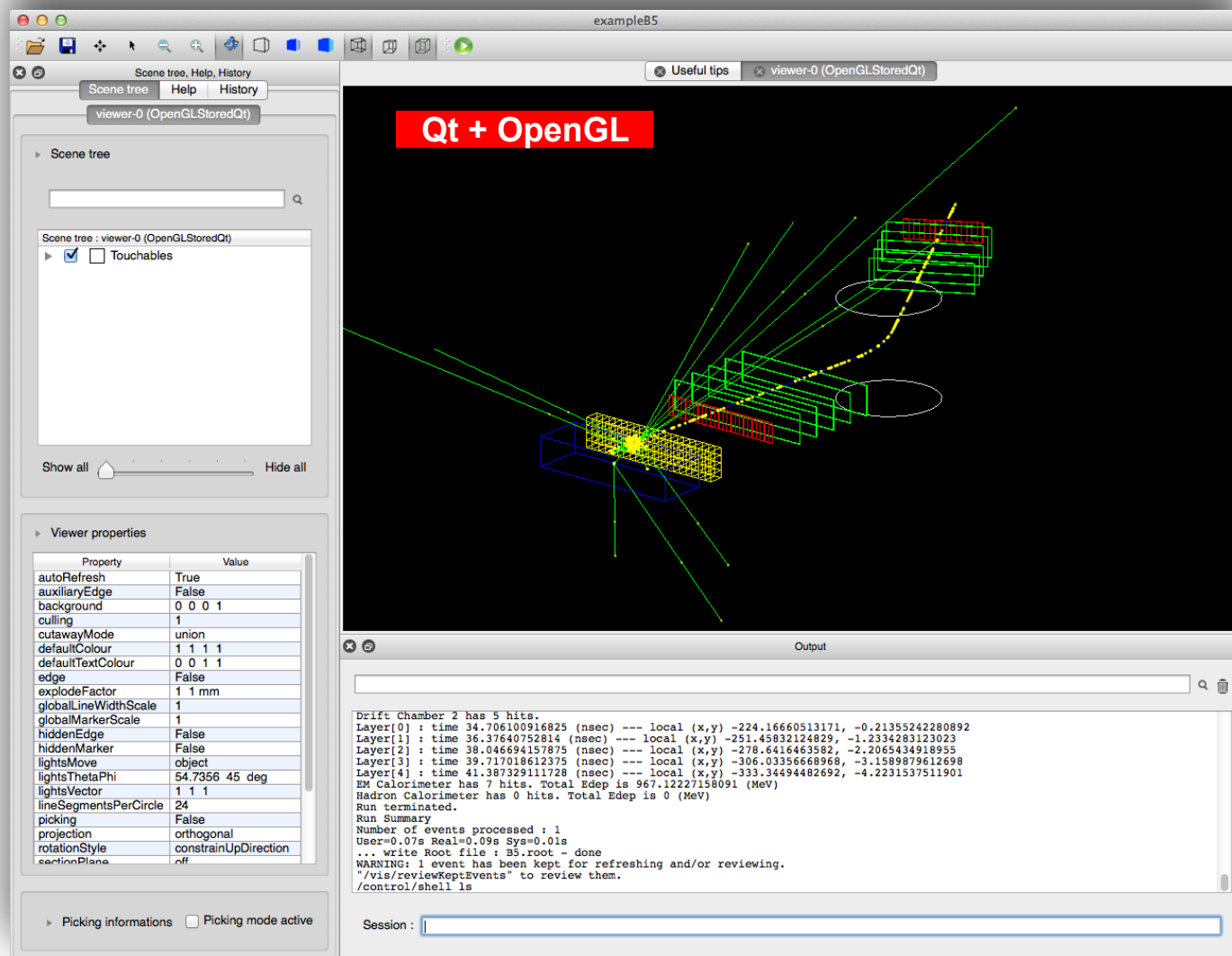


DAWN

Type of visualization drivers



Qt GUI with OpenGL visualization driver:

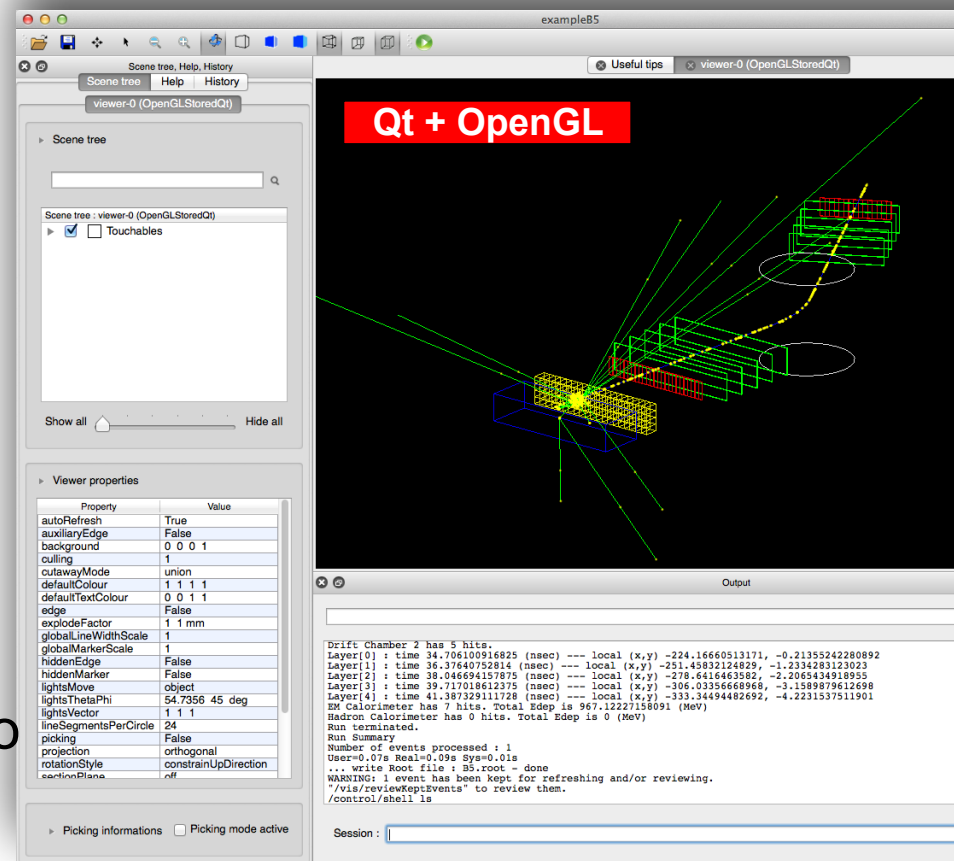


Visualization

QT GUI WITH OPENGL DRIVER

Qt GUI with OpenGL visualization driver:

- recent developments focused on this combination
- documentation is available at [Qt+OpenGL](#)
- Geant4 OpenGL tutorial with commands [here](#)
- to visualize the geometry:
 - `/vis/open OGL`
 - `/vis/drawVolume`
- most of the Geant4 examples comes with a visualization macro (*vis.mac*)
- we will write ours



Scene tree, Help, History

Scene tree Help History

viewer-0 (OpenGLStoredQt)

Scene tree

Scene tree : viewer-0 (OpenGLStoredQt)

☒ ☐ Touchables

Show all Hide all

Viewer properties

Property	Value
autoRefresh	True
auxiliaryEdge	False
background	0 0 0 1
culling	1
cutawayMode	union
defaultColour	1 1 1 1
defaultTextColour	0 0 1 1
edge	False
explodeFactor	1 1 mm
globalLineWidthScale	1
globalMarkerScale	1
hiddenEdge	False
hiddenMarker	False
lightsMove	object
lightsThetaPhi	54.7356 45 deg
lightsVector	1 1 1
lineSegmentsPerCircle	24
picking	False
projection	orthogonal
rotationStyle	constrainUpDirection
sectionPlane	off

Picking informations ☐ Picking mode active

Useful tips viewer-0 (OpenGLStoredQt)

Interactive commands to G4 kernel

Output

```

Drift Chamber 2 has 5 hits.
Layer[0] : time 34.706100916825 (nsec) --- local (x,y) -224.16660513171, -0.21355242280892
Layer[1] : time 36.37640752814 (nsec) --- local (x,y) -251.45832124829, -1.2334283123023
Layer[2] : time 38.046694157875 (nsec) --- local (x,y) -278.6416463582, -2.2065434918955
Layer[3] : time 39.717018612375 (nsec) --- local (x,y) -306.03356668968, -3.1589879612698
Layer[4] : time 41.387329111728 (nsec) --- local (x,y) -333.34494482692, -4.2231537511901
EM Calorimeter has 7 hits. Total Edep is 967.12227158091 (MeV)
Hadron Calorimeter has 0 hits. Total Edep is 0 (MeV)
Run terminated.
Run Summary
Number of events processed : 1
User=0.07s Real=0.09s Sys=0.01s
... write Root file : B5.root - done
WARNING: 1 event has been kept for refreshing and/or reviewing.
"/vis/reviewKeptEvents" to review them.
/control/shell ls

```

Session :

Scene tree, Help, History

Scene tree Help History

viewer-0 (OpenGLStoredQt)

Scene tree

Scene tree : viewer-0 (OpenGLStoredQt)

☒ ☐ Touchables

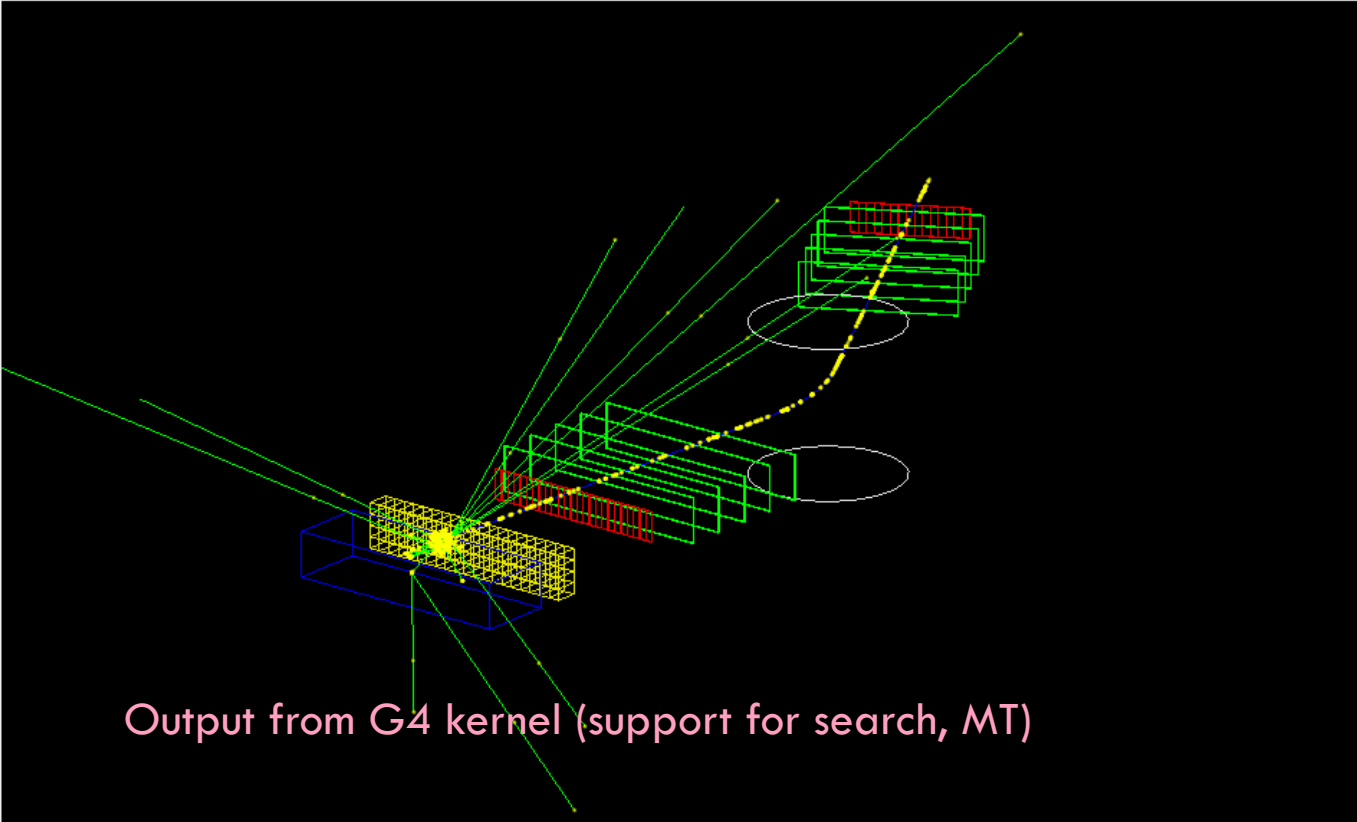
Show all Hide all

Viewer properties

Property	Value
autoRefresh	True
auxiliaryEdge	False
background	0 0 0 1
culling	1
cutawayMode	union
defaultColour	1 1 1 1
defaultTextColour	0 0 1 1
edge	False
explodeFactor	1 1 mm
globalLineWidthScale	1
globalMarkerScale	1
hiddenEdge	False
hiddenMarker	False
lightsMove	object
lightsThetaPhi	54.7356 45 deg
lightsVector	1 1 1
lineSegmentsPerCircle	24
picking	False
projection	orthogonal
rotationStyle	constrainUpDirection
sectionPlane	off

Picking informations ☐ Picking mode active

Useful tips viewer-0 (OpenGLStoredQt)



Output from G4 kernel (support for search, MT)

Output

```

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```

Session :

Scene tree, Help, History

Scene tree Help History

viewer-0 (OpenGLStoredQt)

Scene tree

Scene tree : viewer-0 (OpenGLStoredQt)

☒ ☐ Touchables

Show all Hide all

Viewer properties

Property	Value
autoRefresh	True
auxiliaryEdge	False
background	0 0 0 1
culling	1
cutawayMode	union
defaultColour	1 1 1 1
defaultTextColour	0 0 1 1
edge	False
explodeFactor	1 1 mm
globalLineWidthScale	1
globalMarkerScale	1
hiddenEdge	False
hiddenMarker	False
lightsMove	object
lightsThetaPhi	54.7356 45 deg
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lineSegmentsPerCircle	24
picking	False
projection	orthogonal
rotationStyle	constrainUpDirection
sectionPlane	off

Picking informations ☐ Picking mode active

Useful tips viewer-0 (OpenGLStoredQt)

Visualization, one tab per viewer
Interactivity with mouse: rotate, zoom, move, pick

Output

```

Drift Chamber 2 has 5 hits.
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Layer[1] : time 36.37640752814 (nsec) --- local (x,y) -251.45832124829, -1.2334283123023
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/control/shell ls
  
```

Session :

Scene tree, Help, History

viewer-0 (OpenGLStoredQt)

Scene tree

Scene tree : viewer-0 (OpenGLStoredQt)

☒ ☐ Touchables

Show all Hide all

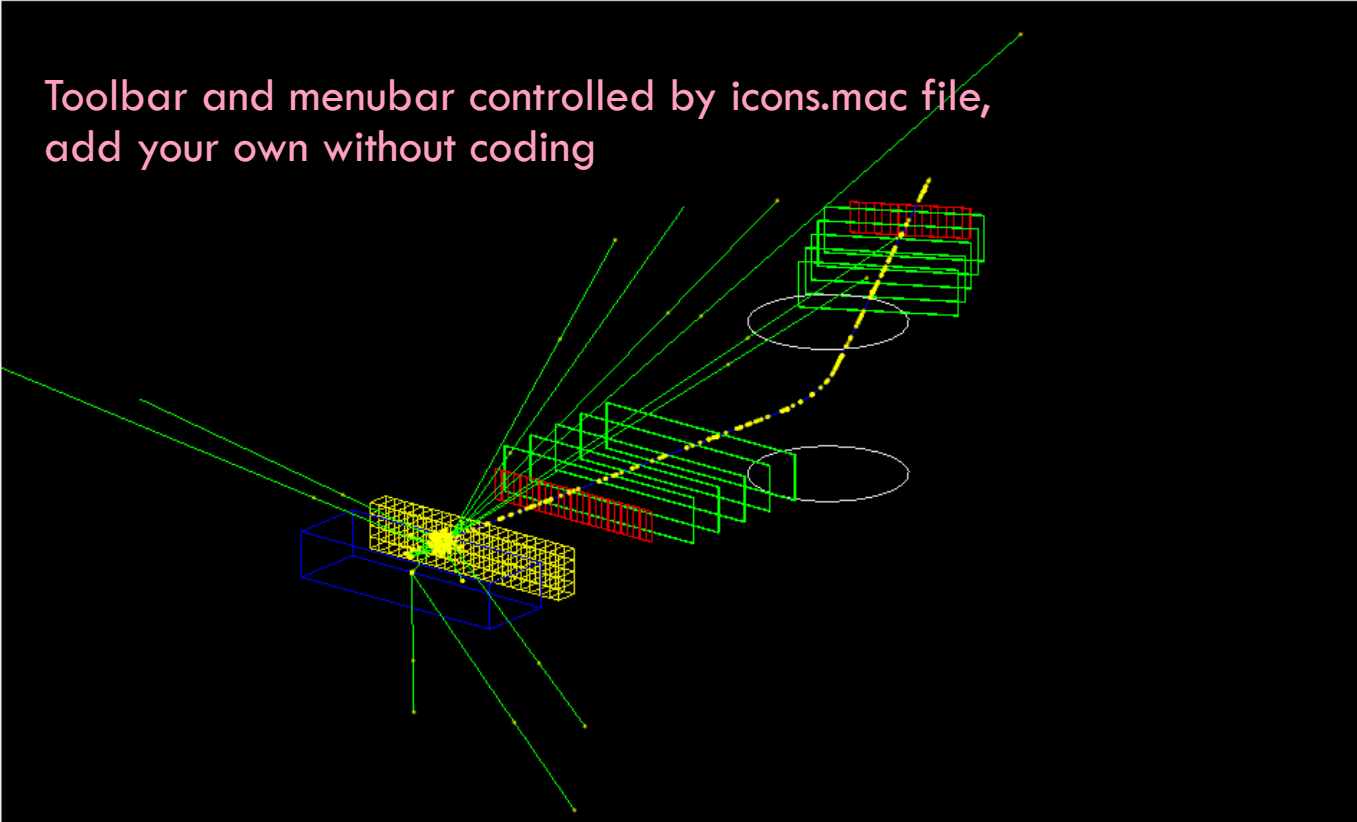
Viewer properties

Property	Value
autoRefresh	True
auxiliaryEdge	False
background	0 0 0 1
culling	1
cutawayMode	union
defaultColour	1 1 1 1
defaultTextColour	0 0 1 1
edge	False
explodeFactor	1 1 mm
globalLineWidthScale	1
globalMarkerScale	1
hiddenEdge	False
hiddenMarker	False
lightsMove	object
lightsThetaPhi	54.7356 45 deg
lightsVector	1 1 1
lineSegmentsPerCircle	24
picking	False
projection	orthogonal
rotationStyle	constrainUpDirection
sectionPlane	off

Picking informations ☐ Picking mode active

Useful tips viewer-0 (OpenGLStoredQt)

Toolbar and menubar controlled by icons.mac file, add your own without coding



Output

```

Drift Chamber 2 has 5 hits.
Layer[0] : time 34.706100916825 (nsec) --- local (x,y) -224.16660513171, -0.21355242280892
Layer[1] : time 36.37640752814 (nsec) --- local (x,y) -251.45832124829, -1.2334283123023
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Layer[3] : time 39.717018612375 (nsec) --- local (x,y) -306.03356668968, -3.1589879612698
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/control/shell ls
  
```

Session :



Scene tree, Help, History

Scene tree

Help

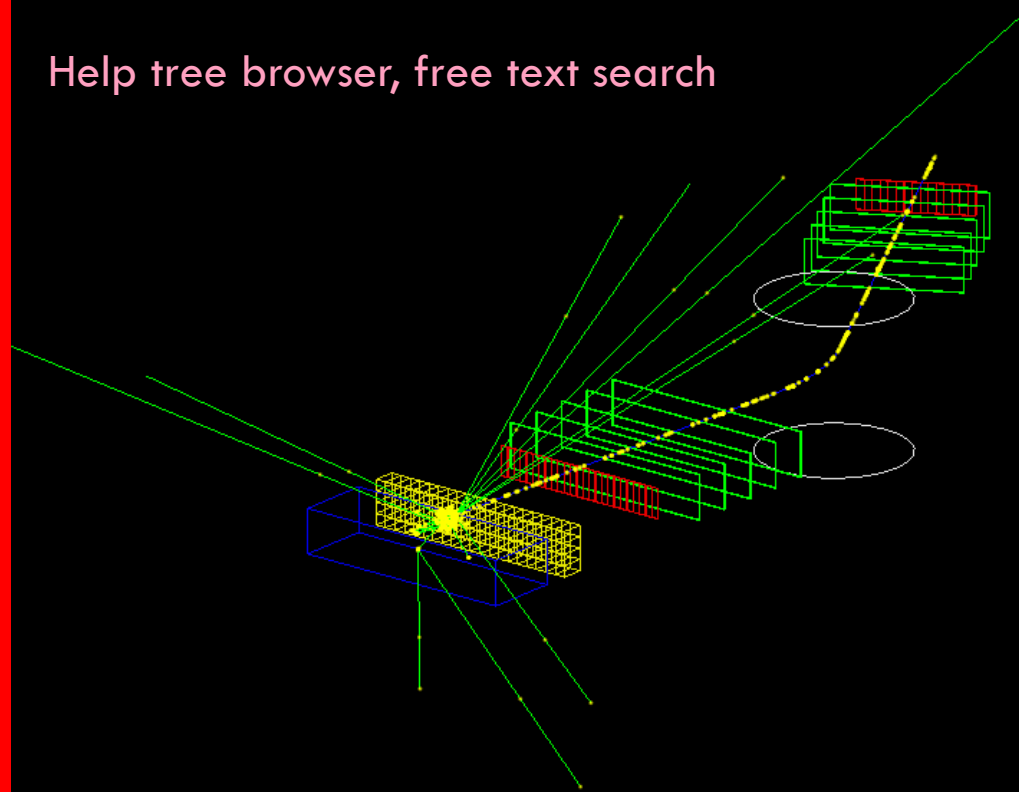
History

```
/run/beamOn 1  
/control/shell ls
```

Useful tips

viewer-0 (OpenGLStoredQt)

Help tree browser, free text search



Output

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Drift Chamber 2 has 5 hits.  
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Run terminated.  
Run Summary  
Number of events processed : 1  
User=0.07s Real=0.09s Sys=0.01s  
... write Root file : B5.root - done  
WARNING: 1 event has been kept for refreshing and/or reviewing.  
"/vis/reviewKeptEvents" to review them.  
/control/shell ls
```

Session :

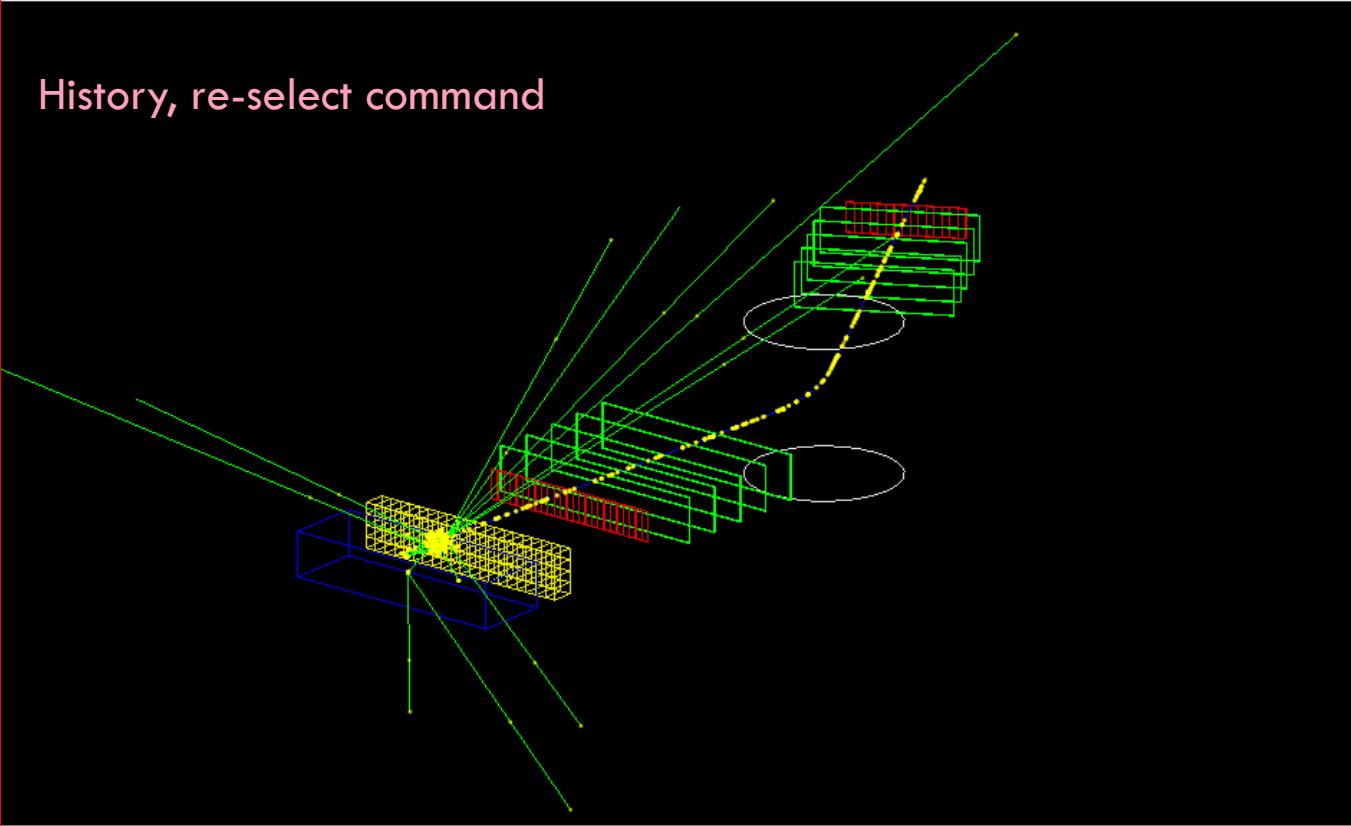
Scene tree, Help, History

Scene tree Help History

```
/run/beamOn 1
/control/shell ls
```

Useful tips viewer-0 (OpenGLStoredQt)

History, re-select command



Output

```
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/control/shell ls
```

Session :

Scene tree, Help, History

Scene tree

Help

History

viewer-0 (OpenGLStoredQt)

► Scene tree

Scene tree : viewer-0 (OpenGLStoredQt)

- ☒ Touchables
 - ☐ worldPhysical [0]
 - ☐ magneticPhysical [0]
 - ☐ firstArmPhysical [0]
 - ☐ hodoscope1Physica...
 - ☐ hodoscope1Physica...
 - ☐ hodoscope1Physica...
 - ☐ hodoscope1Physica...
 - ☐ hodoscope1Physica...
 - ☐ hodoscope1Physica...
 - ☐ hodoscope1Physica...

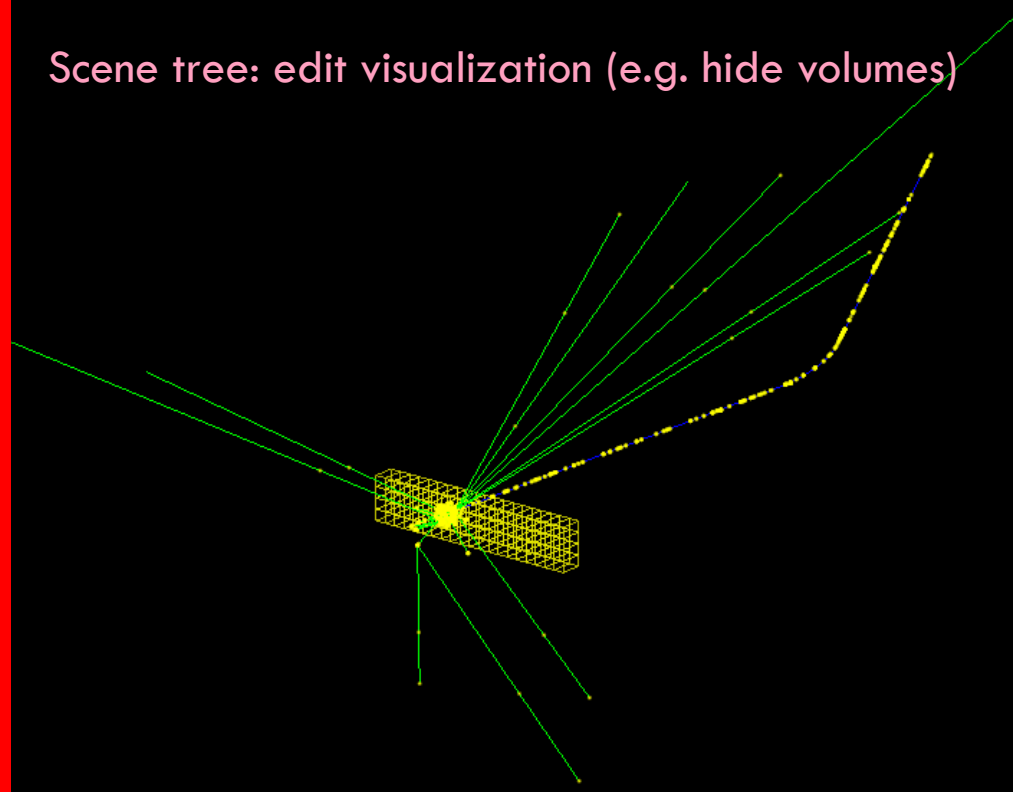
Show all Hide all

► Viewer properties

Property	Value
autoRefresh	True
auxiliaryEdge	False
background	0 0 0 1
culling	1
cutawayMode	union
defaultColour	1 1 1 1
defaultTextColour	0 0 1 1
edge	False
explodeFactor	1 1 mm
globalLineWidthScale	1
globalMarkerScale	1
hiddenEdge	False
hiddenMarker	False
lightsMove	object
lightsThetaPhi	54.7356 45 deg
lightsVector	1 1 1
lineSegmentsPerCircle	24
picking	False
projection	orthogonal
rotationStyle	constrainUpDirection
sectionPlane	off

► Picking informations ☐ Picking mode active

Scene tree: edit visualization (e.g. hide volumes)



Output

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```

Session :

Visualization

**TIME TO ADD VISUALISATION OPTION
TO OUR APPLICATION**

Activate visualisation in the `main` method:

- visualization is controlled by the Visualization Manager
- the **G4VisManager** base class (with the `RegisterGraphicsSystems()` pure virtual method) is available in the **Geant4** toolkit to implement **any graphics system**
- **Geant4** provides the **G4VisExecutive** as one implementation of this interface, that can be used directly in the `main` method of the application:
 - **include** the default Visualization Manager i.e. **G4VisExecutive**
 - **create** the Visualization Manager object and **initialise** it **before the run**
 - **delete** the Visualization Manager object **at the end** of the application

Activate visualisation in the main method:

- visualization is controlled by the Visualization Manager

```
// include the default Visualization Manager i.e. G4VisExecutive
#include "G4VisManager.hh"

...

...

//
// Add visualization:
// - create a G4VisExecutive object as the Visualization Manager
G4VisManager* visManager = new G4VisExecutive;
// - note, that G4VisExecutive can take a verbosity argument
// G4VisManager* visManager = new G4VisExecutive("Quiet");
// - initialize the Visualization Manager (will handle all vis components)
visManager->Initialize();

...

...

// delete the Visualization Manager at the end
delete visManager;
```

Simple visualisation setup (the run must be initialised before /run/initialize) :

```
# Use this open statement to create an OpenGL view:
/vis/open OGLI
#
# Draw the geometry
/vis/drawVolume
#
# Set the World volume ("logic-World") invisible
/vis/geometry/set/visibility logic-World 0 false
#
/vis/geometry/set/colour logic-Target 0 0 0 255 0.3
/vis/viewer/set/style surface
#
# Add axes (orientation) and a scale (size)
/vis/scene/add/axes
/vis/scene/add/scale
#
# Add (smooth) trajectories
/vis/scene/add/trajectories smooth
#
# Set to accumulate trajectories up to 100 events
/vis/scene/endOfEventAction accumulate 100
```