

view_frames Result

Recorded at time: 1628198827.7437356

base_link

Broadcaster: /robot_state_publisher
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

lidar_1

Broadcaster: /robot_state_publisher
Average rate: 10.204
Buffer length: 4.9
Most recent transform: 1628198827.671
Oldest transform: 1628198822.771

l_tyre_1

Broadcaster: /robot_state_publisher
Average rate: 10.204
Buffer length: 4.9
Most recent transform: 1628198827.671
Oldest transform: 1628198822.771

r_tyre_1