Logan Pachulski Mrs. Juka Independent Study - Differential Equations February 20th, 2020

Unit 2 Lesson 2

• For a differential equation of this form:

$$\circ \quad m\ddot{x} + b\dot{x} + kx = 0$$

• We define m as the mass constant, b as the damping constant, and k as the spring constant.

$$\circ \quad \text{If } b=0 \text{, then } x=A\cos(\omega t-\phi); \ \omega=\sqrt{\frac{k}{m}}$$

- Different values of b have different values based off of the solutions to r in the differential equation:
 - $\circ \quad b=0$ is the *simple harmonic oscillator/undamped*. This differential equation and its graph is of the shape $A\cos(\omega t \phi)$.
 - $b^2 \le 4mk$ is underdamped.
 - \circ $b^2 = 4mk$ is critically damped.
 - o $b^2 \ge 4mk$ is overdamped.
- Practice problem:
 - \circ Start with $\ddot{x}+\omega^2x=0$. What is the characteristic polynomial? What are its roots? What are the exponential solutions the solutions of the form e^{at} ? These may be complex exponentials. What are their real and imaginary parts? Check that these are also solutions to the original equation. What is the general real solution?
- Practice solution:
 - $\hbox{ We get polynomial } r^2+\omega^2=0; \hbox{ solving yields } r=\pm i\omega. \hbox{ We get exponential solutions } e^{\omega it}, e^{-\omega it}; \hbox{ in turn we get real solutions } \pm -\cos(\omega t) \hbox{ and imaginary solutions } \pm\sin(\omega t). \hbox{ The general solution is of the form } x=A\cos(\omega t-\phi).$