

# 18.03 Differential Equations: Week 11

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# Progress Update

Over the past week we have covered:

- ① Frequency Response
- ② RLC circuits

# Frequency response

For a differential equation of the form

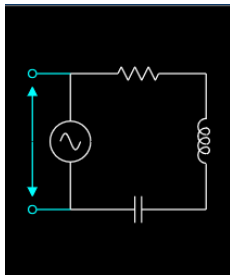
$$m\ddot{x} + b\dot{x} + kx = B \cos(\omega t) \quad (1)$$

there are a few variables that are "applied" to the input signal that get you your output signal:

- 1 Complex gain =  $(p(i\omega))^{-1}$ , the ratio between the input and output signals when you consider the complex case of each.
- 2 Gain =  $|(\text{Complex Gain})|$ , is the ratio between the real parts of the input and output.
- 3 Phase lag =  $\tan^{-1}\left(\frac{b\omega}{k - m\omega^2}\right)$

# RLC Circuits

Consider this circuit of a resistor, coil, and capacitor in series:



Unfortunately my understanding of this scenario is very poor, but there is one significant piece of information I was able to extract; for certain values of resistance, inductance, and capacitance, you can generate voltage drops perfectly in phase, out of phase, etc by supplying a sinusoidal input.

# Example Problem

Consider this problem:

1. Write down the equation for the system we are working with. Compute its complex gain  $H(\omega)$ . (That is, make the complex replacement  $F_{cx} = e^{i\omega t}$  for the input signal, and express the exponential system response  $z_p$  as a complex multiple of  $F_{cx}$ :  $z_p = H(\omega)F_{cx}$ .)

And the corresponding solution: We get the equation

$$\ddot{x} + \frac{1}{4}\dot{x} + 2x = \cos \omega t \quad (2)$$

and using the characteristic polynomial of the complex replacement

$$p(i\omega) = -\omega^2 + \frac{i\omega}{4} + 2 \quad (3)$$

we have the complex gain

$$(\text{Complex Gain}) = \frac{1}{-\omega^2 + \frac{i\omega}{4} + 2} \quad (4)$$