ANDREW DAHDOUH

Robotics Engineer

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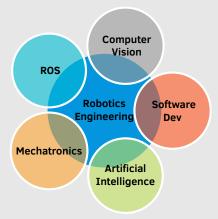
/in/andrewdahdouh



atomoclast

Skills —

Overview



Programming

 $0\ LOC \longrightarrow 10000\ LOC$

Python • Linux

Embedded Systems • Mechatronics

C • C++ • ROS

Projects -

Autonomous Rover - A differential wheeled mobile robot capable of path planning, state estimation, and navigation through static environments.

CS6475 - An Unsorted Structure from Motion Pipeline in C++.

CS7637 - An AI agent capable of visually solving 3x3 Raven's Progressive Matrices.

Team Cerebro - A anthropamorphic Robot Arm with a Brain-Machine Interface for control.

Experience

Nov 2017 - Robotics Software Engineer Present

Verb Surgical

- Experience in Robotics, Controls and Motion Planning, VR/AR, Physics Simulations
- Experience developing real-time SW in C++ with strong debugging skills.
- · Solid understanding of Kinematics and Dynamics.
- Strong background in object oriented programming
- Experience developing software as part of a development team (experience with code reviews, version control, unit tests)
- · Strong background in Math and Physics
- Computer Vision experience with processing endoscopic video.

Dec 2015 - **Robotics Engineer** Nov 2017

Houston Mechatronics, Inc

- Advanced robotics system research, development, and implementation. Experience in a highly dynamic research and development environment on advanced intelligent, dexterous and autonomous robotic systems. Job tasks and duties include: Computer Vision and Machine Learning, Supervised autonomy, Motion planning, Teleperception, Robotic Simulation, and Dexterous Control.
- Development in Python and C++ with utilization of the ROS framework in a highly dynamic Agile/Scrum development team.

Oct 2014 - System Developer Aug 2015

Optimation Technology, Inc

• Job tasks include identifying system requirements, developing technical design documentation, software development, and installation of software and hardware based solutions.

June 2014 - Embedded Software Engineer (Contract) Oct 2014

Advanced Pharmacy

- Development, testing, and maintenance of Kernel and RTOS code for mechatronic pharmaceutical dispensers.
- Development and implementation of software in Embedded C.

Aug 2013 -June 2014

Embedded Software Engineer (Contract)

Baker Hughes

 Embedded software engineering experience for hydraulic fracturing and coil tubing industrial equipment.

Jan 2013 -Aug 2013

Design Engineer

Oceaneering DTS

 Engineering position in a fast paced, high risk environment providing solutions and tooling for ROV systems in deepwater situations in subsea engineering.

Education

2018 - 2020 **MSc., Computer Science** Perception, Robotics and AIGeorgia Institue of Technology, Online

2016 - 2017 Robotics Specialization Coursera

University of Pennsylvania

2008 - 2012 **BSc., Mechanical, Computer Engineering Technology** University of Houston

Publications

A. Dahdouh, M. A. Moges, L. Pollonini, "An integrated ear-mounted sensor for pulse oximetry and EKG measurments," in 2012 IEEE Health Innovations Conference, IEEE, 2012.