```
view_frames Result

Recorded at time: 1574656672.280
```

world

Broadcaster: /LArm/robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1574656672.280 sec old)
Buffer length: 0.000 sec

Broadcaster: /LArm/robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1574656672.280 sec old)
Buffer length: 0.000 sec

Broadcaster: /LArm/link1_broadcaster
Average rate: 10.193 Hz
Most recent transform: 1574656672.337 (-0.056 sec old)
Buffer length: 4.807 sec

D435base_link

link0

camera_link

Broadcaster: /LArm/robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1574656672.280 sec old)
Buffer length: 0.000 sec

Broadcaster: /LArm/robot_state_publisher
Average rate: 10.209 Hz
Most recent transform: 1574656672.185 (0.095 sec old)
Buffer length: 4.800 sec

D435_link

link1

Broadcaster: /LArm/robot_state_publisher
Average rate: 10.209 Hz
Most recent transform: 1574656672.185 (0.095 sec old)
Buffer length: 4.800 sec

link2

Broadcaster: /LArm/robot_state_publisher
Average rate: 10.209 Hz
Most recent transform: 1574656672.185 (0.095 sec old)
Buffer length: 4.800 sec

link3

Broadcaster: /LArm/robot_state_publisher
Average rate: 10.209 Hz
Most recent transform: 1574656672.185 (0.095 sec old)
Buffer length: 4.800 sec

link4

Broadcaster: /LArm/robot_state_publisher
Average rate: 10.209 Hz
Most recent transform: 1574656672.185 (0.095 sec old)
Buffer length: 4.800 sec

link5

Broadcaster: /LArm/robot_state_publisher
Average rate: 10.209 Hz
Most recent transform: 1574656672.185 (0.095 sec old)
Buffer length: 4.800 sec

link6

Broadcaster: /LArm/robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1574656672.280 sec old)
Buffer length: 0.000 sec

EEFlink

Broadcaster: /LArm/robot_state_publisher
Average rate: 10.209 Hz
Most recent transform: 1574656672.185 (0.095 sec old)
Buffer length: 4.800 sec

Broadcaster: /LArm/robot_state_publisher
Average rate: 10.209 Hz
Most recent transform: 1574656672.185 (0.095 sec old)
Buffer length: 4.800 sec

left_gripper

right_gripper