



Lecture 5

11/11/2022

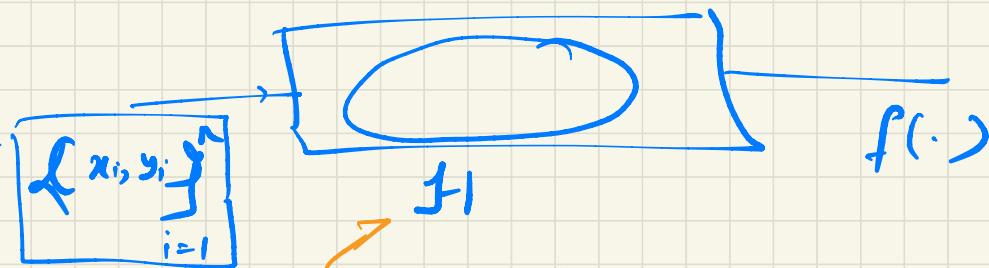
- ⇒ $X \leftarrow \text{Space}$
- ⇒ $(X, d) \leftarrow \{ \}$
- ⇒ $(X, \| \cdot \|)$
- ⇒ $(X, \langle \cdot, \cdot \rangle)$
- ⇒ $A \in \mathbb{R}^{m \times n}$
- ⇒ EVD, SVD,
- ⇒ Column Space

Learning Problem

• Supervised Learning

$$x_i \in \mathbb{R}^n \quad y_i \in \mathbb{C}$$

$$\left\langle x_i \in \mathbb{R}^n, y_i \in \mathbb{R} \right\rangle_{i=1}^n \leftarrow \text{Training data}$$



$$\frac{y_i = f(u_i)}{f(u_{\text{new}}) = y_{\text{new}}}$$

x_{new}

: X : input space; $X \subseteq \mathbb{R}^D$

Y : o/p space $Y \subseteq \mathbb{R}$

$Z = X \times Y$ called the data space

$$y_{pred} = f_S(x_{new})$$

R_i

\Rightarrow Problem
Regun. $Y \subseteq \mathbb{R}$

$x_i \rightarrow$

\rightarrow Binary: $Y = \{-1, 1\}$

\rightarrow Multi-class: $Y = \{1, 2, \dots, T\}$

① $Z = X \times Y$, $u(\mathcal{Z}) = u(x, y)$

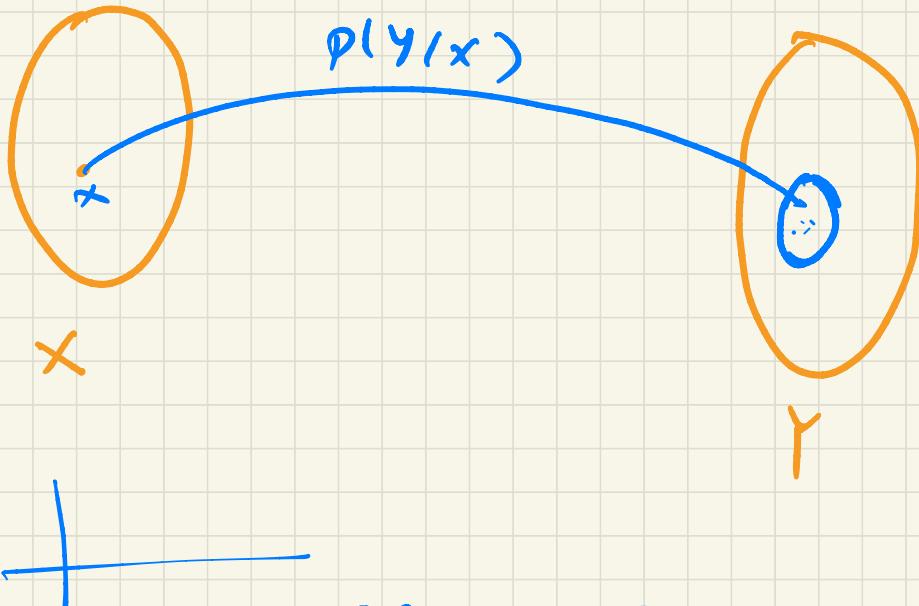
$\sim (\mathcal{Z})$

$$\left(\langle x_i, y_i, y^n \rangle_{i=1}^n \right)$$

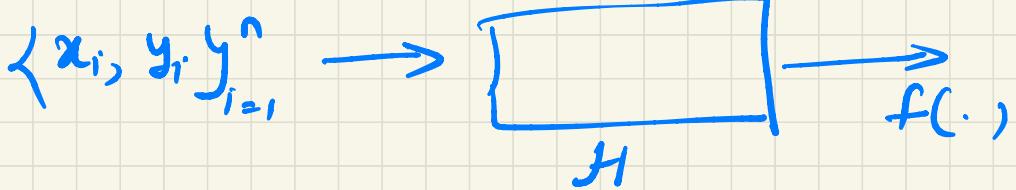
Each i/p o/p pair (x, y) is sampled

from a fixed but unknown distribution

$$P(x, y) = P(y|x) P(x) \quad \text{factorization}$$



$$P(x,y) = P_x(x) P(y|x)$$



A learning algorithm is a map,

$L: \mathbb{Z}^n \rightarrow \mathcal{H}$ that looks at ' S '

and selects from \mathcal{H} a function

$f_S: x \rightarrow Y$ such that $f_S(x) \approx y$

in a predictive way.

~~y_{j+1}~~ $\langle x_i, \underbrace{\quad}_{j=0+1 \dots -}$



$f(x_i) \approx y_i$

f f S.I

$$f(x_i) \approx y_i \quad x_i = -r$$

Learning Problem

1) $(x_i, y_i) \in \mathbb{Z}^2$

2) H

3) Loss function

4) I

I

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Loss function

A loss function $L: X \times Y \rightarrow \underline{\mathbb{R}_+^I}$ determines the plus $L(f(x), y)$, how pay if we predict $f(x)$ when instead the true obj in Y .

$$L(f(x), y) = (f(x) - y)^2 \Rightarrow L_2$$

$$= |f(x) - y| \Rightarrow L_1$$

$$= (|f(x) - y| - \epsilon)_+$$

Loss function

$\triangleright x_i, y_i : L(f(x_i), y_i) \leftarrow$



Expected Risk:

$$E[f] = \int L(f(x), y) p(x, y) dx dy$$

$x \sim p(x, y)$

$$= E_x[L]$$

.

\Rightarrow A good function should have small expected risk.

\Rightarrow the i th row is one we do not know
the probability $\sim p(x, y)$

Empirical Risk

$$E_n(f_n) = \frac{1}{n} \sum_{i=1}^n L(f(x_i), y_i)$$

↳ An estimate of the target function

$$E_n(f_n) \leftarrow \text{Empirical Risk}$$

$$E[f] \leftarrow \text{Expected Risk}$$

$$\boxed{E[f] - E_n(f_n) = 0}$$

$$\lim_{n \rightarrow \infty} E_n [E(f) - E_n(f)] = 0$$

How to design an algorithm.

- 1) Fitting: An estimator should fit data well.
- 2) Stability: An estimator should be stable, it should not change much if data changes slightly.

$$\Rightarrow S = \sum_{i=1}^n (x_i, y_i)$$

H:

$$f_S = \underset{f \in \mathcal{H}}{\text{arg min}} E_n(f)$$

$$L(\beta) = (f(x) - y)^2 \text{ w.r.t. } \beta$$

Lineal approx: Ax

$$x \rightarrow y_i = f(x_i), i=1, \dots, n$$

f: should satisfy certain additional properties.

ERM

$$\min_{f \in H} \frac{1}{n} \sum_{i=1}^n L(f(x_i), y_i)$$

IIL-pred.

f(

Regularization

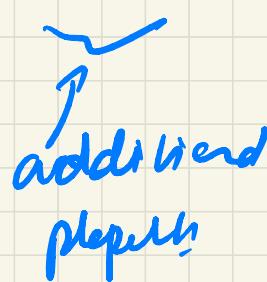
$$\min_{f \in H} \frac{1}{n} \sum_{i=1}^n L(f(x_i), y_i) + R(f)$$

↗

$$\min_{f \in H} \frac{1}{n} \sum_{i=1}^n L(f(x_i), y_i) + R(f) \leq A$$

] Invariant
Regular

$$= \min_f \sum_{i=1}^n L(f(x_i), y_i) + \gamma R(f)$$



goal additional
 penalty

$$: R(f) := \|f\|_K^2, \text{ where } \|f\|_K^2$$

is the norm in RKHS, depends
the kernel K .