# User Manual of orbit following code TASK/OB

### Contents

# Outline of TASK/OB

#### Purpose of TASK/OB 1.1

The purpose of TASK/OB is to describe charged particle orbits in a given magnetic configuration. At present, gyro orbits in the Boozer coordinates are described based on the textbook by R. White. More general coordinates including vacuum regions and full orbit description will be included in future.

#### Modules included 1.2

| obcomm_parm | Deficuition of input parameters                          |
|-------------|--|
| obcomm      | Definition of common variables                           |
| obinit      | Initialization of input parameters                       |
| obparm      | Procedures of input parameters (read, check, broadcast)  |
| obview      | Print out input parameters                               |
| obmenu      | Command menu   |
| obprep      | Preparation for calculation (equilibrium, interpolation) |
| obcalc      | Calculation of coefficients                              |
| obexec      | Solving equation of motion                               |
| obgout      | Visualization of orbits                                  |
| obfile      | File output of orbits                                    |

Common subroutines using obcomm obsub

oblib Common subroutines independent of obcomm

### Parameters

# Adjustable parameters, but fixed at compilation time

nobt\_m 100 maximum number of orbits

# Input parameters and their default values

| modelg      | 3     | geometry model (parameter of plparm)            |
|-------------|-------|---|
| $nobt\_max$ | 1     | number of orbits                                |
| $nstp\_max$ | 10000 | maximum number of orbit step                    |
| $ns\_ob$    | 2     | id of particle species                          |
| $lmax_nw$   | 20    | maximum number of iteration (initial condition) |

| mdlobp               | 0     | model id of equation of motion  0: Eq of Motion with Boozer coordinates   |
|----------------------|-------|---|
| mdlobi               | 0     | 1: Eq of Motion with Cylindrical coord. model id of input scheme of initial parameters 0: penergy,pcangle,zeta,psipn,theta 1: penergy,pcangle,zeta,rr,zz (TBI) 100: line input with psipn,theta |
| mdlobq               | 0     | 101: line input with rr,zz (TBI) model id of ODE solver 0: 4th-order Runge-Kutta-Gill 1: universal ODE solver (TBI)   |
| mdlobt               | 1     | <ul><li>2: symplectic solver (TBI)</li><li>model id of time normalization</li><li>0: real time</li><li>1: normalized by approximate bounce time</li></ul>                                       |
| mdlobc               | 0     | model id of one cycle calculation  0: independent of cycle, until tmax_ob  1: one cycle for trapped and untrapped   |
| mdlobw               | 3     | model id of output interval  0: no output  1: every step  2: every 10 step  3: every 100 step  4: every 1000 step  5: every 10000 step  |
| mdlobg               | 0     | model id of graphics 0: default   |
| mdlobx               | 1     | model id of wall  0: calculate only inside the wall (psip_ob;=psipa)  1: continue Runge-Kutta (psip_ob;psipa)   |
| tmax_ob              | 10.D0 | maximum of orbit following time in omega_bounce   |
| delt_ob              | 0.1D0 | time step size in omega_bounce t_bounce = 2 Pi/ omega_bounce omega bounce = (v_perp/qR) SQRT(r/2R) omega_bounce <sup>2</sup> = (mu B /m)*(r/q <sup>2</sup> R <sup>3</sup> )                     |
| eps_ob               | 1.D-6 | convergence criterion of orbit solution   |
| del_ob               | 1.D-4 | step size of iteration (initial condition)  |
| eps_nw               | 1.D-6 | convergence criterion of iteration (initial c.)   |
| penergy_ob_in(1)     | 1.D0  | initial particle energy (mdlobi=0,1) [keV]: conserved   |
| $pcangle\_ob\_in(1)$ | 0.5D0 | initial cosine of pitch angle (mdlobi=0,1)  |
| $zeta\_ob\_in(1)$    | 0.D0  | initial toroidal angle (mdlobi=0,1) [degree]  |
| $psipn\_ob\_in(1)$   | 0.5D0 | initial normalized poloidal flux (mdlobi=0)   |
| $theta\_ob\_in(1)$   | 0.D0  | initial poloidal angle (mdlobi=0) [deg]   |
| $rr\_ob\_in(1)$      | 4.D0  | initial major radius (mdlobi=1) [m]   |
| $zz\_ob\_in(1)$      | 0.D0  | initial vertical position (mdlobi=1) [m]  |
| nrmax_ob             | 100   | number of equilibrium radial meshes   |
| $nthmax\_ob$         | 64    | number of equilibrium poloidal meshes   |
| $nsumax\_ob$         | 100   | number of equilibrium plasma boundary meshes  |

# 2.3 Initial orbit parameters and results

• Initial orbit parameters: (nobt)

penergy\_ob\_in(1) initial particle energy (mdlobi=0,1) [keV]
pcangle\_ob\_in(1) initial cosine of pitch angle (mdlobi=0,1)
zeta\_ob\_in(1) initial toroidal angle (mdlobi=0,1) [degree]
psipn\_ob\_in(1) initial normalized poloidal flux (mdlobi=0)
theta\_ob\_in(1) initial poloidal angle (mdlobi=0) [deg]
nthmax\_ob\_in(1) number of equilibrium poloidal meshes
nsumax\_ob\_in(1) number of equilibrium plasma boundary meshes

• Initial variables: (nobt)

zetab\_pos toroidal boozer angle zeta translated from obts

thetab\_pos poloidal boozer angle theta psip\_pos poloidal magnetic flux

rhopara\_pos parallel velocity devidede by cyclotron freq.

• Orbit results: (nstp,nobt)

time\_ob time

zetab\_ob toroidal boozer angle zeta translated from obts

thetab\_ob poloidal boozer angle theta psip\_ob poloidal magnetic flux

rhopara\_ob parallel velocity devidede by cyclotron freq.

pzeta\_ob toroidal momentum pzeta ptheta\_ob poloidal momentum ptheta babs\_ob absolute value of magnetic field

phi\_ob electrostatic potential

vpara\_ob parallel velocity

vperp\_ob perpendicular velocity psit\_ob toroidal magnetic flux

zeta\_ob toroidal angle
rr\_ob major radius
zz\_ob vertical positon
rs\_ob minor radius
theta\_ob poloidal angle