# Intro to Univariate State-Space Models FISH 507 – Applied Time Series Analysis

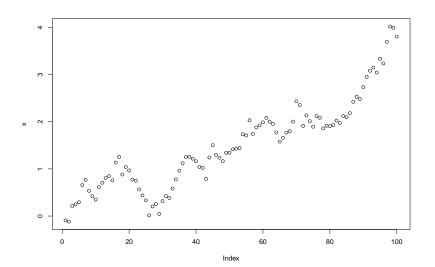
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## Warning in !is.null(rmarkdown::metadata\$output) && rmar!
## %in% : 'length(x) = 2 > 1' in coercion to 'logical(1)'

# Dickey-Fuller test with 'ur.df'

```
x <- cumsum(rnorm(100, 0.02, 0.2))
plot(x)</pre>
```



# Dickey-Fuller stationarity test

$$x_t = \phi x_{t-1} + \mu + at + e_t$$
  
$$x_t - x_{t-1} = \gamma x_{t-1} + \mu + at + e_t$$

Test is for unit root is whether  $\gamma = 0$ .

- ► Standard linear regression test statistics won't work since the response variable is correlated with our explanatory variable.
- ur.df() reports the critical values we want in the summary info or attr(test,"cval").

```
library(urca)
test <- ur.df(x, type="trend", lags=0)
summary(test)</pre>
```

Value of test-statistic is: -3.1375 4.6773 4.9583

```
attr(test, "teststat")

## tau3 phi2 phi3
## statistic -1.936144 2.970519 2.110123
attr(test, "cval")

## 1pct 5pct 10pct
```

## tau3 -4.04 -3.45 -3.15 ## phi2 6.50 4.88 4.16 ## phi3 8.73 6.49 5.47 The tau3 is the one we want. This is the test that  $\gamma=0$  which would mean that  $\phi=0$  (random walk).

$$x_t = \phi x_{t-1} + \mu + at + e_t$$
  
 $x_t - x_{t-1} = \gamma x_{t-1} + \mu + at + e_t$ 

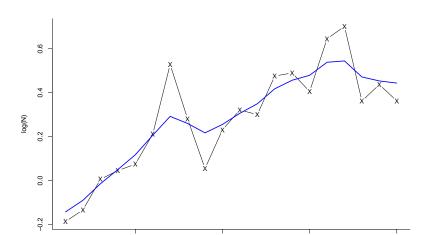
The hypotheses reported in the output are

- ▶ tau (or tau2 or tau3):  $\gamma = 0$
- ▶ phi reported values: are for the tests that  $\gamma = 0$  and/or the other parameters a and  $\mu$  are also 0.

Since we are focused on the random walk (non-stationary) test, we focus on the tau (or tau2 or tau3) statistics and critical values

### Univariate state-space models

Autoregressive state-space models fit a random walk AR(1) through the data. The variability in the data contains both process and non-process (observation) variability.

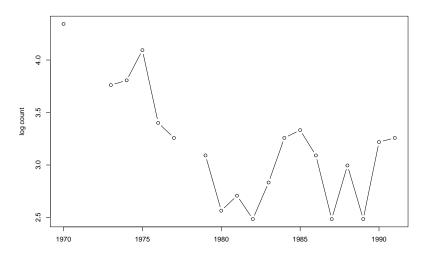


# PVA example

One use of univariate state-space models is "count-based" population viability analysis (chap 7 HWS2014)

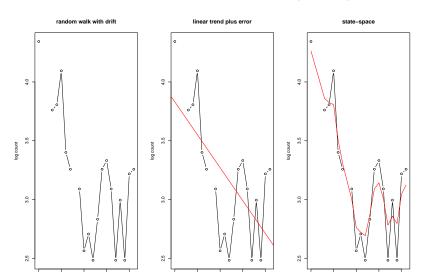


Imagine you were tasked with estimating the probability of the population going extinct (N=1) within certain time frames (10, 20, years).

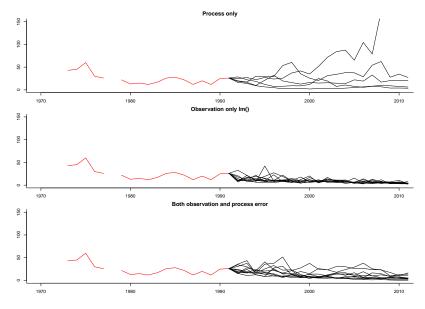


# How might we approach our forecast?

- ► Fit a model
- ► Simulate with that model many times
- ightharpoonup Count how often the simulation hit N=1 (logN=0)



# How you model your data has a large impact on your forecasts



#### Stochastic level models

Flat level

$$x = u$$
$$y_t = x + v_t$$

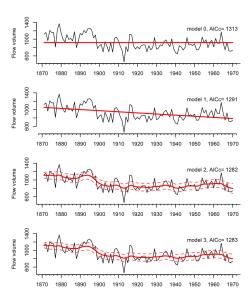
Linear level

$$x_t = u + c \times t$$
$$y_t = x_t + v_t$$

Stochastic level

$$x_t = x_{t-1} + u + w_t$$
$$y_t = x_t + v_t$$

### Nile River example



#### Kalman filter and smoother

The **Kalman filter** is an algorithm for computing the expected value of the  $x_t$  conditioned on the data up to t-1 and t and the model parameters.

$$x_t = bx_{t-1} + u + w_t, \quad w_t \sim N(0, q)$$

$$y_t = zx_t + a + v_t, \ v_t \sim N(0, r)$$

The **Kalman smoother** computes the expected value of the  $x_t$  conditioned on all the data.

# Diagnostics

#### Innovations residuals =

data at time t minus model predictions given data up to t-1

$$\hat{y_t} = E[Y_t | y_{t-1}]$$

residuals(fit)

Standard diagnostics

- ACF
- Normality

# MARSS package

We will be using the MARSS package to fit univariate and multivariate state-space models.

$$egin{aligned} \mathbf{x}_t &= \mathbf{B} \mathbf{x}_{t-1} + \mathbf{U} + \mathbf{w}_t, & \mathbf{w}_t \sim \mathit{MVN}(0, \mathbf{Q}) \ & \mathbf{y}_t &= \mathbf{Z} \mathbf{x}_t + \mathbf{A} + \mathbf{v}_t, & \mathbf{v}_t \sim \mathit{MVN}(0, \mathbf{R}) \end{aligned}$$

The main function is MARSS():

fit <- MARSS(data, model=list())</pre>

data are a univariate vector, univariate ts or a matrix with time

going along the columns.

model list is a list with the structure of all the parameters.

## Univariate example

$$x_t = x_{t-1} + u + w_t, \ w_t \sim N(0, q)$$
  
 $y_t = x_t + v_t, \ v_t \sim N(0, r)$ 

Write where everything bold is a matrix.

```
\begin{aligned} x_t &= \mathbf{B} x_{t-1} + \mathbf{U} + w_t, & w_t \sim MVN(0, \mathbf{Q}) \\ y_t &= \mathbf{Z} x_t + \mathbf{A} + v_t, & v_t \sim MVN(0, \mathbf{R}) \\ \text{mod.list} &<- \text{list}(\\ \text{B} &= \text{matrix}(1), & \text{U} &= \text{matrix}("u"), & \text{Q} &= \text{matrix}("q"), \\ \text{Z} &= \text{matrix}(1), & \text{A} &= \text{matrix}(0), & \text{R} &= \text{matrix}("r"), \\ \text{x0} &= \text{matrix}("x0"), \\ \text{tinitx} &= 0 \end{aligned} \right)
```

