#### **Solvers**

The solvers module in SymPy implements methods for solving equations. Here is a list of the most commonly used methods:

## **Algebraic equations**

There are two high-level functions to solve equations, solve() and solveset().

```
In [1]: import sympy as sp
          from sympy.abc import x, y
          sp.solve(x**2 - y, x)
 Out[1]: [-sqrt(y), sqrt(y)]
 In [2]: sp.solveset(x**2 - y, x)
 Out[2]: \left\{-\sqrt{y}, \sqrt{y}\right\}
 In [4]: sp.solve(x**2 - y, x, dict=True)
 Out[4]: [{x: -sqrt(y)}, {x: sqrt(y)}]
 In [5]: eqn = sp.Eq(x**2, y)
          eqn
 Out[5]: x^2 = y
 In [8]: | solutions = sp.solve(eqn, x, dict=True)
          solutions
          # solutions[0][x]
 Out[8]: [{x: -sqrt(y)}, {x: sqrt(y)}]
In [14]: solutions_set = sp.solveset(eqn, x)
          for sol in solutions_set:
              print(sol)
          solution_list = list(solutions_set)
          solution_list[0]
         sqrt(y)
         -sqrt(y)
Out[14]: \sqrt{y}
In [18]: \# x = sp.Symbol("x")
          x = sp.Symbol("x", real=True)
          sp.solve(x**4 - 256, x, dict=True)
```

```
Out[18]: [{x: -4}, {x: 4}]
In [20]: x = sp.Symbol("x", real=True)
           expr = (x - 4) * (x - 3) * (x - 2) * (x - 1)
           solution = sp.solve(expr, x)
           print(solution)
           solution outside 2 3 = [sol for sol in solution if sol < 2 or sol > 3]
           print(solution outside 2 3)
          [1, 2, 3, 4]
          [1, 4]
In [21]: from sympy.abc import x
           sp.solveset(x**4 - 256, x, domain=sp.S.Reals)
Out[21]: \{-4,4\}
In [24]: sp.solve(x**2 + 1, x)
Out[24]: [-I, I]
           Why Solveset?

    solveset has an alternative consistent input and output interface: solveset

               returns a set object and a set object takes care of all types of output. For cases
               where it does not "know" all the solutions a ConditionSet with a partial
               solution is returned. For input it only takes the equation, the variables to solve for
               and the optional argument domain over which the equation is to be solved.
             • solveset can return infinitely many solutions. For example solving for
               \sin{(x)}=0 returns \{2n\pi|n\in\mathbb{Z}\}\cup\{2n\pi+\pi|n\in\mathbb{Z}\}, whereas solve only
               returns [0,\pi].
             • There is a clear code level and interface level separation between solvers for
               equations in the complex domain and the real domain. For example solving
               e^x = 1 when x is to be solved in the complex domain, returns the set of all
               solutions, that is \{2ni\pi|n\in\mathbb{Z}\}, whereas if is to be solved in the real domain
               then only \{0\} is returned.
In [25]: solution = sp.solveset(sp.sin(x), x)
           solution
Out [25]: \{2n\pi \mid n \in \mathbb{Z}\} \cup \{2n\pi + \pi \mid n \in \mathbb{Z}\}
```

```
In [15]: # system of equations
sp.solve([x - 3, y**2 - 1]) # solve can handle system of equations
# sp.solveset can handle only uni-variate equations
```

In [4]:  $sp.solveset(x^{**2} + 1, x)$  # Complex solution set is default

# sp.solveset(x\*\*2 + 1, x, domain=sp.S.Reals)

Out[4]: 0

```
\# sp.solveset([x - 3, y**2 - 1]) \# will raise error
         x, y, z = sp.symbols("x y z")
         Eqns = [3 * x + 2 * y - z - 1, 2 * x - 2 * y + 4 * z + 2, -x + y / 2 - z]
         sp.linsolve(Eqns, x, y, z)
Out[15]: \{(1, -2, -2)\}
In [ ]: # Non-linear system of equations
         sp.nonlinsolve([x - 3, y**2 - 1], [x, y])
In [23]: # If any equation does not depend on the symbol(s) given,
         # it will be eliminated from the equation set
         sp.solve(x - y, x, dict=True)
         # sp.solveset(x - y, x)
         \# sp.solve([x - y, y - 3], x, dict=True)
Out[23]: [{x: y}]
In [32]: # In case the system is underdetermined, the function will return a param
         A = sp.Matrix([[1, 2, 3], [4, 5, 6], [7, 8, 9]])
         b = sp.Matrix([3, 6, 9])
         sp.linsolve((A, b), x, y, z)
         # sp.linsolve((A, b)) # if the parametric symbols are not given, it will
Out[32]: \{(z-1, 2-2z, z)\}
In [42]: import numpy as np
         a = np.array([[1, 2], [3, 5]])
         b = np.array([1, 2])
         x = np.linalg.solve(a, b)
Out[42]: array([-1., 1.])
In [44]: A = np.array([[1, 2, 3], [4, 5, 6], [7, 8, 9]])
         b = np.array([3, 6, 9])
         x = np.linalg.lstsq(A, b, rcond=None)[0]
Out[44]: array([-0.16666667, 0.33333333, 0.83333333])
In [33]: # linsolve can accept augmented matrix as well
         aug = sp.Matrix([[2, 1, 3, 1], [2, 6, 8, 3], [6, 8, 18, 5]])
         sp.linsolve(aug, x, y, z)
         \left\{ \left(\frac{3}{10},\,\frac{2}{5},\,0\right) \right\}
Out[33]:
In [34]: a, b, c, d, e, f = sp.symbols("a, b, c, d, e, f")
```

```
eqns = [a * x + b * y - c, d * x + e * y - f]
          sp.linsolve(eqns, x, y)
Out[34]: \left\{ \left( \frac{-bf + ce}{ae - bd}, \frac{af - cd}{ae - bd} \right) \right\}
In [37]: # use sympy to reduce inequalities
          sp.solve(x**2 - 4 > 0, x)
          \# sp.solveset(x**2 - 4 > 0, x)
Out [37]: (-\infty < x \land x < -2) \lor (2 < x \land x < \infty)
In [17]: sp.Abs(x - 5) - 3
          sp.solve(sp.Abs(x - 5) - 3 > 0, x)
Out [17]: (-\infty < x \land x < 2) \lor (8 < x \land x < \infty)
In [29]: sp.solve\_univariate\_inequality(sp.sin(x) > 0, x, relational=False)
Out[29]: (0,\pi)
In [32]: domain = domain = sp.Interval(0, sp.oo)
          sp.solve\_univariate\_inequality(x**2 >= 4, x)
          # sp.solve univariate inequality(x**2 >= 4, x, relational=False)
          # sp.solve univariate inequality(x**2 >= 4, x, domain=domain)
Out[32]: (2 \le x \land x < \infty) \lor (x \le -2 \land -\infty < x)
          Differential equations
 In [1]: # undefined functions
          x = sp.Symbol("x")
          f = sp.Function("f")
          g = sp.Function("g")(x)
          \# f(x)
          # f(0)
          # g(0) # will raise error
          g.subs(x, 0)
 Out[1]: q(0)
 In [8]: f = sp.symbols("f", cls=sp.Function)(x)
 Out[8]: f(x)
 In [9]: g.diff()
          # f(x).diff()
          # f(x).diff(x)
          # sp.Derivative(f(x), x)
```

```
Out[9]: \frac{d}{dx}g(x)
In [22]: # assumptions can be passed to the function
          f = sp.Function("f", real=True)
          f(x).is real
Out[22]: True
In [24]: x.diff(x)
          # if y is variable
          # y.diff(x)
          # if y is a function of x
          \# y = sp.Function("y")(x)
          # y.diff(x)
Out[24]: 1
In [26]: f(x).diff(x).subs(x, 0)
Out[26]: \frac{d}{dx}f(x)\Big|_{x=0}
In [27]: # solve differential equations
          f = sp.Function("f")
          sp.dsolve(f(x).diff(x) - f(x), f(x))
Out[27]: f(x) = C_1 e^x
In [25]: f = sp.Function("f")(x)
         f_x = f.diff(x)
          f_x = f.diff(x, x)
          sp.dsolve(f xx + f, f)
Out[25]: f(x) = C_1 \sin(x) + C_2 \cos(x)
 In [4]: # system of differential equations
          t = sp.symbols("t")
          x, y = sp.symbols("x, y", cls=sp.Function)
          eq = (
              sp.Eq(sp.Derivative(x(t), t), 12 * t * x(t) + 8 * y(t)),
              sp.Eq(sp.Derivative(y(t), t), 21 * x(t) + 7 * t * y(t)),
          sp.dsolve(eq)
          # sp.pprint(sp.dsolve(eq))
          \# sp.dsolve(eq, [x(t), y(t)])
```

```
Out[4]: [Eq(x(t), C1*x0(t) + C2*x0(t)*Integral(8*exp(Integral(7*t, t))*exp(Integral(7*t, t))*exp(Integral(8*exp(Integral(8*exp(Integral(8*exp(Integral(8*exp(Integral(8*exp(Integral(8*exp(Integral(8*exp(Integral(8*exp(Integral(8*exp(Integral(8*exp(Integral(8*exp(Integral(8*exp(Integral(8*exp(Integral(8*exp(Integral(8*exp(Integral(8*exp(Integral(8*exp(Integral(8*exp(Integral(8*exp(Integral(8*exp(Integral(8*exp(Integral(8*exp(Integral(8*exp(Integral(8*exp(Integral(8*exp(Integral(8*exp(Integral(8*exp(Integral(8*exp(Integral(8*exp(Integral(8*exp(Integral(8*exp(Integral(8*exp(Integral(8*exp(Integral(8*exp(Integral(8*exp(Integral(8*exp(Integral(8*exp(Integral(8*exp(Integral(8*exp(Integral(8*exp(Integral(8*exp(Integral(8*exp(Integral(8*exp(Integral(8*exp(Integral(8*exp(Integral(8*exp(Integral(8*exp(Integral(8*exp(Integral(8*exp(Integral(8*exp(Integral(8*exp(Integral(8*exp(Integral(8*exp(Integral(8*exp(Integral(8*exp(Integral(8*exp(Integral(8*exp(Integral(8*exp(Integral(8*exp(Integral(8*exp(Integral(8*exp(Integral(8*exp(Integral(8*exp(Integral(8*exp(Integral(8*exp(Integral(8*exp(Integral(8*exp(Integral(8*exp(Integral(8*exp(Integral(8*exp(Integral(8*exp(Integral(8*exp(Integral(8*exp(Integral(8*exp(Integral(8*exp(Integral(8*exp(Integral(8*exp(Integral(8*exp(Integral(8*exp(Integral(8*exp(Integral(8*exp(Integral(8*exp(Integral(8*exp(Integral(8*exp(Integral(8*exp(Integral(8*exp(Integral(8*exp(Integral(8*exp(Integral(8*exp(Integral(8*exp(Integral(8*exp(Integral(8*exp(Integral(8*exp(Integral(8*exp(Integral(8*exp(Integral(8*exp(Integral(8*exp(Integral(8*exp(Integral(8*exp(Integral(8*exp(Integral(8*exp(Integral(8*exp(Integral(8*exp(Integral(8*exp(Integral(8*exp(Integral(8*exp(Integral(8*exp(Integral(8*exp(Integral(8*exp(Integral(8*exp(Integral(8*exp(Integral(8*exp(Integral(8*exp(Integral(8*exp(Integral(8*exp(Integral(8*exp(Integral(8*exp(Integral(8*exp(Integral(8*exp(Integral(8*exp(Integral(8*exp(Integral(8*exp(Integral(8*exp(Integral(8*exp(Integral(8*exp(Integra(8*exp(Integral(8*exp(Integral(8*exp(Integral(8*exp(Integral(8*
                                           ral(12*t, t))/x0(t)**2, t)),
                                               Eq(y(t), C1*y0(t) + C2*(y0(t)*Integral(8*exp(Integral(7*t, t))*exp(Integral(7*t, t))*e
                                           gral(12*t, t))/x0(t)**2, t) + exp(Integral(7*t, t))*exp(Integral(12*t, t))
                                           t))/x0(t)))]
In [33]: # initial conditions
                                         f, g = sp.symbols("f g", cls=sp.Function)
                                         x = sp.symbols("x")
                                         eqs = [sp.Eq(f(x).diff(x), g(x)), sp.Eq(g(x).diff(x), f(x))]
                                         sp.dsolve(eqs, [f(x), g(x)])
                                         # sp.dsolve(eqs, [f(x), g(x)], ics=\{f(0): 1, g(2): 3\})
Out[33]: [Eq(f(x), -C1*exp(-x) + C2*exp(x)), Eq(g(x), C1*exp(-x) + C2*exp(x))]
In [34]: # derivative conditions
                                         eqn = sp.Eq(f(x).diff(x), f(x))
                                         sp.dsolve(eqn, f(x), ics=\{f(x).diff(x).subs(x, 1): 2\})
                                     f(x) = \frac{2e^x}{e}
Out[34]:
In [36]: y = sp.Function("y")
                                         result = sp.dsolve(sp.Derivative(y(x), x, x) + 9 * y(x), y(x))
                                         result
                                         # result.rhs
                                         # y res = result.rhs
                                         # # y_res.subs(x, 0)
                                         \# C1, C2 = sp.symbols("C1, C2")
                                         # y res.subs({C1: 9, C2: sp.pi})
Out [36]: y(x) = C_1 \sin(3x) + C_2 \cos(3x)
    In []: # not all equations can be solved by dsolve
                                         y = sp.Function("y")
                                         x, C = sp.symbols("x C1:2")
                                         # NotImplementedError will be raised
                                         sp.dsolve(sp.Derivative(y(x), x, 3) - (y(x) ** 2), y(x)).rhs
```

#### **Example: Seperable ODE**

Let the following Cauchy problem be given:

$$\begin{cases} \frac{df(t)}{dt} = -2tf(t) \\ f(0) = 1 \end{cases}$$

whose exact solution is  $f(t) = e^{-t^2}$ .

```
In [38]: t = sp.symbols("t") f = sp.Eq(f(t).diff(t), -2 * t * f(t)) eq = sp.Eq(f(t).diff(t), -2 * t * f(t)) print("ODE class:", sp.classify_ode(eq)[0]) result = sp.dsolve(eq, f(t), ics={f(0): 1}) f = result.rhs f ODE class: separable Out[38]: e^{-t^2}
```

#### **Example: Linear ODE**

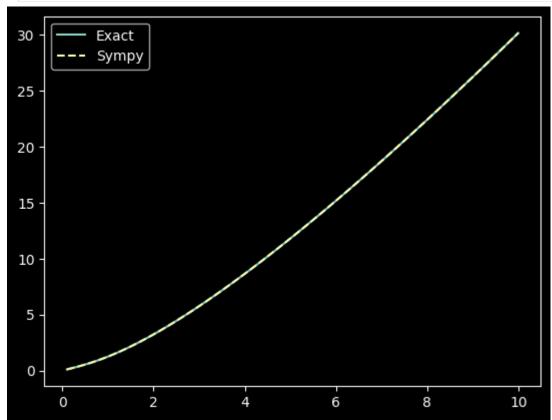
Let the following Cauchy problem be given:

$$\begin{cases} \frac{d}{dt}f(t) = \frac{tf(t)}{1+t^2} + 1\\ f(0) = 0 \end{cases}$$

whose exact solution is  $f(t) = \sqrt{1+t^2} \ln(t+\sqrt{1+t^2})$ 

```
In [43]: t = sp.symbols("t")
         f = sp.Function("f")
         f = sp.sqrt(1 + t**2) * sp.ln(t + sp.sqrt(1 + t**2))
         eq = sp.Eq(f(t).diff(t), (t / (1 + t**2)) * f(t) + 1)
          eq
          print("ODE class:", sp.classify_ode(eq)[0])
         f result = sp.dsolve(eq, ics={f(0): 0}).rhs
          # f result = sp.dsolve(eq, hint="1st linear", ics={f(0): 0}).rhs
         f result
          # f result.simplify()
        ODE class: factorable
Out [43]: t^2 \operatorname{asinh}(t) + \operatorname{asinh}(t)
In [44]: sp.checkodesol(eq, f result)
Out[44]: (True, 0)
In [45]: import matplotlib.pyplot as plt
          import numpy as np
          f_exact_lambdified = sp.lambdify(t, f_exact, modules="numpy")
          f_result_lambdified = sp.lambdify(t, f_result, modules="numpy")
          t_vals = np.linspace(0.1, 10, 100)
```

```
fig = plt.figure()
plt.plot(t_vals, f_exact_lambdified(t_vals), label="Exact")
plt.plot(t_vals, f_result_lambdified(t_vals), "--", label="Sympy")
plt.legend()
plt.show()
plt.close(fig)
```



### **Partial Differential Equations**

```
In [1]: import sympy as sp
from sympy.abc import x, y

f = sp.Function("f")(x, y) # f is a function of x and y

# fx will be the partial derivative of f with respect to x
fx = sp.Derivative(f, x)

# fy will be the partial derivative of f with respect to y
fy = sp.Derivative(f, y)
```

```
In [9]: f = sp.Function("f") # varibales are not passed

u = f(x, y) # now u is a function of x and y

ux = u.diff(x)

uy = u.diff(y)

eq = sp.Eq(1 + (2 * (ux / u)) + (3 * (uy / u)), 0)

sp.pdsolve(eq)
# sp.pdsolve(eq, f(x, y))
```

```
In [10]: result = sp.pdsolve(eq).rhs
sp.checkpdesol(eq, result)
```

Out[10]: (True, 0)

# Example: Linear partial differential equation with constant coefficients

The general form of this partial differential equation is

$$arac{\partial f(x,y)}{\partial x} + brac{\partial f(x,y)}{\partial y} + cf(x,y) = G(x,y)$$

where a, b, c are constants and G(x, y) is a function of x and y.

The general solution of the PDE is:

$$f(x,y)=\left[F(\eta)+rac{1}{a^2+b^2}\int\limits_{-a^2+b^2}^{ax+by}G\left(rac{a\xi+b\eta}{a^2+b^2},rac{-a\eta+b\xi}{a^2+b^2}
ight)e^{rac{c\xi}{a^2+b^2}}d\xi
ight]e^{-rac{c\xi}{a^2+b^2}}igg|_{egin{array}{c} \eta=-a,\ \xi=ax \end{array}}$$

Out[12]: 
$$arac{\partial}{\partial x}f(x,y)+brac{\partial}{\partial y}f(x,y)+cf(x,y)-G(x,y)$$

In [16]: # sp.pdsolve(genform)
sp.pdsolve(genform, hint="lst\_linear\_constant\_coeff\_Integral")