

What is a Notebook?

A notebook is a document that contains both **code** and **rich text elements**, such as *figures, links, equations*, and so on. with using the power of markdown language.

Because of the mix of code and text elements, these documents are the ideal place to bring together an analysis description, and its results, as well as they can be executed perform the data analysis in real time.

Numerical Computation with NumPy

NumPy is a Python library used for working with arrays. It also has functions for working in domain of linear algebra, fourier transform, and matrices. NumPy was created in 2005. It is an open source project and you can use it freely. NumPy stands for Numerical Python.

Creating NumPy Arrays

There are 6 general mechanisms for creating arrays:

1. Conversion from other Python structures (i.e. lists and tuples)

```
In [43]: import numpy as np
```

```
# 1D array
a1D = np.array((1, 2, 3, 4))
# 2D array
a2D = np.array([[1, 2], [3, 4]])
# 3D array
a3D = np.array([[[1, 2], [3, 4]], [[5, 6], [7, 8]]])

a1D
```

```
Out[43]: array([1, 2, 3, 4])
```

```
In [2]: # type(a1D)
a1D.shape
```

```
Out[2]: (4,)
```

```
In [3]: # reshape 1D array to 2D array
a1D[:, np.newaxis]
# a1D.reshape(4, 1)
```

```
Out[3]: array([[1],
               [2],
               [3],
               [4]])
```

2. Intrinsic NumPy array creation functions (e.g. arange, ones, zeros, etc.)

```
In [4]: # range of numbers  
np.arange(10)
```

```
Out[4]: array([0, 1, 2, 3, 4, 5, 6, 7, 8, 9])
```

```
In [5]: np.arange(2, 10, dtype=float)
```

```
Out[5]: array([2., 3., 4., 5., 6., 7., 8., 9.])
```

```
In [6]: np.arange(2, 3, 0.1)
```

```
Out[6]: array([2. , 2.1, 2.2, 2.3, 2.4, 2.5, 2.6, 2.7, 2.8, 2.9])
```

```
In [7]: # evenly spaced numbers  
np.linspace(1.0, 4.0, 6)
```

```
Out[7]: array([1. , 1.6, 2.2, 2.8, 3.4, 4. ])
```

```
In [8]: # identity matrix  
np.eye(3)  
# np.eye(3, 4)
```

```
Out[8]: array([[1., 0., 0.],  
               [0., 1., 0.],  
               [0., 0., 1.]])
```

```
In [9]: # diagonal matrix with diagonal values  
np.diag([1, 2, 3])  
# np.diag([1, 2, 3], k=1)
```

```
Out[9]: array([[1, 0, 0],  
               [0, 2, 0],  
               [0, 0, 3]])
```

```
In [10]: # vandermonde matrix  
np.vander([1, 2, 3, 4], 2)
```

```
Out[10]: array([[1, 1],  
               [2, 1],  
               [3, 1],  
               [4, 1]])
```

```
In [11]: # zeros matrix  
# np.zeros((2, 3))  
np.zeros(3)
```

```
Out[11]: array([0., 0., 0.])
```

```
In [12]: # ones matrix  
np.ones((2, 3))
```

```
Out[12]: array([[1., 1., 1.],  
               [1., 1., 1.]])
```

```
In [13]: # random numbers between 0 and 1  
np.random.rand(2, 3)
```

```
Out[13]: array([[0.21786602, 0.81414132, 0.37531209],
               [0.36782051, 0.42463562, 0.96816076]])
```

```
In [14]: # random integers between 0 and 10
np.random.randint(1, 10, (2, 3))
```

```
Out[14]: array([[9, 1, 1],
               [5, 8, 4]])
```

```
In [15]: # random numbers from a normal distribution
np.random.randn(2, 3)
```

```
Out[15]: array([[ -0.69995692,  1.07337203, -0.06679744],
               [ 1.39563005,  1.21962269,  0.24407526]])
```

```
In [16]: # random numbers from a uniform distribution
# np.random.seed(0)
np.random.uniform(1, 10, (2, 3))
```

```
Out[16]: array([[7.96024217, 2.07225477, 1.84135566],
               [7.49776892, 9.54121129, 6.11969497]])
```

3. Replicating, joining, or mutating existing arrays

```
In [17]: a = np.array([1, 2, 3, 4, 5, 6])
b = a[:2] # create a view of the first two elements
b += 1
# b.base
b, a
```

```
Out[17]: (array([2, 3]), array([2, 3, 3, 4, 5, 6]))
```

```
In [18]: # copy gives a new array
a = np.array([1, 2, 3, 4, 5, 6])
b = a[:2].copy()
b += 1
# b.base # is None since it is a new array
b, a
```

```
Out[18]: (array([2, 3]), array([1, 2, 3, 4, 5, 6]))
```

```
In [19]: # reshape creates a view
a = np.array([1, 2, 3, 4, 5, 6])
b = a.reshape(2, 3)
b.base
```

```
Out[19]: array([1, 2, 3, 4, 5, 6])
```

```
In [20]: # vertical stacking
a = np.array([1, 2, 3])
b = np.array([4, 5, 6])
np.vstack((a, b))
# np.concatenate((a.reshape(1, 3), b.reshape(1, 3)))
```

```
Out[20]: array([[1, 2, 3],
               [4, 5, 6]])
```

```
In [21]: # horizontal stacking
a = np.array([1, 2, 3])
```

```
b = np.array([4, 5, 6])
np.hstack((a, b))
# np.concatenate((a, b))
```

Out[21]: array([1, 2, 3, 4, 5, 6])

```
In [22]: a = np.array([[1], [2], [3]])
b = np.array([[4], [5], [6]])
# np.vstack((a, b))
np.concatenate((a, b))
```

Out[22]: array([[1],
[2],
[3],
[4],
[5],
[6]])

```
In [23]: a = np.array([[1], [2], [3]])
b = np.array([[4], [5], [6]])
np.hstack((a, b))
# np.concatenate((a, b), axis=1)
```

Out[23]: array([[1, 4],
[2, 5],
[3, 6]])

```
In [24]: # creating block matrices
A = np.ones((2, 2))
B = np.eye(2, 2)
C = np.zeros((2, 2))
D = np.diag((-3, -4))
np.block([[A, B], [C, D]])
```

Out[24]: array([[1., 1., 1., 0.],
[1., 1., 0., 1.],
[0., 0., -3., 0.],
[0., 0., 0., -4.]])

4. Reading arrays from disk, either from standard or custom formats

```
In [25]: # save data to a .csv file
a = np.array([[1, 2], [3, 4], [5, 6], [7, 8]])
np.savetxt("simple.csv", a, delimiter=",", header="x, y")
```

```
In [26]: # load data from a .csv file
np.loadtxt("simple.csv", delimiter=",", skiprows=1)
```

Out[26]: array([[1., 2.],
[3., 4.],
[5., 6.],
[7., 8.]])

```
In [27]: # save data to a .npy file
a = np.array([1, 2, 3, 4, 5])
np.save("a.npy", a)
```

```
In [28]: # load data from a .npy file
```

```
np.load("a.npy")
```

```
Out[28]: array([1, 2, 3, 4, 5])
```

```
In [29]: # save data to a .npz file
a = np.array([1, 2, 3, 4, 5])
b = np.array([6, 7, 8, 9, 10])
np.savez("ab.npz", a=a, b=b)
# np.savez_compressed("ab.npz", a=a, b=b) # compressed
```

```
In [30]: # load data from a .npz file
data = np.load("ab.npz")
data["a"], data["b"]
```

```
Out[30]: (array([1, 2, 3, 4, 5]), array([ 6,  7,  8,  9, 10]))
```

```
In [31]: # save data to a .txt file
a = np.array([1, 2, 3, 4, 5])

np.savetxt("a.txt", a)
```

```
In [32]: # load data from a .txt file
np.loadtxt("a.txt")
```

```
Out[32]: array([1., 2., 3., 4., 5.])
```

Broadcasting

NumPy operations are usually done on pairs of arrays on an element-by-element basis.

In the simplest case, the two arrays must have exactly the same shape, as in the following example:

```
In [33]: # broadcasting in vector/matrix multiplication
a = np.array([1.0, 2.0, 3.0])
b = np.array([2.0, 2.0, 2.0])

a * b
```

```
Out[33]: array([2., 4., 6.])
```

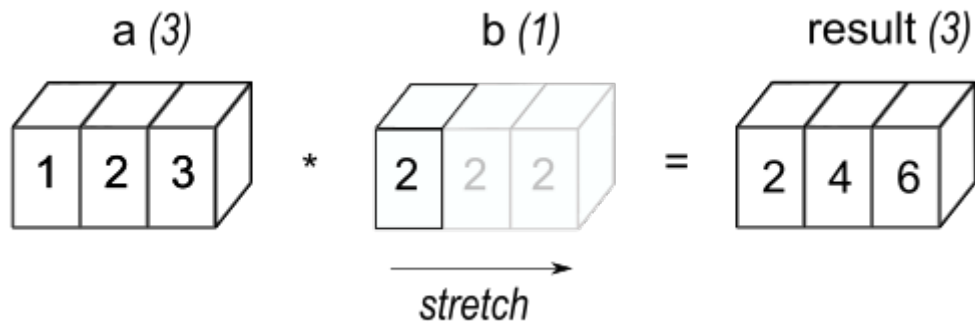
NumPy's broadcasting rule relaxes this constraint when the arrays' shapes meet certain constraints.

The simplest broadcasting example occurs when an array and a scalar value are combined in an operation:

```
In [34]: # broadcasting in scalar multiplication
a = np.array([1.0, 2.0, 3.0])
b = 2.0

a * b
```

```
Out[34]: array([2., 4., 6.])
```



```
In [35]: a = np.array([1, 2, 3])
         2**a
```

```
Out[35]: array([2, 4, 8])
```

General broadcasting rules

When operating on two arrays, NumPy compares their shapes element-wise.

It starts with the trailing (i.e. rightmost) dimension and works its way left.

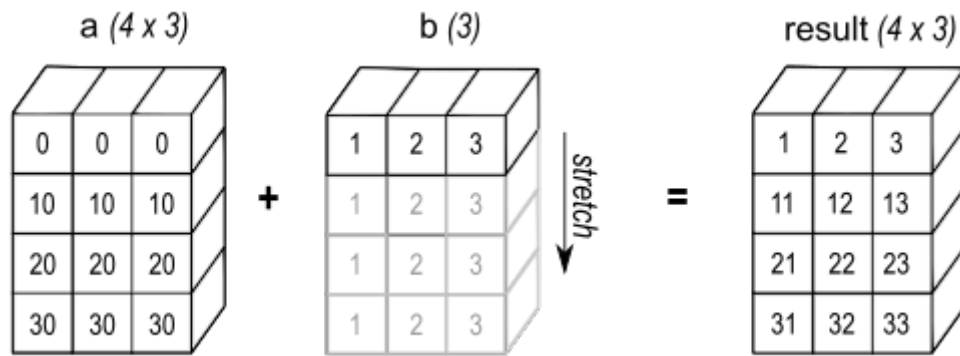
Two dimensions are compatible when

- they are equal, or
- one of them is 1.

```
In [36]: # broadcasting in vector addition with shape matching trailing dimensions
a = np.array(
    [
        [0.0, 0.0, 0.0],
        [10.0, 10.0, 10.0],
        [20.0, 20.0, 20.0],
        [30.0, 30.0, 30.0],
    ]
)
b = np.array([1.0, 2.0, 3.0])
print(a.shape, b.shape)
a + b
```

```
(4, 3) (3,)
```

```
Out[36]: array([[ 1.,  2.,  3.],
                [11., 12., 13.],
                [21., 22., 23.],
                [31., 32., 33.]])
```

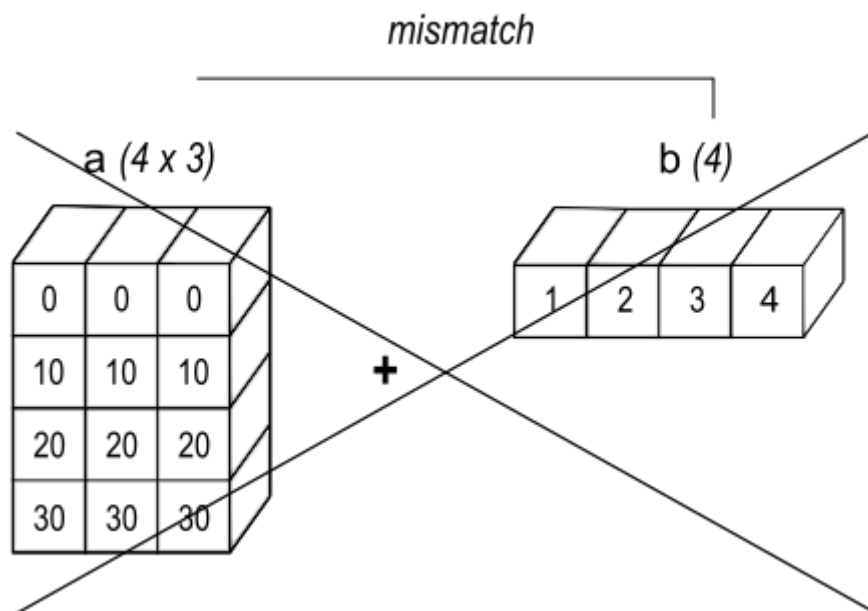


```
In [37]: # broadcasting in vector addition with one of the arrays having a single
a = np.array(
    [
        [0.0, 0.0, 0.0],
        [10.0, 10.0, 10.0],
        [20.0, 20.0, 20.0],
        [30.0, 30.0, 30.0],
    ]
)
b = np.array([1.0])
a + b
```

```
Out[37]: array([[ 1.,  1.,  1.],
               [11., 11., 11.],
               [21., 21., 21.],
               [31., 31., 31.]])
```

```
In [38]: # broadcasting doesn't work in vector addition with shape mismatch
a = np.array(
    [
        [0.0, 0.0, 0.0],
        [10.0, 10.0, 10.0],
        [20.0, 20.0, 20.0],
        [30.0, 30.0, 30.0],
    ]
)
b = np.array([1.0, 2.0, 3.0, 4.0])

# a + b
```



In [39]: *# broadcasting in higher dimensions*

```
array_3d = np.array(
    [
        [[1, 2, 3, 4], [5, 6, 7, 8], [9, 10, 11, 12]],
        [[13, 14, 15, 16], [17, 18, 19, 20], [21, 22, 23, 24]],
    ]
)

print("3D Array shape:", array_3d.shape)

array_2d = np.array([[1, 2, 3, 4], [5, 6, 7, 8], [9, 10, 11, 12]])

print("2D Array shape:", array_2d.shape)

result = array_3d * array_2d

print("3D Array:\n", array_3d)
print("\n2D Array:\n", array_2d)
print("\nResult:\n", result)
```


3D Array shape: (2, 3, 4)

2D Array shape: (3, 4)

3D Array:

```
[[[ 1  2  3  4]
   [ 5  6  7  8]
   [ 9 10 11 12]]
```

```
[[13 14 15 16]
 [17 18 19 20]
 [21 22 23 24]]]
```

2D Array:

```
[[ 1  2  3  4]
 [ 5  6  7  8]
 [ 9 10 11 12]]
```

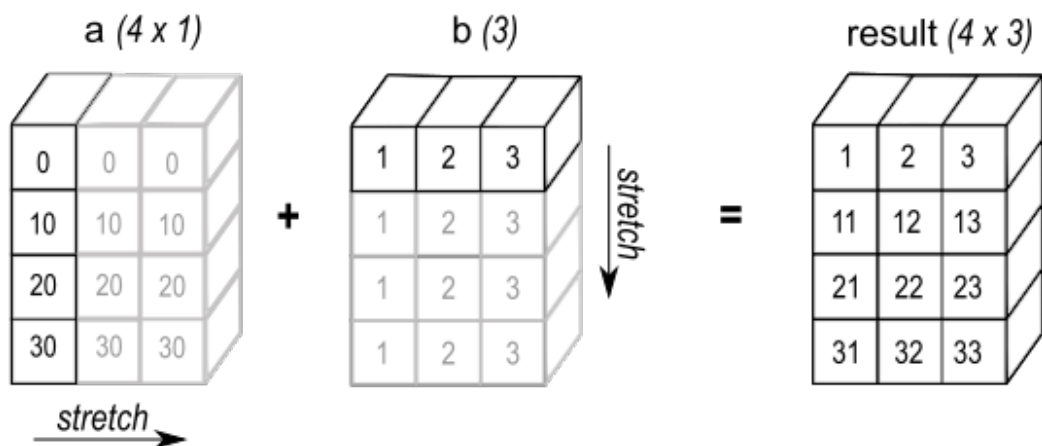
Result:

```
[[[ 1  4  9 16]
   [25 36 49 64]
   [81 100 121 144]]
```

```
[[ 13 28 45 64]
 [ 85 108 133 160]
 [189 220 253 288]]]
```

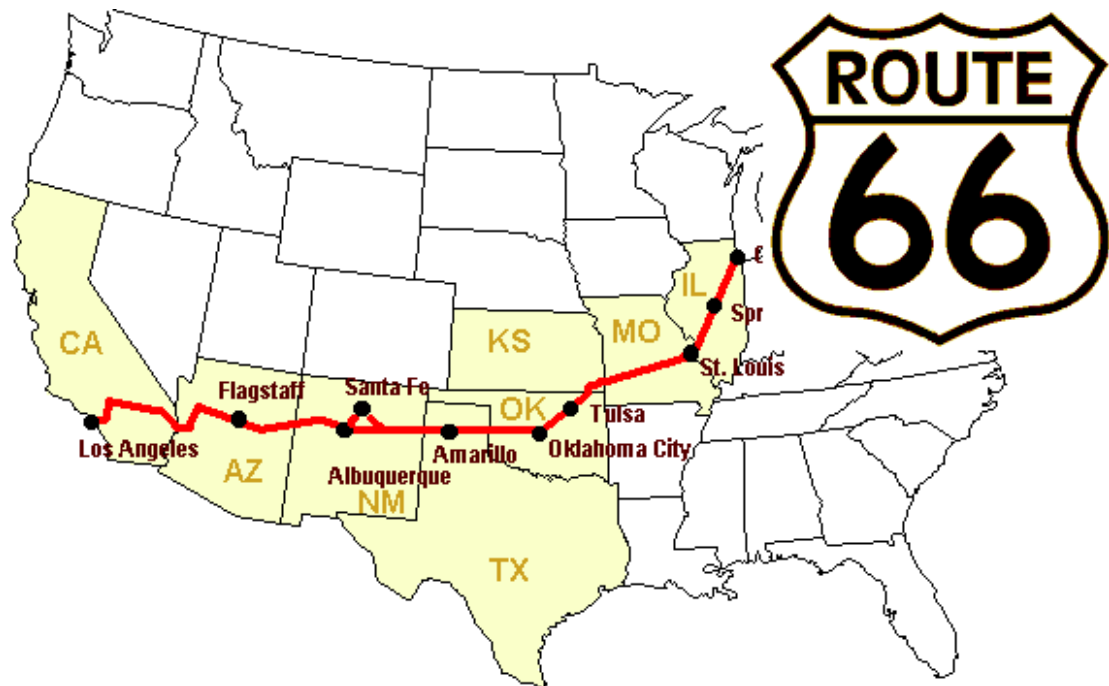
```
In [40]: # In some cases, broadcasting stretches both arrays to form
# an output array larger than either of the initial arrays.
a = np.array([0.0, 10.0, 20.0, 30.0])
b = np.array([1.0, 2.0, 3.0])
a[:, np.newaxis] + b
```

```
Out[40]: array([[ 1.,  2.,  3.],
                [11., 12., 13.],
                [21., 22., 23.],
                [31., 32., 33.]])
```



Worked Example: Broadcasting

Let's construct an array of distances (in miles) between cities of Route 66: Chicago, Springfield, Saint-Louis, Tulsa, Oklahoma City, Amarillo, Santa Fe, Albuquerque, Flagstaff and Los Angeles.



```
In [49]: # mileposts along the road shows the distance between the mileposts
mileposts = np.array([0, 198, 303, 736, 871, 1175, 1475, 1544, 1913, 2448])
distance_array = np.abs(mileposts - mileposts[:, np.newaxis])
distance_array
```

```
Out[49]: array([[ 0, 198, 303, 736, 871, 1175, 1475, 1544, 1913, 2448],
 [198,  0, 105, 538, 673, 977, 1277, 1346, 1715, 2250],
 [303, 105,  0, 433, 568, 872, 1172, 1241, 1610, 2145],
 [736, 538, 433,  0, 135, 439, 739, 808, 1177, 1712],
 [871, 673, 568, 135,  0, 304, 604, 673, 1042, 1577],
 [1175, 977, 872, 439, 304,  0, 300, 369, 738, 1273],
 [1475, 1277, 1172, 739, 604, 300,  0,  69, 438, 973],
 [1544, 1346, 1241, 808, 673, 369,  69,  0, 369, 904],
 [1913, 1715, 1610, 1177, 1042, 738, 438, 369,  0, 535],
 [2448, 2250, 2145, 1712, 1577, 1273, 973, 904, 535,  0]])
```

```
In [55]: import sympy as sp
```

```
cities = [
    "Chicago",
    "Springfield",
    "Saint-Louis",
    "Tulsa",
    "Oklahoma City",
    "Amarillo",
    "Santa Fe",
    "Albuquerque",
    "Flagstaff",
    "Los Angeles",
]
```

```
table = distance_array.tolist()
```

```
sp.TableForm(table, alignments=">", headings=(cities, cities))
```

```
Out[55]: | Chicago Springfield Saint-Louis Tulsa Oklahoma City Amar
illo Santa Fe Albuquerque Flagstaff Los Angeles
-----
-----
Chicago | 198 303 736 871
1175 1475 1544 1913 2448
Springfield | 198 105 538 673
977 1277 1346 1715 2250
Saint-Louis | 303 105 433 568
872 1172 1241 1610 2145
Tulsa | 736 538 433 135
439 739 808 1177 1712
Oklahoma City | 871 673 568 135
304 604 673 1042 1577
Amarillo | 1175 977 872 439 304
300 369 738 1273
Santa Fe | 1475 1277 1172 739 604
300 69 438 973
Albuquerque | 1544 1346 1241 808 673
369 69 369 904
Flagstaff | 1913 1715 1610 1177 1042
738 438 369 535
Los Angeles | 2448 2250 2145 1712 1577
1273 973 904 535
```

Example: Distance between points

If we want to compute the distance from the origin of points on a 5x5 grid, we can do

```
In [80]: x, y = np.arange(5), np.arange(5)[: , np.newaxis]
distance = np.sqrt(x**2 + y**2)
distance
```

```
Out[80]: array([[0. , 1. , 2. , 3. , 4. ],
 [1. , 1.41421356, 2.23606798, 3.16227766, 4.12310563],
 [2. , 2.23606798, 2.82842712, 3.60555128, 4.47213595],
 [3. , 3.16227766, 3.60555128, 4.24264069, 5. ],
 [4. , 4.12310563, 4.47213595, 5. , 5.65685425]])
```

```
In [81]: # assignment to a slice of an array uses broadcasting
a = np.ones((4, 5))
a[0] = 2
a
```

```
Out[81]: array([[2., 2., 2., 2., 2.],
 [1., 1., 1., 1., 1.],
 [1., 1., 1., 1., 1.],
 [1., 1., 1., 1., 1.]])
```

```
In [82]: # warning!
# array multiplication is not matrix multiplication
a = np.array([[1, 2], [3, 4]])
b = np.array([[1, 2], [3, 4]])

a * b
```

```
Out[82]: array([[ 1,  4],
 [ 9, 16]])
```

```
In [83]: # matrix multiplication
a = np.array([[1, 2], [3, 4]])
b = np.array([[1, 2], [3, 4]])

a @ b
# np.matmul(a, b)
```

```
Out[83]: array([[ 7, 10],
               [15, 22]])
```

```
In [84]: # element-wise comparison
a = np.array([1, 2, 3, 4])
b = np.array([4, 2, 2, 4])
# a == b
a > b
```

```
Out[84]: array([False, False,  True, False])
```

```
In [85]: # array-wise comparison
a = np.array([1, 2, 3, 4])
b = np.array([4, 2, 2, 4])
c = np.array([1, 2, 3, 4])
np.array_equal(a, b)
# np.array_equal(a, c)
```

```
Out[85]: False
```

```
In [4]: # using any and all
a = np.zeros((100, 100))
np.any(a != 0)
# np.all(a == a)
```

```
[[0. 0. 0. ... 0. 0. 0.]
 [0. 0. 0. ... 0. 0. 0.]
 [0. 0. 0. ... 0. 0. 0.]
 ...
 [0. 0. 0. ... 0. 0. 0.]
 [0. 0. 0. ... 0. 0. 0.]
 [0. 0. 0. ... 0. 0. 0.]]
```

```
Out[4]: np.False_
```

```
In [87]: # transcendental functions
x = np.arange(5)
y = np.sin(x)
# y = np.exp(x)
# y = np.log(np.exp(x))
y
```

```
Out[87]: array([ 0.          ,  0.84147098,  0.90929743,  0.14112001, -0.7568025 ])
```

```
In [88]: # computing sums
x = np.array([1, 2, 3, 4])

np.sum(x)
# x.sum()
```

```
Out[88]: np.int64(10)
```

```
In [89]: x = np.array([[1, 1], [2, 2]])  
x.sum()
```

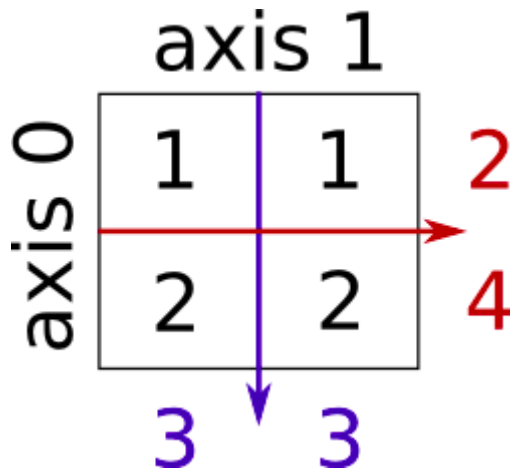
```
Out[89]: np.int64(6)
```

```
In [90]: x.shape
```

```
Out[90]: (2, 2)
```

```
In [91]: # x.sum(axis=0)  
x.sum(axis=1)
```

```
Out[91]: array([2, 4])
```



```
In [92]: # computing minima and maxima  
x = np.array([1, 3, 2])  
# x.min()  
x.max()
```

```
Out[92]: np.int64(3)
```

```
In [93]: # index of minimum and maximum  
# x.argmin()  
x.argmax()
```

```
Out[93]: np.int64(1)
```

```
In [94]: # computing minimum and maximum along a given axis  
x = np.array([[1, 2, 3], [4, 5, 6]])  
# x.min(axis=0)  
x.max(axis=1)
```

```
Out[94]: array([3, 6])
```

```
In [95]: a = np.array([[1, 2, 3], [4, 5, 6]])  
# a.ravel()  
a.flatten()
```

```
Out[95]: array([1, 2, 3, 4, 5, 6])
```

```
In [96]: # a.T.flatten()  
a.T.ravel()
```

```
Out[96]: array([1, 4, 2, 5, 3, 6])
```

```
In [5]: a = np.array([[4, 3, 5], [1, 2, 1]])  
b = np.sort(a, axis=0)  
b
```

```
Out[5]: array([[1, 2, 1],  
              [4, 3, 5]])
```

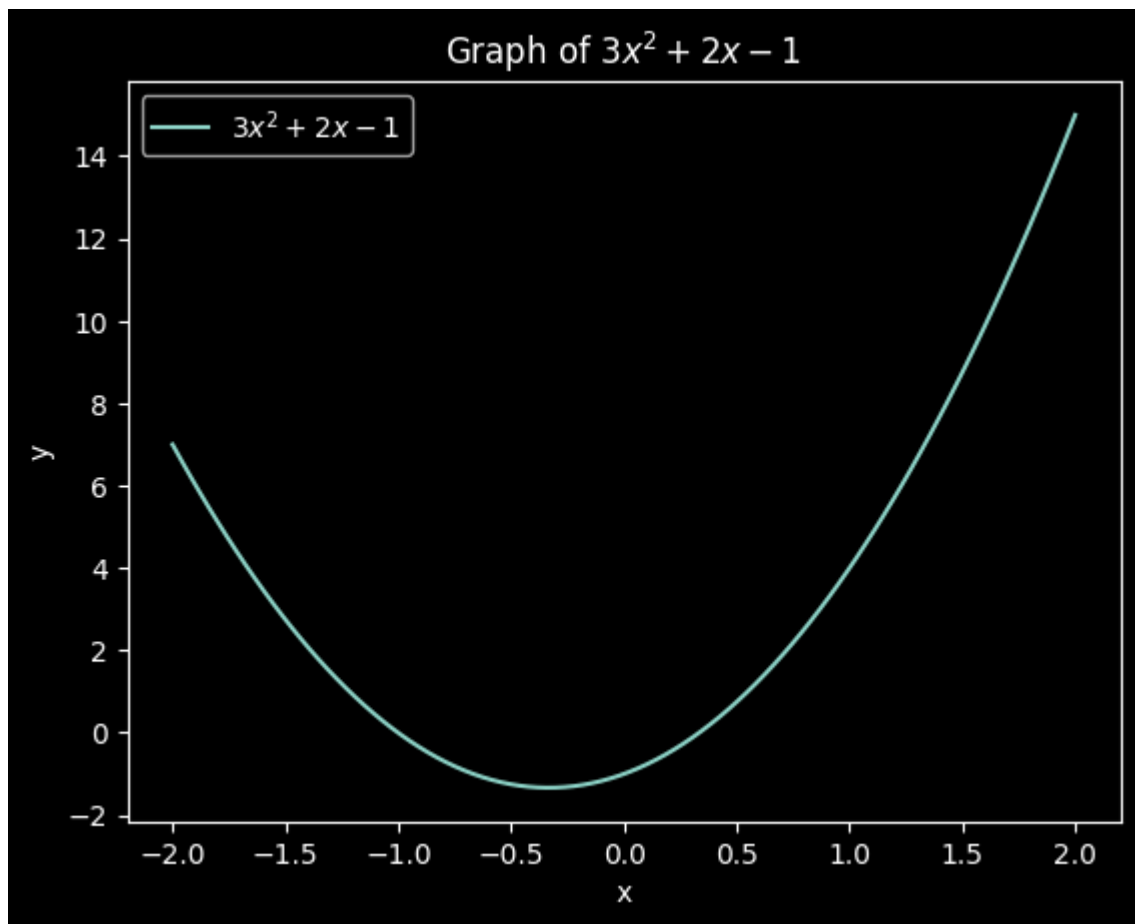
```
In [98]: a.sort(axis=1)  
a
```

```
Out[98]: array([[3, 4, 5],  
              [1, 1, 2]])
```

```
In [13]: # the polynomial 3x^2 + 2x - 1 is represented by the coefficients [3, 2,  
p = np.polyld([3, 2, -1])  
p(2)  
# np.polyval([3, 2, -1], 2)  
# p.roots  
# p.order
```

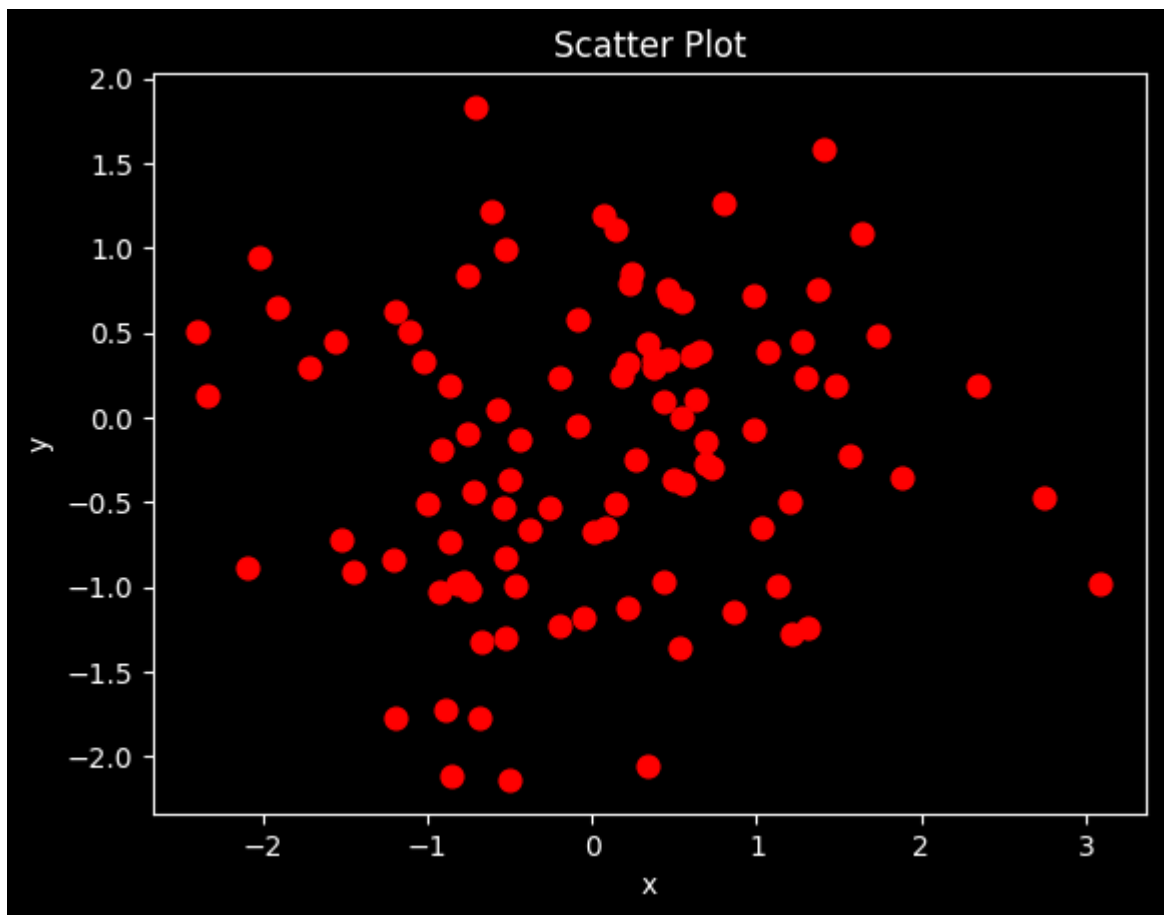
```
Out[13]: np.int64(15)
```

```
In [100... # graphing a polynomial using matplotlib  
import matplotlib.pyplot as plt  
  
p = np.polyld([3, 2, -1])  
x = np.linspace(-2, 2, 100)  
y = p(x)  
  
fig = plt.figure()  
plt.plot(x, y, label=r"$3x^2 + 2x - 1$")  
plt.xlabel("x")  
plt.ylabel("y")  
plt.legend(loc="best")  
plt.title(r"Graph of $3x^2 + 2x - 1$")  
plt.show()  
plt.close(fig)
```



```
In [101]: # graphing scatter plots using matplotlib
x = np.random.randn(100)
y = np.random.randn(100)

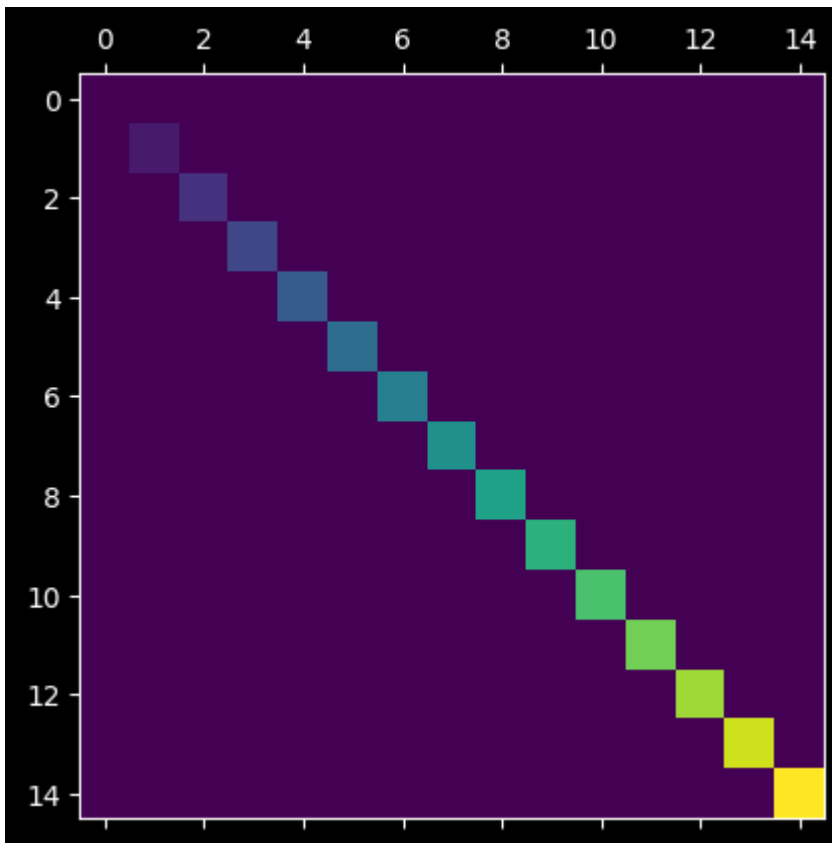
fig = plt.figure()
plt.scatter(x, y, color="r", marker="o", s=60)
plt.xlabel("x")
plt.ylabel("y")
plt.title("Scatter Plot")
plt.show()
plt.close(fig)
```



```
In [102... a = np.diag(range(15))

fig = plt.figure()
plt.matshow(a)
# plt.imshow(a, cmap="hot")
# plt.colorbar()
plt.show()
plt.close(fig)
```

<Figure size 640x480 with 0 Axes>



```
In [103... import pyodide
import io
from PIL import Image

url = "https://upload.wikimedia.org/wikipedia/commons/4/46/Plac_Wilsona_W
fetch = await pyodide.http.pyfetch(url)
data = await fetch.bytes()

img_file = io.BytesIO(data)
img = Image.open(img_file)
image_array = np.array(img)
print(image_array.shape)

(2736, 3648, 3)
```

Symbolic Computation with SymPy

SymPy is a Python library for symbolic mathematics. It aims to become a full-featured computer algebra system (CAS) while keeping the code as simple as possible in order to be comprehensible and easily extensible. SymPy is written entirely in Python.

```
In [104... import sympy as sp
from sympy.abc import x, y, z

# x, y, z = sp.symbols("x y z")

expr = sp.cos(x) + 1
expr.subs(x, y)
# expr.subs(x, 0)
```

Out[104... $\cos(y) + 1$

```
In [105... # multiple substitutions
expr = x**3 + 4 * x * y - z
expr.subs([(x, 2), (y, 4), (z, 0)])
```

Out[105... 40

```
In [106... expr = x**4 - 4 * x**3 + 4 * x**2 - 2 * x + 3
replacements = [(x**i, y**i) for i in range(5) if i % 2 == 0]
expr.subs(replacements)
```

Out[106... $-4x^3 - 2x + y^4 + 4y^2 + 3$

```
In [107... # converting strings to sympy expressions
str_expr = "x**2 + 3*x - 1/2"
expr = sp.sympify(str_expr)

expr
```

Out[107... $x^2 + 3x - \frac{1}{2}$

```
In [108... # evaluating expressions
expr = sp.sqrt(8)
# expr = sp.pi
expr
# expr.evalf()
```

Out[108... $2\sqrt{2}$

```
In [109... # evaluating expressions with precision
one = sp.cos(1) ** 2 + sp.sin(1) ** 2
# (one - 1).evalf()
(one - 1).evalf(chop=True)
```

Out[109... 0

```
In [110... # using lambdify to convert sympy expressions to numerical functions
a = np.arange(10)
expr = sp.sin(x)
# expr.subs(x, a)
f = sp.lambdify(x, expr, "numpy")
f(a)
```

Out[110... array([0. , 0.84147098, 0.90929743, 0.14112001, -0.7568025 ,
 -0.95892427, -0.2794155 , 0.6569866 , 0.98935825, 0.41211849])

```
In [111... # simplifying expressions
expr = sp.sin(x) ** 2 + sp.cos(x) ** 2
# sp.simplify(expr)
# expr.simplify()
expr
```

Out[111... $\sin^2(x) + \cos^2(x)$

```
In [112... sp.simplify((x**3 + x**2 - x - 1) / (x**2 + 2 * x + 1))
```

```
Out[112...  $x - 1$ 
```

```
In [113... sp.simplify(sp.gamma(x) / sp.gamma(x - 2))
```

```
Out[113...  $(x - 2)(x - 1)$ 
```

```
In [114... # polynomial simplification is factoring
sp.simplify(x**2 + 2 * x + 1)
# sp.factor(x**2 + 2 * x + 1)
# sp.factor(x**2 * z + 4 * x * y * z + 4 * y**2 * z)
sp.factor_list(x**2 * z + 4 * x * y * z + 4 * y**2 * z)
```

```
Out[114... (1, [(z, 1), (x + 2*y, 2)])
```

```
In [115... # expanding expressions
# sp.expand((x + 2) * (x - 3))
sp.expand((x + 1) * (x - 2) - (x - 1) * x)
```

```
Out[115... -2
```

```
In [116... # expanding will also work with trigonometric functions
sp.expand((sp.cos(x) + sp.sin(x)) ** 2)
sp.factor(sp.cos(x) ** 2 + 2 * sp.cos(x) * sp.sin(x) + sp.sin(x) ** 2)
```

```
Out[116...  $(\sin(x) + \cos(x))^2$ 
```

```
In [117... sp.trigsimp(sp.sin(x) ** 4 - 2 * sp.cos(x) ** 2 * sp.sin(x) ** 2 + sp.cos
```

```
Out[117...  $\frac{\cos(4x)}{2} + \frac{1}{2}$ 
```

```
In [118... sp.expand_trig(sp.tan(2 * x))
```

```
Out[118...  $\frac{2 \tan(x)}{1 - \tan^2(x)}$ 
```

```
In [119... x, y = sp.symbols("x y", positive=True)
a, b = sp.symbols("a b", real=True)

# simplifying expressions with assumptions
# sp.sqrt(x**2)
# sp.powsimp(x**a * x**b)
sp.powsimp(x**a * y**a)
```

```
Out[119...  $(xy)^a$ 
```

```
In [120... x, y = sp.symbols("x y", positive=True)
n = sp.symbols("n", real=True)

sp.expand_log(sp.ln(x * y))
# sp.expand_log(sp.log(x**n))
# sp.logcombine(sp.log(x) + sp.log(y))
```

Out[120... $\log(x) + \log(y)$

```
In [121... x, y, z = sp.symbols("x y z")
k, m, n = sp.symbols("k m n")

sp.factorial(n)
# sp.binomial(n, k)
# sp.gamma(z)
```

Out[121... $n!$

```
In [3]: import sympy as sp

n = sp.symbols("n", integer=True, positive=True)
# sp.tan(x).rewrite(sp.cos)
# sp.factorial(x).rewrite(sp.gamma)
# sp.gamma(x + 1).rewrite(sp.factorial)
# sp.gamma(-n)
sp.factorial(-n)
```

Out[3]: $(-n)!$

```
In [123... # derivatives
f = sp.Function("f")(x)

f.diff(x)
# sp.diff(f, x)
# f.diff(x, x)
# f.diff(x, 2)
```

Out[123... $\frac{d}{dx}f(x)$

```
In [124... expr = sp.exp(x * y * z)
# sp.diff(expr, x, y, y, z, z, z, z)

# to create an unevaluated derivative, use sp.Derivative
deriv = sp.Derivative(expr, x, y, y, z, 4)
# deriv
deriv.doit()
```

Out[124... $x^3y^2(x^3y^3z^3 + 14x^2y^2z^2 + 52xyz + 48)e^{xyz}$

```
In [125... # integrals

# indefinite integrals
f = sp.Function("f")(x)

f.integrate(x)
# sp.integrate(f, x)
```

Out[125... $\int f(x) dx$

```
In [127... # definite integrals
f = sp.exp(-x)
```

```
sp.integrate(f, (x, 0, 1))
# sp.integrate(f, (x, 0, sp.oo))
```

Out[127... $1 - e^{-1}$

```
In [128... expr = sp.Integral(sp.log(x) ** 2, x)

expr
# expr.doit()
```

Out[128... $\int \log(x)^2 dx$

```
In [132... integral = sp.Integral(sp.sqrt(2) * x, (x, 0, 1))

# integral
# integral.doit()
integral.evalf(50)
```

Out[132... 0.70710678118654752440084436210484903928483593768847

```
In [133... # limits
sp.limit(sp.sin(x) / x, x, 0)
```

Out[133... 1

```
In [135... expr = x**2 / sp.exp(x)

expr.subs(x, sp.oo)
# sp.limit(expr, x, sp.oo)
```

Out[135... 0

```
In [136... expr = sp.Limit((sp.cos(x) - 1) / x, x, 0)
expr
# expr.doit()
```

Out[136... $\lim_{x \rightarrow 0^+} \left(\frac{\cos(x) - 1}{x} \right)$

```
In [140... # series expansion
expr = sp.exp(sp.sin(x))
# sp.series(expr, x, 0, 6)
expr.series(x, 0, 6).remove0()
```

Out[140... $-\frac{x^5}{15} - \frac{x^4}{8} + \frac{x^2}{2} + x + 1$

```
In [139... x + x**3 + x**6 + sp.O(x**4)
```

Out[139... $x + x^3 + O(x^4)$

In [141... `sp.exp(x - 6).series(x, x0=6)`

Out[141...
$$-5 + \frac{(x-6)^2}{2} + \frac{(x-6)^3}{6} + \frac{(x-6)^4}{24} + \frac{(x-6)^5}{120} + x + O\left((x-6)^6; x \rightarrow 6\right)$$