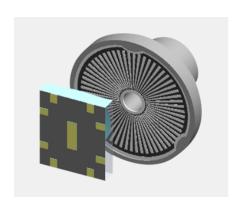
## **Encoder**

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# Very compact design encoder was made possible by designing in one body with the motor.



#### **Magnetic encoder**

Magnetic sensor detects the change of magnetic density and converts into output signals.

#### **Optical encoder**

Consists of a high precision code wheel with reflection/no refection area patterns, and one-package sensor that includes emitter and detector. Output signals are generated according to motor rotation.

An encoder is a device that "encodes".

An encoder is a device or software that converts information into data code under a fixed rule and records or converts data written in one format to another format. This process is called 'encoding'. Examples include conversion pictorial image or moving image, and data compaction or encryption.

A motor encoder detects speed, position or angle of rotation and converts the information into digital signals, which helps with accurate positioning and speed control.

Namiki has 2 types of encoders, magnetic and optical, depending on the dynamic principles.

### **Encoder List**

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Products	Dia.[mm]	Туре	Channel	Resolution [ppr]	Max Rotation Speed [rpm]	Motor Combination	
EHM07-3B	7	Magnetic	3ch	64	55,000	O CMS07 series	
ETD07-2B	,	Optical	2ch	64	50,000	△ BMS07 series (need modification	
ETD10-2C		Optical	2ch	128	50,000		
ETD10-2D	10	Optical	2ch	256	50,000	<ul> <li>CMS10 Series</li> </ul>	
ETD10-2E		Optical	2ch	512	50,000	△ BMS10 series (need modification)	
EHM10-3B		Magnetic	3ch	64	55,000		
ETD12-2C		Optical	2ch	128	50,000		
ETD12-2D	12	Optical	2ch	256	50,000	○ CMS12 series △ BMS12 series (need modification)	
ETD12-2E		Optical	2ch	512	50,000		
ETD16-2D		Optical	2ch	256	25,000		
ETD16-2E		Optical	2ch	512	25,000		
ETD16-2F	16	Optical	2ch	1024	25,000	○ CMS16 series △ BMS16 series (need modification)	
ETD16-3D		Optical	3ch	256	25,000		
ETD16-3E		Optical	3ch	512	25,000		

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Products	Dia.[mm]	Туре	Channel	Resolution [ppr]	Max Rotation Speed [rpm]	Motor Combination
ETD16-3F		Optical	3ch	1024	25,000	
	optio	nal, not standa	ard			
	unde	r developmen	t			

Please refer to " " for dimension when combined with motor and gear.

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