view_frames Result

Recorded at time: 1587133484.786

laser

map Broadcaster: /hector_mapping Broadcaster: /hector_mapping Average rate: 15.315 Hz Average rate: 7.921 Hz Most recent transform: 1587133484.548 (0.238 sec old) Most recent transform: 1587133484.448 (0.338 sec old) Buffer length: 4.897 sec Buffer length: 4.797 sec odom scanmatcher_frame Broadcaster: /robot_pose_ekf Average rate: 11.364 Hz Most recent transform: 1587133484.574 (0.212 sec old) Buffer length: 4.928 sec base_link Broadcaster: /base_to_laser_broadcaster Average rate: 10.175 Hz Most recent transform: 1587133484.831 (-0.045 sec old) Buffer length: 4.816 sec