## Part 1:

• For the first part, I started with a simple for loop that goes through each of the spheres, returning red if the ray intersects with any of them. Returns bgcolor otherwise

```
{
    Vector3f pixelColor = bgcolor;

// TODO: implement ray tracing as described in the homework description float t0, t1;
    for (int i = 0; i < spheres.size(); i++) {
        if (spheres[i].intersect(rayOrigin, rayDirection, t0, t1)) {
            pixelColor = Vector3f(1.0, 0.0, 0.0);
            return pixelColor;
        }
}

return pixelColor;
}</pre>
```

• To return the colors of the spheres intersected, I had to determine which sphere was in front. I did this by keeping track of the smallest t0 returned by intersect() and the sphere associated with it. After going through all spheres, I return the color of the closest sphere.

```
Vector3f pixelColor = bgcolor;

// TODO: implement ray tracing as described in the homework description
float t0, t1, minDist = 0.0;
int closestSphere = -1;

for (int i = 0; i < spheres.size(); i++) {
    if (spheres[i].intersect(rayOrigin, rayDirection, t0, t1)) {
        //If this is the first sphere intersected, make it the closestSphere
    if (closestSphere == -1) {
        minDist = t0;
        closestSphere = i;
    }

    //Update the closestSphere if it is closer to the origin than the current closestSphere
    else {
        if (t0 < minDist) {
            minDist = t0;
            closestSphere = i;
        }
    }
    pixelColor = spheres[closestSphere].surfaceColor;
}
</pre>
```

## Part 2:

• Using the same for loop from above to find the closestSphere, I then add 3 new variables to find the effect of the light on the spheres:

```
Vector3f intersectionPoint = Vector3f(0.0, 0.0, 0.0);
Vector3f lightDirection = Vector3f(0.0, 0.0, 0.0);
bool lightBlocked = false;
```

• Once I know the closestSphere and the closest distance minDist (which is essentially the point visible from origin), I store the location of where the ray hit the closestSphere in intersectionPoint. Using this point as the new origin, I check if a ray from the point to each light intersects a sphere. If there are no intersections, the light contributes 0.333 \* surfaceColor to the pixel, creating shadows.

## Part 3:

• To implement the diffuse shading, the only additions I had to make to part 2 was a way to compute the surface normal at point P, and to put in the equation described in the pdf. For starters, I defined a new variable surfaceNormal:

```
Vector3f surfaceNormal = Vector3f(0.0, 0.0, 0.0);
```

• I then computed the surface normal using the point P (intersection point) and the center of the sphere in question (closestSphere):

```
if (closestSphere != -1) {
    //The coordinates of the point of intersection closest to the origin.
    intersectionPoint = rayOrigin + (minDist * rayDirection);
    surfaceNormal = intersectionPoint - spheres[closestSphere].center;
    surfaceNormal.normalize();
```

• I now have L (lightDirection), N (surfaceNormal), diffuseColor (spheres[closestSphere].surfaceColor), and kd (1). With this information, I simply define diffuse using the equation in the pdf:

```
Vector3f diffuse(const Vector3f &L, // direction vector from the point on the surface towards a light source
    const Vector3f &N, // normal at this point on the surface
    const Vector3f &diffuseColor,
    const float kd // diffuse reflection constant
    )
{
    Vector3f resColor = Vector3f::Zero();

    // TODO: implement diffuse shading model
    resColor += 0.333 * kd * std::max(L.dot(N), 0.0f) * diffuseColor;
    return resColor;
}
```

• And finally, I call diffuse whenever I increment pixelColor, which is when there are no spheres blocking the light:

```
//Add the light's contribution if it is not blocked above
if (!lightBlocked)
    pixelColor += diffuse(lightDirection, surfaceNormal, spheres[closestSphere].surfaceColor, 1.0);
```

• Next, for the complete Phong shading model, I am only lacking the parameter V, which I define as againstRay and compute below:

```
//Calculate V, the vector pointing against the ray
againstRay = rayOrigin - intersectionPoint;
againstRay.normalize();
```

• I now have every parameter needed to pass to phong, which is defined as the summation of the diffuse and specular components for each light. I do this similarly to previous steps: I just add what is returned by phong to the pixelColor

• To define phong, I first get the diffuse component by calling diffuse with the appropriate parameters. I then find the specular component by first finding the reflection vector R as defined in the lecture slides, and then plugging it into the equation (also defined in the

slides):  $E_S = I_i \cdot C_S \cdot k_S \cdot \max(\cos \beta, 0)^h$ 

```
Vector3f resColor = Vector3f::Zero();
Vector3f R = Vector3f::Zero();

// TODO: implement Phong shading model
resColor += diffuse(L, N, diffuseColor, kd);

R = 2 * N * (N.dot(L)) - L;
resColor += 0.333 * specularColor * ks * pow(std::max(R.dot(V), 0.0f), alpha);
return resColor;
}
```

• And these were the only changes needed to implement phong shading. My final and complete implementation of trace is below:

```
Vector3f trace(
    const Vector3f &rayOrigin,
    const Vector3f &rayOrigin,
    const Vector3f &rayOrigin,
    const Vector3f pixelColor = Vector3f::Zero();

// TODO: implement ray tracing as described in the homework description
    float t0, t1, minDist = 0.0;
    int closestSphere = -1;
    Vector3f intersectionPoint = Vector3f(0.0, 0.0, 0.0);
    Vector3f intersectionPoint = Vector3f(0.0, 0.0, 0.0);
    Vector3f surfaceNormal = Vector3f(0.0, 0.0, 0.0);
    Vector3f sainstRay = Vector3f(0.0, 0.0, 0.0);
    Vector3f againstRay = Vector3f(0.0, 0.0, 0.0);
    Vector3f againstRay = Vector3f(0.0, 0.0, 0.0);
    bool lightBlocked = false;

for (int i = 0; i < spheres.size(); i++) {
        if (spheres[i].intersect(rayOrigin, rayDirection, t0, t1)) {
            //If this is the first sphere intersected, make it the closestSphere
        if (closestSphere == -1) {
            minDist = t0;
            closestSphere if it is closer to the origin than the current closestSphere else {
            if (t0 < minDist) {
                minDist = t0;
            closestSphere = i;
            }
        }
    }
}
</pre>
```