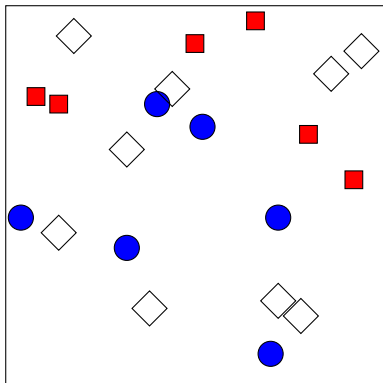


# strelka2Somatic

SomaticEVS



DP—read depth