# Access

|  |
| --- |
| **getLockStatus** This function returns if the device is locked and if the current client is authorized to use the device. |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| Out | locked | Is the device locked? |
| authorized | Is the client authorized? |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: getLockStatus |
| params: [] |
| Result: [locked, authorized] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_getLockStatus**(int deviceHandle, bool\* locked, bool\* authorized) |

|  |
| --- |
| **Python** |

|  |
| --- |
| locked, authorized = **[dev].access.getLockStatus**() |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [locked, authorized] = **AMC\_getLockStatus**() |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **grantAccess** Grants access to a locked device for the requesting IP by checking against the password |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | password | string the current password |
| Out | errNo | errorCode |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: grantAccess |
| params: [password] |
| Result: [errNo] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_grantAccess**(int deviceHandle, const char\* password) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo = **[dev].access.grantAccess**(password) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo] = **AMC\_grantAccess**(password) |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **lock** This function locks the device with a password, so the calling of functions is only possible with this password. The locking IP is automatically added to the devices which can access functions |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | password | string the password to be set |
| Out | errNo | errorCode |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: lock |
| params: [password] |
| Result: [errNo] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_lock**(int deviceHandle, const char\* password) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo = **[dev].access.lock**(password) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo] = **AMC\_lock**(password) |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **unlock** This function unlocks the device, so it will not be necessary to execute the grantAccess function to run any function |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | password | string the current password |
| Out | errNo | errorCode |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: unlock |
| params: [password] |
| Result: [errNo] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_unlock**(int deviceHandle, const char\* password) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo = **[dev].access.unlock**(password) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo] = **AMC\_unlock**(password) |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

# Amcids

|  |
| --- |
| **getLowerSoftLimit** Gets the lower boundary of the soft limit protection.  This protection is needed if the IDS working range is smaller than the positioners travel range.  It is no hard limit, so, it is possible to overshoot it! |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | axis | Axis of the AMC to get the soft limit status from |
| Out | errNo | int32 Error number if one occured, 0 in case of no error |
| limit | double Lower boundary in pm |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.amc.amcids.getLowerSoftLimit |
| params: [axis] |
| Result: [errNo, limit] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_amcids\_getLowerSoftLimit**(int deviceHandle, int axis, double\* limit) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo, limit = **[dev].amcids.getLowerSoftLimit**(axis) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo, limit] = **amcids\_getLowerSoftLimit**(axis) |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **getSoftLimitEnabled** Gets whether the soft limit protection is enabled.  This protection is needed if the IDS working range is smaller than the positioners travel range.  It is no hard limit, so, it is possible to overshoot it! |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | axis | Axis of the AMC to get the soft limit status from |
| Out | errNo | int32 Error number if one occured, 0 in case of no error |
| enabled | boolean True, if the soft limit should be enabled on this axis |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.amc.amcids.getSoftLimitEnabled |
| params: [axis] |
| Result: [errNo, enabled] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_amcids\_getSoftLimitEnabled**(int deviceHandle, int axis, bool\* enabled) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo, enabled = **[dev].amcids.getSoftLimitEnabled**(axis) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo, enabled] = **amcids\_getSoftLimitEnabled**(axis) |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

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| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **getSoftLimitReached** Gets whether the current position is out of the soft limit boundaries.  This protection is needed if the IDS working range is smaller than the positioners travel range.  It is no hard limit, so, it is possible to overshoot it! |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | axis | Axis of the AMC to get the soft limit status from |
| Out | errNo | int32 Error number if one occured, 0 in case of no error |
| enabled | boolean True, if the position is not within the boundaries |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.amc.amcids.getSoftLimitReached |
| params: [axis] |
| Result: [errNo, enabled] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_amcids\_getSoftLimitReached**(int deviceHandle, int axis, bool\* enabled) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo, enabled = **[dev].amcids.getSoftLimitReached**(axis) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo, enabled] = **amcids\_getSoftLimitReached**(axis) |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

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| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **getUpperSoftLimit** Gets the upper lower boundary of the soft limit protection.  This protection is needed if the IDS working range is smaller than the positioners travel range.  It is no hard limit, so, it is possible to overshoot it! |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | axis | Axis of the AMC to get the soft limit status from |
| Out | errNo | int32 Error number if one occured, 0 in case of no error |
| limit | double Upper boundary in pm |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.amc.amcids.getUpperSoftLimit |
| params: [axis] |
| Result: [errNo, limit] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_amcids\_getUpperSoftLimit**(int deviceHandle, int axis, double\* limit) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo, limit = **[dev].amcids.getUpperSoftLimit**(axis) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo, limit] = **amcids\_getUpperSoftLimit**(axis) |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

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| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **resetIdsAxis** Resets the position value to zero of a specific measurement axis.  Use this for positioners with an IDS as sensor.  This method does not work for NUM and RES sensors. Use com.attocube.amc.control.resetAxis instead. |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | axis | Axis of the IDS to reset the position |
| Out | errNo | int32 Error number if one occured, 0 in case of no error |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.amc.amcids.resetIdsAxis |
| params: [axis] |
| Result: [errNo] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_amcids\_resetIdsAxis**(int deviceHandle, int axis) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo = **[dev].amcids.resetIdsAxis**(axis) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo] = **amcids\_resetIdsAxis**(axis) |

|  |
| --- |
| **C#** |

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| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

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| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **setLowerSoftLimit** Sets the lower boundary of the soft limit protection in pm.  This protection is needed if the IDS working range is smaller than the positioners travel range.  It is no hard limit, so, it is possible to overshoot it! |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | axis | Axis of the AMC where the soft limit should be changed |
| limit | Lower boundary in pm |
| Out | errNo | int32 Error number if one occured, 0 in case of no error |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.amc.amcids.setLowerSoftLimit |
| params: [axis, limit] |
| Result: [errNo] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_amcids\_setLowerSoftLimit**(int deviceHandle, int axis, double limit) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo = **[dev].amcids.setLowerSoftLimit**(axis, limit) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo] = **amcids\_setLowerSoftLimit**(axis, limit) |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **setSoftLimitEnabled** Enables/disables the soft limit protection.  This protection is needed if the IDS working range is smaller than the positioners travel range.  It is no hard limit, so, it is possible to overshoot it! |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | axis | Axis of the AMC where the soft limit should be changed |
| enabled | True, if the soft limit should be enabled on this axis |
| Out | errNo | int32 Error number if one occured, 0 in case of no error |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.amc.amcids.setSoftLimitEnabled |
| params: [axis, enabled] |
| Result: [errNo] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_amcids\_setSoftLimitEnabled**(int deviceHandle, int axis, bool enabled) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo = **[dev].amcids.setSoftLimitEnabled**(axis, enabled) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo] = **amcids\_setSoftLimitEnabled**(axis, enabled) |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **setUpperSoftLimit** Sets the upper boundary of the soft limit protection in pm.  This protection is needed if the IDS working range is smaller than the positioners travel range.  It is no hard limit, so, it is possible to overshoot it! |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | axis | Axis of the AMC where the soft limit should be changed |
| limit | Upper boundary in pm |
| Out | errNo | int32 Error number if one occured, 0 in case of no error |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.amc.amcids.setUpperSoftLimit |
| params: [axis, limit] |
| Result: [errNo] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_amcids\_setUpperSoftLimit**(int deviceHandle, int axis, double limit) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo = **[dev].amcids.setUpperSoftLimit**(axis, limit) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo] = **amcids\_setUpperSoftLimit**(axis, limit) |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

# Control

|  |
| --- |
| **MultiAxisPositioning** Simultaneously set 3 axes positions  and get positions to minimize network latency |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | set1 | axis1 otherwise pos1 target is ignored |
| set2 | axis2 otherwise pos2 target is ignored |
| set3 | axis3 otherwise pos3 target is ignored |
| target1 | target position of axis 1 |
| target2 | target position of axis 2 |
| target3 | target position of axis 3 |
| Out | errNo | errNo |
| ref1 | Status of axis 1 |
| ref2 | Status of axis 2 |
| ref3 | Status of axis 3 |
| refpos1 | reference Position of axis 1 |
| refpos2 | reference Position of axis 2 |
| refpos3 | reference Position of axis 3 |
| pos1 | position of axis 1 |
| pos2 | position of axis 2 |
| pos3 | position of axis 3 |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.amc.control.MultiAxisPositioning |
| params: [set1, set2, set3, target1, target2, target3] |
| Result: [errNo, ref1, ref2, ref3, refpos1, refpos2, refpos3, pos1, pos2, pos3] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_control\_MultiAxisPositioning**(int deviceHandle, bool set1, bool set2, bool set3, int target1, int target2, int target3, bool\* ref1, bool\* ref2, bool\* ref3, int\* refpos1, int\* refpos2, int\* refpos3, int\* pos1, int\* pos2, int\* pos3) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo, ref1, ref2, ref3, refpos1, refpos2, refpos3, pos1, pos2, pos3 = **[dev].control.MultiAxisPositioning**(set1, set2, set3, target1, target2, target3) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo, ref1, ref2, ref3, refpos1, refpos2, refpos3, pos1, pos2, pos3] = **control\_MultiAxisPositioning**(set1, set2, set3, target1, target2, target3) |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **getActorName** This function gets the name of the positioner of the selected axis. |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | axis | [0|1|2] |
| Out | errNo | errNo |
| actor\_name | actor\_name |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.amc.control.getActorName |
| params: [axis] |
| Result: [errNo, actor\_name] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_control\_getActorName**(int deviceHandle, int axis, char\* actor\_name, int size0) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo, actor\_name = **[dev].control.getActorName**(axis) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo, actor\_name] = **control\_getActorName**(axis) |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **getActorParametersActorName** Control the actors parameter: actor name |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | axis | [0|1|2] |
| Out | errNo | errNo |
| actorname | actorname |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.amc.control.getActorParametersActorName |
| params: [axis] |
| Result: [errNo, actorname] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_control\_getActorParametersActorName**(int deviceHandle, int axis, char\* actorname, int size0) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo, actorname = **[dev].control.getActorParametersActorName**(axis) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo, actorname] = **control\_getActorParametersActorName**(axis) |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **getActorSensitivity** Get the setting for the actor parameter sensitivity |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | axis | [0|1|2] |
| Out | errNo | errNo |
| sensitivity | sensitivity |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.amc.control.getActorSensitivity |
| params: [axis] |
| Result: [errNo, sensitivity] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_control\_getActorSensitivity**(int deviceHandle, int axis, int\* sensitivity) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo, sensitivity = **[dev].control.getActorSensitivity**(axis) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo, sensitivity] = **control\_getActorSensitivity**(axis) |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **getActorType** This function gets the type of the positioner of the selected axis. |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | axis | [0|1|2] |
| Out | errNo | errNo |
| actor\_type | 0: linear , 1: goniometer, 2: rotator |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.amc.control.getActorType |
| params: [axis] |
| Result: [errNo, actor\_type] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_control\_getActorType**(int deviceHandle, int axis, int\* actor\_type) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo, actor\_type = **[dev].control.getActorType**(axis) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo, actor\_type] = **control\_getActorType**(axis) |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **getAutoMeasure** This function returns if the automeasurement on axis enable is enabled |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | axis | [0|1|2] |
| Out | errNo | errNo |
| enable | boolean true: enable automeasurement, false: disable automeasurement |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.amc.control.getAutoMeasure |
| params: [axis] |
| Result: [errNo, enable] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_control\_getAutoMeasure**(int deviceHandle, int axis, bool\* enable) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo, enable = **[dev].control.getAutoMeasure**(axis) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo, enable] = **control\_getAutoMeasure**(axis) |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **getControlAmplitude** This function gets the amplitude of the actuator signal of the selected axis. |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | axis | [0|1|2] |
| Out | errNo | errNo |
| amplitude | in mV |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.amc.control.getControlAmplitude |
| params: [axis] |
| Result: [errNo, amplitude] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_control\_getControlAmplitude**(int deviceHandle, int axis, int\* amplitude) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo, amplitude = **[dev].control.getControlAmplitude**(axis) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo, amplitude] = **control\_getControlAmplitude**(axis) |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **getControlAutoReset** This function resets the position every time the reference position is detected. |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | axis | [0|1|2] |
| Out | errNo | errNo |
| enabled | boolean |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.amc.control.getControlAutoReset |
| params: [axis] |
| Result: [errNo, enabled] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_control\_getControlAutoReset**(int deviceHandle, int axis, bool\* enabled) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo, enabled = **[dev].control.getControlAutoReset**(axis) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo, enabled] = **control\_getControlAutoReset**(axis) |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **getControlFixOutputVoltage** This function gets the DC level output of the selected axis. |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | axis | [0|1|2] |
| Out | errNo | errNo |
| amplitude\_mv | in mV |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.amc.control.getControlFixOutputVoltage |
| params: [axis] |
| Result: [errNo, amplitude\_mv] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_control\_getControlFixOutputVoltage**(int deviceHandle, int axis, int\* amplitude\_mv) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo, amplitude\_mv = **[dev].control.getControlFixOutputVoltage**(axis) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo, amplitude\_mv] = **control\_getControlFixOutputVoltage**(axis) |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **getControlFrequency** This function gets the frequency of the actuator signal of the selected axis. |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | axis | [0|1|2] |
| Out | errNo | errNo |
| frequency | in mHz |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.amc.control.getControlFrequency |
| params: [axis] |
| Result: [errNo, frequency] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_control\_getControlFrequency**(int deviceHandle, int axis, int\* frequency) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo, frequency = **[dev].control.getControlFrequency**(axis) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo, frequency] = **control\_getControlFrequency**(axis) |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

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| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **getControlMove** This function gets the approach of the selected axis’ positioner to the target position. |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | axis | [0|1|2] |
| Out | errNo | errNo |
| enable | boolean true: closed loop control enabled, false: closed loop control disabled |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.amc.control.getControlMove |
| params: [axis] |
| Result: [errNo, enable] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_control\_getControlMove**(int deviceHandle, int axis, bool\* enable) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo, enable = **[dev].control.getControlMove**(axis) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo, enable] = **control\_getControlMove**(axis) |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **getControlOutput** This function gets the status of the output relays of the selected axis. |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | axis | [0|1|2] |
| Out | errNo | errNo |
| value\_boolean1 | boolean power status (true = enabled,false = disabled) |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.amc.control.getControlOutput |
| params: [axis] |
| Result: [errNo, value\_boolean1] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_control\_getControlOutput**(int deviceHandle, int axis, bool\* value\_boolean1) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo, value\_boolean1 = **[dev].control.getControlOutput**(axis) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo, value\_boolean1] = **control\_getControlOutput**(axis) |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **getControlReferenceAutoUpdate** This function gets the status of whether the reference position is updated when the reference mark is hit.  When this function is disabled, the reference marking will be considered only the first time and after then ignored. |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | axis | [0|1|2] |
| Out | errNo | errNo |
| enabled | boolen |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.amc.control.getControlReferenceAutoUpdate |
| params: [axis] |
| Result: [errNo, enabled] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_control\_getControlReferenceAutoUpdate**(int deviceHandle, int axis, bool\* enabled) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo, enabled = **[dev].control.getControlReferenceAutoUpdate**(axis) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo, enabled] = **control\_getControlReferenceAutoUpdate**(axis) |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **getControlTargetRange** This function gets the range around the target position in which the flag "In Target Range" becomes active. |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | axis | [0|1|2] |
| Out | errNo | errNo |
| targetrange | in nm |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.amc.control.getControlTargetRange |
| params: [axis] |
| Result: [errNo, targetrange] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_control\_getControlTargetRange**(int deviceHandle, int axis, int\* targetrange) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo, targetrange = **[dev].control.getControlTargetRange**(axis) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo, targetrange] = **control\_getControlTargetRange**(axis) |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **getCrosstalkThreshold** This function gets the threshold range and slip phase time which is used while moving another axis |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | axis | [0|1|2] |
| Out | errNo | errNo |
| range | in pm |
| time | after slip phase which is waited until the controller is acting again in microseconds |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.amc.control.getCrosstalkThreshold |
| params: [axis] |
| Result: [errNo, range, time] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_control\_getCrosstalkThreshold**(int deviceHandle, int axis, int\* range, int\* time) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo, range, time = **[dev].control.getCrosstalkThreshold**(axis) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo, range, time] = **control\_getCrosstalkThreshold**(axis) |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **getCurrentOutputVoltage** This function gets the current Voltage which is applied to the Piezo |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | axis | [0|1|2] |
| Out | errNo | errNo |
| amplitude | in mV |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.amc.control.getCurrentOutputVoltage |
| params: [axis] |
| Result: [errNo, amplitude] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_control\_getCurrentOutputVoltage**(int deviceHandle, int axis, int\* amplitude) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo, amplitude = **[dev].control.getCurrentOutputVoltage**(axis) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo, amplitude] = **control\_getCurrentOutputVoltage**(axis) |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **getExternalSensor** This function gets whether the sensor source of closed loop is IDS  It is only available when the feature AMC/IDS closed loop has been activated |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | axis | [0|1|2] |
| Out | errNo | errNo |
| enabled | enabled |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.amc.control.getExternalSensor |
| params: [axis] |
| Result: [errNo, enabled] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_control\_getExternalSensor**(int deviceHandle, int axis, bool\* enabled) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo, enabled = **[dev].control.getExternalSensor**(axis) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo, enabled] = **control\_getExternalSensor**(axis) |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **getMotionControlThreshold** This function gets the threshold range within the closed-loop controlled movement stops to regulate. |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | axis | [0|1|2] |
| Out | errNo | errNo |
| range | in pm |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.amc.control.getMotionControlThreshold |
| params: [axis] |
| Result: [errNo, range] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_control\_getMotionControlThreshold**(int deviceHandle, int axis, int\* range) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo, range = **[dev].control.getMotionControlThreshold**(axis) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo, range] = **control\_getMotionControlThreshold**(axis) |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **getPositionsAndVoltages** Simultaneously get 3 axes positions as well as the DC offset  to maximize sampling rate over network |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| Out | errNo | errNo |
| pos1 | position of axis 1 |
| pos2 | position of axis 2 |
| pos3 | position of axis 3 |
| val1 | dc voltage of of axis 1 in mV |
| val2 | dc voltage of of axis 2 in mV |
| val3 | dc voltage of of axis 3 in mV |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.amc.control.getPositionsAndVoltages |
| params: [] |
| Result: [errNo, pos1, pos2, pos3, val1, val2, val3] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_control\_getPositionsAndVoltages**(int deviceHandle, int\* pos1, int\* pos2, int\* pos3, int\* val1, int\* val2, int\* val3) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo, pos1, pos2, pos3, val1, val2, val3 = **[dev].control.getPositionsAndVoltages**() |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo, pos1, pos2, pos3, val1, val2, val3] = **control\_getPositionsAndVoltages**() |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **getReferencePosition** This function gets the reference position of the selected axis. |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | axis | [0|1|2] |
| Out | errNo | errNo |
| position | position: For linear type actors the position is defined in nm for goniometer an rotator type actors it is µ°. |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.amc.control.getReferencePosition |
| params: [axis] |
| Result: [errNo, position] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_control\_getReferencePosition**(int deviceHandle, int axis, int\* position) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo, position = **[dev].control.getReferencePosition**(axis) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo, position] = **control\_getReferencePosition**(axis) |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **getSensorDirection** This function gets whether the IDS sensor source of closed loop is inverted  It is only available when the feature AMC/IDS closed loop has been activated |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | axis | [0|1|2] |
| Out | errNo | errNo |
| inverted | boolen |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.amc.control.getSensorDirection |
| params: [axis] |
| Result: [errNo, inverted] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_control\_getSensorDirection**(int deviceHandle, int axis, bool\* inverted) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo, inverted = **[dev].control.getSensorDirection**(axis) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo, inverted] = **control\_getSensorDirection**(axis) |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **getSensorEnabled** Get sensot power supply status |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | axis | [0|1|2] |
| Out | errNo | errNo |
| value | true if enabled, false otherwise |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.amc.control.getSensorEnabled |
| params: [axis] |
| Result: [errNo, value] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_control\_getSensorEnabled**(int deviceHandle, int axis, bool\* value) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo, value = **[dev].control.getSensorEnabled**(axis) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo, value] = **control\_getSensorEnabled**(axis) |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **getStatusMovingAllAxes** Get Status of all axes, see getStatusMoving for coding of the values |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| Out | errNo | errNo |
| moving1 | status of axis 1 |
| moving2 | status of axis 2 |
| moving3 | status of axis 3 |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.amc.control.getStatusMovingAllAxes |
| params: [] |
| Result: [errNo, moving1, moving2, moving3] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_control\_getStatusMovingAllAxes**(int deviceHandle, int\* moving1, int\* moving2, int\* moving3) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo, moving1, moving2, moving3 = **[dev].control.getStatusMovingAllAxes**() |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo, moving1, moving2, moving3] = **control\_getStatusMovingAllAxes**() |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

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| **LabVIEW** |

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| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **searchReferencePosition** This function searches for the reference position of the selected axis. |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | axis | [0|1|2] |
| Out | errNo | errNo |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.amc.control.searchReferencePosition |
| params: [axis] |
| Result: [errNo] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_control\_searchReferencePosition**(int deviceHandle, int axis) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo = **[dev].control.searchReferencePosition**(axis) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo] = **control\_searchReferencePosition**(axis) |

|  |
| --- |
| **C#** |

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| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

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| **LabVIEW** |

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| Updated LabVIEW library will be available as a new version later, for now use the old version |

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| --- |
| **setActorParametersByName** This function sets the name for the positioner on the selected axis. The possible names can be retrieved by executing getPositionersList.vi |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | axis | [0|1|2] |
| actorname | name of the actor |
| Out | errNo | errNo |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.amc.control.setActorParametersByName |
| params: [axis, actorname] |
| Result: [errNo] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_control\_setActorParametersByName**(int deviceHandle, int axis, const char\* actorname) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo = **[dev].control.setActorParametersByName**(axis, actorname) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo] = **control\_setActorParametersByName**(axis, actorname) |

|  |
| --- |
| **C#** |

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| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

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| --- |
| **LabVIEW** |

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| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **setActorParametersJson** Select and override a positioner out of the Current default list only override given parameters set others default |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | axis | [0|1|2] |
| json\_dict | dict with override params |
| Out | errNo | errorCode |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.amc.control.setActorParametersJson |
| params: [axis, json\_dict] |
| Result: [errNo] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_control\_setActorParametersJson**(int deviceHandle, int axis, const char\* json\_dict) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo = **[dev].control.setActorParametersJson**(axis, json\_dict) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo] = **control\_setActorParametersJson**(axis, json\_dict) |

|  |
| --- |
| **C#** |

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| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

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| --- |
| **LabVIEW** |

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| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **setActorSensitivity** Control the actor parameter closed loop sensitivity |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | axis | [0|1|2] |
| sensitivity |  |
| Out | errNo | errNo |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.amc.control.setActorSensitivity |
| params: [axis, sensitivity] |
| Result: [errNo] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_control\_setActorSensitivity**(int deviceHandle, int axis, int sensitivity) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo = **[dev].control.setActorSensitivity**(axis, sensitivity) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo] = **control\_setActorSensitivity**(axis, sensitivity) |

|  |
| --- |
| **C#** |

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| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

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| --- |
| **LabVIEW** |

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| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **setAutoMeasure** This function enables/disables the automatic C/R measurement on axis enable |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | axis | [0|1|2] |
| enable | boolean true: enable automeasurement, false: disable automeasurement |
| Out | errNo | errNo |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.amc.control.setAutoMeasure |
| params: [axis, enable] |
| Result: [errNo] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_control\_setAutoMeasure**(int deviceHandle, int axis, bool enable) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo = **[dev].control.setAutoMeasure**(axis, enable) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo] = **control\_setAutoMeasure**(axis, enable) |

|  |
| --- |
| **C#** |

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| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

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| --- |
| **LabVIEW** |

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| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

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| --- |
| **setControlAmplitude** This function sets the amplitude of the actuator signal of the selected axis. |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | axis | [0|1|2] |
| amplitude | in mV |
| Out | errNo | errNo |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.amc.control.setControlAmplitude |
| params: [axis, amplitude] |
| Result: [errNo] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_control\_setControlAmplitude**(int deviceHandle, int axis, int amplitude) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo = **[dev].control.setControlAmplitude**(axis, amplitude) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo] = **control\_setControlAmplitude**(axis, amplitude) |

|  |
| --- |
| **C#** |

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| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

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| --- |
| **LabVIEW** |

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| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

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| --- |
| **setControlAutoReset** This function resets the position every time the reference position is detected. |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | axis | [0|1|2] |
| enable | boolean |
| Out | errNo | errNo |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.amc.control.setControlAutoReset |
| params: [axis, enable] |
| Result: [errNo] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_control\_setControlAutoReset**(int deviceHandle, int axis, bool enable) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo = **[dev].control.setControlAutoReset**(axis, enable) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo] = **control\_setControlAutoReset**(axis, enable) |

|  |
| --- |
| **C#** |

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| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

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| --- |
| **LabVIEW** |

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| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

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| --- |
| **setControlFixOutputVoltage** This function sets the DC level output of the selected axis. ( must perform applyControlFixOutputVoltage to apply on the positioner) |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | axis | [0|1|2] |
| amplitude\_mv | in mV |
| Out | errNo | errNo |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.amc.control.setControlFixOutputVoltage |
| params: [axis, amplitude\_mv] |
| Result: [errNo] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_control\_setControlFixOutputVoltage**(int deviceHandle, int axis, int amplitude\_mv) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo = **[dev].control.setControlFixOutputVoltage**(axis, amplitude\_mv) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo] = **control\_setControlFixOutputVoltage**(axis, amplitude\_mv) |

|  |
| --- |
| **C#** |

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| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

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| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **setControlFrequency** This function sets the frequency of the actuator signal of the selected axis.  Note: Approximate the slewrate of the motion controller according to Input Frequency |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | axis | [0|1|2] |
| frequency | in mHz |
| Out | errNo | errNo |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.amc.control.setControlFrequency |
| params: [axis, frequency] |
| Result: [errNo] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_control\_setControlFrequency**(int deviceHandle, int axis, int frequency) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo = **[dev].control.setControlFrequency**(axis, frequency) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo] = **control\_setControlFrequency**(axis, frequency) |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

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| --- |
| **LabVIEW** |

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| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **setControlMove** This function sets the approach of the selected axis’ positioner to the target position. |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | axis | [0|1|2] |
| enable | boolean true: eanble the approach , false: disable the approach |
| Out | errNo | errNo |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.amc.control.setControlMove |
| params: [axis, enable] |
| Result: [errNo] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_control\_setControlMove**(int deviceHandle, int axis, bool enable) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo = **[dev].control.setControlMove**(axis, enable) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo] = **control\_setControlMove**(axis, enable) |

|  |
| --- |
| **C#** |

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| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

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| --- |
| **LabVIEW** |

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| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **setControlOutput** This function sets the status of the output relays of the selected axis.  Enable only if cable is connected and FlyBack is enabled  use a PWM startup of 1sec |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | axis | [0|1|2] |
| enable | boolean true: enable drives, false: disable drives |
| Out | errNo | errNo |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.amc.control.setControlOutput |
| params: [axis, enable] |
| Result: [errNo] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_control\_setControlOutput**(int deviceHandle, int axis, bool enable) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo = **[dev].control.setControlOutput**(axis, enable) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo] = **control\_setControlOutput**(axis, enable) |

|  |
| --- |
| **C#** |

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| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

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| --- |
| **LabVIEW** |

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| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **setControlReferenceAutoUpdate** This function sets the status of whether the reference position is updated when the reference mark is hit.  When this function is disabled, the reference marking will be considered only the first time and after then ignored. |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | axis | [0|1|2] |
| enable | boolean |
| Out | errNo | errNo |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.amc.control.setControlReferenceAutoUpdate |
| params: [axis, enable] |
| Result: [errNo] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_control\_setControlReferenceAutoUpdate**(int deviceHandle, int axis, bool enable) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo = **[dev].control.setControlReferenceAutoUpdate**(axis, enable) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo] = **control\_setControlReferenceAutoUpdate**(axis, enable) |

|  |
| --- |
| **C#** |

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| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

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| --- |
| **LabVIEW** |

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| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

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| --- |
| **setControlTargetRange** This function sets the range around the target position in which the flag "In Target Range" (see VIII.7.a) becomes active. |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | axis | [0|1|2] |
| range | in nm |
| Out | errNo | errNo |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.amc.control.setControlTargetRange |
| params: [axis, range] |
| Result: [errNo] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_control\_setControlTargetRange**(int deviceHandle, int axis, int range) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo = **[dev].control.setControlTargetRange**(axis, range) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo] = **control\_setControlTargetRange**(axis, range) |

|  |
| --- |
| **C#** |

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| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

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| --- |
| **LabVIEW** |

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| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **setCrosstalkThreshold** This function sets the threshold range and slip phase time which is used while moving another axis |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | axis | [0|1|2] |
| threshold | in pm |
| slipphasetime | time after slip phase which is waited until the controller is acting again in microseconds |
| Out | errNo | errNo |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.amc.control.setCrosstalkThreshold |
| params: [axis, threshold, slipphasetime] |
| Result: [errNo] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_control\_setCrosstalkThreshold**(int deviceHandle, int axis, int threshold, int slipphasetime) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo = **[dev].control.setCrosstalkThreshold**(axis, threshold, slipphasetime) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo] = **control\_setCrosstalkThreshold**(axis, threshold, slipphasetime) |

|  |
| --- |
| **C#** |

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| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

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| --- |
| **LabVIEW** |

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| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **setExternalSensor** This function sets the sensor source of closed loop to the IDS when enabled. Otherwise the normal AMC Sensor depending on the configuration (e.g. NUM or RES) is used  It is only available when the feature AMC/IDS closed loop has been activated |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | axis | [0|1|2] |
| enabled | boolean |
| Out | warning | warning |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.amc.control.setExternalSensor |
| params: [axis, enabled] |
| Result: [warning] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_control\_setExternalSensor**(int deviceHandle, int axis, bool enabled, int\* warning) |

|  |
| --- |
| **Python** |

|  |
| --- |
| warning = **[dev].control.setExternalSensor**(axis, enabled) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [warning] = **control\_setExternalSensor**(axis, enabled) |

|  |
| --- |
| **C#** |

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| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

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| --- |
| **LabVIEW** |

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| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **setMotionControlThreshold** This function sets the threshold range within the closed-loop controlled movement stops to regulate. Default depends on connected sensor type |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | axis | [0|1|2] |
| threshold | in pm |
| Out | errNo | errNo |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.amc.control.setMotionControlThreshold |
| params: [axis, threshold] |
| Result: [errNo] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_control\_setMotionControlThreshold**(int deviceHandle, int axis, int threshold) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo = **[dev].control.setMotionControlThreshold**(axis, threshold) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo] = **control\_setMotionControlThreshold**(axis, threshold) |

|  |
| --- |
| **C#** |

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| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

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| --- |
| **LabVIEW** |

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| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

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| --- |
| **setReset** This function resets the actual position of the selected axis given by the NUM sensor to zero and marks the reference position as invalid.  It does not work for RES positioners and positions read by IDS.  For IDS, use com.attocube.ids.displacement.resetAxis() or com.attocube.amc.amcids.resetIdsAxis() instead. |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | axis | [0|1|2] |
| Out | errNo | errNo |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.amc.control.setReset |
| params: [axis] |
| Result: [errNo] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_control\_setReset**(int deviceHandle, int axis) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo = **[dev].control.setReset**(axis) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo] = **control\_setReset**(axis) |

|  |
| --- |
| **C#** |

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| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

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| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **setSensorDirection** This function sets the IDS sensor source of closed loop to inverted when true.  It is only available when the feature AMC/IDS closed loop has been activated |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | axis | [0|1|2] |
| inverted |  |
| Out | errNo | errNo |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.amc.control.setSensorDirection |
| params: [axis, inverted] |
| Result: [errNo] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_control\_setSensorDirection**(int deviceHandle, int axis, bool inverted) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo = **[dev].control.setSensorDirection**(axis, inverted) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo] = **control\_setSensorDirection**(axis, inverted) |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **setSensorEnabled** Set sensor power supply status, can be switched off to save heat generated by sensor [NUM or RES]  Positions retrieved will be invalid when activating this, so closed-loop control should be switched off beforehand |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | axis | [0|1|2] |
| value | true if enabled, false otherwise |
| Out | errNo | errNo |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.amc.control.setSensorEnabled |
| params: [axis, value] |
| Result: [errNo] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_control\_setSensorEnabled**(int deviceHandle, int axis, bool value) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo = **[dev].control.setSensorEnabled**(axis, value) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo] = **control\_setSensorEnabled**(axis, value) |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

# Description

|  |
| --- |
| **checkChassisNbr** Get Chassis and Slot Number, only works when AMC is within a Rack |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| Out | errNo | errorCode |
| slotNbr | slotNbr |
| chassisNbr | chassisNbr |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.amc.description.checkChassisNbr |
| params: [] |
| Result: [errNo, slotNbr, chassisNbr] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_description\_checkChassisNbr**(int deviceHandle, int\* slotNbr, int\* chassisNbr) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo, slotNbr, chassisNbr = **[dev].description.checkChassisNbr**() |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo, slotNbr, chassisNbr] = **description\_checkChassisNbr**() |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **getDeviceType** This function gets the device type based on its EEPROM configuration. |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| Out | errNo | errNo |
| devicetype | Device name (AMC100, AMC300) with attached feature ( AMC100\\NUM, AMC100\\NUM\\PRO) |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.amc.description.getDeviceType |
| params: [] |
| Result: [errNo, devicetype] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_description\_getDeviceType**(int deviceHandle, char\* devicetype, int size0) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo, devicetype = **[dev].description.getDeviceType**() |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo, devicetype] = **description\_getDeviceType**() |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **getFeaturesActivated** Get the activated features and return as a string |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| Out | errNo | errNo |
| features | activated on device concatenated by comma e.g. Closed loop Operation, Pro, Wireless Controller, IO |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.amc.description.getFeaturesActivated |
| params: [] |
| Result: [errNo, features] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_description\_getFeaturesActivated**(int deviceHandle, char\* features, int size0) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo, features = **[dev].description.getFeaturesActivated**() |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo, features] = **description\_getFeaturesActivated**() |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

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| --- |
| **LabVIEW** |

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| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **getPositionersList** This function reads the actor names that can be connected to the device. |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| Out | errNo | errNo |
| PositionersList | PositionersList |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.amc.description.getPositionersList |
| params: [] |
| Result: [errNo, PositionersList] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_description\_getPositionersList**(int deviceHandle, char\* PositionersList, int size0) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo, PositionersList = **[dev].description.getPositionersList**() |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo, PositionersList] = **description\_getPositionersList**() |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

# Diagnostic

|  |
| --- |
| **getDiagnosticPower** Returns the current power consumption |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | axis | [0|1|2] |
| Out | errNo | errNo |
| power | power |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.amc.diagnostic.getDiagnosticPower |
| params: [axis] |
| Result: [errNo, power] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_diagnostic\_getDiagnosticPower**(int deviceHandle, int axis, int\* power) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo, power = **[dev].diagnostic.getDiagnosticPower**(axis) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo, power] = **diagnostic\_getDiagnosticPower**(axis) |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **getDiagnosticResults** Returns the results of the last diagnostic run and an error, if there was no run, it is currently running or the run failed |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | axis | [0|1|2] |
| Out | errNo | errNo |
| capacity | in nF |
| resistance | in Ohm |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.amc.diagnostic.getDiagnosticResults |
| params: [axis] |
| Result: [errNo, capacity, resistance] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_diagnostic\_getDiagnosticResults**(int deviceHandle, int axis, int\* capacity, int\* resistance) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo, capacity, resistance = **[dev].diagnostic.getDiagnosticResults**(axis) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo, capacity, resistance] = **diagnostic\_getDiagnosticResults**(axis) |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **getDiagnosticTemperature** Returns the current axis temperature |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | axis | [0|1|2] |
| Out | errNo | errNo |
| temperature | temperature |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.amc.diagnostic.getDiagnosticTemperature |
| params: [axis] |
| Result: [errNo, temperature] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_diagnostic\_getDiagnosticTemperature**(int deviceHandle, int axis, int\* temperature) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo, temperature = **[dev].diagnostic.getDiagnosticTemperature**(axis) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo, temperature] = **diagnostic\_getDiagnosticTemperature**(axis) |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **startDiagnostic** Start the diagnosis procedure for the given axis |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | axis | [0|1|2] |
| Out | errNo | errNo |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.amc.diagnostic.startDiagnostic |
| params: [axis] |
| Result: [errNo] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_diagnostic\_startDiagnostic**(int deviceHandle, int axis) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo = **[dev].diagnostic.startDiagnostic**(axis) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo] = **diagnostic\_startDiagnostic**(axis) |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

# Move

|  |
| --- |
| **getControlContinuousBkwd** This function gets the axis’ movement status in backward direction. |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | axis | [0|1|2] |
| Out | errNo | errNo |
| value\_boolean1 | boolean true if movement backward is active , false otherwise |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.amc.move.getControlContinuousBkwd |
| params: [axis] |
| Result: [errNo, value\_boolean1] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_move\_getControlContinuousBkwd**(int deviceHandle, int axis, bool\* value\_boolean1) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo, value\_boolean1 = **[dev].move.getControlContinuousBkwd**(axis) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo, value\_boolean1] = **move\_getControlContinuousBkwd**(axis) |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **getControlContinuousFwd** This function gets the axis’ movement status in positive direction. |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | axis | [0|1|2] |
| Out | errNo | errNo |
| value\_boolean1 | boolean true if movement Fwd is active , false otherwise |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.amc.move.getControlContinuousFwd |
| params: [axis] |
| Result: [errNo, value\_boolean1] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_move\_getControlContinuousFwd**(int deviceHandle, int axis, bool\* value\_boolean1) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo, value\_boolean1 = **[dev].move.getControlContinuousFwd**(axis) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo, value\_boolean1] = **move\_getControlContinuousFwd**(axis) |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **getControlEotOutputDeactive** This function gets the output applied to the selected axis on the end of travel. |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | axis | [0|1|2] |
| Out | errNo | errNo |
| value\_boolean1 | boolean If true, the output of the axis will be deactivated on positive EOT detection. |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.amc.move.getControlEotOutputDeactive |
| params: [axis] |
| Result: [errNo, value\_boolean1] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_move\_getControlEotOutputDeactive**(int deviceHandle, int axis, bool\* value\_boolean1) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo, value\_boolean1 = **[dev].move.getControlEotOutputDeactive**(axis) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo, value\_boolean1] = **move\_getControlEotOutputDeactive**(axis) |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **getControlTargetPosition** This function gets the target position for the movement on the selected axis. |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | axis | [0|1|2] |
| Out | errNo | errNo |
| position | defined in nm for goniometer an rotator type actors it is µ°. |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.amc.move.getControlTargetPosition |
| params: [axis] |
| Result: [errNo, position] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_move\_getControlTargetPosition**(int deviceHandle, int axis, double\* position) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo, position = **[dev].move.getControlTargetPosition**(axis) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo, position] = **move\_getControlTargetPosition**(axis) |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **getGroundAxis** Pull axis piezo drive to GND actively  only in AMC300 |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | axis | montion controler axis [0|1|2] |
| Out | errNo | 0 or error |
| grounded | true or false |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.amc.move.getGroundAxis |
| params: [axis] |
| Result: [errNo, grounded] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_move\_getGroundAxis**(int deviceHandle, int axis, bool\* grounded) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo, grounded = **[dev].move.getGroundAxis**(axis) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo, grounded] = **move\_getGroundAxis**(axis) |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **getGroundAxisAutoOnTarget** Pull axis piezo drive to GND if positioner is in ground target range  ONLY DUMMY RIGHT NOW  only in AMC300 |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | axis | montion controler axis [0|1|2] |
| Out | errNo | 0 or error |
| value | true or false |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.amc.move.getGroundAxisAutoOnTarget |
| params: [axis] |
| Result: [errNo, value] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_move\_getGroundAxisAutoOnTarget**(int deviceHandle, int axis, bool\* value) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo, value = **[dev].move.getGroundAxisAutoOnTarget**(axis) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo, value] = **move\_getGroundAxisAutoOnTarget**(axis) |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **getGroundTargetRange** Retrieves the range around the target position in which the auto grounding becomes active.  only in AMC300 |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | axis | [0|1|2] |
| Out | errNo | errNo |
| targetrange | in nm |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.amc.move.getGroundTargetRange |
| params: [axis] |
| Result: [errNo, targetrange] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_move\_getGroundTargetRange**(int deviceHandle, int axis, int\* targetrange) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo, targetrange = **[dev].move.getGroundTargetRange**(axis) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo, targetrange] = **move\_getGroundTargetRange**(axis) |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **getNSteps** This function gets the number of Steps in desired direction. |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | axis | [0|1|2] |
| Out | errNo | errNo |
| nbrstep | nbrstep |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.amc.move.getNSteps |
| params: [axis] |
| Result: [errNo, nbrstep] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_move\_getNSteps**(int deviceHandle, int axis, int\* nbrstep) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo, nbrstep = **[dev].move.getNSteps**(axis) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo, nbrstep] = **move\_getNSteps**(axis) |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **getPosition** This function gets the current position of the positioner on the selected axis.  The axis on the web application are indexed from 1 to 3 |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | axis | [0|1|2] |
| Out | errNo | errNo |
| position | defined in nm for goniometer an rotator type actors it is µ°. |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.amc.move.getPosition |
| params: [axis] |
| Result: [errNo, position] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_move\_getPosition**(int deviceHandle, int axis, double\* position) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo, position = **[dev].move.getPosition**(axis) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo, position] = **move\_getPosition**(axis) |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **performNSteps** Perform the OL command for N steps |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | axis | [0|1|2] |
| backward | Selects the desired direction. False triggers a forward step, true a backward step |
| Out | errNo | errNo |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.amc.move.performNSteps |
| params: [axis, backward] |
| Result: [errNo] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_move\_performNSteps**(int deviceHandle, int axis, bool backward) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo = **[dev].move.performNSteps**(axis, backward) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo] = **move\_performNSteps**(axis, backward) |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **setControlContinuousBkwd** This function sets a continuous movement on the selected axis in backward direction. |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | axis | [0|1|2] |
| enable | If enabled a present movement in the opposite direction is stopped. The parameter "false" stops all movement of the axis regardless its direction |
| Out | errNo | errNo |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.amc.move.setControlContinuousBkwd |
| params: [axis, enable] |
| Result: [errNo] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_move\_setControlContinuousBkwd**(int deviceHandle, int axis, bool enable) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo = **[dev].move.setControlContinuousBkwd**(axis, enable) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo] = **move\_setControlContinuousBkwd**(axis, enable) |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **setControlContinuousFwd** This function sets a continuous movement on the selected axis in positive direction. |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | axis | [0|1|2] |
| enable | If enabled a present movement in the opposite direction is stopped. The parameter "false" stops all movement of the axis regardless its direction. |
| Out | errNo | errNo |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.amc.move.setControlContinuousFwd |
| params: [axis, enable] |
| Result: [errNo] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_move\_setControlContinuousFwd**(int deviceHandle, int axis, bool enable) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo = **[dev].move.setControlContinuousFwd**(axis, enable) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo] = **move\_setControlContinuousFwd**(axis, enable) |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **setControlEotOutputDeactive** This function sets the output applied to the selected axis on the end of travel. |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | axis | [0|1|2] |
| enable | boolean If enabled, the output of the axis will be deactivated on positive EOT detection. |
| Out | errNo | errNo |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.amc.move.setControlEotOutputDeactive |
| params: [axis, enable] |
| Result: [errNo] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_move\_setControlEotOutputDeactive**(int deviceHandle, int axis, bool enable) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo = **[dev].move.setControlEotOutputDeactive**(axis, enable) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo] = **move\_setControlEotOutputDeactive**(axis, enable) |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **setControlTargetPosition** This function sets the target position for the movement on the selected axis.  careful: the maximum positon in nm is 2\*\*47/1000 |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | axis | [0|1|2] |
| target | absolute position : For linear type actors the position is defined in nm for goniometer an rotator type actors it is µ°. |
| Out | errNo | errNo |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.amc.move.setControlTargetPosition |
| params: [axis, target] |
| Result: [errNo] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_move\_setControlTargetPosition**(int deviceHandle, int axis, double target) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo = **[dev].move.setControlTargetPosition**(axis, target) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo] = **move\_setControlTargetPosition**(axis, target) |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **setGroundAxis** Pull axis piezo drive to GND actively  only in AMC300  this is used in MIC-Mode |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | axis | motion controler axis [0|1|2] |
| enabled | true or false |
| Out | errNo | 0 or error |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.amc.move.setGroundAxis |
| params: [axis, enabled] |
| Result: [errNo] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_move\_setGroundAxis**(int deviceHandle, int axis, bool enabled) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo = **[dev].move.setGroundAxis**(axis, enabled) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo] = **move\_setGroundAxis**(axis, enabled) |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **setGroundAxisAutoOnTarget** Pull axis piezo drive to GND if positioner is in ground target range  ONLY DUMMY RIGHT NOW  only in AMC300  this is used in MIC-Mode |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | axis | montion controler axis [0|1|2] |
| enabled | true or false |
| Out | errNo | 0 or error |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.amc.move.setGroundAxisAutoOnTarget |
| params: [axis, enabled] |
| Result: [errNo] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_move\_setGroundAxisAutoOnTarget**(int deviceHandle, int axis, bool enabled) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo = **[dev].move.setGroundAxisAutoOnTarget**(axis, enabled) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo] = **move\_setGroundAxisAutoOnTarget**(axis, enabled) |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **setGroundTargetRange** Set the range around the target position in which the auto grounding becomes active.  only in AMC300 |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | axis | [0|1|2] |
| range | in nm |
| Out | errNo | errNo |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.amc.move.setGroundTargetRange |
| params: [axis, range] |
| Result: [errNo] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_move\_setGroundTargetRange**(int deviceHandle, int axis, int range) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo = **[dev].move.setGroundTargetRange**(axis, range) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo] = **move\_setGroundTargetRange**(axis, range) |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **setNSteps** This function triggers n steps on the selected axis in desired direction. |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | axis | [0|1|2] |
| backward | Selects the desired direction. False triggers a forward step, true a backward step |
| step | number of step |
| Out | errNo | errNo |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.amc.move.setNSteps |
| params: [axis, backward, step] |
| Result: [errNo] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_move\_setNSteps**(int deviceHandle, int axis, bool backward, int step) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo = **[dev].move.setNSteps**(axis, backward, step) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo] = **move\_setNSteps**(axis, backward, step) |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **writeNSteps** set N steps |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | axis | [0|1|2] |
| step | number of step |
| Out | errNo | errNo |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.amc.move.writeNSteps |
| params: [axis, step] |
| Result: [errNo] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_move\_writeNSteps**(int deviceHandle, int axis, int step) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo = **[dev].move.writeNSteps**(axis, step) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo] = **move\_writeNSteps**(axis, step) |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

# Res

|  |
| --- |
| **getChainGain** Get chain gain |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | axis | number of axis |
| Out | errNo | errNo |
| gaincoeff | gaincoeff |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.amc.res.getChainGain |
| params: [axis] |
| Result: [errNo, gaincoeff] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_res\_getChainGain**(int deviceHandle, int axis, int\* gaincoeff) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo, gaincoeff = **[dev].res.getChainGain**(axis) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo, gaincoeff] = **res\_getChainGain**(axis) |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **getLinearization** Gets wether linearization is enabled or not |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| Out | errNo | errNo |
| enabled | true when enabled |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.amc.res.getLinearization |
| params: [] |
| Result: [errNo, enabled] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_res\_getLinearization**(int deviceHandle, bool\* enabled) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo, enabled = **[dev].res.getLinearization**() |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo, enabled] = **res\_getLinearization**() |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **getLutSn** get the identifier of the loaded lookuptable (will be empty if disabled) |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | axis | [0|1|2] |
| Out | errNo | errNo |
| value\_string1 | string : identifier |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.amc.res.getLutSn |
| params: [axis] |
| Result: [errNo, value\_string1] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_res\_getLutSn**(int deviceHandle, int axis, char\* value\_string1, int size0) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo, value\_string1 = **[dev].res.getLutSn**(axis) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo, value\_string1] = **res\_getLutSn**(axis) |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **getMode** Get mode of RES application |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| Out | errNo | errNo |
| mode | mode |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.amc.res.getMode |
| params: [] |
| Result: [errNo, mode] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_res\_getMode**(int deviceHandle, int\* mode) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo, mode = **[dev].res.getMode**() |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo, mode] = **res\_getMode**() |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **setChainGain** Set signal chain gain to control overall power |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | axis | number of axis |
| gainconfig | 0: 0dB ( power 600mVpkpk^2/R), 1 : -10 dB , 2 : -15 dB , 3 : -20 dB |
| Out | errNo | errNo |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.amc.res.setChainGain |
| params: [axis, gainconfig] |
| Result: [errNo] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_res\_setChainGain**(int deviceHandle, int axis, int gainconfig) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo = **[dev].res.setChainGain**(axis, gainconfig) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo] = **res\_setChainGain**(axis, gainconfig) |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **setConfigurationFile** Load configuration file which either contains JSON parameters or the LUT file itself (as legacy support) |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | axis | [0|1|2] |
| content | 1k \* 24 bit string or JSON File |
| Out | errNo | errNo |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.amc.res.setConfigurationFile |
| params: [axis, content] |
| Result: [errNo] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_res\_setConfigurationFile**(int deviceHandle, int axis, const char\* content) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo = **[dev].res.setConfigurationFile**(axis, content) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo] = **res\_setConfigurationFile**(axis, content) |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **setLinearization** Control if linearization is enabled or not |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | enable | boolean ( true: enable linearization) |
| Out | errNo | errNo |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.amc.res.setLinearization |
| params: [enable] |
| Result: [errNo] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_res\_setLinearization**(int deviceHandle, bool enable) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo = **[dev].res.setLinearization**(enable) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo] = **res\_setLinearization**(enable) |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **setMode** Get mode of RES application |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | mode | 1: Individual mode with triple ortho frequency rejection method 2: Mic Mode with dual frequency rejection method |
| Out | errNo | errNo |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.amc.res.setMode |
| params: [mode] |
| Result: [errNo] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_res\_setMode**(int deviceHandle, int mode) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo = **[dev].res.setMode**(mode) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo] = **res\_setMode**(mode) |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

# Rotcomp

|  |
| --- |
| **getControlTargetRanges** Checks if all three axis are in target range. |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| Out | errNo | int32 Error code, if there was an error, otherwise 0 for ok |
| in\_target\_range | boolean true all three axes are in target range, false at least one axis is not in target range |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.amc.rotcomp.getControlTargetRanges |
| params: [] |
| Result: [errNo, in\_target\_range] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_rotcomp\_getControlTargetRanges**(int deviceHandle, bool\* in\_target\_range) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo, in\_target\_range = **[dev].rotcomp.getControlTargetRanges**() |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo, in\_target\_range] = **rotcomp\_getControlTargetRanges**() |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **getEnabled** Gets the enabled status of the rotation compensation |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| Out | errNo | int32 Error code, if there was an error, otherwise 0 for ok |
| enabled | boolean true Rotation compensation is enabled, false Rotation compensation is disabled |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.amc.rotcomp.getEnabled |
| params: [] |
| Result: [errNo, enabled] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_rotcomp\_getEnabled**(int deviceHandle, bool\* enabled) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo, enabled = **[dev].rotcomp.getEnabled**() |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo, enabled] = **rotcomp\_getEnabled**() |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **getLUT** Gets the LUT file as JSON string |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| Out | errNo | int32 Error code, if there was an error, otherwise 0 for ok |
| lut | string JSON string of the LUT file for the rotation compensation |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.amc.rotcomp.getLUT |
| params: [] |
| Result: [errNo, lut] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_rotcomp\_getLUT**(int deviceHandle, char\* lut, int size0) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo, lut = **[dev].rotcomp.getLUT**() |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo, lut] = **rotcomp\_getLUT**() |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **setEnabled** Enables and disables the rotation compensation |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | enabled | true Rotation compensation is enabled, false Rotation compensation is disabled |
| Out | errNo | int32 Error code, if there was an error, otherwise 0 for ok |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.amc.rotcomp.setEnabled |
| params: [enabled] |
| Result: [errNo] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_rotcomp\_setEnabled**(int deviceHandle, bool enabled) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo = **[dev].rotcomp.setEnabled**(enabled) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo] = **rotcomp\_setEnabled**(enabled) |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **setLUT** Sets the LUT file from a JSON string |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | lut\_string | JSON string of the LUT file for the rotation compensation |
| Out | errNo | int32 Error code, if there was an error, otherwise 0 for ok |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.amc.rotcomp.setLUT |
| params: [lut\_string] |
| Result: [errNo] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_rotcomp\_setLUT**(int deviceHandle, const char\* lut\_string) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo = **[dev].rotcomp.setLUT**(lut\_string) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo] = **rotcomp\_setLUT**(lut\_string) |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **updateOffsets** Updates the start offsets of the axes |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | offset\_axis0 | Offset of axis 1 in [nm] |
| offset\_axis1 | Offset of axis 2 in [nm] |
| offset\_axis2 | Offset of axis 3 in [nm] |
| Out | errNo | int32 Error code, if there was an error, otherwise 0 for ok |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.amc.rotcomp.updateOffsets |
| params: [offset\_axis0, offset\_axis1, offset\_axis2] |
| Result: [errNo] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_rotcomp\_updateOffsets**(int deviceHandle, int offset\_axis0, int offset\_axis1, int offset\_axis2) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo = **[dev].rotcomp.updateOffsets**(offset\_axis0, offset\_axis1, offset\_axis2) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo] = **rotcomp\_updateOffsets**(offset\_axis0, offset\_axis1, offset\_axis2) |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

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| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

# Rtin

|  |
| --- |
| **apply** Apply all realtime input function |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| Out | errNo | errNo |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.amc.rtin.apply |
| params: [] |
| Result: [errNo] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_rtin\_apply**(int deviceHandle) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo = **[dev].rtin.apply**() |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo] = **rtin\_apply**() |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **discard** Discard all values beting set and not yet applieds |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| Out | errNo | errNo |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.amc.rtin.discard |
| params: [] |
| Result: [errNo] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_rtin\_discard**(int deviceHandle) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo = **[dev].rtin.discard**() |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo] = **rtin\_discard**() |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **getControlAQuadBIn** check if AQuadB input is enabled. NOT USED |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | axis | [0|1|2] |
| Out | errNo | errNo |
| value\_boolean1 | boolean |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.amc.rtin.getControlAQuadBIn |
| params: [axis] |
| Result: [errNo, value\_boolean1] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_rtin\_getControlAQuadBIn**(int deviceHandle, int axis, int\* value\_boolean1) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo, value\_boolean1 = **[dev].rtin.getControlAQuadBIn**(axis) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo, value\_boolean1] = **rtin\_getControlAQuadBIn**(axis) |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **getControlAQuadBInResolution** This function gets the AQuadB input resolution for setpoint parameter. |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | axis | [0|1|2] |
| tempvalue | boolean if true get the tempory value ( from the set function) |
| Out | errNo | errNo |
| resolution | ion nm |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.amc.rtin.getControlAQuadBInResolution |
| params: [axis, tempvalue] |
| Result: [errNo, resolution] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_rtin\_getControlAQuadBInResolution**(int deviceHandle, int axis, bool tempvalue, int\* resolution) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo, resolution = **[dev].rtin.getControlAQuadBInResolution**(axis, tempvalue) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo, resolution] = **rtin\_getControlAQuadBInResolution**(axis, tempvalue) |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **getControlMoveGPIO** This function gets the status for real time input on the selected axis in closed-loop mode. |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | axis | [0|1|2] |
| Out | errNo | errNo |
| enable | boolean true: approach enabled , false: approach disabled |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.amc.rtin.getControlMoveGPIO |
| params: [axis] |
| Result: [errNo, enable] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_rtin\_getControlMoveGPIO**(int deviceHandle, int axis, bool\* enable) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo, enable = **[dev].rtin.getControlMoveGPIO**(axis) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo, enable] = **rtin\_getControlMoveGPIO**(axis) |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **getGpioMode** get the GPIO mode for Mic Mode feature |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| Out | errNo | errNo |
| gpio\_mode | gpio\_mode: 0: Standard GPIO 1: NSL-/Mic-Mode |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.amc.rtin.getGpioMode |
| params: [] |
| Result: [errNo, gpio\_mode] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_rtin\_getGpioMode**(int deviceHandle, int\* gpio\_mode) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo, gpio\_mode = **[dev].rtin.getGpioMode**() |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo, gpio\_mode] = **rtin\_getGpioMode**() |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **getNslMux** get the axis the NSL multiplexer is set to |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | mux\_mode | [0|1|2|3]  0: Off  1: Axis 1  2: Axis 2  3: Axis 3 |
| Out | errNo | errNo |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.amc.rtin.getNslMux |
| params: [mux\_mode] |
| Result: [errNo] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_rtin\_getNslMux**(int deviceHandle, int mux\_mode) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo = **[dev].rtin.getNslMux**(mux\_mode) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo] = **rtin\_getNslMux**(mux\_mode) |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **getRealTimeInChangePerPulse** This function gets the change per pulse for the selected axis under real time input in the closed-loop mode. |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | axis | [0|1|2] |
| tempvalue | boolean if true get the tempory value ( from the set function) |
| Out | errNo | errNo |
| resolution | to be added in current pos in nm |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.amc.rtin.getRealTimeInChangePerPulse |
| params: [axis, tempvalue] |
| Result: [errNo, resolution] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_rtin\_getRealTimeInChangePerPulse**(int deviceHandle, int axis, bool tempvalue, int\* resolution) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo, resolution = **[dev].rtin.getRealTimeInChangePerPulse**(axis, tempvalue) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo, resolution] = **rtin\_getRealTimeInChangePerPulse**(axis, tempvalue) |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **getRealTimeInFeedbackLoopMode** Get if the realtime function must operate in close loop operation or open loop operation |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | axis | [0|1|2] |
| tempvalue | boolean if true get the tempory value ( from the set function) |
| Out | errNo | errNo |
| mode | 0: open loop, 1 : close-loop |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.amc.rtin.getRealTimeInFeedbackLoopMode |
| params: [axis, tempvalue] |
| Result: [errNo, mode] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_rtin\_getRealTimeInFeedbackLoopMode**(int deviceHandle, int axis, bool tempvalue, int\* mode) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo, mode = **[dev].rtin.getRealTimeInFeedbackLoopMode**(axis, tempvalue) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo, mode] = **rtin\_getRealTimeInFeedbackLoopMode**(axis, tempvalue) |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **getRealTimeInHsslClk** Get the HSSL clock |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | axis | [0|1|2] |
| tempvalue | boolean if true get the tempory value ( from the set function) |
| Out | errNo | errNo |
| clk | clock is given in nanoseconds |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.amc.rtin.getRealTimeInHsslClk |
| params: [axis, tempvalue] |
| Result: [errNo, clk] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_rtin\_getRealTimeInHsslClk**(int deviceHandle, int axis, bool tempvalue, int\* clk) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo, clk = **[dev].rtin.getRealTimeInHsslClk**(axis, tempvalue) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo, clk] = **rtin\_getRealTimeInHsslClk**(axis, tempvalue) |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **getRealTimeInHsslGap** Get the HSSL Gap |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | axis | [0|1|2] |
| tempvalue | boolean if true get the tempory value ( from the set function) |
| Out | errNo | errNo |
| gap | indicates the gap between the end of the HSSL word and the beginning of the next HSSL word. The unit of G is HSSL clock cycles. |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.amc.rtin.getRealTimeInHsslGap |
| params: [axis, tempvalue] |
| Result: [errNo, gap] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_rtin\_getRealTimeInHsslGap**(int deviceHandle, int axis, bool tempvalue, int\* gap) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo, gap = **[dev].rtin.getRealTimeInHsslGap**(axis, tempvalue) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo, gap] = **rtin\_getRealTimeInHsslGap**(axis, tempvalue) |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **getRealTimeInHsslHigh** Get the higher part of the HSSL resolution |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | axis | [0|1|2] |
| tempvalue | boolean if true get the tempory value ( from the set function) |
| Out | errNo | errNo |
| highresolution | highresolution |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.amc.rtin.getRealTimeInHsslHigh |
| params: [axis, tempvalue] |
| Result: [errNo, highresolution] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_rtin\_getRealTimeInHsslHigh**(int deviceHandle, int axis, bool tempvalue, int\* highresolution) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo, highresolution = **[dev].rtin.getRealTimeInHsslHigh**(axis, tempvalue) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo, highresolution] = **rtin\_getRealTimeInHsslHigh**(axis, tempvalue) |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **getRealTimeInHsslLow** Get the lower part of the HSSL resolution |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | axis | [0|1|2] |
| tempvalue | boolean if true get the tempory value ( from the set function) |
| Out | errNo | errNo |
| lowresolution | lowresolution |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.amc.rtin.getRealTimeInHsslLow |
| params: [axis, tempvalue] |
| Result: [errNo, lowresolution] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_rtin\_getRealTimeInHsslLow**(int deviceHandle, int axis, bool tempvalue, int\* lowresolution) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo, lowresolution = **[dev].rtin.getRealTimeInHsslLow**(axis, tempvalue) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo, lowresolution] = **rtin\_getRealTimeInHsslLow**(axis, tempvalue) |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **getRealTimeInMode** This function sets or gets the real time input mode for the selected axis. |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | axis | [0|1|2] |
| tempvalue | boolean if true get the tempory value ( from the set function) |
| Out | errNo | errNo |
| mode | see `RT\_IN\_MODES` |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.amc.rtin.getRealTimeInMode |
| params: [axis, tempvalue] |
| Result: [errNo, mode] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_rtin\_getRealTimeInMode**(int deviceHandle, int axis, bool tempvalue, int\* mode) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo, mode = **[dev].rtin.getRealTimeInMode**(axis, tempvalue) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo, mode] = **rtin\_getRealTimeInMode**(axis, tempvalue) |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **getRealTimeInStepsPerPulse** Get the change in step per pulse of the realtime input when trigger and stepper mode is used |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | axis | [0|1|2] |
| tempvalue | boolean if true get the tempory value ( from the set function) |
| Out | errNo | errNo |
| steps | number of steps to applied |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.amc.rtin.getRealTimeInStepsPerPulse |
| params: [axis, tempvalue] |
| Result: [errNo, steps] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_rtin\_getRealTimeInStepsPerPulse**(int deviceHandle, int axis, bool tempvalue, int\* steps) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo, steps = **[dev].rtin.getRealTimeInStepsPerPulse**(axis, tempvalue) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo, steps] = **rtin\_getRealTimeInStepsPerPulse**(axis, tempvalue) |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **setControlAQuadBIn** AQuadB input enable. NOT USED |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | axis | [0|1|2] |
| enable |  |
| Out | errNo | errNo |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.amc.rtin.setControlAQuadBIn |
| params: [axis, enable] |
| Result: [errNo] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_rtin\_setControlAQuadBIn**(int deviceHandle, int axis, bool enable) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo = **[dev].rtin.setControlAQuadBIn**(axis, enable) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo] = **rtin\_setControlAQuadBIn**(axis, enable) |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **setControlAQuadBInResolution** This function sets the AQuadB input resolution for setpoint parameter. |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | axis | [0|1|2] |
| resolution | ion nm |
| Out | errNo | errNo |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.amc.rtin.setControlAQuadBInResolution |
| params: [axis, resolution] |
| Result: [errNo] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_rtin\_setControlAQuadBInResolution**(int deviceHandle, int axis, int resolution) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo = **[dev].rtin.setControlAQuadBInResolution**(axis, resolution) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo] = **rtin\_setControlAQuadBInResolution**(axis, resolution) |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **setControlMoveGPIO** This function sets the status for real time input on the selected axis in closed-loop mode. |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | axis | [0|1|2] |
| enable | boolean true: eanble the approach , false: disable the approach |
| Out | errNo | errNo |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.amc.rtin.setControlMoveGPIO |
| params: [axis, enable] |
| Result: [errNo] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_rtin\_setControlMoveGPIO**(int deviceHandle, int axis, bool enable) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo = **[dev].rtin.setControlMoveGPIO**(axis, enable) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo] = **rtin\_setControlMoveGPIO**(axis, enable) |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **setGpioMode** set the GPIO mode for Mic Mode feature |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | gpio\_mode | [0|1]  0: Standard GPIO  1: NSL-/Mic-Mode |
| Out | errNo | errNo |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.amc.rtin.setGpioMode |
| params: [gpio\_mode] |
| Result: [errNo] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_rtin\_setGpioMode**(int deviceHandle, int gpio\_mode) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo = **[dev].rtin.setGpioMode**(gpio\_mode) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo] = **rtin\_setGpioMode**(gpio\_mode) |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **setNslMux** set the axis the NSL multiplexer is set to |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | mux\_mode | [0|1|2|3]  0: Off  1: Axis 1  2: Axis 2  3: Axis 3 |
| Out | errNo | errNo |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.amc.rtin.setNslMux |
| params: [mux\_mode] |
| Result: [errNo] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_rtin\_setNslMux**(int deviceHandle, int mux\_mode) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo = **[dev].rtin.setNslMux**(mux\_mode) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo] = **rtin\_setNslMux**(mux\_mode) |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

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| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **setRealTimeInChangePerPulse** This function sets the change per pulse for the selected axis under real time input in the closed-loop mode.  only used in closed loop operation |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | axis | [0|1|2] |
| resolution | to be added in current pos in nm |
| Out | errNo | errNo |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.amc.rtin.setRealTimeInChangePerPulse |
| params: [axis, resolution] |
| Result: [errNo] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_rtin\_setRealTimeInChangePerPulse**(int deviceHandle, int axis, int resolution) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo = **[dev].rtin.setRealTimeInChangePerPulse**(axis, resolution) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo] = **rtin\_setRealTimeInChangePerPulse**(axis, resolution) |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

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| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **setRealTimeInFeedbackLoopMode** Set if the realtime function must operate in close loop operation or open loop operation |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | axis | [0|1|2] |
| mode | 0: open loop, 1 : close-loop |
| Out | errNo | errNo |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.amc.rtin.setRealTimeInFeedbackLoopMode |
| params: [axis, mode] |
| Result: [errNo] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_rtin\_setRealTimeInFeedbackLoopMode**(int deviceHandle, int axis, int mode) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo = **[dev].rtin.setRealTimeInFeedbackLoopMode**(axis, mode) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo] = **rtin\_setRealTimeInFeedbackLoopMode**(axis, mode) |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **setRealTimeInHsslClk** Set the HSSL clock |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | axis | [0|1|2] |
| hssl\_clk | clock is given in nanoseconds: N = data/40 - 1 |
| Out | errNo | errNo |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.amc.rtin.setRealTimeInHsslClk |
| params: [axis, hssl\_clk] |
| Result: [errNo] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_rtin\_setRealTimeInHsslClk**(int deviceHandle, int axis, int hssl\_clk) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo = **[dev].rtin.setRealTimeInHsslClk**(axis, hssl\_clk) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo] = **rtin\_setRealTimeInHsslClk**(axis, hssl\_clk) |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **setRealTimeInHsslGap** Set the HSSL Gaps |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | axis | [0|1|2] |
| hssl\_gap | indicates the gap between the end of the HSSL word and the beginning of the next HSSL word in units of HSSL clock cycles. |
| Out | errNo | errNo |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.amc.rtin.setRealTimeInHsslGap |
| params: [axis, hssl\_gap] |
| Result: [errNo] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_rtin\_setRealTimeInHsslGap**(int deviceHandle, int axis, int hssl\_gap) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo = **[dev].rtin.setRealTimeInHsslGap**(axis, hssl\_gap) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo] = **rtin\_setRealTimeInHsslGap**(axis, hssl\_gap) |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **setRealTimeInHsslHigh** Set the higher part of the HSSL resolution |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | axis | [0|1|2] |
| resohigh |  |
| Out | errNo | errNo |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.amc.rtin.setRealTimeInHsslHigh |
| params: [axis, resohigh] |
| Result: [errNo] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_rtin\_setRealTimeInHsslHigh**(int deviceHandle, int axis, int resohigh) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo = **[dev].rtin.setRealTimeInHsslHigh**(axis, resohigh) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo] = **rtin\_setRealTimeInHsslHigh**(axis, resohigh) |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **setRealTimeInHsslLow** Set the lower part of the HSSL resolution |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | axis | [0|1|2] |
| resolow |  |
| Out | errNo | errNo |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.amc.rtin.setRealTimeInHsslLow |
| params: [axis, resolow] |
| Result: [errNo] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_rtin\_setRealTimeInHsslLow**(int deviceHandle, int axis, int resolow) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo = **[dev].rtin.setRealTimeInHsslLow**(axis, resolow) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo] = **rtin\_setRealTimeInHsslLow**(axis, resolow) |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **setRealTimeInMode** This function sets the real time input mode for the selected axis. |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | axis | [0|1|2] |
| mode | see `RT\_IN\_MODES` @see realtime |
| Out | errNo | errNo |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.amc.rtin.setRealTimeInMode |
| params: [axis, mode] |
| Result: [errNo] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_rtin\_setRealTimeInMode**(int deviceHandle, int axis, int mode) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo = **[dev].rtin.setRealTimeInMode**(axis, mode) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo] = **rtin\_setRealTimeInMode**(axis, mode) |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **setRealTimeInStepsPerPulse** Set the change in step per pulse of the realtime input when trigger and stepper mode is used  only used in open loop operation |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | axis | [0|1|2] |
| steps | number of steps to applied |
| Out | errNo | errNo |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.amc.rtin.setRealTimeInStepsPerPulse |
| params: [axis, steps] |
| Result: [errNo] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_rtin\_setRealTimeInStepsPerPulse**(int deviceHandle, int axis, int steps) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo = **[dev].rtin.setRealTimeInStepsPerPulse**(axis, steps) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo] = **rtin\_setRealTimeInStepsPerPulse**(axis, steps) |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

# Rtout

|  |
| --- |
| **apply** Apply for all rtout function |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| Out | errNo | errNo |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.amc.rtout.apply |
| params: [] |
| Result: [errNo] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_rtout\_apply**(int deviceHandle) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo = **[dev].rtout.apply**() |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo] = **rtout\_apply**() |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **applyAxis** Apply for rtout function of specific axis |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | axis | [0|1|2] |
| Out | errNo | errNo |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.amc.rtout.applyAxis |
| params: [axis] |
| Result: [errNo] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_rtout\_applyAxis**(int deviceHandle, int axis) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo = **[dev].rtout.applyAxis**(axis) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo] = **rtout\_applyAxis**(axis) |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **discard** Discard all rtout value set by the set function(not applied yet) |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| Out | errNo | errNo |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.amc.rtout.discard |
| params: [] |
| Result: [errNo] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_rtout\_discard**(int deviceHandle) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo = **[dev].rtout.discard**() |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo] = **rtout\_discard**() |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **discardAxis** Discard rtout value of specific axis set by the set function(not applied yet) |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | axis | [0|1|2] |
| Out | errNo | errNo |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.amc.rtout.discardAxis |
| params: [axis] |
| Result: [errNo] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_rtout\_discardAxis**(int deviceHandle, int axis) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo = **[dev].rtout.discardAxis**(axis) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo] = **rtout\_discardAxis**(axis) |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **discardSignalMode** Discard value set by setSignalMode |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| Out | errNo | errNo |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.amc.rtout.discardSignalMode |
| params: [] |
| Result: [errNo] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_rtout\_discardSignalMode**(int deviceHandle) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo = **[dev].rtout.discardSignalMode**() |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo] = **rtout\_discardSignalMode**() |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **getControlAQuadBOut** This function gets status of AQuadB output for position indication. |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | axis | [0|1|2] |
| tempvalue | boolean if true get the tempory value ( from the set function) |
| Out | errNo | errNo |
| value\_boolean1 | boolean |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.amc.rtout.getControlAQuadBOut |
| params: [axis, tempvalue] |
| Result: [errNo, value\_boolean1] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_rtout\_getControlAQuadBOut**(int deviceHandle, int axis, int tempvalue, bool\* value\_boolean1) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo, value\_boolean1 = **[dev].rtout.getControlAQuadBOut**(axis, tempvalue) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo, value\_boolean1] = **rtout\_getControlAQuadBOut**(axis, tempvalue) |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **getControlAQuadBOutClock** This function gets the clock for AQuadB output. |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | axis | [0|1|2] |
| tempvalue | boolean if true get the tempory value ( from the set function) |
| Out | errNo | errNo |
| clock\_in\_ns | Clock in multiples of 20ns. Minimum 2 (40ns), maximum 65535 (1,310700ms) |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.amc.rtout.getControlAQuadBOutClock |
| params: [axis, tempvalue] |
| Result: [errNo, clock\_in\_ns] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_rtout\_getControlAQuadBOutClock**(int deviceHandle, int axis, bool tempvalue, int\* clock\_in\_ns) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo, clock\_in\_ns = **[dev].rtout.getControlAQuadBOutClock**(axis, tempvalue) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo, clock\_in\_ns] = **rtout\_getControlAQuadBOutClock**(axis, tempvalue) |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **getControlAQuadBOutResolution** This function gets the AQuadB output resolution for position indication. |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | axis | [0|1|2] |
| tempvalue | boolean if true get the tempory value ( from the set function) |
| Out | errNo | errNo |
| resolution | in nm |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.amc.rtout.getControlAQuadBOutResolution |
| params: [axis, tempvalue] |
| Result: [errNo, resolution] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_rtout\_getControlAQuadBOutResolution**(int deviceHandle, int axis, bool tempvalue, int\* resolution) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo, resolution = **[dev].rtout.getControlAQuadBOutResolution**(axis, tempvalue) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo, resolution] = **rtout\_getControlAQuadBOutResolution**(axis, tempvalue) |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **getMode** Get Mode |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | axis | [0|1|2] |
| tempvalue |  |
| Out | errNo | errNo |
| mode | 0: Off, 1: AquadB, 2: Trigger |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.amc.rtout.getMode |
| params: [axis, tempvalue] |
| Result: [errNo, mode] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_rtout\_getMode**(int deviceHandle, int axis, bool tempvalue, int\* mode) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo, mode = **[dev].rtout.getMode**(axis, tempvalue) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo, mode] = **rtout\_getMode**(axis, tempvalue) |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **getSignalMode** This function gets the real time output mode for the selected axis. |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | tempvalue |  |
| Out | errNo | errNo |
| mode | 0: TTL, 1: LVDS |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.amc.rtout.getSignalMode |
| params: [tempvalue] |
| Result: [errNo, mode] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_rtout\_getSignalMode**(int deviceHandle, bool tempvalue, int\* mode) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo, mode = **[dev].rtout.getSignalMode**(tempvalue) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo, mode] = **rtout\_getSignalMode**(tempvalue) |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **getTriggerConfig** Get the real time output trigger config |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | axis | [0|1|2] |
| tempvalue | boolean |
| Out | errNo | errNo |
| higher | upper limit in nm / µdeg |
| lower | lower limit in nm / µdeg |
| epsilon | hysteresis in nm / µdeg |
| polarity | 0: active high, 1: active low |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.amc.rtout.getTriggerConfig |
| params: [axis, tempvalue] |
| Result: [errNo, higher, lower, epsilon, polarity] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_rtout\_getTriggerConfig**(int deviceHandle, int axis, bool tempvalue, int\* higher, int\* lower, int\* epsilon, int\* polarity) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo, higher, lower, epsilon, polarity = **[dev].rtout.getTriggerConfig**(axis, tempvalue) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo, higher, lower, epsilon, polarity] = **rtout\_getTriggerConfig**(axis, tempvalue) |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **setControlAQuadBOutClock** This function sets the clock for AQuadB output. |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | axis | [0|1|2] |
| clock | Clock in multiples of 20ns. Minimum 2 (40ns), maximum 65535 (1,310700ms) |
| Out | errNo | errNo |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.amc.rtout.setControlAQuadBOutClock |
| params: [axis, clock] |
| Result: [errNo] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_rtout\_setControlAQuadBOutClock**(int deviceHandle, int axis, int clock) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo = **[dev].rtout.setControlAQuadBOutClock**(axis, clock) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo] = **rtout\_setControlAQuadBOutClock**(axis, clock) |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **setControlAQuadBOutResolution** This function sets the AQuadB output resolution for position indication. |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | axis | [0|1|2] |
| resolution | in nm |
| Out | errNo | errNo |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.amc.rtout.setControlAQuadBOutResolution |
| params: [axis, resolution] |
| Result: [errNo] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_rtout\_setControlAQuadBOutResolution**(int deviceHandle, int axis, int resolution) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo = **[dev].rtout.setControlAQuadBOutResolution**(axis, resolution) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo] = **rtout\_setControlAQuadBOutResolution**(axis, resolution) |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **setMode** Set the real time output signal mode |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | axis | [0|1|2] |
| mode | 0: Off, 1: AquadB, 2: Trigger |
| Out | errNo | errNo |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.amc.rtout.setMode |
| params: [axis, mode] |
| Result: [errNo] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_rtout\_setMode**(int deviceHandle, int axis, int mode) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo = **[dev].rtout.setMode**(axis, mode) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo] = **rtout\_setMode**(axis, mode) |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **setSignalMode** This function sets the real time output mode for the selected axis. |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | mode | 0: TTL, 1: LVDS |
| Out | errNo | errNo |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.amc.rtout.setSignalMode |
| params: [mode] |
| Result: [errNo] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_rtout\_setSignalMode**(int deviceHandle, int mode) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo = **[dev].rtout.setSignalMode**(mode) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo] = **rtout\_setSignalMode**(mode) |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **setTriggerConfig** Control the real time output trigger config |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | axis | [0|1|2] |
| higher | upper limit in nm / µdeg |
| lower | lower limit in nm / µdeg |
| epsilon | hysteresis in nm / µdeg |
| polarity | 0: active high, 1: active low |
| Out | errNo | errNo |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.amc.rtout.setTriggerConfig |
| params: [axis, higher, lower, epsilon, polarity] |
| Result: [errNo] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_rtout\_setTriggerConfig**(int deviceHandle, int axis, int higher, int lower, int epsilon, int polarity) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo = **[dev].rtout.setTriggerConfig**(axis, higher, lower, epsilon, polarity) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo] = **rtout\_setTriggerConfig**(axis, higher, lower, epsilon, polarity) |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

# Status

|  |
| --- |
| **getFullCombinedStatus** Get the full combined status of a positioner axis and return the status as a string (to be used in the Webapplication) |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | axis | [0|1|2] |
| Out | errNo | errNo |
| value\_string1 | string can be "moving","in target range", "backward limit reached", "forward limit reached", "positioner not connected", "output not enabled" |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.amc.status.getFullCombinedStatus |
| params: [axis] |
| Result: [errNo, value\_string1] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_status\_getFullCombinedStatus**(int deviceHandle, int axis, char\* value\_string1, int size0) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo, value\_string1 = **[dev].status.getFullCombinedStatus**(axis) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo, value\_string1] = **status\_getFullCombinedStatus**(axis) |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **getOlStatus** Get the Feedback status of the positioner |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | axis | [0|1|2] |
| Out | errNo | errNo |
| sensorstatus | as integer 0: NUM Positioner connected 1: OL positioner connected 2: No positioner connected , 3: RES positione connected |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.amc.status.getOlStatus |
| params: [axis] |
| Result: [errNo, sensorstatus] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_status\_getOlStatus**(int deviceHandle, int axis, int\* sensorstatus) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo, sensorstatus = **[dev].status.getOlStatus**(axis) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo, sensorstatus] = **status\_getOlStatus**(axis) |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **getStatusConnected** This function gets information about the connection status of the selected axis’ positioner. |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | axis | [0|1|2] |
| Out | errNo | errNo |
| value\_boolean1 | boolean If true, the actor is connected |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.amc.status.getStatusConnected |
| params: [axis] |
| Result: [errNo, value\_boolean1] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_status\_getStatusConnected**(int deviceHandle, int axis, bool\* value\_boolean1) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo, value\_boolean1 = **[dev].status.getStatusConnected**(axis) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo, value\_boolean1] = **status\_getStatusConnected**(axis) |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **getStatusEot** Retrieves the status of the end of travel (EOT) detection in backward direction or in forward direction. |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | axis | [0|1|2] |
| Out | errNo | errNo |
| value\_boolean1 | boolean true= detected$ |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.amc.status.getStatusEot |
| params: [axis] |
| Result: [errNo, value\_boolean1] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_status\_getStatusEot**(int deviceHandle, int axis, bool\* value\_boolean1) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo, value\_boolean1 = **[dev].status.getStatusEot**(axis) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo, value\_boolean1] = **status\_getStatusEot**(axis) |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **getStatusEotBkwd** This function gets the status of the end of travel detection on the selected axis in backward direction. |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | axis | [0|1|2] |
| Out | errNo | errNo |
| value\_boolean1 | boolean true= detected |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.amc.status.getStatusEotBkwd |
| params: [axis] |
| Result: [errNo, value\_boolean1] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_status\_getStatusEotBkwd**(int deviceHandle, int axis, bool\* value\_boolean1) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo, value\_boolean1 = **[dev].status.getStatusEotBkwd**(axis) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo, value\_boolean1] = **status\_getStatusEotBkwd**(axis) |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **getStatusEotFwd** This function gets the status of the end of travel detection on the selected axis in forward direction. |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | axis | [0|1|2] |
| Out | errNo | errNo |
| value\_boolean1 | boolean true= detected |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.amc.status.getStatusEotFwd |
| params: [axis] |
| Result: [errNo, value\_boolean1] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_status\_getStatusEotFwd**(int deviceHandle, int axis, bool\* value\_boolean1) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo, value\_boolean1 = **[dev].status.getStatusEotFwd**(axis) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo, value\_boolean1] = **status\_getStatusEotFwd**(axis) |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **getStatusMoving** This function gets information about the status of the stage output. |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | axis | [0|1|2] |
| Out | errNo | errNo |
| status | 0: Idle, i.e. within the noise range of the sensor, 1: Moving, i.e the actor is actively driven by the output stage either for closed-loop approach or continous/single stepping and the output is active.  2 : Pending means the output stage is driving but the output is deactivated |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.amc.status.getStatusMoving |
| params: [axis] |
| Result: [errNo, status] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_status\_getStatusMoving**(int deviceHandle, int axis, int\* status) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo, status = **[dev].status.getStatusMoving**(axis) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo, status] = **status\_getStatusMoving**(axis) |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **getStatusReference** This function gets information about the status of the reference position. |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | axis | [0|1|2] |
| Out | errNo | errNo |
| value\_boolean1 | boolean true= valid, false = not valid |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.amc.status.getStatusReference |
| params: [axis] |
| Result: [errNo, value\_boolean1] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_status\_getStatusReference**(int deviceHandle, int axis, bool\* value\_boolean1) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo, value\_boolean1 = **[dev].status.getStatusReference**(axis) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo, value\_boolean1] = **status\_getStatusReference**(axis) |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **getStatusTargetRange** This function gets information about whether the selected axis’ positioner is in target range or not. |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | axis | [0|1|2] |
| Out | errNo | errNo |
| value\_boolean1 | boolean (true = within the target range, false: not ion the target range) |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.amc.status.getStatusTargetRange |
| params: [axis] |
| Result: [errNo, value\_boolean1] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **AMC\_status\_getStatusTargetRange**(int deviceHandle, int axis, bool\* value\_boolean1) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo, value\_boolean1 = **[dev].status.getStatusTargetRange**(axis) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo, value\_boolean1] = **status\_getStatusTargetRange**(axis) |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

# About

|  |
| --- |
| **getInstalledPackages** Get list of packages installed on the device |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| Out | errNo | errorCode |
| value\_string1 | string: Comma separated list of packages |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.system.about.getInstalledPackages |
| params: [] |
| Result: [errNo, value\_string1] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **system\_about\_getInstalledPackages**(int deviceHandle, char\* value\_string1, int size0) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo, value\_string1 = **[dev].about.getInstalledPackages**() |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo, value\_string1] = **system\_about\_getInstalledPackages**() |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **getPackageLicense** Get the license for a specific package |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | pckg | string: Package name |
| Out | errNo | errorCode |
| value\_string1 | string: License for this package |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.system.about.getPackageLicense |
| params: [pckg] |
| Result: [errNo, value\_string1] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **system\_about\_getPackageLicense**(int deviceHandle, const char\* pckg, char\* value\_string1, int size0) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo, value\_string1 = **[dev].about.getPackageLicense**(pckg) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo, value\_string1] = **system\_about\_getPackageLicense**(pckg) |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

# System\_service

|  |
| --- |
| **apply** Apply temporary system configuration |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| Out | errNo | errorCode |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.system.apply |
| params: [] |
| Result: [errNo] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **system\_apply**(int deviceHandle) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo = **[dev].system\_service.apply**() |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo] = **system\_apply**() |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **errorNumberToRecommendation** Get a recommendation for the error code |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | language | integer: Language code |
| errNbr | interger: Error code to translate |
| Out | errNo | errorCode |
| value\_string1 | string: Error recommendation (currently returning an int = 0 until we have recommendations) |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.system.errorNumberToRecommendation |
| params: [language, errNbr] |
| Result: [errNo, value\_string1] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **system\_errorNumberToRecommendation**(int deviceHandle, int language, int errNbr, char\* value\_string1, int size0) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo, value\_string1 = **[dev].system\_service.errorNumberToRecommendation**(language, errNbr) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo, value\_string1] = **system\_errorNumberToRecommendation**(language, errNbr) |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **errorNumberToString** Get a description of an error code |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | language | integer: Language code 0 for the error name, 1 for a more user friendly error message |
| errNbr | interger: Error code to translate |
| Out | errNo | errorCode |
| value\_string1 | string: Error description |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.system.errorNumberToString |
| params: [language, errNbr] |
| Result: [errNo, value\_string1] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **system\_errorNumberToString**(int deviceHandle, int language, int errNbr, char\* value\_string1, int size0) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo, value\_string1 = **[dev].system\_service.errorNumberToString**(language, errNbr) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo, value\_string1] = **system\_errorNumberToString**(language, errNbr) |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **factoryReset** Turns on the factory reset flag. To perform the factory reset, a reboot is necessary afterwards. All settings will be set to default and the IDS will be configured as DHCP server. |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| Out | errNo | errorCode |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.system.factoryReset |
| params: [] |
| Result: [errNo] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **system\_factoryReset**(int deviceHandle) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo = **[dev].system\_service.factoryReset**() |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo] = **system\_factoryReset**() |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **getDeviceName** Get the actual device name |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| Out | errNo | errorCode |
| value\_string1 | string: actual device name |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.system.getDeviceName |
| params: [] |
| Result: [errNo, value\_string1] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **system\_getDeviceName**(int deviceHandle, char\* value\_string1, int size0) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo, value\_string1 = **[dev].system\_service.getDeviceName**() |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo, value\_string1] = **system\_getDeviceName**() |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **getFirmwareVersion** Get the firmware version of the system |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| Out | errNo | errorCode |
| value\_string1 | string: The firmware version |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.system.getFirmwareVersion |
| params: [] |
| Result: [errNo, value\_string1] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **system\_getFirmwareVersion**(int deviceHandle, char\* value\_string1, int size0) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo, value\_string1 = **[dev].system\_service.getFirmwareVersion**() |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo, value\_string1] = **system\_getFirmwareVersion**() |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **getFluxCode** Get the flux code of the system |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| Out | errNo | errorCode |
| value\_string1 | string: flux code |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.system.getFluxCode |
| params: [] |
| Result: [errNo, value\_string1] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **system\_getFluxCode**(int deviceHandle, char\* value\_string1, int size0) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo, value\_string1 = **[dev].system\_service.getFluxCode**() |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo, value\_string1] = **system\_getFluxCode**() |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **getHostname** Return device hostname |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| Out | errNo | errorCode |
| available | available |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.system.getHostname |
| params: [] |
| Result: [errNo, available] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **system\_getHostname**(int deviceHandle, char\* available, int size0) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo, available = **[dev].system\_service.getHostname**() |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo, available] = **system\_getHostname**() |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **getMacAddress** Get the mac address of the system |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| Out | errNo | errorCode |
| value\_string1 | string: Mac address of the system |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.system.getMacAddress |
| params: [] |
| Result: [errNo, value\_string1] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **system\_getMacAddress**(int deviceHandle, char\* value\_string1, int size0) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo, value\_string1 = **[dev].system\_service.getMacAddress**() |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo, value\_string1] = **system\_getMacAddress**() |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **getSerialNumber** Get the serial number of the system |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| Out | errNo | errorCode |
| value\_string1 | string: Serial number |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.system.getSerialNumber |
| params: [] |
| Result: [errNo, value\_string1] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **system\_getSerialNumber**(int deviceHandle, char\* value\_string1, int size0) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo, value\_string1 = **[dev].system\_service.getSerialNumber**() |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo, value\_string1] = **system\_getSerialNumber**() |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

# Network

|  |
| --- |
| **apply** Apply temporary IP configuration and load it |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| Out | errNo | errorCode |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.system.network.apply |
| params: [] |
| Result: [errNo] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **system\_network\_apply**(int deviceHandle) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo = **[dev].network.apply**() |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo] = **system\_network\_apply**() |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **configureWifi** Change the wifi configuration and applies it |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | wifi | mode: 0: Access point, 1: Wifi client |
| SSID |  |
| psk | Pre-shared key |
| Out | errNo | errorCode |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.system.network.configureWifi |
| params: [wifi, SSID, psk] |
| Result: [errNo] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **system\_network\_configureWifi**(int deviceHandle, int wifi, const char\* SSID, const char\* psk) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo = **[dev].network.configureWifi**(wifi, SSID, psk) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo] = **system\_network\_configureWifi**(wifi, SSID, psk) |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **discard** Discard temporary IP configuration |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| Out | errNo | errorCode |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.system.network.discard |
| params: [] |
| Result: [errNo] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **system\_network\_discard**(int deviceHandle) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo = **[dev].network.discard**() |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo] = **system\_network\_discard**() |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **getDefaultGateway** Get the default gateway of the device |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| Out | errNo | errorCode |
| Default | gateway |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.system.network.getDefaultGateway |
| params: [] |
| Result: [errNo, Default] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **system\_network\_getDefaultGateway**(int deviceHandle, char\* Default, int size0) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo, Default = **[dev].network.getDefaultGateway**() |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo, Default] = **system\_network\_getDefaultGateway**() |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **getDnsResolver** Get the DNS resolver |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | priority | of DNS resolver (Usually: 0 = Default, 1 = Backup) |
| Out | errNo | errorCode |
| IP | address of DNS resolver |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.system.network.getDnsResolver |
| params: [priority] |
| Result: [errNo, IP] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **system\_network\_getDnsResolver**(int deviceHandle, int priority, char\* IP, int size0) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo, IP = **[dev].network.getDnsResolver**(priority) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo, IP] = **system\_network\_getDnsResolver**(priority) |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **getEnableDhcpClient** Get the state of DHCP client |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| Out | errNo | errorCode |
| value\_boolean1 | boolean: true = DHCP client enable, false = DHCP client disable |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.system.network.getEnableDhcpClient |
| params: [] |
| Result: [errNo, value\_boolean1] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **system\_network\_getEnableDhcpClient**(int deviceHandle, bool\* value\_boolean1) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo, value\_boolean1 = **[dev].network.getEnableDhcpClient**() |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo, value\_boolean1] = **system\_network\_getEnableDhcpClient**() |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **getEnableDhcpServer** Get the state of DHCP server |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| Out | errNo | errorCode |
| value\_boolean1 | boolean: true = DHCP server enable, false = DHCP server disable |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.system.network.getEnableDhcpServer |
| params: [] |
| Result: [errNo, value\_boolean1] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **system\_network\_getEnableDhcpServer**(int deviceHandle, bool\* value\_boolean1) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo, value\_boolean1 = **[dev].network.getEnableDhcpServer**() |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo, value\_boolean1] = **system\_network\_getEnableDhcpServer**() |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **getIpAddress** Get the IP address of the device |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| Out | errNo | errorCode |
| IP | address as string |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.system.network.getIpAddress |
| params: [] |
| Result: [errNo, IP] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **system\_network\_getIpAddress**(int deviceHandle, char\* IP, int size0) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo, IP = **[dev].network.getIpAddress**() |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo, IP] = **system\_network\_getIpAddress**() |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **getProxyServer** Get the proxy settings of the devide |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| Out | errNo | errorCode |
| Proxy | Server String, empty for no proxy |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.system.network.getProxyServer |
| params: [] |
| Result: [errNo, Proxy] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **system\_network\_getProxyServer**(int deviceHandle, char\* Proxy, int size0) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo, Proxy = **[dev].network.getProxyServer**() |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo, Proxy] = **system\_network\_getProxyServer**() |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **getRealIpAddress** Get the real IP address of the device set to the network interface (br0, eth1 or eth0) |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| Out | errNo | errorCode |
| IP | address as string |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.system.network.getRealIpAddress |
| params: [] |
| Result: [errNo, IP] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **system\_network\_getRealIpAddress**(int deviceHandle, char\* IP, int size0) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo, IP = **[dev].network.getRealIpAddress**() |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo, IP] = **system\_network\_getRealIpAddress**() |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **getSubnetMask** Get the subnet mask of the device |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| Out | errNo | errorCode |
| Subnet | mask as string |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.system.network.getSubnetMask |
| params: [] |
| Result: [errNo, Subnet] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **system\_network\_getSubnetMask**(int deviceHandle, char\* Subnet, int size0) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo, Subnet = **[dev].network.getSubnetMask**() |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo, Subnet] = **system\_network\_getSubnetMask**() |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **getWifiMode** Get the operation mode of the wifi adapter |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| Out | errNo | errorCode |
| wifi | mode: 0: Access point, 1: Wifi client |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.system.network.getWifiMode |
| params: [] |
| Result: [errNo, wifi] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **system\_network\_getWifiMode**(int deviceHandle, int\* wifi) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo, wifi = **[dev].network.getWifiMode**() |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo, wifi] = **system\_network\_getWifiMode**() |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **getWifiPassphrase** Get the the passphrase of the network hosted (mode: Access point) or connected to (mode: client) |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| Out | errNo | errorCode |
| psk | Pre-shared key |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.system.network.getWifiPassphrase |
| params: [] |
| Result: [errNo, psk] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **system\_network\_getWifiPassphrase**(int deviceHandle, char\* psk, int size0) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo, psk = **[dev].network.getWifiPassphrase**() |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo, psk] = **system\_network\_getWifiPassphrase**() |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **getWifiPresent** Returns is a Wifi interface is present |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| Out | errNo | errorCode |
| True | True, if interface is present |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.system.network.getWifiPresent |
| params: [] |
| Result: [errNo, True] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **system\_network\_getWifiPresent**(int deviceHandle, bool\* True) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo, True = **[dev].network.getWifiPresent**() |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo, True] = **system\_network\_getWifiPresent**() |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **getWifiSSID** Get the the SSID of the network hosted (mode: Access point) or connected to (mode: client) |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| Out | errNo | errorCode |
| SSID | SSID |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.system.network.getWifiSSID |
| params: [] |
| Result: [errNo, SSID] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **system\_network\_getWifiSSID**(int deviceHandle, char\* SSID, int size0) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo, SSID = **[dev].network.getWifiSSID**() |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo, SSID] = **system\_network\_getWifiSSID**() |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **setDefaultGateway** Set the default gateway of the device |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | gateway | Default gateway as string |
| Out | errNo | errorCode |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.system.network.setDefaultGateway |
| params: [gateway] |
| Result: [errNo] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **system\_network\_setDefaultGateway**(int deviceHandle, const char\* gateway) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo = **[dev].network.setDefaultGateway**(gateway) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo] = **system\_network\_setDefaultGateway**(gateway) |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **setDnsResolver** Set the DNS resolver |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | priority | of DNS resolver (Usually: 0 = Default, 1 = Backup) |
| resolver | The resolver's IP address as string |
| Out | errNo | errorCode |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.system.network.setDnsResolver |
| params: [priority, resolver] |
| Result: [errNo] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **system\_network\_setDnsResolver**(int deviceHandle, int priority, const char\* resolver) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo = **[dev].network.setDnsResolver**(priority, resolver) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo] = **system\_network\_setDnsResolver**(priority, resolver) |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **setEnableDhcpClient** Enable or disable DHCP client |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | enable | boolean: true = enable DHCP client, false = disable DHCP client |
| Out | errNo | errorCode |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.system.network.setEnableDhcpClient |
| params: [enable] |
| Result: [errNo] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **system\_network\_setEnableDhcpClient**(int deviceHandle, bool enable) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo = **[dev].network.setEnableDhcpClient**(enable) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo] = **system\_network\_setEnableDhcpClient**(enable) |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **setEnableDhcpServer** Enable or disable DHCP server |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | enable | boolean: true = enable DHCP server, false = disable DHCP server |
| Out | errNo | errorCode |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.system.network.setEnableDhcpServer |
| params: [enable] |
| Result: [errNo] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **system\_network\_setEnableDhcpServer**(int deviceHandle, bool enable) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo = **[dev].network.setEnableDhcpServer**(enable) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo] = **system\_network\_setEnableDhcpServer**(enable) |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **setIpAddress** Set the IP address of the device |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | address | IP address as string |
| Out | errNo | errorCode |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.system.network.setIpAddress |
| params: [address] |
| Result: [errNo] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **system\_network\_setIpAddress**(int deviceHandle, const char\* address) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo = **[dev].network.setIpAddress**(address) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo] = **system\_network\_setIpAddress**(address) |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **setProxyServer** Set the proxy server of the device |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | proxyServer | Proxy Server Setting as string |
| Out | errNo | errorCode |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.system.network.setProxyServer |
| params: [proxyServer] |
| Result: [errNo] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **system\_network\_setProxyServer**(int deviceHandle, const char\* proxyServer) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo = **[dev].network.setProxyServer**(proxyServer) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo] = **system\_network\_setProxyServer**(proxyServer) |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

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| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **setSubnetMask** Set the subnet mask of the device |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | netmask | Subnet mask as string |
| Out | errNo | errorCode |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.system.network.setSubnetMask |
| params: [netmask] |
| Result: [errNo] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **system\_network\_setSubnetMask**(int deviceHandle, const char\* netmask) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo = **[dev].network.setSubnetMask**(netmask) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo] = **system\_network\_setSubnetMask**(netmask) |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **setWifiMode** Change the operation mode of the wifi adapter |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | wifi | mode: 0: Access point, 1: Wifi client |
| Out | errNo | errorCode |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.system.network.setWifiMode |
| params: [wifi] |
| Result: [errNo] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **system\_network\_setWifiMode**(int deviceHandle, int wifi) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo = **[dev].network.setWifiMode**(wifi) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo] = **system\_network\_setWifiMode**(wifi) |

|  |
| --- |
| **C#** |

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| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

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| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **setWifiPassphrase** Change the passphrase of the network hosted (mode: Access point) or connected to (mode: client) |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | psk | Pre-shared key |
| Out | errNo | errorCode |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.system.network.setWifiPassphrase |
| params: [psk] |
| Result: [errNo] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **system\_network\_setWifiPassphrase**(int deviceHandle, const char\* psk) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo = **[dev].network.setWifiPassphrase**(psk) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo] = **system\_network\_setWifiPassphrase**(psk) |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **setWifiSSID** Change the SSID of the network hosted (mode: Access point) or connected to (mode: client) |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | SSID |  |
| Out | errNo | errorCode |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.system.network.setWifiSSID |
| params: [SSID] |
| Result: [errNo] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **system\_network\_setWifiSSID**(int deviceHandle, const char\* SSID) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo = **[dev].network.setWifiSSID**(SSID) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo] = **system\_network\_setWifiSSID**(SSID) |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **verify** Verify that temporary IP configuration is correct |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| Out | errNo | errorCode |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.system.network.verify |
| params: [] |
| Result: [errNo] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **system\_network\_verify**(int deviceHandle) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo = **[dev].network.verify**() |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo] = **system\_network\_verify**() |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

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| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

# System\_service

|  |
| --- |
| **rebootSystem** Reboot the system |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| Out | errNo | errorCode |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.system.rebootSystem |
| params: [] |
| Result: [errNo] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **system\_rebootSystem**(int deviceHandle) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo = **[dev].system\_service.rebootSystem**() |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo] = **system\_rebootSystem**() |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **setDeviceName** Set custom name for the device |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | name | string: device name |
| Out | errNo | errorCode |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.system.setDeviceName |
| params: [name] |
| Result: [errNo] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **system\_setDeviceName**(int deviceHandle, const char\* name) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo = **[dev].system\_service.setDeviceName**(name) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo] = **system\_setDeviceName**(name) |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

# Update

|  |
| --- |
| **getLicenseUpdateProgress** Get the progress of running license update |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| Out | errNo | errorCode |
| value\_int1 | int: progress in percent |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.system.update.getLicenseUpdateProgress |
| params: [] |
| Result: [errNo, value\_int1] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **system\_update\_getLicenseUpdateProgress**(int deviceHandle, int\* value\_int1) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo, value\_int1 = **[dev].update.getLicenseUpdateProgress**() |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo, value\_int1] = **system\_update\_getLicenseUpdateProgress**() |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **getSwUpdateProgress** Get the progress of running update |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| Out | errNo | errorCode |
| value\_int1 | int: progress in percent |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.system.update.getSwUpdateProgress |
| params: [] |
| Result: [errNo, value\_int1] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **system\_update\_getSwUpdateProgress**(int deviceHandle, int\* value\_int1) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo, value\_int1 = **[dev].update.getSwUpdateProgress**() |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo, value\_int1] = **system\_update\_getSwUpdateProgress**() |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **licenseUpdateBase64** Execute the license update with base64 file uploaded. After execution, a manual reboot is nevessary. |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| Out | errNo | errorCode |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.system.update.licenseUpdateBase64 |
| params: [] |
| Result: [errNo] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **system\_update\_licenseUpdateBase64**(int deviceHandle) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo = **[dev].update.licenseUpdateBase64**() |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo] = **system\_update\_licenseUpdateBase64**() |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **softwareUpdateBase64** Execute the update with base64 file uploaded. After completion, a manual reboot is necessary. |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| Out | errNo | errorCode |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.system.update.softwareUpdateBase64 |
| params: [] |
| Result: [errNo] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **system\_update\_softwareUpdateBase64**(int deviceHandle) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo = **[dev].update.softwareUpdateBase64**() |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo] = **system\_update\_softwareUpdateBase64**() |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **uploadLicenseBase64** Upload new license file in format base 64 |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | offset | int: offset of the data |
| b64Data | string: base64 data |
| Out | errNo | errorCode |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.system.update.uploadLicenseBase64 |
| params: [offset, b64Data] |
| Result: [errNo] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **system\_update\_uploadLicenseBase64**(int deviceHandle, int offset, const char\* b64Data) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo = **[dev].update.uploadLicenseBase64**(offset, b64Data) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo] = **system\_update\_uploadLicenseBase64**(offset, b64Data) |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |

|  |
| --- |
| **uploadSoftwareImageBase64** Upload new firmware image in format base 64 |

|  |
| --- |
| **Function specific parameters** |

|  |  |  |
| --- | --- | --- |
| In | offset | int: offset of the data |
| b64Data | string: base64 data |
| Out | errNo | errorCode |

|  |
| --- |
| **JSON Method** |

|  |
| --- |
| method: com.attocube.system.update.uploadSoftwareImageBase64 |
| params: [offset, b64Data] |
| Result: [errNo] |

|  |
| --- |
| **C-DLL call** |

|  |
| --- |
| int **system\_update\_uploadSoftwareImageBase64**(int deviceHandle, int offset, const char\* b64Data) |

|  |
| --- |
| **Python** |

|  |
| --- |
| errNo = **[dev].update.uploadSoftwareImageBase64**(offset, b64Data) |

|  |
| --- |
| **Matlab** |

|  |
| --- |
| [errNo] = **system\_update\_uploadSoftwareImageBase64**(offset, b64Data) |

|  |
| --- |
| **C#** |

|  |
| --- |
| The C# library will be available as a new version later, for now use the old version and the corresponding helpfile |

|  |
| --- |
| **LabVIEW** |

|  |
| --- |
| Updated LabVIEW library will be available as a new version later, for now use the old version |