OIF OPTICAL INTERNETWORKING FORUM

System Packet Interface Level 3: OC-48 System Interface for Physical and Link Layer Devices

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4   <u>Document Revision History</u>

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5   <u>Introduction</u>

This document specifies the Optical Internetworking Forum's recommended interface for the interconnection of Physical Layer (PHY) devices to Link Layer devices. This specification is based on the SATURN Development Group's "POS-PHY Level 3" interface [1], which will be referred to hereon as the SPI-3 interface.

SPI-3 fulfills the need for system designers to target a standard POS Physical Layer interface. Although targeted at implementing POS, the SPI-3 specification is not restricted to this application. It provides a versatile bus interface for exchanging packets within a communication system.

SPI-3 defines the requirements for interoperable single-PHY (one PHY layer device connected to one Link Layer device) and multi-PHY (multiple PHY layer devices connected to one Link Layer device) applications. It stresses simplicity of operation to allow forward migration to more elaborate PHY and Link Layer devices.

This specification defines 1-the physical implementation of the SPI-3 bus, 2-the signaling protocol used to communicate data and 3-the data structure used to store the data into holding FIFO's.

6   SPI-3 Interface Reference Definition

The SPI-3 interface defines the interface between SONET/SDH Physical layer devices and Link Layer devices, which can be used to implement several packet-based protocols like HDLC and PPP.

Figure 6.1: SPI-3 Reference Points

Facility Interface   PHY-Link Interface

```
PMD          Link
Device        Layer

PHY
```
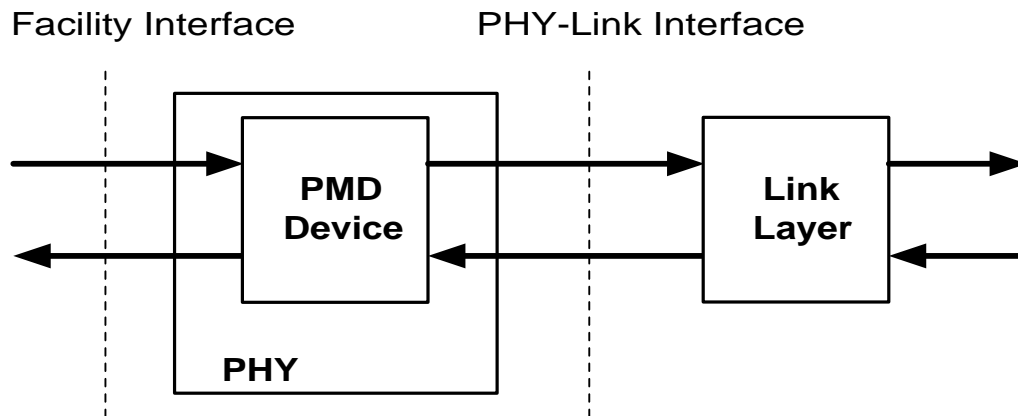
Diagram Definitions

Facility:	An optical fiber, twisted pair electrical or coaxial cable electrical transmission facility.
Link Layer:	Switching Function Layer.
PHY:	Physical Layer for Packet over SONET.
PHY-LINK:	Physical Layer to Link Layer electrical interface.
PMD:	Physical Medium Dependent Layer.

SPI-3 specifies the PHY-LINK interface. The Facility Interface (such as SONET OC-3) is defined by several National and International standards organizations including Bellcore and ITU.

7   Compatibility Options

The SPI-3 specification does not attempt to be compatible to any existing standard. There is no existing equivalent standard. Specifically, SPI-3 does not intend to be compatible with similar ATM specifications like Utopia [3, 4] and SCI-PHY [2]. Although this information is not critical to any implementation, the following bullets highlight the differences between the Utopia/SCI-PHY and SPI-3 interfaces.

- Allowance for an 8-bit bus or a 32-bit bus interface running at a maximum speed of 104 MHz. The bus interface is point-to-point (one output driving only one input load).

- Byte or double-word (4 bytes) data format that can accommodate variable size packets.

- Modification to the RSOC/TSOC start of cell signals to identify the start of packets being transferred over the interface. Renamed the signals to RSOP/TSOP.

- Addition of the REOP/TEOP end of packet signals which delineate the end of packets being transferred over the interface.

- Addition of the RMOD[1:0]/TMOD[1:0] modulo signals which indicate if the last double-word of the packet transfer contains 1, 2, 3 or 4 valid bytes of data.

- Addition of the RERR/TERR error signals which, during the end of the packet, indicates if the transferred packet must be discarded/aborted.

- Deletion of the RCA signal. Receive interface of the PHY pushes packet data to the Layer device. Multi-port PHY devices are responsible for performing round-robin servicing of their ports. PHY address is inserted in-band with the packet data.

- Transmit interface of the PHY is selected using an in-band address that is provided on the same bus transferring the packet data.

- Addition of the RSX/TSX start of transfer signals which identify when the in-band port address of the PHY is on the RDAT/TDAT bus.

- Modification of the TCA cell available signals to form the TPA packet available signals. TPA logic values are defined based on the FIFO fill level (in terms of bytes). In multi-port PHY devices, PHY status indication can be provided using either a polling or a direct status indication scheme.

Polled PHY address is provided by a separate address bus and has pipelined timing.

- Interface FIFO fill level granularity is byte-based. For the Transmit Interface FIFO, the packet available status and start of transmission FIFO fill levels are programmable. For the Receive Interface, the maximum burst transfer size is programmable.

8   Specification Summary

8.1   Signal Naming Conventions

The interface where data flows from the Link Layer device to the Physical layer device will be labeled the Transmit Interface. The interface where data flows from the Physical Layer device to the Link Layer device will be labeled the Receive Interface. All signals are active high unless denoted by a trailing "B".

SIGNAL   Active high signaling.
SIGNALB   Active low signaling.

8.2   Bus Widths

SPI-3 compatible devices support an 8-bit and/or a 32-bit data bus structure. The bus interface is point-to-point (one output driving only one input load) and thus a 32-bit data bus would support only one device. To support multiple lower rate devices with point-to-point connections, an 8-bit data bus structure is defined. Thus, each PHY device would use an 8-bit interface reducing the total number of pins required.

To support variable length packets, the RMOD[1:0]/TMOD[1:0] signals are defined to specify valid bytes in the 32-bit data bus structure. Each double-word must contain four valid bytes of packet data until the last double-word of the packet transfer which is marked with the end of packet REOP/TEOP signal. This last double-word of the transfer will contain up to four valid bytes specified by the RMOD[1:0]/TMOD[1:0] signals.

8.3   Clock Rates

SPI-3 compatible devices can support a transfer clock rate up to 104 MHz. Some devices may support multiple rates. Generally, devices targeted at single or multi-PHY applications, where the aggregate PHY bit rate approaches 622 Mbit/s will use the 8-bit data bus structure with a 104 MHz FIFO clock rate. Devices targeted at applications where the aggregate PHY

bit rate approaches 2.4 Gbit/s will use the 32-bit data bus structure with a 104 MHz FIFO clock rate.

8.4 Packet Interface Synchronization

The SPI-3 packet interface supports transmit and receive data transfers at clock rates independent of the line bit rate. As a result, PHY layer devices must support packet rate decoupling using FIFOs.

To ease the interface between the Link Layer and PHY layer devices and to support multiple PHY layer interfaces, FIFOs are used. Control signals are provided to both the Link Layer and PHY layer devices to allow either one to exercise flow control. Since the bus interface is point-to-point, the receive interface of the PHY device pushes data to the Link Layer device. For the transmit interface, the packet available status granularity is byte-based.

In the receive direction, when the PHY layer device has stored an end-of-packet (a complete small packet or the end of a larger packet) or some predefined number of bytes in its receive FIFO, it sends the in-band address followed by FIFO data to the Link Layer device. The data on the interface bus is marked with the valid signal (RVAL) asserted. A multi-port PHY device with multiple FIFOs would service each port in a round-robin fashion when sufficient data is available in its FIFO. The Link Layer device can pause the data flow by deasserting the enable signal (RENB).

In the transmit direction, when the PHY layer device has space for some predefined number of bytes in its transmit FIFO, it informs the Link Layer device by asserting a transmit packet available (TPA). The Link Layer device can then write the in-band address followed by packet data to the PHY layer device using an enable signal (TENB). The Link Layer device shall monitor TPA for a high to low transition, which would indicate that the transmit FIFO is near full (the number of bytes left in the FIFO can be user selectable, but must be predefined), and suspend data transfer to avoid an overflow. The Link Layer device can pause the data flow by deasserting the enable signal (TENB).

SPI-3 defines both byte-level and packet-level transfer control in the transmit direction. In byte-level transfer, FIFO status information is presented on a cycle-by-cycle basis. With packet-level transfer, the FIFO status information applies to segments of data. When using byte level transfer, direct status indication must be used. In this case, the PHY layer device provides the transmit packet available status of the selected port (STPA) in the PHY device. As well, the PHY layer device may provide direct access to the transmit packet available status of all ports (DTPA[]) in the PHY device if the number of ports is small. With packet level transfer, the Link Layer device is able to do status polling on the transmit direction. The Link Layer device can

use the transmit port address TADR[] to poll individual ports of the PHY device, which all respond on a common polled (PTPA) signal.

Since the variable size nature of packets does not allow any guarantee as to the number of bytes available, in both transmit and receive directions, a selected PHY transmit packet available is provided on signal STPA and a receive data valid on signal RVAL. STPA and RVAL always reflect the status of the selected PHY to or from which data is being transferred. RVAL indicates if valid data is available on the receive data bus and is defined such that data transfers can be aligned with packet boundaries.

Physical layer port selection is performed using in-band addressing. In the transmit direction, the Layer device selects a PHY port by sending the address on the TDAT[] bus marked with the TSX signal active and TENB signal inactive. All subsequent TDAT[] bus operations marked with the TSX signal inactive and the TENB active will be packet data for the specified port. In the receive direction, the PHY device will specify the selected port by sending the address on the RDAT[] bus marked with the RSX signal active and RVAL signal inactive. All subsequent RDAT[] bus operations marked with RSX inactive and RVAL active will be packet data from the specified port.

Both byte-level and packet-level modes are specified in this standard in order to support the current low density multi-port physical layer devices and future higher density multi-port devices. When the number of ports in the physical layer device is limited, byte-level transfer using DTPA[] signals provides a simpler implementation and reduces the need for addressing pins. In this case, direct access will start to become unreasonable as the number of ports increase. Packet-level transfer provides a lower pin count solution using the TADR[] bus when the number of ports is large. In-band addressing ensures the protocol remains consistent between the two approaches. However, the final choice left to the system designers and physical layer device manufacturers to select which approach best suits their desired applications.

8.5   Application Line Rates

The numerous combinations of clock rates and bus widths allow the Packet over SONET Interface for PHY layer devices (SPI-3) to support a wide range of line rates. Table 8.1 gives examples of line rates supported by POS-PHY interfaces and the maximum number of channels supported by the interface definitions.

Table 8.1: Interface Bit Rates

Standard Reference	Bit Rate (Mbit/s)	Number of PHYs (800 Mbit/s bus)	Number of PHYs (3.2 Gbit/s bus)
SONET STS-1	51.84	12	48
SONET STS-3 SDH STM-1	155.52	4	16
SONET STS-12 SDH STM-4	622.08	1	4
SONET STS-48 SDH STM-16	2488.32	N/A	1

8.6   PHY and Link Layer Interface Example

Figure 8.1 illustrates a conceptual example of how a single multi-port PHY device may be interfaced to a Link Layer device. In the example, the Link Layer device is connected to a single package four channel PHY layer device using the 32-bit interface. Figure 8.2 illustrates a conceptual example of how multi-port PHY devices may be interfaced to a single Link Layer device. The Link Layer device is connected to two four-channel PHY layer devices using 8-bit interfaces.

In both examples, the PHY devices are using the direct status indication signals DTPA[]. Optionally, the Link Layer device can perform multiplexed status polling using the PTPA signals.

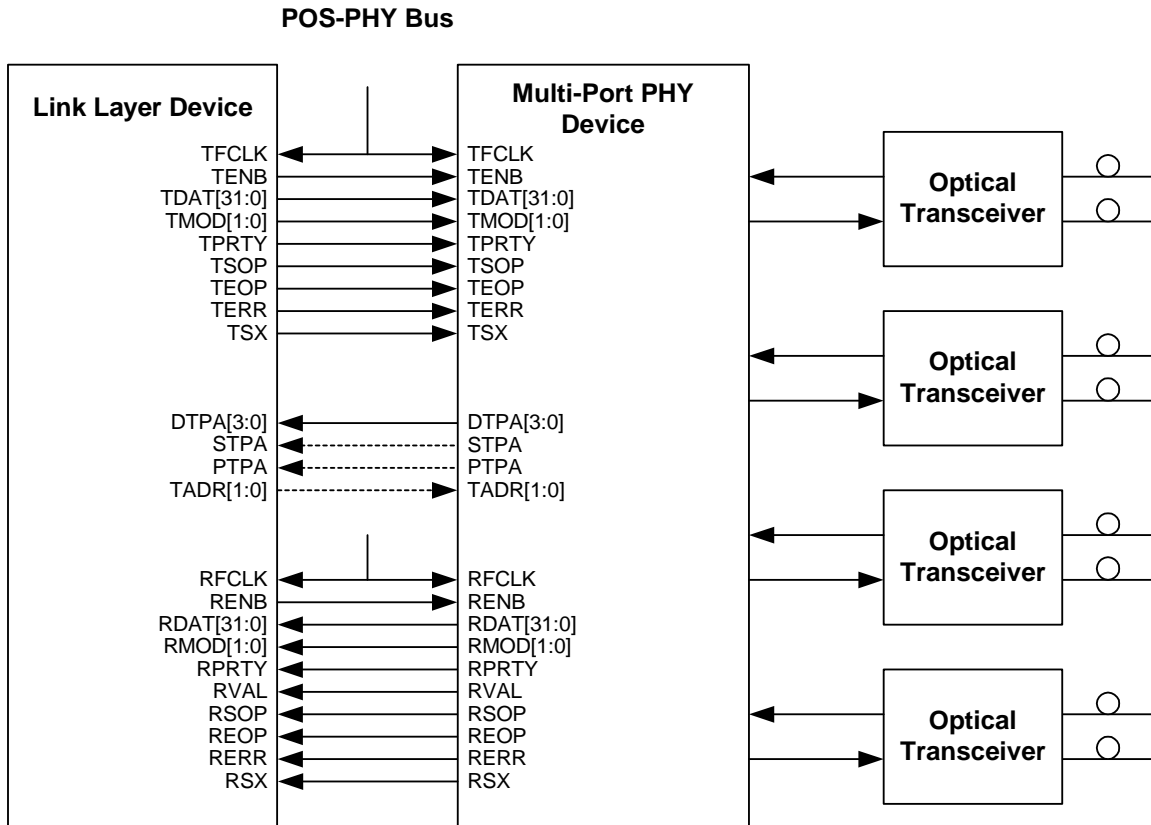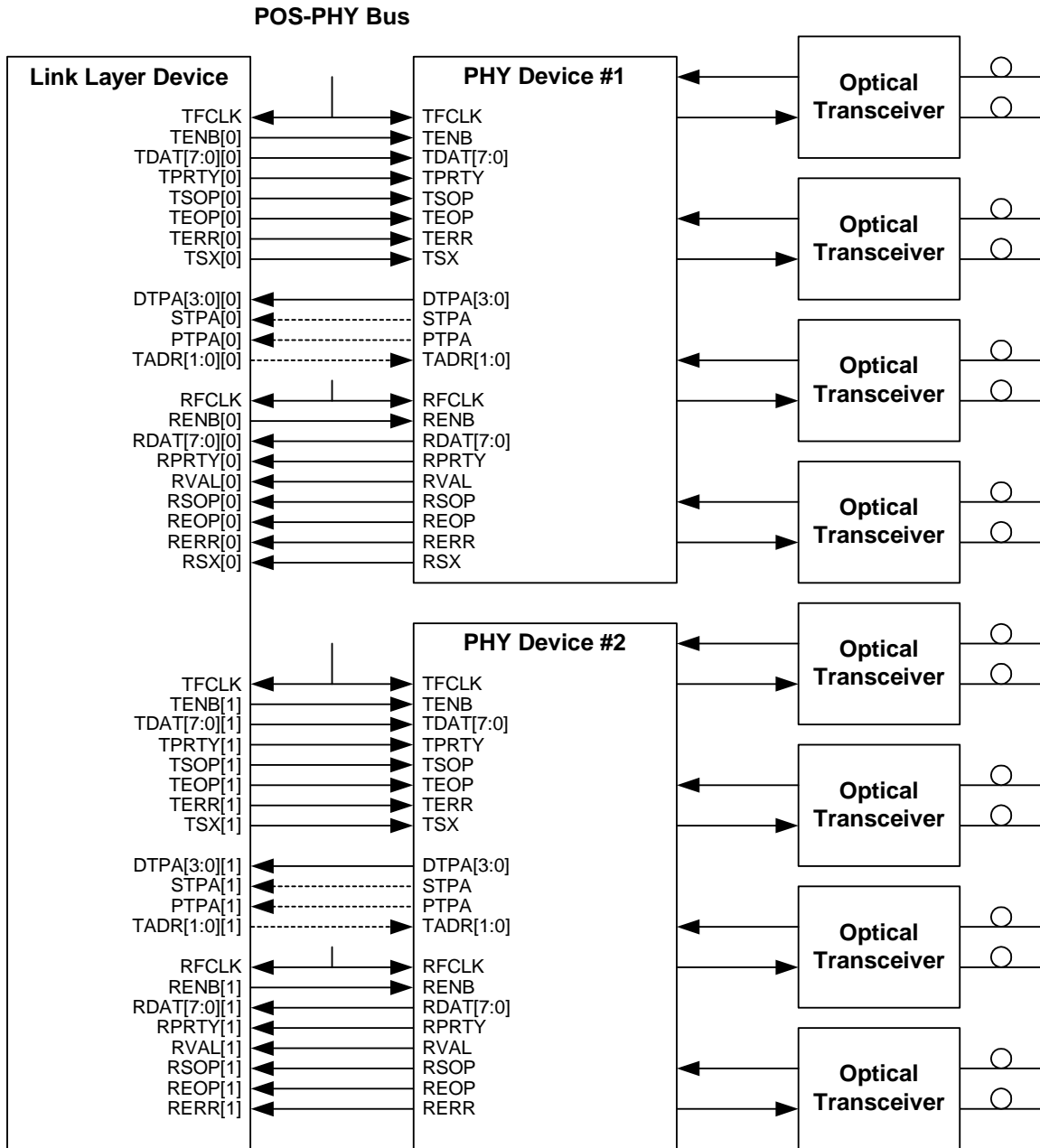**Figure 8.1: POS-PHY PHY to Link Layer 32-bit Interface**

POS-PHY Bus

Figure 8.2: POS-PHY PHY to Link Layer 8-Bit Interface

9 Interface Data Structures

Packets shall be written into the transmit FIFO and read from the receive FIFO using a defined data structure. Octets are written in the same order they are to be transmitted or they were received on the SONET line. Within an octet, the MSB (bit 7) is the first bit to be transmitted. The SPI-3 specification does not preclude the transfer of 1-byte packets. In this case, both start of packet and end of packet signals shall be asserted simultaneously.

For packets longer than the PHY device FIFO, the packet must be transferred over the bus interface in sections. The number of bytes of packet data in each section may be fixed or variable depending on the application. In general, the Receive Interface will round-robin between receive FIFOs with fill levels exceeding a programmable high water mark or with at least one end of packet stored in the FIFO. The Receive Interface would end the transfer of data when an end of a packet is transferred or when a programmable number of bytes have been transferred. The Link Layer device may send fixed size sections of packets on the Transmit Interface or use the TPA signal to determine when the FIFO reaches a full level.

Figure 9.1 illustrates the data structure for the 32-bit bus interface. The double-word with the last byte of the packet is marked with TEOP asserted and TMOD[1:0] specifying the number of valid bytes. Figure 9.2 illustrates the data structure for the 8-bit bus interface. The first byte of the packet is marked with TSOP asserted. The last byte of the packet is marked with TEOP asserted. In all cases, the PHY address is marked with TSX asserted.

In both illustrations, the in-band port address for multi-port PHY devices is not shown. The Transmit Interface would send the PHY port address, on the same bus as the data, marked with the TSX signal active and the TENB signal inactive. Subsequent data transfers on the Transmit Interface would use the transmit FIFO selected by the in-band address. On the Receive Interface, the PHY device reports the receive FIFO address in-band with the RSX signal active and the RVAL signal inactive before transferring packet data. For both cases, large packets which exceed the FIFO size will be transferred over the POS-PHY interface in sections with appropriate in-band addressing prefixing each section.

The in-band address is specified in a single clock cycle operation marked with the RSX/TSX signals. The port address is specified by the TDAT[7:0]/RDAT[7:0] signals. The address is the numeric value of the TDAT[7:0]/RDAT[7:0] signals where bit 0 is the least significant bit and bit 7 is the most significant bit. Thus, up to 256 ports may be supported by a single interface. With a 32-bit interface, the upper 24 bits shall be ignored.

The SPI-3 specification does not define the usage of any packet data. In particular, SPI-3 does not define any field for error correction. Notice that if the Link Layer device uses the PPP protocol, a Frame Check Sequence (FCS) must be processed. If the Physical Layer device does not insert the FCS field before transmission, these bytes should be included at the end of the packet. If the Physical Layer device does not strip the FCS field in the receive direction, these bytes will be included at the end of the packet.

Figure 9.1: 32-bit Interface Data Structures

	Bit 31 Bit 24	Bit 23 Bit 16	Bit 15 Bit 8	Bit 7 Bit 0
Dword 1	Byte 1	Byte 2	Byte 3	Byte 4
Dword 2	Byte 5	Byte 6	Byte 7	Byte 8
Dword 3	Byte 9	Byte 10	Byte 11	Byte 12
Dword 4	Byte 13	Byte 14	Byte 15	Byte 16
Dword 5	Byte 17	Byte 18	Byte 19	Byte 20
Dword 6	Byte 21	Byte 22	Byte 23	Byte 24
	⋮	⋮	⋮	⋮
Dword 28	Byte 109	XX	XX	XX

A 109 Byte Packet

Figure 9.2: 8-bit Interface Data Structures

	Bit 7 Bit 0
Byte 1	Byte 1
Byte 2	Byte 2
Byte 3	Byte 3
Byte 4	Byte 4
Byte 5	Byte 5
Byte 6	Byte 6
	⋮
Byte 62	Byte 62

A 62 Byte Packe

10 Transmit Packet Interface Description

The standard FIFO depth for POS-PHY interfaces is 256 octets. The transmit buffer shall have a programmable threshold defined in terms of the number of bytes available in the FIFO for the assertion and deassertion of the transmit packet available flags.

In this fashion, transmit latency can be managed, and advance TPA lookahead can be achieved. This will allow a Link Layer device to continue to burst data in, without overflowing the transmit buffer, after TPA has been deasserted.

In the transmit direction, the PHY layer device shall not initiate data transmission before a predefined number of bytes or an end of packet flag has been stored in the transmit FIFO. This capability does not affect the SPI-3 bus protocol, but is required to avoid transmit FIFO underflow and frequent data retransmission by the higher layers.

10.1 <u>Transmit Signals</u>

Table 10.1 lists the transmit side SPI-3 specification signals. All signals are expected to be updated and sampled using the rising edge of the transmit FIFO clock TFCLK. A fully compatible POS-PHY Physical Layer device requires at least a 256 byte deep FIFO.

Table 10.1: Transmit Signal Descriptions

Signal Name	Direction	Function
TFCLK	Clock Source to Link and PHY	Transmit FIFO Write Clock (TFCLK). TFCLK is used to synchronize data transfer transactions between the LINK Layer device and the PHY layer device. TFCLK may cycle at a rate up to 104 MHz.
TERR	LINK to PHY	Transmit Error Indicator (TERR) signal. TERR is used to indicate that there is an error in the current packet. TERR should only be asserted when TEOP is asserted; it is considered valid only when TENB is simultaneously asserted.

Signal Name	Direction	Function
TENB	LINK to PHY	Transmit Write Enable (TENB) signal.
		The TENB signal is used to control the flow of data to the transmit FIFOs. When TENB is high, the TDAT, TMOD, TSOP, TEOP and TERR signals are invalid and are ignored by the PHY. The TSX signal is valid and is processed by the PHY when TENB is high.
		When TENB is low, the TDAT, TMOD, TSOP, TEOP and TERR signals are valid and are processed by the PHY. Also, the TSX signal is ignored by the PHY when TENB is low.
TDAT[31:0]	LINK to PHY	Transmit Packet Data Bus (TDAT[]) bus.
		This bus carries the packet octets that are written to the selected transmit FIFO and the in-band port address to select the desired transmit FIFO. The TDAT bus is considered valid only when TENB is simultaneously asserted.
		When a 32-bit interface is used, data must be transmitted in big endian order on TDAT[31:0]. Given the define data structure, bit 31 is transmitted first and bit 0 is transmitted last.
		When an 8-bit interface is used, the PHY supports only TDAT[7:0].
TPRTY	LINK to PHY	Transmit bus parity (TPRTY) signal.
		The transmit parity (TPRTY) signal indicates the parity calculated over the TDAT bus. When an 8-bit interface is used, the PHY only supports TPRTY calculated over TDAT[7:0]. TPRTY is considered valid only when TENB or TSX is asserted.
		When TPRTY is supported, the PHY layer device is required to support odd parity. The PHY layer device is required to report any parity error to higher layers, but shall not interfere with the transferred data.

Signal Name	Direction	Function
TMOD[1:0]	LINK to PHY	Transmit Word Modulo (TMOD[1:0]) signal. TMOD[1:0] indicates the number of valid bytes of data in TDAT[31:0]. The TMOD bus should always be all zero, except during the last double-word transfer of a packet on TDAT[31:0]. When TEOP is asserted, the number of valid packet data bytes on TDAT[31:0] is specified by TMOD[1:0]. TMOD[1:0] = "00" TDAT[31:0] valid TMOD[1:0] = "01" TDAT[31:8] valid TMOD[1:0] = "10" TDAT[31:16] valid TMOD[1:0] = "11" TDAT[31:24] valid When an 8-bit interface is used, the TMOD[1:0] bus is not required. TMOD is considered valid only when TENB is simultaneously asserted.
TSX	LINK to PHY	Transmit Start of Transfer (TSX) signal. TSX indicates when the in-band port address is present on the TDAT bus. When TSX is high and TENB is high, the value of TDAT[7:0] is the address of the transmit FIFO to be selected. Subsequent data transfers on the TDAT bus will fill the FIFO specified by this in-band address. For single port PHY devices, the TSX signal is optional as the PHY device will ignore in-band addresses when TENB is high. TSX is considered valid only when TENB is not asserted.
TSOP	LINK to PHY	Transmit Start of Packet (TSOP) signal. TSOP is used to delineate the packet boundaries on the TDAT bus. When TSOP is high, the start of the packet is present on the TDAT bus. TSOP is required to be present at the beginning of every packet and is considered valid only when TENB is asserted.

Signal Name	Direction	Function
TEOP	LINK to PHY	Transmit End of Packet (TEOP) signal.
		TEOP is used to delineate the packet boundaries on the TDAT bus. When TEOP is high, the end of the packet is present on the TDAT bus.
		When a 32-bit interface is used, TMOD[1:0] indicates the number of valid bytes the last double-word is composed of when TEOP is asserted. When an 8-bit interface is used, the last byte of the packet is on TDAT[7:0] when TEOP is asserted.
		TEOP is required to be present at the end of every packet and is considered valid only when TENB is asserted.
TADR[]	LINK to PHY Packet-Level Mode	Transmit PHY Address (TADR[]) bus.
		The TADR bus is used with the PTPA signal to poll the transmit FIFO's packet available status.
		When TADR is sampled on the rising edge of TFCLK by the PHY, the polled packet available indication PTPA signal is updated with the status of the port specified by the TADR address on the following rising edge of TFCLK.
DTPA[]	PHY to LINK Byte-Level Mode	Direct Transmit Packet Available (DTPA[]).
		The DTPA bus provides direct status indication for the corresponding ports in the PHY device.
		DTPA transitions high when a predefined (normally user programmable) minimum number of bytes is available in its transmit FIFO. Once high, the DTPA signal indicates that its corresponding transmit FIFO is not full. When DTPA transitions low, it optionally indicates that its transmit FIFO is full or near full (normally user programmable).
		DTPA is required if byte-level transfer mode is supported. DTPA is updated on the rising edge of TFCLK.

| Signal Name	Direction	Function
STPA	PHY to LINK Byte-Level Mode	Selected-PHY Transmit Packet Available (STPA) signal. STPA transitions high when a predefined (normally user programmable) minimum number of bytes are available in the transmit FIFO specified by the in-band address on TDAT. Once high, STPA indicates the transmit FIFO is not full. When STPA transitions low, it indicates that the transmit FIFO is full or near full (normally user programmable). STPA always provides status indication for the selected port of the PHY device in order to avoid FIFO overflows while polling is performed. The port which STPA reports is updated on the following rising edge of TFCLK after the PHY address on TDAT is sampled by the PHY device. STPA is required if byte-level transfer mode is supported. STPA is updated on the rising edge of TFCLK.
PTPA	PHY to LINK Packet-Level Mode	Polled-PHY Transmit Packet Available (PTPA) signal. PTPA transitions high when a predefined (normally user programmable) minimum number of bytes are available in the polled transmit FIFO. Once high, PTPA indicates that the transmit FIFO is not full. When PTPA transitions low, it optionally indicates that the transmit FIFO is full or near full (normally user programmable). PTPA allows the polling of the PHY selected by the TADR address bus. The port which PTPA reports is updated on the following rising edge of TFCLK after the PHY address on TADR is sampled by the PHY device. PTPA is required if packet-level transfer mode is supported. PTPA is updated on the rising edge of TFCLK.

10.2 <u>Examples</u>

The following examples are not part of the requirements definition of the SPI-3 compatibility specification. They are only informative and provide an aid in the visualization of the interface operation. The examples only present a limited set of scenarios; they are not intended to imply restrictions beyond that presented in the text of the specification. If any apparent discrepancies exist between the examples and the text, the text shall take precedence.

The SPI-3 transmit interface is controlled by the Link Layer device using the TENB signal. All signals must be updated and sampled using the rising edge of the transmit FIFO clock, TFCLK. Figure 10.1 is an example of a multi-port PHY device with two channels. The PHY layer device indicates that a FIFO is not full by asserting the appropriate transmit packet available signal DTPA. DTPA remains asserted until the transmit FIFO is almost full. Almost full implies that the PHY layer device can accept at most a predefined number of writes after the current write.

If DTPA is asserted and the Link Layer device is ready to write a word, it should assert TSX, deassert TENB and present the port address on the TDAT bus if required. Subsequent data transfers with TENB low are treated as packet data which is written to the selected FIFO. At any time, if the Link Layer device does not have data to write, it can deassert TENB. The TSOP and TEOP signals must be appropriately marked at the start and end of packets on the TDAT bus.

Figure 10.1: Transmit Logical Timing
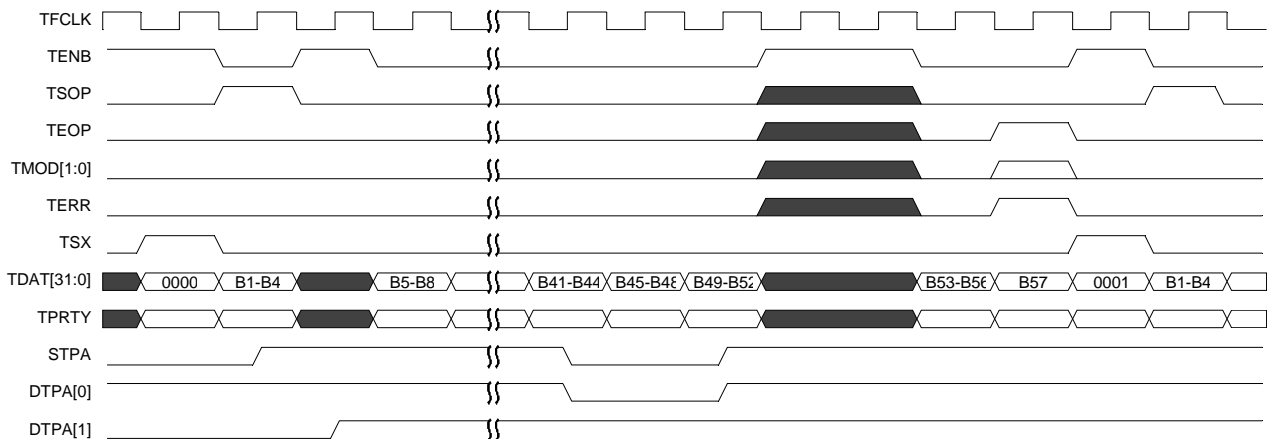
When DTPA transitions low and it has been sampled, the Link Layer device can write no more than a predefined number of bytes to the selected FIFO. In this example, the predefined value is two double-words or eight bytes. If the

Link Layer writes more than that predefined number of words and DTPA remains deasserted throughout, the PHY layer device should indicate an error condition and ignore additional writes until it asserts DTPA again.

Figure 10.2 is an example of the Link Layer device using the polling feature of the Transmit Interface. For comparison purposes, the direct transmit packet available signals for the example ports are provided in the diagram. The status of a given PHY port may be determined by setting the polling address TADR bus to the port address. The polled transmit packet available signal PTPA is updated with the transmit FIFO status in a pipelined manner. The Link Layer device is not restricted in its polling order. The selected transmit packet available STPA signal allows monitoring the selected PHY status and halting data transfer once the FIFO is full. The PTPA signal allows polling other PHY's at any time, including while a data transfer is in progress. The system could be configured differently.

Figure 10.2: Packet-Level Transmit Polling Logical Timing

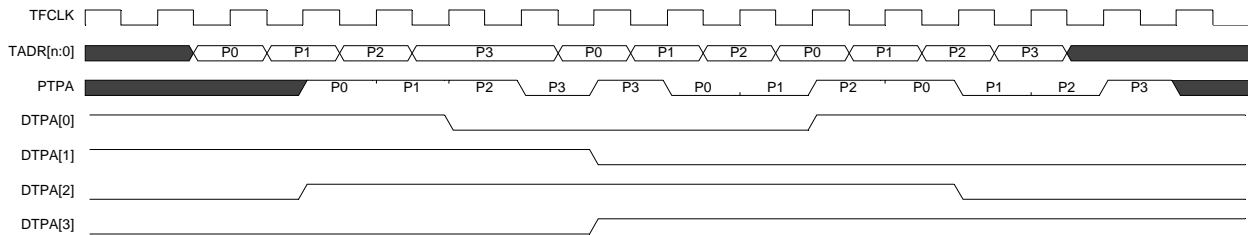Figure 10.3 shows an example of data transfer to a single-port PHY device without the use of in-band addressing, which is optional for single-port applications. During packet transfer, the Link Layer device pauses for its own internal reasons. As in Figure 10.1, the PHY device indicates its FIFO status by means of DTPA.

Figure 10.3: Transmit Logical Timing

**(single-port example without in-band addressing)**
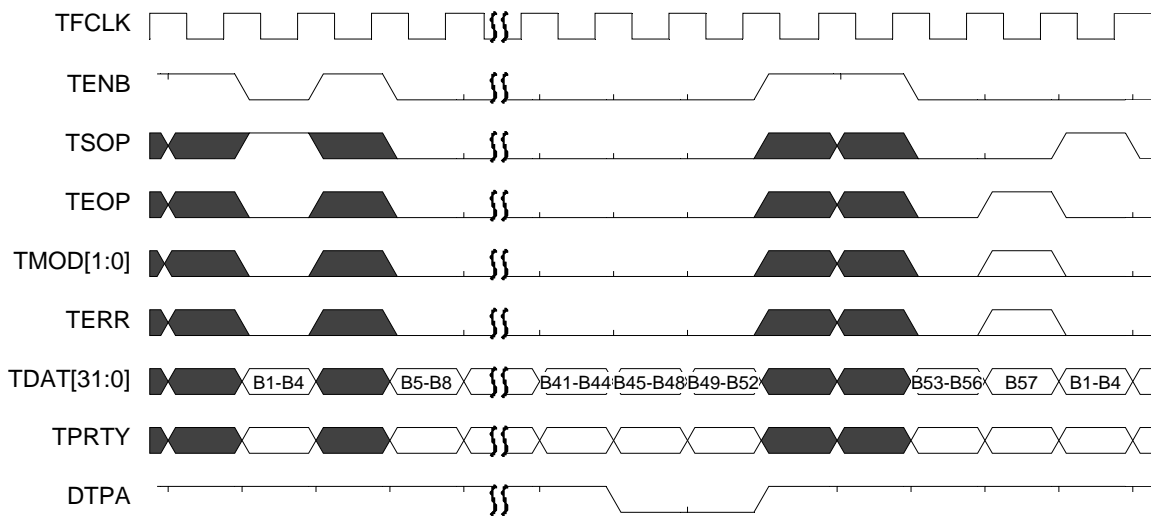
10.3 AC Timing

All AC Timing is from the perspective of the PHY layer device in a PHY-LINK interface.

Table 10.2: Transmit Interface Timing

Symbol	Description	Min	Max	Units
	TFCLK Frequency		104	MHz
	TFCLK Duty Cycle	40	60	%
tS_{tenb}	TENB Set-up time to TFCLK	2		ns
tH_{tenb}	TENB Hold time to TFCLK	0.5		ns
tS_{tdat}	TDAT[15:0] Set-up time to TFCLK	2		ns
tH_{tdat}	TDAT[15:0] Hold time to TFCLK	0.5		ns
tS_{tprty}	TPRTY Set-up time to TFCLK	2		ns
tH_{tprty}	TPRTY Hold time to TFCLK	0.5		ns
tS_{tsop}	TSOP Set-up time to TFCLK	2		ns
tH_{tsop}	TSOP Hold time to TFCLK	0.5		ns
tS_{teop}	TEOP Set-up time to TFCLK	2		ns
tH_{teop}	TEOP Hold time to TFCLK	0.5		ns
tS_{tmod}	TMOD Set-up time to TFCLK	2		ns
tH_{tmod}	TMOD Hold time to TFCLK	0.5		ns
tS_{terr}	TERR Set-up time to TFCLK	2		ns
tH_{terr}	TERR Hold time to TFCLK	0.5		ns
tS_{tsx}	TSX Set-up time to TFCLK	2		ns
tH_{tsx}	TSX Hold time to TFCLK	0.5		ns
tS_{tadr}	TADR[4:0] Set-up time to TFCLK	2		ns
tH_{tadr}	TADR[4:0] Hold time to TFCLK	0.5		ns
tP_{dtpa}	TFCLK High to DTPA Valid	1.5	6	ns
tP_{stpa}	TFCLK High to STPA Valid	1.5	6	ns
tP_{ptpa}	TFCLK High to PTPA Valid	1.5	6	ns

Figure 10.4. Transmit Physical Timing
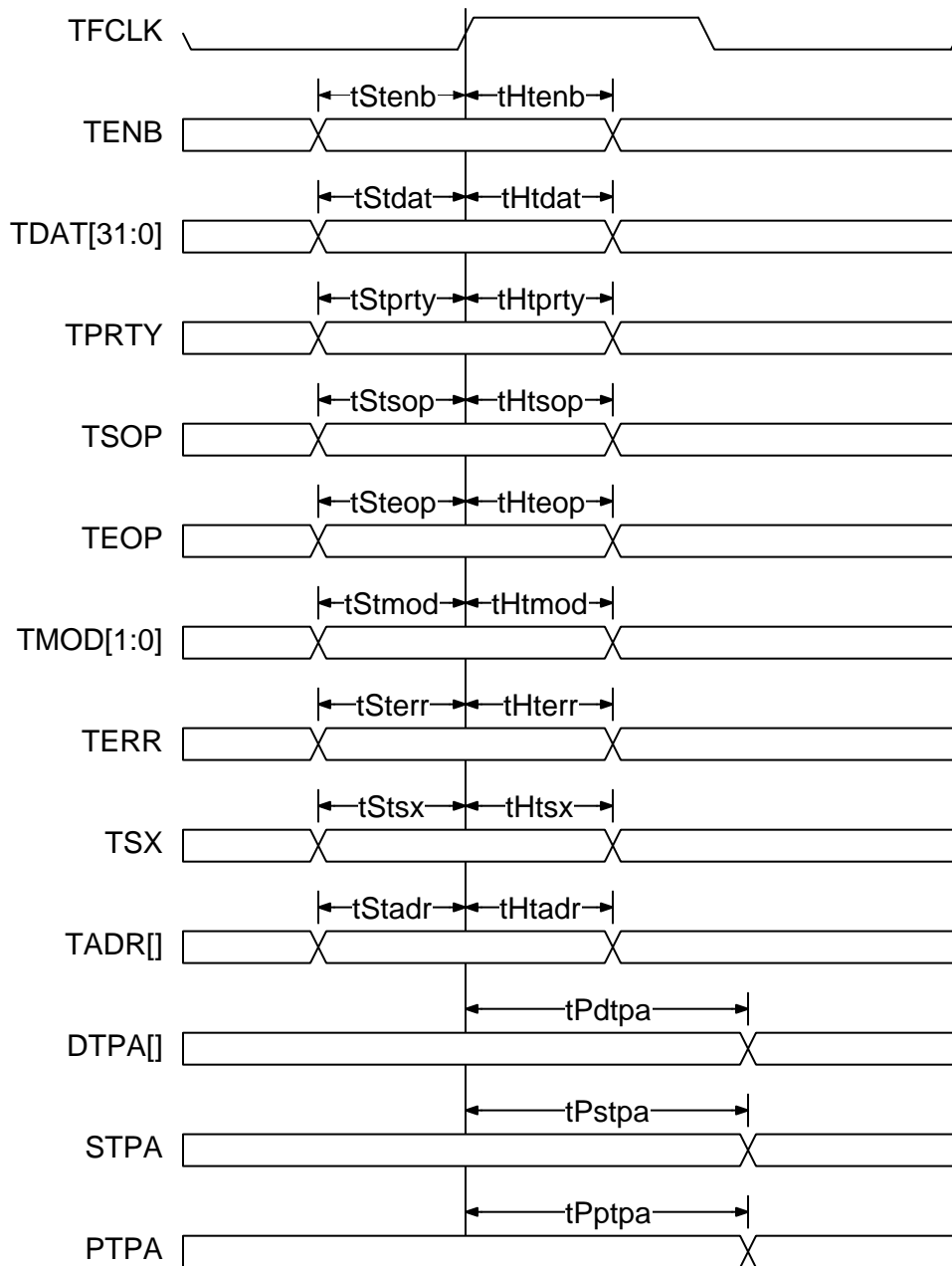
Notes on Transmit I/O Timing:

Note 1:   When a set-up time is specified between an input and a clock, the
           set-up time is the time in nanoseconds from the 1.4 Volt point of the
           input to the 1.4 Volt point of the clock.

Note 2:   When a hold time is specified between an input and a clock, the
           hold time is the time in nanoseconds from the 1.4 Volt point of the
           clock to the 1.4 Volt point of the input.

Note 3:   Output propagation delay time is the time in nanoseconds from the 1.4 Volt point of the reference signal to the 1.4 Volt point of the output.

Note 4:   Maximum output propagation delays are measured with a 30 pF load on the outputs.

11 Receive Packet Interface Description

The standard FIFO depth for SPI-3 interfaces is 256 octets. As the interface is point-to-point, the PHY device is required to push receive packet data to the Link Layer device. This arrangement simplifies the interface between the PHY device and the Link Layer device. Traditional polling schemes for the receive side are not required, saving a significant number of pins.

The receive FIFO shall have a programmable threshold defined in terms of the number of bytes of packet data stored in the FIFO. A multi-port PHY device must service each receive FIFO with sufficient packet data to exceed the threshold or with an end of packet. The PHY should service the required FIFOs in a round-robin fashion. The type of round-robin algorithm will depend on the various data rates supported by the PHY device and is outside this specification.

The amount of packet data transferred, when servicing the receive FIFO, is bounded by the FIFO's programmable threshold. Thus, a transfer is limited to a maximum of 256 bytes of data (64 cycles for a 32-bit interface or 256 cycles for an 8-bit interface) or until an end of packet is transferred to the Layer device. At the end of a transfer, the PHY device will round-robin to the next receive FIFO.

The PHY device should support a programmable minimum pause of 0 or 2 clock cycles between transfers. A pause of 0 clock cycles maximizes the throughput of the interface. A pause of 2 clock cycles allows the Layer device to pause between transfers.

11.1 <u>Receive Signals</u>

Table 11.1 lists the receive side POS-PHY specification signals. All signals are expected to be updated and sampled using the rising edge of the receive FIFO clock, RFCLK. A fully compatible POS-PHY Physical Layer device requires at least a 256-byte receive FIFO.

Table 11.1: Receive Signal Descriptions

Signal Name	Direction	Function
RFCLK	Clock Source to Link and PHY	Receive FIFO Write Clock (RFCLK). RFCLK is used to synchronize data transfer transactions between the Link Layer device and the PHY layer device. RFCLK may cycle at a rate up to 104 MHz.
RVAL	PHY to LINK .	Receive Data Valid (RVAL) signal. RVAL indicates the validity of the receive data signals. RVAL is low between transfers and when RSX is asserted; it is also low when the PHY pauses a transfer due to an empty receive FIFO. When a transfer is paused by holding RENB high, RVAL will hold its value unchanged, although no new data will be present on RDAT[31:0] until the transfer resumes. When RVAL is high, the RDAT[31:0], RMOD[1:0], RSOP, REOP and RERR signals are valid. When RVAL is low, the RDAT[31:0], RMOD[1:0], RSOP, REOP and RERR signals are invalid and must be disregarded. The RSX signal is valid when RVAL is low.

Signal Name	Direction	Function
RENB	LINK to PHY	Receive Read Enable (RENB) signal.
		The RENB signal is used to control the flow of data from the receive FIFO's. During data transfer, RVAL must be monitored as it will indicate if the RDAT[31:0], RPRTY, RMOD[1:0], RSOP, REOP, RERR and RSX are valid. The system may deassert RENB at anytime if it is unable to accept data from the PHY device.
		When RENB is sampled low by the PHY device, a read is performed from the receive FIFO and the RDAT[31:0], RPRTY, RMOD[1:0], RSOP, REOP, RERR, RSX and RVAL signals are updated on the following rising edge of RFCLK.
		When RENB is sampled high by the PHY device, a read is not performed and the RDAT[31:0], RPRTY, RMOD[1:0], RSOP, REOP, RERR, RSX and RVAL signals will remain unchanged on the following rising edge of RFCLK.
RDAT[31:0]	PHY to LINK	Receive Packet Data Bus (RDAT[31:0]).
		The RDAT[31:0] bus carries the packet octets that are read from the receive FIFO and the in-band port address of the selected receive FIFO. RDAT[31:0] is considered valid only when RVAL is asserted.
		When a 32-bit interface is used, data must be received in big endian order on RDAT[31:0]. Given the defined data structure, bit 31 is received first and bit 0 is received last.
		When an 8-bit interface is used, the PHY supports only RDAT[7:0].
RPRTY	PHY to LINK	Receive Parity (RPRTY) signal.
		The receive parity (RPRTY) signal indicates the parity calculated over the RDAT bus. When an 8-bit interface is used, the PHY only supports RPRTY calculated over RDAT[7:0].
		When RPRTY is supported, the PHY layer device must support odd parity. RPRTY is considered valid only when RVAL or RSX is asserted.

Signal Name	Direction	Function
RMOD[1:0]	PHY to LINK	Receive Word Modulo (RMOD) signal. RMOD[1:0] indicates the number of valid bytes of data in RDAT[31:0]. The RMOD bus should always be all zero, except during the last double-word transfer of a packet on RDAT[31:0]. When REOP is asserted, the number of valid packet data bytes on RDAT[31:0] is specified by RMOD[1:0]. RMOD[1:0] = "00"　　　　RDAT[31:0] valid RMOD[1:0] = "01"　　　　RDAT[31:8] valid RMOD[1:0] = "10"　　　　RDAT[31:16] valid RMOD[1:0] = "11"　　　　RDAT[31:24] valid When an 8-bit interface is used, the RMOD bus is not required. RMOD[1:0] is considered valid only when RVAL is asserted.
RSOP	PHY to LINK	Receive Start of Packet (RSOP) signal. RSOP is used to delineate the packet boundaries on the RDAT bus. When RSOP is high, the start of the packet is present on the RDAT bus. RSOP is required to be present at the start of every packet and is considered valid when RVAL is asserted.
REOP	PHY to LINK	Receive End Of Packet (REOP) signal. REOP is used to delineate the packet boundaries on the RDAT bus. When REOP is high, the end of the packet is present on the RDAT bus. When a 32-bit interface is used, RMOD[1:0] indicates the number of valid bytes the last double-word is composed of when REOP is asserted. When an 8-bit interface is used, the last byte of the packet is on RDAT[7:0] when REOP is asserted. REOP is required to be present at the end of every packet and is considered valid only when RVAL is asserted.

Signal Name	Direction	Function
RERR	PHY to LINK	Receive error indicator (RERR) signal.
		RERR is used to indicate that the current packet is in error. RERR shall only be asserted when REOP is asserted.
		Conditions that can cause RERR to be set may be, but are not limited to, FIFO overflow, abort sequence detection and FCS error.
		RERR is considered valid only when RVAL is asserted.
RSX	PHY to LINK	Receive Start of Transfer (RSX) signal.
		RSX indicates when the in-band port address is present on the RDAT bus. When RSX is high, the value of RDAT[7:0] is the address of the receive FIFO to be selected by the PHY. Subsequent data transfers on the RDAT bus will be from the FIFO specified by this in-band address.
		For single port PHY devices, the RSX signal is optional as the PHY device will not need to generate in-band addresses.
		For multi-port PHY devices, RSX must be asserted at the beginning of each transfer.
		When RSX is high, RVAL must be low.

11.2 Examples

The following examples are not part of the requirement definition of the SPI-3 compatibility specification. They are only informative and provide an aid in the visualization of the interface operation. The examples only present a limited set of scenarios; they are not intended to imply restrictions beyond that presented in the text of the specification. If any apparent discrepancies exist between the examples and the text, the text shall take precedence.

The SPI-3 Receive Interface is controlled by the Link Layer device using the RENB signal. All signals must be updated and sampled using the rising edge of the receive FIFO clock. The RDAT bus, RPRTY, RMOD, RSOP, REOP and RERR signals are valid in cycles for which RVAL is high and RENB was low in the previous cycle. When transferring data, RVAL is asserted and remains high until the internal FIFO of the PHY layer device is empty or an end of packet is transferred. The RSX signal is valid in the cycle for which RVAL is low and RENB was low in the previous cycle.

Figure 11.1 is an example of a multi-port PHY device with at least two channels. The PHY informs the Link Layer device of the port address of the selected FIFO by asserting RSX with the port address on the RDAT bus. The Link Layer may pause the Receive Interface at any time by deasserting the RENB signal. When the selected FIFO is empty, RVAL is deasserted. In this example, the RVAL is re-asserted, without changing the selected FIFO, transferring the last section of the packet. The end of the packet is indicated with the REOP signal. Thus, the next subsequent FIFO transfer for this port would be the start of the next packet. If an error occurred during the reception of the packet, the RERR would be asserted with REOP. Since another port's FIFO has sufficient data to initiate a bus transfer, RSX is again asserted with the port address. In this case, an intermediate section of the packet is being transferred.
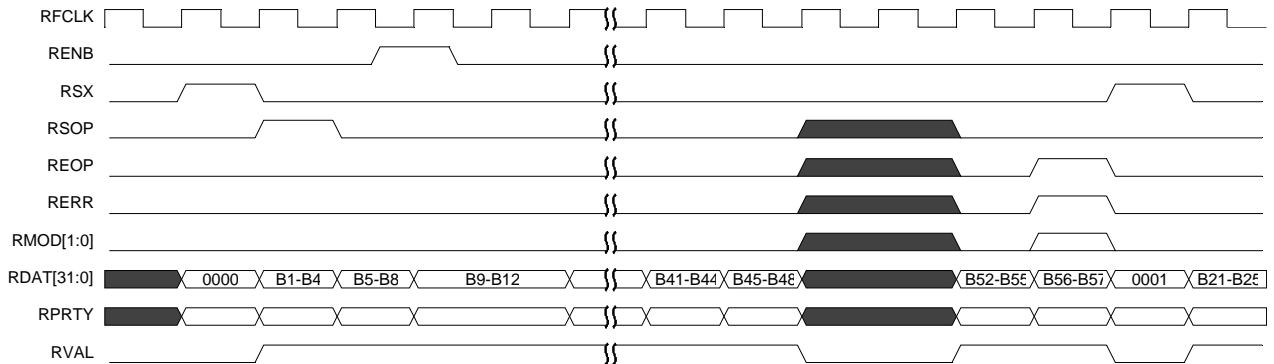
Figure 11.1: Receive Logical Timing

Figure 11.2 is an example of a multi-port PHY configured to gap transfers for two clock cycles. The first transfer is a complete 3-byte packet and the second transfer is the end of a 36-byte packet. The pause allows the Link Layer device to halt the transfer of data between transfers. In order to handle an end of packet, the Link Layer device may deassert the RENB signal when it samples REOP active. As shown in the diagram, the Link Layer device pauses the PHY device on the in-band address for two clock cycles.

Figure 11.2: Receive Logical Timing with Pausing
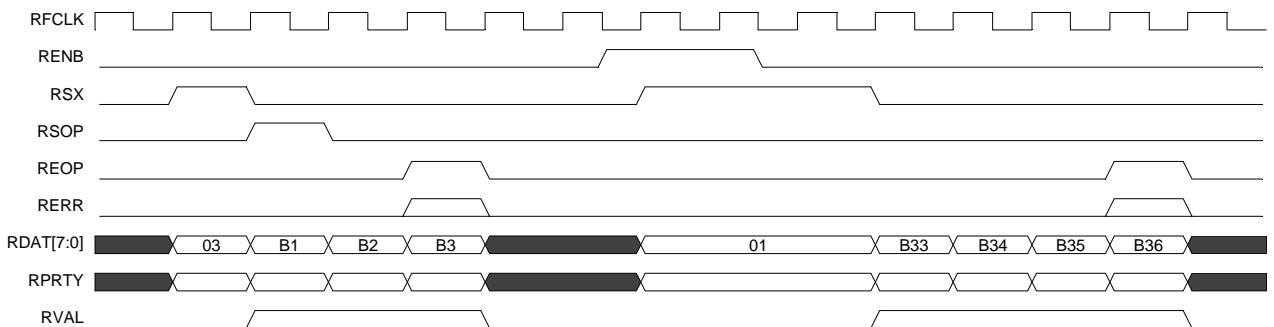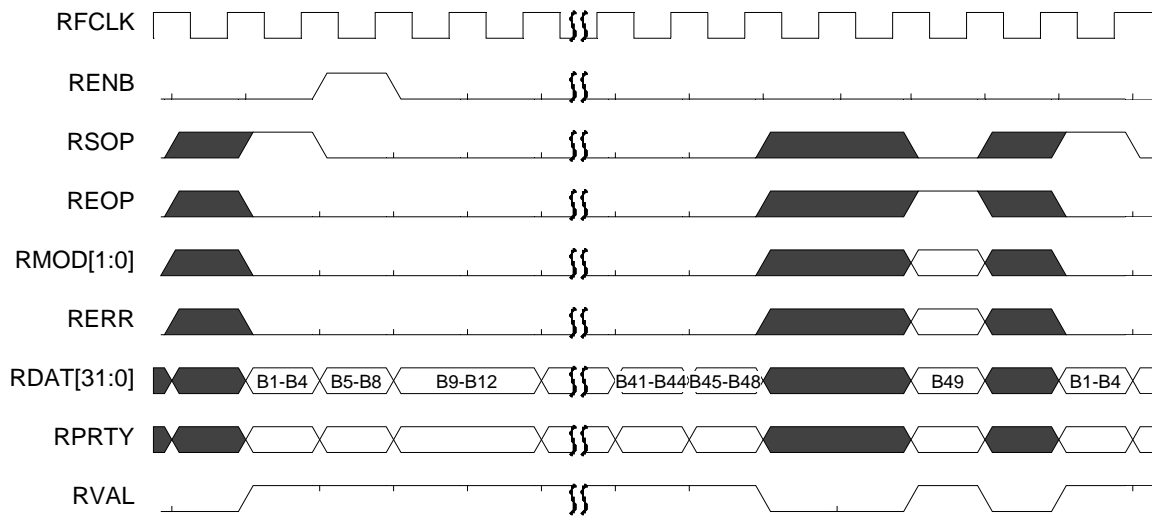
Figure 11.3 shows an example of data transfer from a single-port PHY device, without the use of the RSX signal and in-band addressing, which are optional for single-port applications. Just before reaching end-of-packet, the PHY device happens to pause for two cycles (for internal reasons).

Figure 11.3: Receive Logical Timing

(single-port without in-band addressing)

11.3 AC Timing

All AC Timing is from the perspective of the PHY layer device in a PHY-LINK interface.

Table 11.2: Receive Interface Timing

Symbol	Description	Min	Max	Units
	RFCLK Frequency		104	MHz
	RFCLK Duty Cycle	40	60	%
tS_{renb}	RENB Set-up time to RFCLK	2		ns
tH_{renb}	RENB Hold time to RFCLK	0.5		ns
tP_{rdat}	RFCLK High to RDAT Valid	1.5	6	ns
tP_{rprty}	RFCLK High to RPRTY Valid	1.5	6	ns
tP_{rsop}	RFCLK High to RSOP Valid	1.5	6	ns
tP_{reop}	RFCLK High to REOP Valid	1.5	6	ns
tP_{rmod}	RFCLK High to RMOD Valid	1.5	6	ns
tP_{rerr}	RFCLK High to RERR Valid	1.5	6	ns
tP_{rval}	RFCLK High to RVAL Valid	1.5	6	ns
tP_{rsx}	RFCLK High to RSX Valid	1.5	6	ns

Figure 11.4: Receive Physical Timing
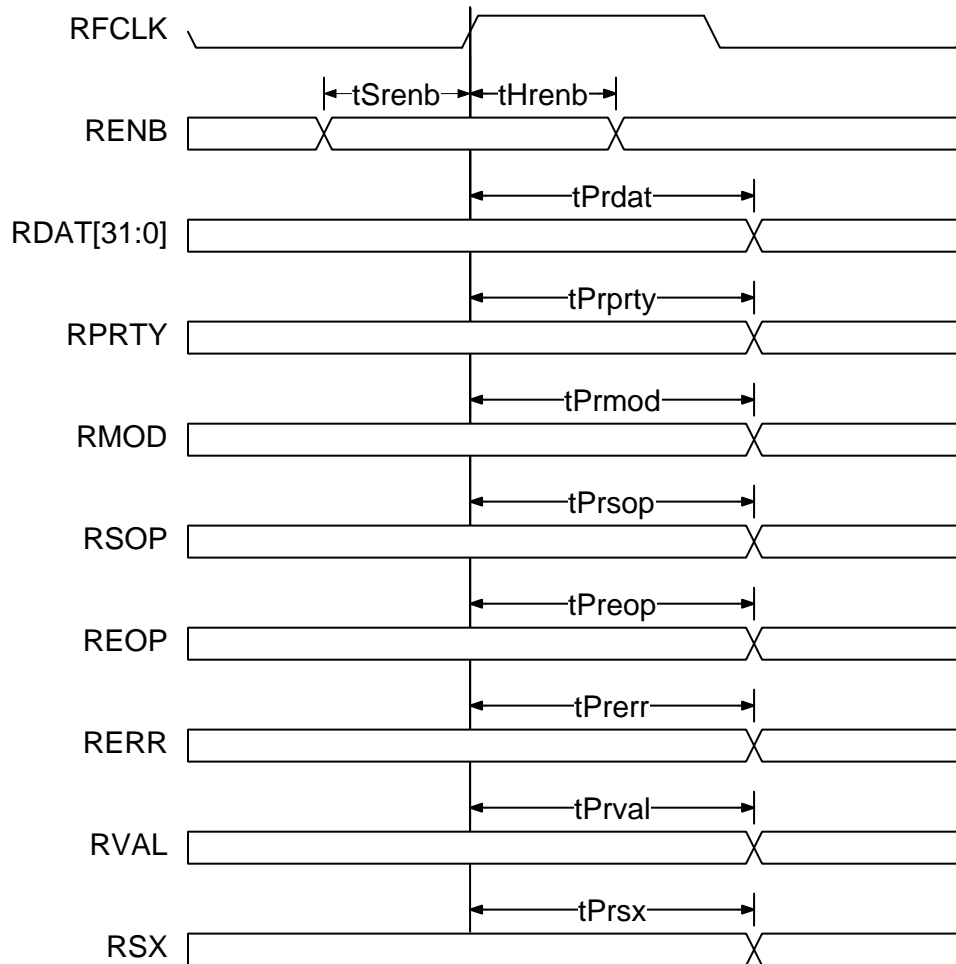
Notes on Receive I/O Timing:

Note 1:   When a set-up time is specified between an input and a clock, the set-up time is the time in nanoseconds from the 1.4 Volt point of the input to the 1.4 Volt point of the clock.

Note 2:   When a hold time is specified between an input and a clock, the hold time is the time in nanoseconds from the 1.4 Volt point of the clock to the 1.4 Volt point of the input.

Note 3:   Output propagation delay time is the time in nanoseconds from the 1.4 Volt point of the reference signal to the 1.4 Volt point of the output.

Note 4:   Maximum output propagation delays are measured with a 30 pF load on the outputs.

12   Summary

This document describes a packet interface for OC-48 aggregate bandwidth applications. It specifies a 32-bit and 8-bit data path, both at a maximum rate of 104 MHz, to support the full OC-48 bandwidth as well as OC-12 bandwidths respectively. The interface supports bidirectional data transfer between two devices, through two different sets of signals that operate independently from the other.

13   References

13.1   Normative references
(None.)

13.2   Informative references

[1] POS-PHY. SATURN Compatible Packet Over SONET Interface Specification for Physical Layer Devices (Level 3). PMC-980495, Issue 3, November 1998.

[2] SCI-PHY. SATURN Compatible Interface Specification for PHY Layer and ATM Layer Devices (Level 2). Issue 3, November 1995.

[3] Utopia Level 2, Version 1.0. af-phy-0039.000, June 1995.

[4] UTOPIA 3 Physical Layer Interface. af-phy-0136.000, November 1999.

14   Appendix A: Glossary

FCS   Frame Check Sequence
FIFO   First-In First-Out (queuing structure)
HDLC   High-level Data Link Control
LINK   Link Layer
PHY   Physical Layer
POS   Packet-Over-SONET/SDH
PPP   Point-to-Point Protocol
SOC   Start Of Cell
SOP   Start Of Packet
SONET   Synchronous Optical Network
TCA   Transmit Cell Available
TPA   Transmit Packet Available

15   Appendix B: Open Issues / current work items

(None.)

16   Appendix C: List of companies belonging to OIF when document was approved

Accelerant Networks
Acorn Networks
AdventNet
Aerie Networks
Agilent Technologies
Agility Communications
Alcatel
Algety Telecom
Alidian Networks
Altera
Alvesta Corporation
Amber Networks
AMCC
America Online
Analog Devices
ANDO Corporation
Appian Communications
Applied Innovation
Artel Video Systems
Astral Point
Communications
AT&T
Atoga Systems
Avici Systems
Axiowave Networks
Axsun Technologies
Bay Microsystems
Blaze Network Products
Bravida Corp
BrightLink Networks
Broadcom
Cable & Wireless
Calient Networks
Calix Networks
Caspian Networks
Catamaran
Communications
Centerpoint Broadband
Technologies
Chiaro Networks
China Advanced Info-
Optical Network
Chip2Chip

Chorum Technologies

Cidra

Cielo Communications

CIENA Communications

Cinta Corporation

Cisco Systems

Computer &
Communications
Research Labs

Conexant

ConnectCom
MicroSystems

CoreEl MicroSystem

Coriolis Networks

Corning

CORVIS Corporation

CSELT

CyOptics

Cypress Semiconductor

Cyras Systems

Deutsche Telekom

Ditech

Dynarc

ECI Telecom

Elisa Communications

Enron Broadband
Services

Equipe Communications

Ericsson

ETRI

Extreme Networks

Ezchip

Fast-Chip

Finisar Corporation

Focused Research

Force 10 Networks

Fujikura

Furukawa Electric
Technologies

Gazillion Bits

General Dynamics

Global Crossing North
American Networks

Gore & Associates

Gtran

GTS Network Services

Helix AG

Hitachi

Honeywell

IBM Corporation

Infineon Technologies

Information Management
Systems

Intel
Iolon
IPOptical
Iris Labs
Ironbridge Networks
JDS Uniphase
Juniper Networks
KDD R&D Laboratories
Korea Telecom
Kromos Technology
Lambda Crossing
LANCAST
Laurel Networks
Level 3 Communications
LightLogic
Lucent Technologies
Luminous Networks
Luxcore
LuxN
LYNX - Photonic Networks
Mahi Networks
Maple Networks
Marconi Communications
Mayan Networks
Memlink
Metro-OptiX
MicroOptical Devices
Mitel Corporation
Mitsubishi Electric
Corporation
Multilink Technology
Corporation
Nanovation
National Security Agency,
US. Dept of Defense
Native Networks
Nayna Networks
NEC
Net Insight
Net-Hopper Systems
NetPlane
Network Associates
Network Elements
Network Photonics
NewPort Communications
NIST
Nokia
Nortel Networks
NTT Corporation
Ocular Networks
OKI Electric Industry
ON Semiconductor

Optical Internetworking Forum

ONI Systems

Opthos

Optix Networks

Optobahn

OptronX

Panstera

Photuris, Inc.

PicoLight

Pine Photonics
Communications

Pluris

PMC Sierra

Procket Networks

Quake Technologies

Quantum Bridge

Redback Networks

Redfern Broadband
Networks

Reversi Networks

RHK

Sandia National
Laboratories

Santec Corporation

Scientific Atlanta

Siemens

SITA Equant

Solidum Systems
Corporation

Solinet Systems

Sorrento Networks

SpectraSwitch

Sprint

Stratos Lightwave

Sumitomo Electric
Industries

Sycamore Networks

TDK Semiconductor

Tektronix

Telcordia Technologies

TELE-WORX

Tellabs

Tellium

Tenor Networks

Terawave
Communications

Texas Instruments

Toshiba Corporation

TranSwitch Corporation

Trellis Photonics

TriQuint Semiconductor

Turin Networks

TyCom

US Conec

Valiant Networks
Verizon
Versanetworks
Vitesse Semiconductor
Vivace Networks
White Rock Networks
Williams Network
WorldCom
Xanoptix
Xilinx
YAFO Networks
Zaffire