

Exercise 7.1 (Bell circuit, part 2)

Generalize Exercise 4.1 by proving the following equivalence for all $a, b \in \{0, 1\}$, where p is the identity matrix, X , iY or Z (depending on a and b). The circuit thus generates one of the Bell states. Hint: See also Exercise 4.2(d).

$$H = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix} \quad \begin{array}{c} \text{---} \bullet \text{---} [H] \text{---} (|a\rangle) \\ | \\ \text{---} \oplus \text{---} (|b\rangle) \end{array} = \frac{1}{\sqrt{2}} \begin{array}{c} \text{---} [p] \text{---} \\ | \\ \text{---} \end{array} \begin{pmatrix} 1 & & & \\ & 1 & & \\ & & 0 & 1 \\ & & 1 & 0 \end{pmatrix} \doteq \begin{array}{c} \text{---} \bullet \text{---} \\ | \\ \text{---} \oplus \text{---} \end{array},$$

$$|a\rangle = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \quad (H \cdot |a\rangle) \otimes |b\rangle = \left(\frac{1}{\sqrt{2}} \cdot \begin{pmatrix} 1 \\ 1 \end{pmatrix} \right) \otimes \begin{pmatrix} 1 \\ 0 \end{pmatrix} = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ 1 \\ 0 \\ 0 \end{pmatrix}$$

$$|b\rangle = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \quad \begin{pmatrix} 1 & & & \\ & 1 & & \\ & & 0 & 1 \\ & & 1 & 0 \end{pmatrix} \cdot \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ 1 \\ 0 \\ 0 \end{pmatrix} = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ 0 \\ 0 \\ 1 \end{pmatrix} = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} = \frac{1}{\sqrt{2}} I$$

$$|a\rangle = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \quad (H \cdot |a\rangle) \otimes |b\rangle = \frac{1}{\sqrt{2}} \cdot \begin{pmatrix} 1 \\ 1 \end{pmatrix} \otimes \begin{pmatrix} 0 \\ 1 \end{pmatrix} = \frac{1}{\sqrt{2}} \cdot \begin{pmatrix} 0 \\ 1 \\ 1 \\ 0 \end{pmatrix}$$

$$\frac{1}{\sqrt{2}} \begin{pmatrix} 1 & & & \\ & 1 & & \\ & & 0 & 1 \\ & & 1 & 0 \end{pmatrix} \cdot \begin{pmatrix} 0 \\ 1 \\ 1 \\ 0 \end{pmatrix} = \frac{1}{\sqrt{2}} \begin{pmatrix} 0 \\ 1 \\ 1 \\ 0 \end{pmatrix} = \frac{1}{\sqrt{2}} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} = \frac{1}{\sqrt{2}} X$$

$$|a\rangle = \begin{pmatrix} 0 \\ 1 \end{pmatrix} \quad (H \cdot |a\rangle) \otimes |b\rangle = \left(\frac{1}{\sqrt{2}} \cdot \begin{pmatrix} 1 \\ -1 \end{pmatrix} \right) \otimes \begin{pmatrix} 1 \\ 0 \end{pmatrix} = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ 0 \\ -1 \\ 0 \end{pmatrix}$$

$$\begin{pmatrix} 1 & & & \\ & 1 & & \\ & & 0 & 1 \\ & & 1 & 0 \end{pmatrix} \cdot \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ 0 \\ -1 \\ 0 \end{pmatrix} = \frac{1}{\sqrt{2}} \cdot \begin{pmatrix} 1 \\ 0 \\ 0 \\ -1 \end{pmatrix} = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} = \frac{1}{\sqrt{2}} Z$$

$$|a\rangle = \begin{pmatrix} 0 \\ 1 \end{pmatrix} \quad (H \cdot |a\rangle) \otimes |b\rangle = \left(\frac{1}{\sqrt{2}} \cdot \begin{pmatrix} 1 \\ -1 \end{pmatrix} \right) \otimes \begin{pmatrix} 0 \\ 1 \end{pmatrix} = \frac{1}{\sqrt{2}} \begin{pmatrix} 0 \\ 1 \\ -1 \\ 0 \end{pmatrix}$$

$$\begin{pmatrix} 1 & & & \\ & 1 & & \\ & & 0 & 1 \\ & & 1 & 0 \end{pmatrix} \cdot \frac{1}{\sqrt{2}} \begin{pmatrix} 0 \\ 1 \\ -1 \\ 0 \end{pmatrix} = \frac{1}{\sqrt{2}} \begin{pmatrix} 0 \\ 1 \\ -1 \\ 0 \end{pmatrix} = \frac{1}{\sqrt{2}} \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix} = \frac{1}{\sqrt{2}} iY$$

exercise7.2_template

June 13, 2022

```
[1]: import numpy as np
import matplotlib.pyplot as plt
```

```
[2]: # Implementation of Exercise 5.2 (a)

def single_mode_matricization(T, j):
    """
    Matricization of numpy array `T` by partitioning into j-th dimension and
    ↪ the remaining dimensions.
    """
    assert j < T.ndim
    # bring j-th dimension to the front
    T = np.transpose(T, [j] + list(range(j)) + list(range(j + 1, T.ndim)))
    T = np.reshape(T, (T.shape[0], -1)) # size of second dimension is inferred
    return T
```

```
[3]: # Implementation of Exercise 5.2 (b)

def single_mode_product(A, T, j):
    """
    Compute the j-mode product between the matrix `A` and tensor `T`.
    """
    T = np.tensordot(A, T, axes=(1, j))
    # original j-th dimension is now 0-th dimension; move back to j-th place
    T = np.transpose(T, list(range(1, j + 1)) + [0] + list(range(j + 1, T.
    ↪ ndim)))
    return T
```

```
[4]: class TuckerTensor(object):
    """
    Tucker format tensor.
    """
    def __init__(self, Ulist, C):
        self.Ulist = [np.array(U) for U in Ulist]
        # core tensor
        self.C = np.array(C)
        # dimension consistency checks
```

```

    assert len(self.Ulist) == self.C.ndim
    for j in range(self.C.ndim):
        assert self.Ulist[j].shape[1] == C.shape[j]

@property
def shape(self):
    """Logical dimensions."""
    return tuple([U.shape[0] for U in self.Ulist])

@property
def ndim(self):
    """Number of logical dimensions."""
    return len(self.Ulist)

def as_full_tensor(self):
    """
    Construct the Tucker format tensor as full (dense) array.
    Note: Should only be used for debugging and testing.
    """
    T = self.C
    for j in range(T.ndim):
        # apply Uj to j-th dimension
        T = single_mode_product(self.Ulist[j], T, j)
    return T

```

[5]: *# Implementation of Exercise 5.2 (d)*

```

def higher_order_svd(T, max_ranks):
    """
    Compute the higher-order singular value decomposition
    (Tucker format approximation) of the NumPy array `T`.
    """
    assert T.ndim == len(max_ranks)
    Ulist = []
    list = []
    for j in range(T.ndim):
        A = single_mode_matricization(T, j)
        U, , Vh = np.linalg.svd(A, full_matrices=False)
        = U.shape[1]
        if max_ranks[j] > 0:
            # truncate in case max_ranks[j] <
            = min( , max_ranks[j])
            Ulist.append(U[:, :])
            list.append( )
    # form the core tensor
    C = T

```

```

for j in range(C.ndim):
    # apply  $U_j^\dagger$  to  $j$ -th dimension
    C = single_mode_product(Ulist[j].conj().T, C, j)
return TuckerTensor(Ulist, C), list

```

```

[6]: def fd_second_derivative_zero_boundary(n):
    """
    Finite difference discretization of  $-d^2/dx^2$  on  $[0, 1]$  with zero boundary
    conditions.
    """
    a = np.full(n-1, 2)
    b = np.full(n-2, -1)

    return n**2 * (np.diag(a) + np.diag(b, 1) + np.diag(b, -1))

```

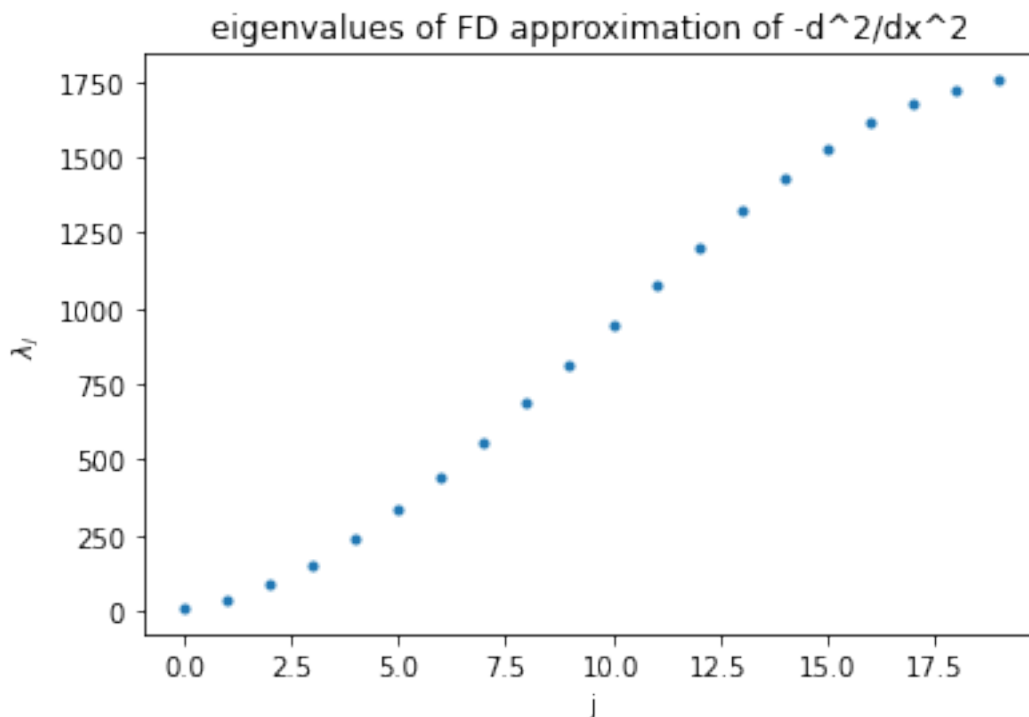
```

[7]: n = 21

A = fd_second_derivative_zero_boundary(n)

# visualize eigenvalues
plt.plot(np.linalg.eigvalsh(A), '.')
plt.xlabel("j")
plt.ylabel(r" $\lambda_j$ ")
plt.title("eigenvalues of FD approximation of  $-d^2/dx^2$ ");

```



```
[8]: # A is symmetric and all eigenvalues are larger than zero, i.e., A is positive
      ↪definite
      min(np.linalg.eigvalsh(A))
```

```
[8]: 9.851211269436485
```

```
[9]: # as short test, this should be zero:
      abs(min(np.linalg.eigvalsh(A)) - 9.851211269436485)
```

```
[9]: 0.0
```

```
[10]: # `L` operator as full matrix, as reference and for tests
      L = (
          np.kron(np.kron(A, np.identity(len(A))), np.
          ↪identity(len(A))) +
          np.kron(np.kron(np.identity(len(A)), A), np.
          ↪identity(len(A))) +
          np.kron(np.kron(np.identity(len(A)), np.identity(len(A))), A
          ↪ ))
      print(L.shape)
```

```
(8000, 8000)
```

```
[11]: def quadratic_form_tucker_isometry(A, phi: TuckerTensor, j):
      """
      Construct the square matrix `K` which expresses  $\langle \phi, L \phi \rangle$  with
       $L = A \times I \times \dots \times I + \dots + I \times \dots \times I \times A$ 
      in dependence of the  $j$ -th isometry  $\phi.Ulist[j]$ , such that
       $\langle \phi, L \phi \rangle = \langle u_j, K u_j \rangle$  with  $u_j = \phi.Ulist[j].flatten()$ .
      """
      n_u = len(phi.Ulist)
      indices = [i for i in range(n_u) if i != j]

      I = np.eye(A.shape[0])
      K = np.tensordot(phi.C, phi.C, axes=(indices, indices))
      K = np.kron(A, K)

      for i in indices:
          M = phi.Ulist[i].transpose().dot(A).dot(phi.Ulist[i])
          MC = np.tensordot(M, phi.C, ([1], [i]))
          MC = np.moveaxis(MC, 0, i)
          K += np.kron(I, np.tensordot(phi.C, MC, axes=(indices, indices)))

      return K
```

```
[12]: # test of `quadratic_form_tucker_isometry`
kdim_test = (2, 3, 4)
test = TuckerTensor([np.linalg.qr(np.random.randn(n-1, kdim_test[j]))[0] for j in range(3)], np.random.standard_normal(kdim_test))
tvec = np.reshape(test.as_full_tensor(), -1)
utest = [np.reshape(test.Ulist[j], -1) for j in range(3)]
# reference value
Lref = np.dot(tvec, L @ tvec)
# relative error should be zero up to numerical rounding errors
err = [abs(np.dot(utest[j], quadratic_form_tucker_isometry(A, test, j) @ utest[j]) - Lref) / abs(Lref) for j in range(3)]
err
```

```
[12]: [0.0, 1.7098997634721596e-16, 0.0]
```

```
[13]: def linear_form_tucker_isometry(phi: TuckerTensor, b: TuckerTensor, j):
    """
    Construct the vector `g` which expresses <phi, b>
    in dependence of the j-th isometry `phi.Ulist[j]`, such that
    <phi, b> = <u_j, g> with u_j = phi.Ulist[j].flatten().
    """
    # all but j-th dimension
    jcompl = list(range(j)) + list(range(j + 1, phi.ndim))
    g = phi.C
    for k in jcompl:
        g = single_mode_product(b.Ulist[k].T @ phi.Ulist[k], g, k)
    g = b.Ulist[j] @ np.tensordot(b.C, g, axes=(jcompl, jcompl))
    assert g.shape == phi.Ulist[j].shape
    return np.reshape(g, -1)
```

```
[14]: def quadratic_form_tucker_core(A, phi: TuckerTensor):
    """
    Construct the square matrix `K` which expresses <phi, L phi> with
    L = A x I x ... x I + ... + I x ... x I x A
    in dependence of the core tensor `phi.C`, such that
    <phi, L phi> = <c, K c> with c = phi.C.flatten().
    """
    K = np.zeros((phi.C.size, phi.C.size))
    for j in range(phi.ndim):
        K1 = np.identity(1)
        for k in range(phi.ndim):
            K1 = np.kron(K1, phi.Ulist[k].T @ A @ phi.Ulist[k] if k == j else
np.identity(phi.Ulist[k].shape[1]))
        K += K1
    return K
```

```
[15]: def linear_form_tucker_core(phi: TuckerTensor, b: TuckerTensor):
    """
    Construct the vector `g` which expresses  $\langle \phi, b \rangle$ 
    in dependence of the core tensor `phi.C`, such that
     $\langle \phi, b \rangle = \langle c, g \rangle$  with  $c = \text{phi.C.flatten}()$ .
    """
    # construct temporary Tucker format tensor
    Alist = [phi.Ulist[j].T @ b.Ulist[j] for j in range(phi.ndim)]
    g = TuckerTensor(Alist, b.C).as_full_tensor()
    return np.reshape(g, -1)

[16]: def factorized_tucker_als_step(A, phi: TuckerTensor, b: TuckerTensor):
    """
    Alternating Least Squares (ALS) optimization step of a Tucker format tensor_
    ↪ `phi`
    for target function  $1/2 \langle \phi, L \phi \rangle - \langle \phi, b \rangle$  with
     $L = A \otimes I \otimes \dots \otimes I + \dots + I \otimes \dots \otimes I \otimes A$ .
    """
    assert phi.ndim == b.ndim
    # optimize U matrices one-by-one
    for j in range(phi.ndim):
        # construct least squares terms for Ulist[j]
        K = quadratic_form_tucker_isometry(A, phi, j)
        g = linear_form_tucker_isometry(phi, b, j)
        Ujnext = np.reshape(np.linalg.solve(K, g), phi.Ulist[j].shape)
        # perform QR decomposition to ensure Ulist[j] remains an isometry
        phi.Ulist[j], R = np.linalg.qr(Ujnext, mode='reduced')
        # absorb R into core tensor
        phi.C = single_mode_product(R, phi.C, j)
    # optimize core tensor
    K = quadratic_form_tucker_core(A, phi)
    g = linear_form_tucker_core(phi, b)
    phi.C = np.reshape(np.linalg.solve(K, g), phi.C.shape)
    # result is stored in updated `phi`

[17]: # construct `b` tensor

bfull = np.array([[[np.sin(3*np.pi*(i + j + k)/n) for k in range(1, n)] for j in
    ↪ in range(1, n)] for i in range(1, n)])
print("bfull.shape:", bfull.shape)

# keep only 2 singular values along each dimension
b, listb = higher_order_svd(bfull, [2, 2, 2])

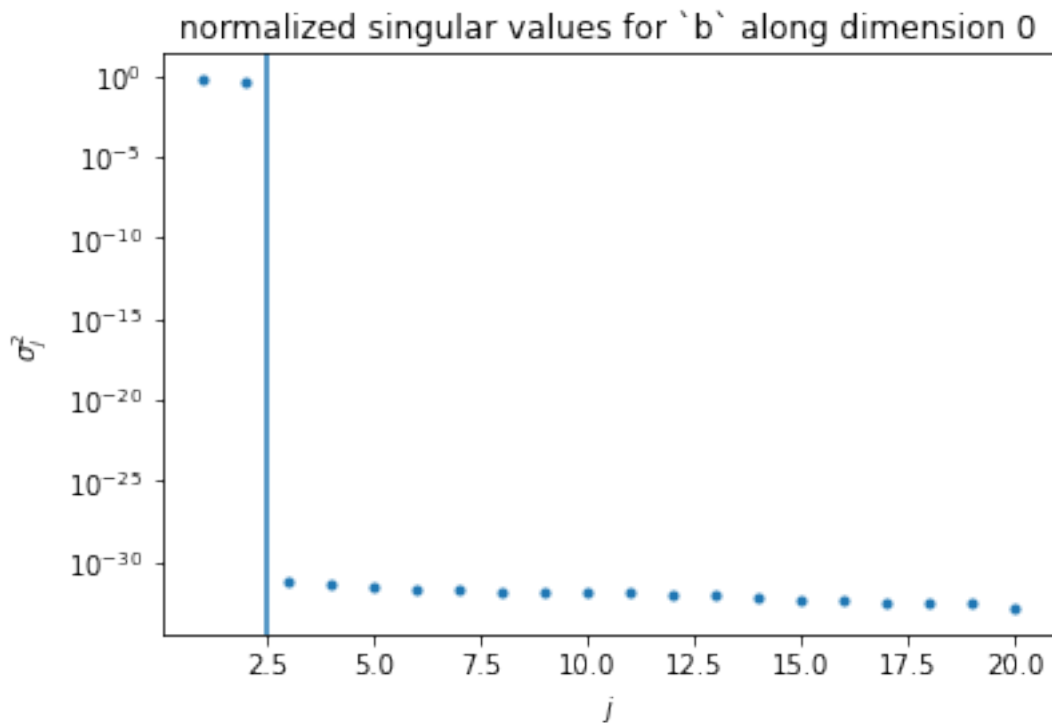
print("b Tucker approximation error:", np.linalg.norm(np.reshape(b.
    ↪ as_full_tensor() - bfull, -1)) / np.linalg.norm(np.reshape(bfull, -1)))
```

bfull.shape: (20, 20, 20)

b Tucker approximation error: 8.336626324261062e-16

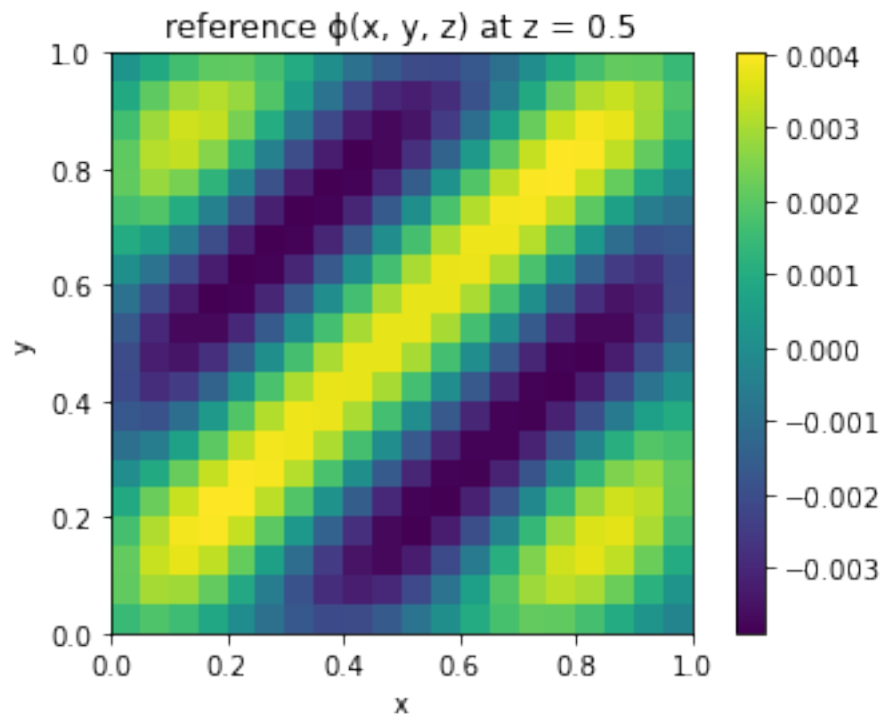
```
[18]: # show some singular values from HOSVD of `b`
plt.semilogy(range(1, len(listb[0]) + 1), listb[0]**2 / np.sum(listb[0]**2),
             ↪ '.')
```

```
plt.axvline(x=2.5)
plt.ylabel("$\\sigma_j^2$")
plt.xlabel("$j$")
plt.title("normalized singular values for `b` along dimension 0");
plt.show()
```



```
[19]: # reference solution
print("Solving reference linear system...")
ref = np.reshape(np.linalg.solve(L, np.reshape(bfull, -1)), bfull.shape)
print("done.")
print(" ref.shape:", ref.shape)
plt.imshow(ref[:, :, n//2], extent=[0,1,0,1])
plt.xlabel("x")
plt.ylabel("y")
plt.title("reference (x, y, z) at z = 0.5")
plt.colorbar()
plt.show()
```


Solving reference linear system...
done.
ref.shape: (20, 20, 20)

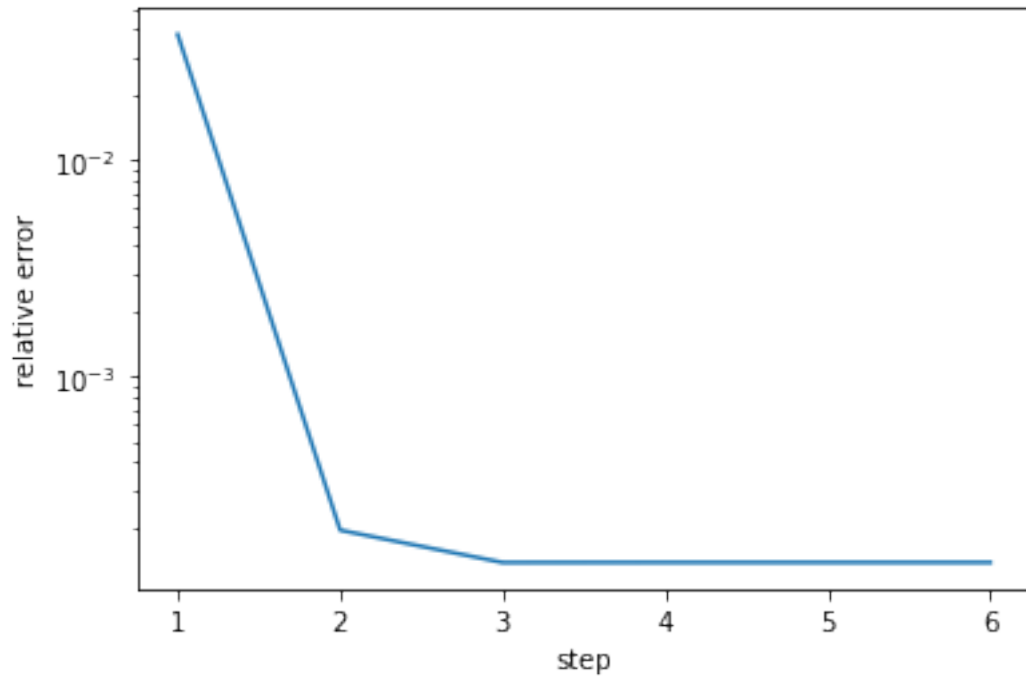


```
[20]: # run optimization

# initial tensor
np.random.seed(42)
k = 4
= TuckerTensor([np.linalg.qr(np.random.randn(n-1, k), mode='reduced')[0] for _
↪_ in range(3)], np.random.randn(k, k, k))

numiter = 6
errlist = []
for i in range(numiter):
    factorized_tucker_als_step(A, , b)
    errlist.append(np.linalg.norm(.as_full_tensor() - ref) / np.linalg.
↪norm(ref))

plt.semilogy(range(1, numiter + 1), errlist)
plt.xlabel("step")
plt.ylabel("relative error")
plt.show()
```



```
[21]: # core tensor
      .C.shape
```

```
[21]: (4, 4, 4)
```

```
[22]: # visualize Tucker format approximation (should be visually indistinguishable
      ↪ from reference solution)
      full = .as_full_tensor()
      plt.imshow(full[:, :, n//2], extent=[0,1,0,1])
      plt.xlabel("x")
      plt.ylabel("y")
      plt.title("Tucker (x, y, z) at z = 0.5")
      plt.colorbar()
      plt.show()
```

