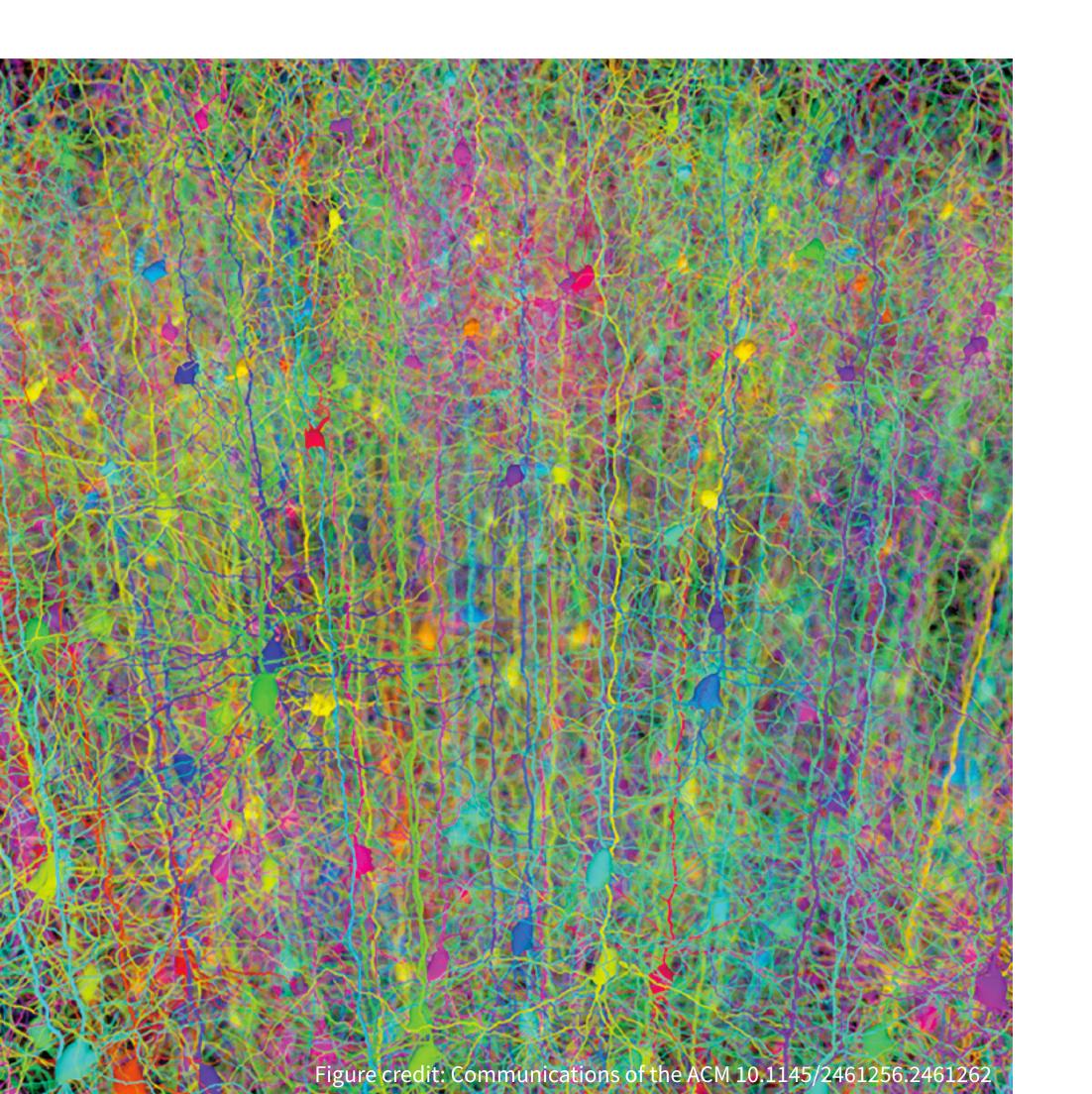
#### Restricted Boltzmann Machines



**GRAHAM TAYLOR** 

VECTOR INSTITUTE

SCHOOL OF ENGINEERING UNIVERSITY OF GUELPH

CANADIAN INSTITUTE FOR ADVANCED RESEARCH



### Scaling ML to the Challenges of Al

Classification algorithms take an input from a high-dimensional distribution and summarize it with a category label

 During this process, the classifier discards most of the information in the input and produces a single output

It is possible to ask our ML models to do many other tasks

- Some of which require them to produce multiple outputs
- Most require a complete understanding of the entire structure of the input, with no option to ignore sections of it

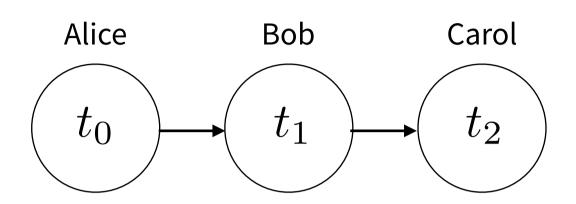
# Structured Probabilistic Models for Machine Learning

Modeling a rich distribution over random variables is a challenging task, both computationally and statistically

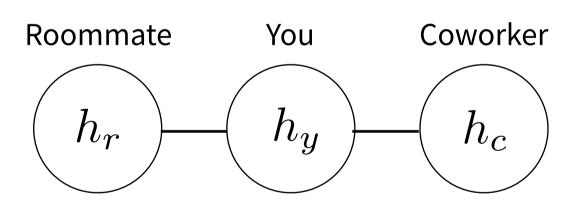
Structured probabilistic models (graphical models) provide a formal framework for modeling only direct interactions between random variables

- significantly fewer parameters
- estimated reliably from less data

directed graphical model

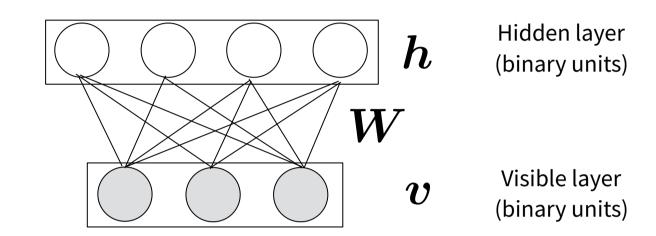


undirected graphical model



#### Restricted Boltzmann Machine

 Undirected graphical model with bipartite structure and restricted connectivity to make inference and learning easier



Energy function:

$$E(\boldsymbol{v}, \boldsymbol{h}) = -\boldsymbol{b}^{\mathsf{T}} \boldsymbol{v} - \boldsymbol{c}^{\mathsf{T}} \boldsymbol{h} - \boldsymbol{v}^{\mathsf{T}} \boldsymbol{W} \boldsymbol{h}$$

Distribution:

$$P(\mathbf{v} = \mathbf{v}, \mathbf{h} = \mathbf{h}) = \frac{1}{Z} \exp(-E(\mathbf{v}, \mathbf{h}))$$

$$Z = \sum_{\boldsymbol{v}} \sum_{\boldsymbol{h}} \exp \left\{ -E(\boldsymbol{v}, \boldsymbol{h}) \right\}$$

partition function (intractable)

#### Markov Network View

Markov network with vector nodes:

$$P(\mathbf{v} = \mathbf{v}, \mathbf{h} = \mathbf{h}) = \exp(-E(\mathbf{v}, \mathbf{h}))/Z$$

$$= \exp(\mathbf{b}^{\top} \mathbf{v} + \mathbf{c}^{\top} \mathbf{h} + \mathbf{v}^{\top} \mathbf{W} \mathbf{h})/Z$$

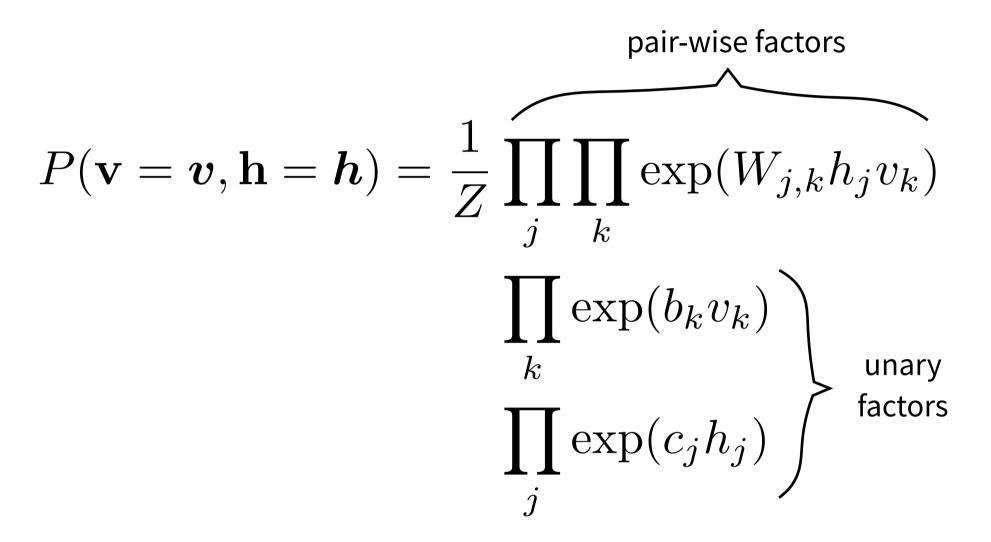
$$= \exp(\mathbf{b}^{\top} \mathbf{v}) \exp(\mathbf{c}^{\top} \mathbf{h}) \exp(\mathbf{v}^{\top} \mathbf{W} \mathbf{h})/Z$$
factors

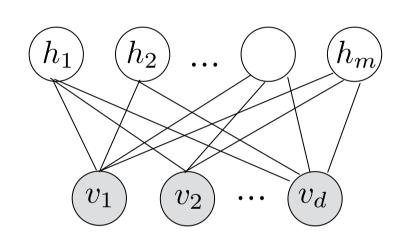
The notation based on an energy function is simply an alternative to the representation as the product of factors

h

## Markov Network View (2)

#### Markov network with scalar nodes:

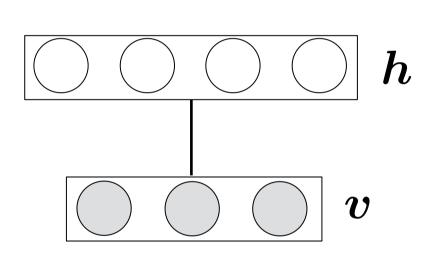


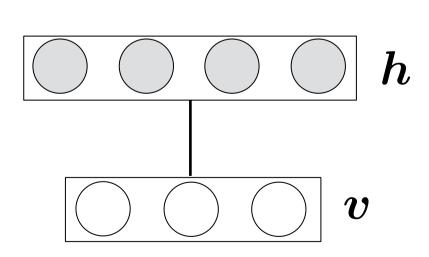


This scalar visualization is more informative of the structure within the vectors

#### Inference in RBM

Though P(v) is intractable, the bipartite graph structure of the RBM has the special property of its conditional distributions P(h|v) and P(v|h) being factorial and relatively simple to compute and sample:





$$egin{aligned} P(m{h}|m{v}) &= \prod_{j} P(h_j = 1|m{v}) \ P(h_j = 1|m{v}) &= rac{1}{1 + \exp(-(c_j + m{v}^ op m{W}_{:,j}))} \ &= \sigma(c_j + m{v}^ op m{W}_{:,j}) & igg( m{j}^ ext{th column of } m{W} \end{aligned}$$

$$egin{align} P(oldsymbol{v}|oldsymbol{h}) &= \prod_k P(v_k = 1|oldsymbol{h}) \ P(v_k = 1|oldsymbol{h}) &= rac{1}{1 + \exp(-(b_k + oldsymbol{W}_{k,:}oldsymbol{h}))} \ &= \sigma(b_k + oldsymbol{W}_{k,:}oldsymbol{h}) \ \end{pmatrix}$$

# Free Energy

- Many algorithms that operate on probabilistic models need to compute not  $p_{
  m model}({m x})$  but only  $\log ilde{p}_{
  m model}({m x})$
- For energy-based models with latent variables h, these algorithms are sometimes phrased in terms of the negative of this quantity, called the free energy:

$$\mathcal{F}(\boldsymbol{x}) = -\log \sum_{\boldsymbol{h}} \exp(-E(\boldsymbol{x}, \boldsymbol{h}))$$

For the RBM:

$$P(\boldsymbol{v}) = \sum_{\boldsymbol{h} \in \{0,1\}^m} P(\boldsymbol{v}, \boldsymbol{h}) = \sum_{\boldsymbol{h} \in \{0,1\}^m} \exp(-E(\boldsymbol{v}, \boldsymbol{h}))/Z$$
$$= \exp\left(\boldsymbol{b}^\top \boldsymbol{v} + \sum_{j=1}^m \log\left(1 + \exp\left(c_j + \boldsymbol{v}^\top \boldsymbol{W}_{:,j}\right)\right)\right)/Z$$
$$= \exp\left(-\mathcal{F}(\boldsymbol{v})\right)/Z$$