

PHY115

Dynamics of Rotation

Digipen

Spring 2022

Torque

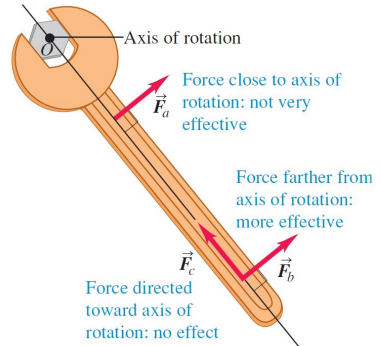
Torque as a vector

Torque and Angular Acceleration

Angular Momentum

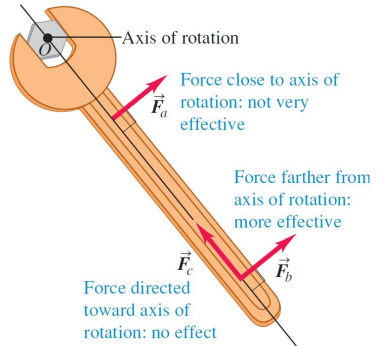
Torque

- ▶ Direction and magnitude of forces \rightarrow affect Translational Motion.
- ▶ The point of application \rightarrow affects Rotational Motion.



Torque

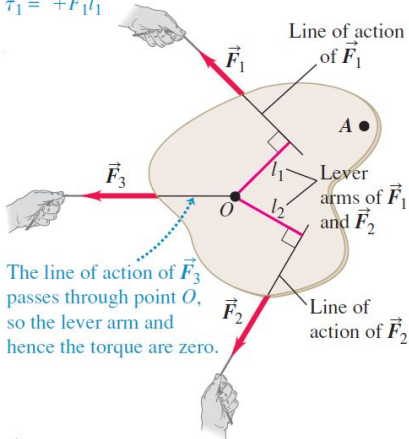
- ▶ Direction and magnitude of forces → affect Translational Motion.
- ▶ The point of application → affects Rotational Motion.



The quantitative measure of the tendency of a force to cause or change a body's rotational motion is called torque;

\vec{F}_1 tends to cause *counterclockwise* rotation about point O , so its torque is *positive*:

$$\tau_1 = +F_1 l_1$$



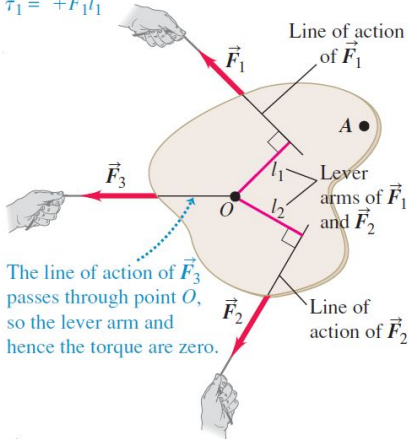
\vec{F}_2 tends to cause *clockwise* rotation about point O , so its torque is *negative*: $\tau_2 = -F_2 l_2$

$$\tau = F\ell$$

ℓ : lever arm

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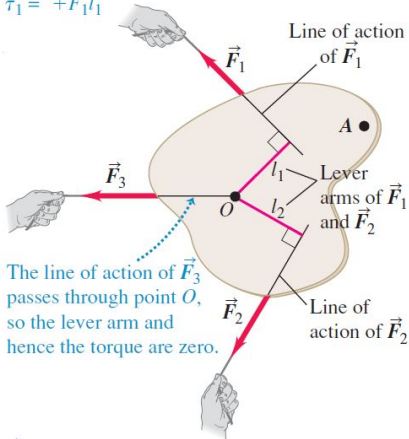
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EXAMPLE: what is the torque?

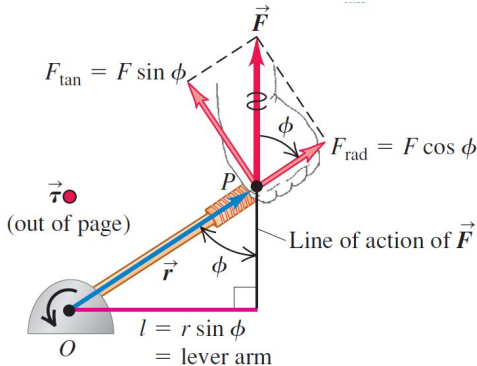


Figure: Image from Sears and Zemansky's University Physics With Modern Physics 13th edition.

EXAMPLE: what is the torque?

$$\tau = F\ell = rF\sin\phi \quad (1)$$

TORQUE AS A VECTOR

- ▶ Angular velocity \rightarrow vector

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- ▶ Angular acceleration \rightarrow vector

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- ▶ Angular velocity \rightarrow vector
- ▶ Angular acceleration \rightarrow vector
- ▶ Torque \rightarrow also a vector

TORQUE AS A VECTOR

$$\vec{\tau} = \vec{r} \times \vec{F} \quad (2)$$

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$$\boxed{\vec{\tau} = \vec{r} \times \vec{F}} \quad (2)$$

- ▶ Magnitude: $\tau = F\ell = rF\sin\Phi$
- ▶ Direction: Right Hand Rule.
 - ▶ $\vec{\tau}$ perpendicular to the plane of \vec{r} and \vec{F}
 - ▶ $(\cdot) \rightarrow \vec{\tau}$ points out the screen.
 - ▶ $(\times) \rightarrow \vec{\tau}$ points into the screen.

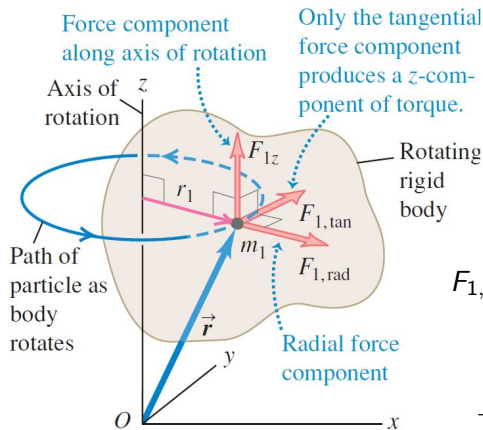
Test Your Understanding of

The figure shows a force P being applied to one end of a lever of length L .

What is the magnitude of the torque of this force about point A ?

1. $PL\sin(\theta)$;
2. $PL\cos(\theta)$;
3. $PL\tan(\theta)$.

Torque and Angular Acceleration for a Rigid Body



$$F_{1,tan} = m_1 a_{1,tan}$$

$$F_{1,tan} r_1 = m_1 r_1 a_{1,tan} = m_1 r_1^2 \alpha_z$$

$$\rightarrow \sum \tau_{iz} = \left(\sum m_i r_i^2 \right) \alpha_z$$

Inertia Momentum

$$I = \left(\sum m_i r_i^2 \right) \quad (3)$$

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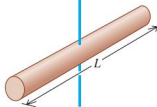
$$\sum \tau_{iz} = I \alpha_z \quad (4)$$

Just as Newton's second law says that the net force on a particle equals the particle's mass times its acceleration, the net torque on a rigid body equals the body's moment of inertia about the rotation axis times its angular acceleration.

Moments of Inertia of Various Bodies

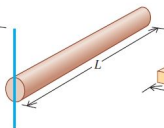
(a) Slender rod,
axis through center

$$I = \frac{1}{12} ML^2$$



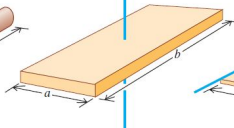
(b) Slender rod,
axis through one end

$$I = \frac{1}{3} ML^2$$



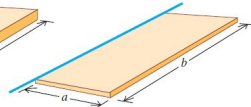
(c) Rectangular plate,
axis through center

$$I = \frac{1}{12} M(a^2 + b^2)$$



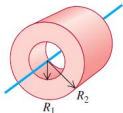
(d) Thin rectangular plate,
axis along edge

$$I = \frac{1}{3} Ma^2$$



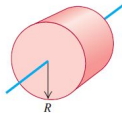
(e) Hollow cylinder

$$I = \frac{1}{2} M(R_1^2 + R_2^2)$$



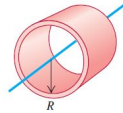
(f) Solid cylinder

$$I = \frac{1}{2} MR^2$$



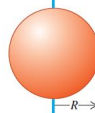
(g) Thin-walled hollow
cylinder

$$I = MR^2$$



(h) Solid sphere

$$I = \frac{2}{5} MR^2$$



(i) Thin-walled hollow
sphere

$$I = \frac{2}{3} MR^2$$

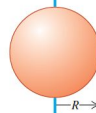
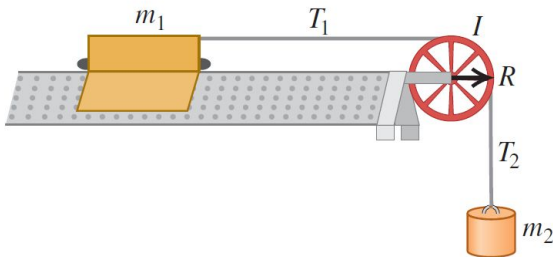


Figure: Image from Sears and Zemansky's University Physics With Modern Physics 13th edition.

Test Your Understanding of the Section

Rank the magnitudes of the following forces that act during the motion, in order from largest to smallest magnitude. (i) the tension force (magnitude T_1) in the horizontal part of the string; (ii) the tension force (magnitude T_2) in the vertical part of the string; (iii) the weight m_2g of the hanging object.



Rolling Without Slipping: Motion of a wheel

The motion of a rolling wheel is the sum of the translational motion of the center of mass plus the rotational motion of the wheel around the center of mass.

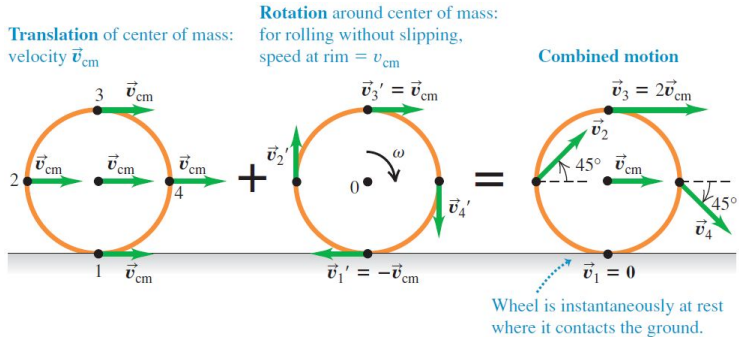


Figure: Image from Sears and Zemansky.

Acceleration of a rolling sphere

A bowling ball rolls without slipping down a ramp, which is inclined at an angle β to the horizontal. What are the ball's acceleration and the magnitude of the friction force on the ball? Treat the ball as a uniform solid sphere, ignoring the finger holes.

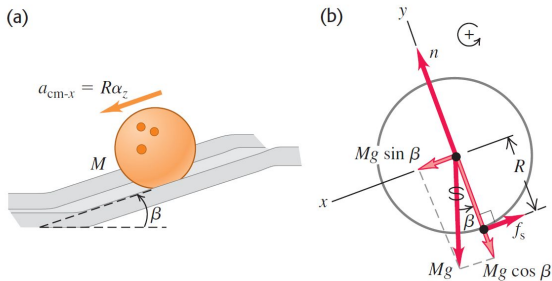


Figure: Image from Sears and Zemansky.

Race of the rolling bodies

What shape should a body have to reach the bottom of the incline first?

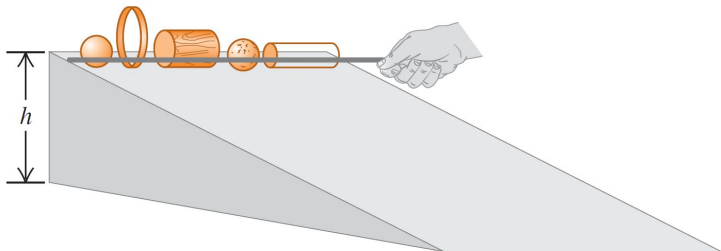


Figure: Image from Sears and Zemansky.

Angular Momentum

Every rotational quantity that we have encountered last sections is the analog of some quantity in the translational motion of a particle.

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The analog of \vec{P} of a particle is angular momentum \vec{L} .

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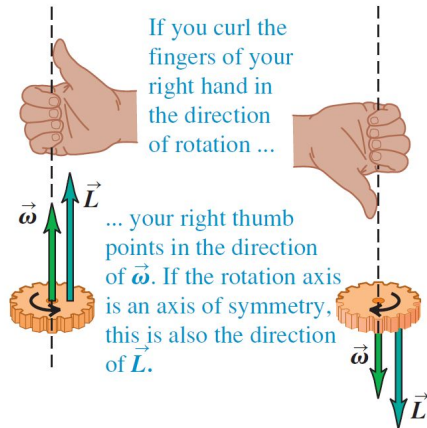
The analog of \vec{P} of a particle is angular momentum \vec{L} .

$$\vec{L} = \vec{r} \times \vec{p} \quad (5)$$

Angular Momentum

For a rigid body rotating around a symmetry axis:

$$\vec{L} = I\vec{\omega} \quad (6)$$



Angular Momentum and Torque

We can show that there is a relation between angular momentum and torque:

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When the net external torque acting on a system is zero, the total angular momentum of the system is constant (conserved).

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No external torque $\rightarrow \vec{L} = \text{constant} \rightarrow \omega I = \text{constant}$

Test Your Understanding of Section

If the polar ice caps were to completely melt due to global warming, the melted ice would redistribute itself over the earth. This change would cause the length of the day (the time needed for the earth to rotate once on its axis) to

1. increase;
2. decrease;
3. remain the same.

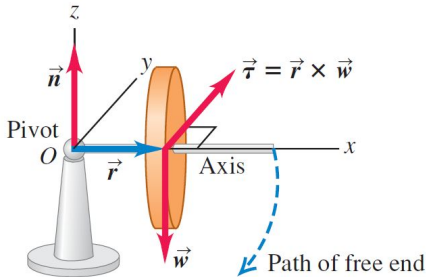
(Hint: Use angular momentum ideas. Assume that the sun, moon, and planets exert negligibly small torques on the earth.)

Test Your Understanding of Section

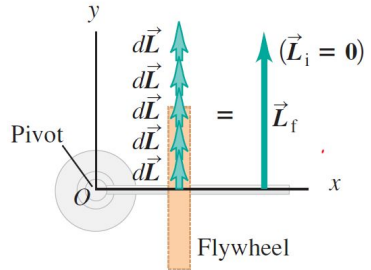
A ball is attached to one end of a piece of string. You hold the other end of the string and whirl the ball in a circle around your hand.

1. If the ball moves at a constant speed, is its linear momentum constant? Why or why not?
2. Is its angular momentum constant? Why or why not?

Gyroscopes



When the flywheel is not rotating, its weight creates a torque around the pivot, causing it to fall along a circular path until its axis rests on the table surface.

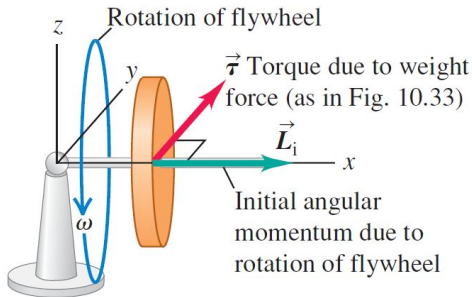


In falling, the flywheel rotates about the pivot and thus acquires an angular momentum \vec{L} . The *direction* of \vec{L} stays constant.

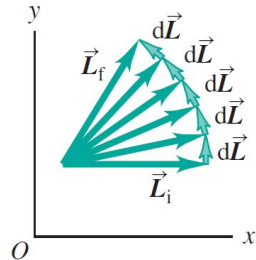
Figure: Image from Sears and Zemansky.

Gyroscopes

When the flywheel is rotating, the system starts with an angular momentum \vec{L}_i parallel to the flywheel's axis of rotation.



Now the effect of the torque is to change the angular momentum to precess the pivot. The gyroscope circles around its pivot without falling.



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3. Experienced cooks can tell whether an egg is raw or hardboiled by rolling it down a slope (taking care to catch it at the bottom). How is this possible? What are they looking for?

Example 1

A square metal plate 0.180m on each side is pivoted about an axis through point O at its center and perpendicular to the plate. Calculate the net torque about this axis due to the three forces shown in the figure if the magnitudes of the forces are $F_1 = 18\text{N}$, $F_2 = 26\text{N}$ and $F_3 = 14\text{N}$. The plate and all forces are in the plane of the page. The plate and all forces are in the plane of the screen.

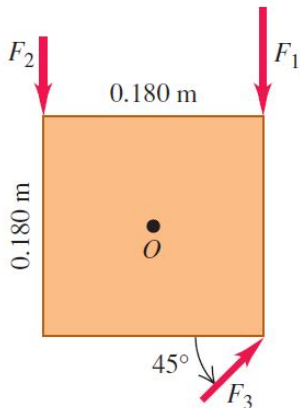


Figure: Image from Sears and Zemansky.

Example 2

A small block on a horizontal surface ($\mu = 0$) with mass 0.025 kg is attached to a massless cord passing through a hole. The block is originally revolving at a distance of 0.3 m from the hole with $\omega = 1.75\text{ rad/s}$. The cord is then pulled from below, shortening the radius to 0.15 m . (a) Is the angular momentum of the block conserved? (b) What is the new angular speed?

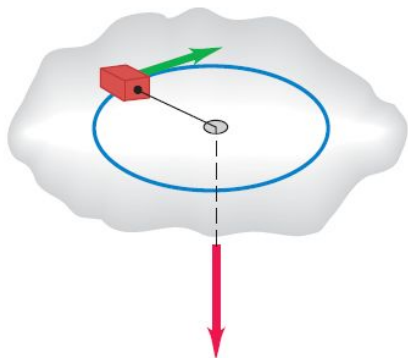


Figure: Image from Sears and Zemansky.

Example 3

A cue ball (mass m , radius R) is at rest on a level pool table. You give the ball a horizontal hit of magnitude F at a height h above the center of the ball. The force of the hit is much greater than the friction force . The hit lasts for a short time Δt . (a) For what value of h will the ball roll without slipping? (b) If you hit the ball center ($h = 0$), the ball will slide across the table for a while, but eventually it will roll without slipping. What will the speed of its center of mass be then?

