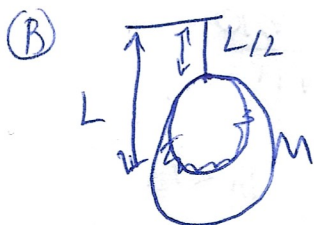
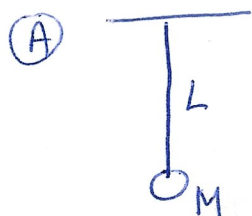


1



Considering that A is a simple pendulum:



2nd Law of Newton: $T - mg \cos \theta = m \cdot a_c$
 $-mg \sin \theta = m \cdot a_T; \rightarrow a_T + g \sin \theta = 0$

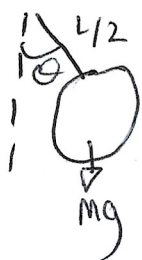
$a_T = l \cdot \alpha$; α (angular acceleration) = $\frac{d^2 \theta}{dt^2}$

$\frac{d^2 \theta}{dt^2} + g \sin \theta = 0$; for small angles $\sin \theta \approx \theta$

$\frac{d^2 \theta}{dt^2} + \frac{g}{l} \theta = 0 \leftarrow \frac{d^2 \theta}{dt^2} + g \theta = 0$; Solution is: $\theta(t) = \theta_0 \cos(\omega t)$

where $\omega = \sqrt{\frac{g}{l}}$; $\omega = \frac{2\pi}{T}$; $T = 2\pi \cdot \sqrt{\frac{l}{g}}$

Considering that B is a physical pendulum



$\vec{\tau} = \vec{r} \times m \vec{g}$

$\vec{\tau} = I_{\text{sphere}} \cdot \alpha = -\frac{L}{2} mg \sin \theta$; for small angles $\sin \theta \approx \theta$

$\alpha = \frac{d^2 \theta}{dt^2}$; $I \cdot \frac{d^2 \theta}{dt^2} = -\frac{L}{2} mg \theta$

$I \cdot \frac{d^2 \theta}{dt^2} + \frac{L}{2} mg \theta = 0$; $\frac{d^2 \theta}{dt^2} + \frac{L}{2I} mg \theta = 0$

Solution: $\theta(t) = \theta_0 \cos(\omega t)$; where $\omega = \sqrt{\frac{2I}{Lmg}}$; $\omega = \sqrt{\frac{Lmg}{2I}}$

$I_{\text{sphere}} = \frac{2}{5} MR^2$; $R = \frac{L}{2}$; $I_{\text{sphere}} = \frac{2}{20} ML^2 = \frac{1}{10} ML^2$; $I_{\text{total}} = I_{\text{center mass}} + ML^2$

$I_{\text{total}} = \frac{11}{10} ML^2$; $T_B = 2\pi \cdot \sqrt{\frac{2I}{Lmg}}$

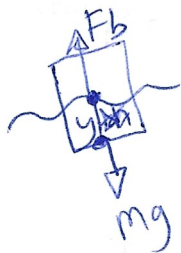
$$T_B = 2\pi \sqrt{\frac{\frac{11}{10} \frac{ML^2}{LAg}}{g}} = 2\pi \sqrt{\frac{\frac{11}{10} L}{g}} = 2\pi \sqrt{\frac{11L}{10g}} = 2\pi \sqrt{\frac{11L}{10g}}$$

$$\frac{T_A}{T_B} = \frac{2\pi \sqrt{\frac{L}{g}}}{2\pi \sqrt{\frac{11L}{10g}}} = \sqrt{\frac{\frac{L}{g}}{\frac{11L}{10g}}} = \sqrt{\frac{10}{11}} = \sqrt{\frac{10}{11}}$$

$$\frac{T_A}{T_B} = \sqrt{\frac{10}{11}}; T_A = \sqrt{\frac{10}{11}} T_B; \boxed{T_A = 0.95 T_B} \quad T_A < T_B$$

Ball B takes longer as its period is greater than the period of ball A

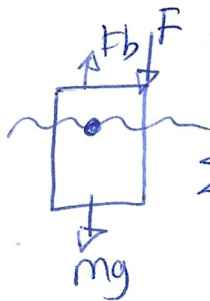
②



$$\begin{aligned} \text{a) } F_b - mg &= 0 \\ F_b &= mg \end{aligned}$$

$$\rho_{\text{fluid}} \cdot g \cdot A \cdot y = mg; \quad \boxed{y = \frac{m}{\rho_{\text{fluid}} \cdot A}}$$

b)



$$\Sigma F = 0; F_b - mg - F = 0;$$

$$F_b = mg + F$$

$A \cdot y$ = Volume submerged; The object will be submerged more;

$$\text{Volume submerged} = A \cdot \text{amount submerged} = A \cdot (y + y_2)$$

$$\rho_{\text{fluid}} \cdot g \cdot A (y + y_2) = mg + F; \quad \text{as } y = \frac{m}{\rho_{\text{fluid}} \cdot A};$$

$$\rho_{\text{fluid}} \cdot g \cdot A \left(\frac{m}{\rho_{\text{fluid}} \cdot A} + y_2 \right) = mg + F;$$

$$\frac{\rho_{\text{fluid}} \cdot g \cdot A m}{\rho_{\text{fluid}} \cdot A} + \rho_{\text{fluid}} \cdot g \cdot A \cdot y_2 = mg + F;$$

$$A \cdot \rho_{\text{fluid}} \cdot g \cdot y_2 = mg + F - mg; \quad \boxed{y_2 = \frac{F}{\rho_{\text{fluid}} \cdot g \cdot A}}$$

c)

$$3 a) v = \sqrt{\frac{F_T}{\mu}} = \sqrt{\frac{5}{0,05}} = 10 \text{ m/s}$$

$$\bar{f} = 40 \text{ Hz} \quad b) v = \lambda f; \lambda = \frac{v}{f}; \lambda = \frac{10}{40} = 0,25 \text{ m}$$

$$A = 3 \text{ cm} = 0,03 \text{ m}$$

$$\mu = 50 \text{ g/m} = 0,05 \text{ kg/m}$$

$$F_T = 5 \text{ N}$$

$$c) D(x,t) = A \cos(kx - \omega t)$$

$$k = \frac{2\pi}{\lambda} = 25,12 \text{ rad/m}$$

$$\omega = \frac{2\pi}{T} = 2\pi f = 251,2 \text{ rad/s}$$

$$D(x,t) = 0,03 \cdot \cos(25,12x - 251,2t)$$

d)

$$y = \frac{dy}{dt} = A\omega \sin(kx - \omega t);$$

$$a_y(x,t) = \frac{dy}{dt} = -A\omega^2 \cos(kx - \omega t)$$

$$\text{acceleration is maximum at } t=0, x=0; a_y(0,0) = -A\omega^2 \cos(0) = -A\omega^2$$

$$= -0,03 \cdot (251,2)^2 = -1893,64 \text{ m/s}^2$$

$$e) g = 9,8 \text{ m/s}^2$$

$$a = 1893,64 \text{ m/s}^2$$

Gravity is so small compared to the acceleration of a point in the wave that it can be ignored, so the results are reasonable approximations

4)

$$a) y_1(x,t) = A \cos(kx + \omega t); \text{ 2 waves generated}$$

$$D_1(x,t) = A \cos(kx + \omega t)$$

$$D_2(x,t) = A \cos(kx - \omega t)$$

$$A \cos(kx + \omega t) + A \cos(kx - \omega t) = A \cdot (\cos(kx + \omega t) + \cos(kx - \omega t))$$

$$= A \cdot \left(2 \cos\left(\frac{(kx + \omega t) + (kx - \omega t)}{2}\right) \cdot \cos\left(\frac{(kx + \omega t) - (kx - \omega t)}{2}\right) \right)$$

$$= 2A \cos(kx) \cdot \cos(\omega t)$$

$$b) \text{ At } x=0; y(x,t) = 2A \cos(\omega t); \text{ Maximum amplitude} = 2A$$

$$\text{Amplitude at } x=0 \text{ is } 2A$$

Hence $x=0$ there is an antinode

c) Max displacement, max speed and max acceleration

We know already that the maximum displacement is $2A$;

$$y_{\max} = 2A;$$

$$v_{y\max} = \frac{dy}{dt} = 2A \cos(kx) \cdot \omega \sin(\omega t) = -2A\omega \cos(kx) \sin(\omega t)$$

$$v_{y\max} \text{ at } x=0; \quad -2A\omega \cos(0) \sin(\omega t) = -2A\omega \sin(\omega t)$$

The maximum velocity is $|-2A\omega| = 2A\omega$

$$a_y = \frac{dv}{dt} = -2A\omega \cos(kx) \cdot \omega \cos(\omega t) = -2A\omega^2 \cos(kx) \cdot \cos(\omega t)$$

$$\text{At } x=0; \quad -2A\omega^2 \cdot \cos(\omega t);$$

$$\text{Maximum acceleration} = 2A\omega^2$$

d)
$$f_{\text{res}} = f_n = \frac{n v}{2L} = \frac{n}{2L} \sqrt{\frac{F_t}{\mu}}$$

Resonant frequency: frequency where it tends to vibrate at a higher amplitude

$$f_n = \frac{n \cdot v_{\max}}{2L}; \quad \boxed{f_n = \frac{n \cdot 2A\omega}{2L}}$$