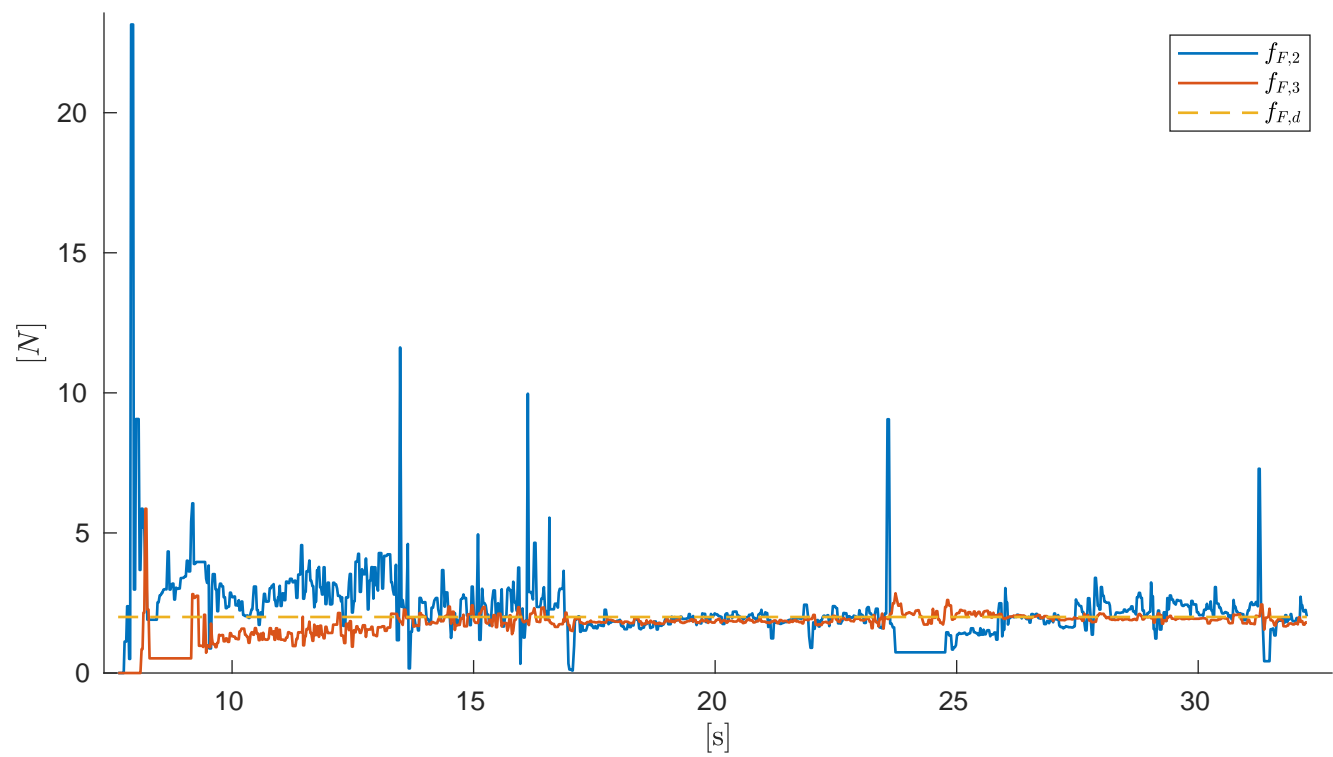


Contact forces



Input joint torques

