

Alexander Winkles Computer Project #2  
09/12/2016

-----  
Problem 1:  
-----

Here is a copy of my code:

```
type newton.m

function newton(f,df,x0,T,S,q)
%newton(f,df,x0,T,S,q)
%
%This is a Newton's method algorithm developed by Alexander Winkles used to
% find roots in functions.
%
%f : the function being studied.
%df : the derivative of the function being studied.
%x0 : the initial point being used.
%T : the tolerance of the final answer.
%S : the number of iterations.
%q : prints the steps (1 for yes, 0 for no).

format long
if q == 1
    fprintf('\nStep \t\t Result\n---\t\t -----\n');
end;
if feval(f,x0) == 0 || abs(feval(f,x0)) < T
    fprintf('\n Your initial guess %d was close enough to zero!',x0);
else
    i = 0;
    while i <= S
        x1 = x0 - feval(f,x0)/feval(df,x0);
        if q == 1
            fprintf('%d \t\t %f\n',i,x1);
        end;
        if feval(f,x1) == 0 || abs(feval(f,x1)) < T
            fprintf('\nThe solution is %d. The computation was a success
                after %d iterations!\n\n',x1,i);
            break;
        end;
        i = i+1;
        x0 = x1;
    end;
    if i == S+1
        fprintf('\nMethod failed after %d iterations.\n\n',S)
    end;
end;

Inputing the function and it's derivative:

f =@(x) tan(x);
```

```
df =@(x) (sec(x))^2;
```

Computing the results:

```
newton(f,df,4.5,1e-5,100,1)
```

Step	Result
0	4.293941
1	3.922657
2	3.422676
3	3.156166
4	3.141595

The solution is 3.141595e+00. The computation was a success after 4 iterations!

```
newton(f,df,7.7,1e-5,100,1)
```

Step	Result
0	7.548441
1	7.261564
2	6.798345
3	6.369614
4	6.283615
5	6.283185

The solution is 6.283185e+00. The computation was a success after 5 iterations!

-----  
 Problem 4:  
 -----

Inputing the function and its derivative:

```
f =@(x) x.^3-5*x.^2+3*x-7;
```

```
df =@(x) 3*x.^2-10*x+3;
```

Computing the results:

```
newton(f,df,5,1e-5,10,1)
```

Step	Result
0	4.714286
1	4.679089
2	4.678574

The solution is 4.678574e+00. The computation was a success after 2 iterations!

This solution was found before 10 steps, so we use a new program to compute it to 10 steps:

```
type newtonstep.m
```

```

function newtonstep(f,df,x0,S)
%newtonstep(f,df,x0,T,S)
%
%This is a program derived from Newton's method algorithm developed by Alexander Winkles used to
% find roots in functions for a certain number of steps.
%
%f : the function being studied.
%df : the derivative of the function being studied.
%x0 : the initial point being used.
%S : the number of steps required.

format long

i = 0;
fprintf('\nStep \t\t Result\n---\t\t -----\n');
while i <= S
    x1 = x0 - feval(f,x0)/feval(df,x0);
    fprintf('%d \t\t %f\n',i,x1);
    i = i+1;
    x0 = x1;
end;
fprintf('\nAfter %d steps, the solution is %d.\n\n',i-1,x1)

```

Which gave these results:

```
newtonstep(f,df,5,10)
```

Step	Result
---	-----
0	4.714286
1	4.679089
2	4.678574
3	4.678574
4	4.678574
5	4.678574
6	4.678574
7	4.678574
8	4.678574
9	4.678574
10	4.678574

After 10 steps, the solution is 4.678574e+00.

-----  
 Problem 9:  
 -----

Here is my code:

```
type steffensen.m
```

```

function steffensen(f,x0,T,S,q)
%steffensen(f,x0,T,S,q)

```

```
%
%This is a Steffensen's method algorithm designed by Alexander Winkles to
% find roots of functions.
%
%f : the function being evaluated.
%x0 : the initial value being used.
%T : the tolerance of the final answer.
%S : the number of iterations.
%q : prints the steps (1 for yes, 0 for no)
%
%*Current issues: does not necessarily converge to the closest zero from the
% starting point.
```

```
format long
if q == 1
    fprintf('\nStep \t\t Result\n---\t\t -----\n');
end;
if abs(feval(f,x0)) < T
    fprintf('\n Your initial guess %d was close enough to zero!',x0);
else
    i = 0;
    while i<= S
        xi = x0 + feval(f,x0);
        x1 = x0 - feval(f,x0)/((feval(f,xi)-feval(f,x0))/feval(f,x0));
        if q == 1
            fprintf('%d \t\t %f\n',i,x1)
        end;
        if abs(feval(f,x1)) < T
            fprintf('\nThe solution is %f. The computation was successful
                after %d iterations!\n\n',x1,i)
            break;
        end;
        i = i+1;
        x0 = x1;
    end;
    if i == S+1
        fprintf('\nThe computation failed after %d iterations.\n\n',S)
    end;
end;
```

Here is my function:

```
f=@(x) tan(x);
```

Here are my results for testing:

```
steffensen(f,4.5,1e-5,100,1)
```

Step	Result
---	-----
0	8.859416
1	9.067304
2	9.333973
3	9.423281

4 9.424778

The solution is 9.424778. The computation was successful after 4 iterations!

```
steffensen(f,7.7,1e-5,100,1)
```

Step	Result
0	7.928445
1	-4.507402
2	-9.211639
3	-9.405459
4	-9.424764
5	-9.424778

The solution is -9.424778. The computation was successful after 5 iterations!

```
f=@(x) tan(x) - x;  
steffensen(f,7.7,1e-5,100,1)
```

Step	Result
0	8.014521
1	-1.820315
2	1.983972
3	-0.375582
4	-0.261593
5	-0.178073
6	-0.119858
7	-0.080252
8	-0.053605
9	-0.035767
10	-0.023854

The solution is -0.023854. The computation was successful after 10 iterations!

```
steffensen(f,4.5,1e-5,100,1)
```

Step	Result
0	4.497787
1	4.495335
2	4.493781
3	4.493423
4	4.493409

The solution is 4.493409. The computation was successful after 4 iterations!

It appears that this method find zeros, but they are not always the closest ones to the starting value.

-----  
Problem 13:  
-----

Here is my code:

```

type newtonsystem.m

function newtonsystem(F,J,x0,y0,T,S,q)
%newtonsystem(F,J,x0,y1,T,S,q)
%
%This is a Newton's method algorithm developed by Alexander Winkles used to
% find roots in systems of nonlinear equations.
%
%F : the function matrix being studied.
%J : the Jacobian of the function matrix being studied.
%x0 : the initial vector being used.
%T : the tolerance vector of the final answer.
%S : the number of iterations.
%q : prints the steps (1 for yes, 0 for no).

format long g

if q == 1
    fprintf('\nStep \t\t x \t\t\t y\n---\t\t ----- \t\t -----\n');
end;
if abs(feval(F,x0,y0)) < T
    fprintf('\nYour initial guess (%d %d) was close enough to zero!',x0,y0);
else
    i = 0;
    while i <= S
        H = -inv(J(x0,y0))*F(x0,y0);
        x1 = x0 + H(1);
        y1 = y0 + H(2);
        if q == 1
            fprintf('%d \t\t %f \t\t %f\n',i,x1,y1);
        end;
        if abs(feval(F,x1,y1)) < T
            fprintf('\nThe solution is (%f, %f). The computation was a success
                after %d iterations!\n\n',x1,y1,i);
            break;
        end;
        i = i + 1;
        x0 = x1;
        y0 = y1;
    end;
    if i == S+1
        fprintf('\nMethod failed after %d iterations.\n\n',S)
    end;
end;

```

Here is my function matrix and its Jacobian:

```

F = @(x,y) [1+x.^2-y.^2 + exp(x)*cos(y); 2*x*y+exp(x)*sin(y)];

J = @(x,y) [1+2*x+exp(x)*cos(y), 1-2*y-exp(x)*sin(y); 2*y+exp(x)*sin(y), 2*x+exp(x)*cos(y)];

```

Here are my results:

```
newtonsystem(F,J,-1,4,[1e-5;1e-5],100,1)
```

Step	x	y
---	-----	-----
0	-0.565863	1.801265
1	-0.409870	1.137365
2	-0.273568	1.252288
3	-0.296764	1.130502
4	-0.290827	1.198308
5	-0.294538	1.159211
6	-0.292414	1.180442
7	-0.293586	1.168392
8	-0.292928	1.175071
9	-0.293294	1.171320
10	-0.293089	1.173412
11	-0.293204	1.172240
12	-0.293140	1.172895
13	-0.293176	1.172529
14	-0.293156	1.172733
15	-0.293167	1.172619
16	-0.293160	1.172683
17	-0.293164	1.172647
18	-0.293162	1.172667
19	-0.293163	1.172656
20	-0.293162	1.172662

The solution is  $(-0.293162, 1.172662)$ . The computation was a success after 20 iterations!

Notice if we let  $z = x + y*i$ ,  $f(z) = 1 + z^2 + \exp(z)$  becomes

$$1 + x^2 + 2*x*y*i - y^2 + \exp(x)*(\cos(y) + i*\sin(y)).$$

Thus, problem 13 is problem 11, with each function representing either the real or the imaginary part of  $f(z)$ .

diary off