The Bishop Frame.

We now define another wersign of curve framing.

Suppose we start with some (arbitrary) smooth framing F of y, and consider the vector field

 $V(s) = \cos \theta(s) F_2(s) + \sin \theta F_3(s)$

Then

 $V'(s) = -\sin \Theta(s) \cdot \Theta'(s) F_{2}(s)$ $+\cos \Theta(s) (-\alpha_{12}(s) F_{1}(s) + \alpha_{23}(s) F_{3}(s))$ $+\cos \Theta(s) \cdot \Theta'(s) F_{3}(s)$ $+\sin \Theta (-\alpha_{23}(s) F_{1}(s) - \alpha_{23} F_{2}(s))$ Gathering terms,

 $V'(s) = (-\alpha_{12}(s)\cos\theta(s) - \alpha_{13}(s)\sin\theta(s))T_{L}(s)$ $(-\alpha_{23}(s)\sin\theta(s) - \sin\theta(s)\theta'(s))F_{2}(s)$ $(+\alpha_{23}(s)\cos\theta(s) + \cos\theta(s)\theta'(s))F_{3}(s)$

Observe that the Fz, Fz coefficients are

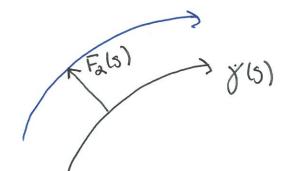
$$-\sin\Theta(5)(\alpha_{23}(5)+\Theta'(5))$$
 and
$$\cos\Theta(5)(\alpha_{23}(5)+\Theta'(5))$$

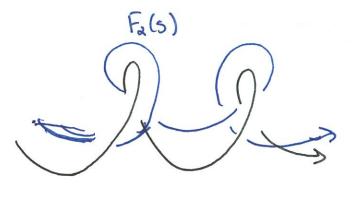
This means that if we set $\Theta'(s) = -\alpha_{23}(s)$ and integrate, we can define a family of frames such a that:

F₂(s) depends on the initial angle Θ(o)=Θ₀, but any two frames with initial difference in angle ΔΘ₀ maintains this angular difference for all 5.

We call this construction the Bishop frame, or relatively parallel adapted frame (RPAF).

The picture is





Traditionally, we write the structure equations

$$T' = K_1 F_2 + K_2 F_3$$

 $F_3' = -K_2 F_3$
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and call $x_{12}(s) = K_{12}(s)$ and $x_{13}(s) = K_{12}(s)$. These two functions are like X, Y:

$$|T'| = \chi(s)$$

= $\sqrt{K_1(s)^2 + K_2^2(s)}$,

50 K(s) is like radius in the Ks, Kz plane.

To compute torsion, observe

$$N(s) = \frac{T'(s)}{|T'(s)|} = \left(\frac{K_1}{K}\right) F_a + \left(\frac{K_2}{X}\right) F_3$$

$$\stackrel{\leftarrow}{L}_{two numbers},$$

$$squares sum to L$$

= (050 F2 + sin 0 F3

Then

$$N'(s) \cdot B(s) = Y(s)$$
 this is B

$$= (\Theta'(s)(-\sin\Theta F_2 + \cos\Theta F_3)$$
+ something in T direction, B)
$$= \Theta'(s).$$

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Since
$$K_1 = \cos\theta$$
, $K_2 = \sin\theta$, we see $\sqrt{K_1^2 + K_2^2}$

Syla)ds is the polar O in the K2, K2 plane.

We can now see to what extent X, Y or Ka, Ka determine the geometry of the conve Y!

We already Know:

y=0 <=> y is planar (and has nonvanishing K)
In our new language, y=0 <=> (K1, K2) is on
a line through the origin.

Proposition (Bishop, 1990's).

y lies on a sphere <=> (K1, K2) lies on a line not through the origin.

Proof. Suppose

(=>) Wlog, we may assume the sphere is centered at the origin and $\langle \gamma(s), \gamma(s) \rangle = r^2$. Differentiating, we see

 $\langle \gamma, \gamma' \rangle = 0.$

Here's a neat trick. Choose any Bishop frame (T, Fz, Fz) on y. For any 5, this is a basis for 123, 50 we can write y(s) in this basis. In principle,

 $\gamma(s) = \lambda_1(s)T(s) + \lambda_2(s)F_a(s) + \lambda_3(s)F_3(s)$ but we know $\langle \gamma(s), T(s) \rangle = 0$, so $\lambda_1(s) = 0$. This leaves us with

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 $\gamma' = \lambda_2' F_2 + \lambda_2 K_1 T + \lambda_3' F_3 + \lambda_3 K_2 T$ or

 $7650 = (\lambda_2 K_1 + \lambda_3 K_2 - 1)T + \lambda_2' F_2 + \lambda_3' F_3$ But this means $\lambda_2' = 0$, $\lambda_3' = 0$ so the λ_1' are constants.

And then we have

 $\lambda_2 K_2(s) + \lambda_3 K_2(s) = 1$

which is exactly the equation of a line not through the origin!

(=) Suppose $\lambda_2 K_1(s) + \lambda_3 K_2(s) = 1$ for some constants $\lambda_2, \lambda_3 = 1$ Consider the choose a Bishop vector

 $\gamma(5) - (\lambda_2 F_2(5) + \lambda_3 F_3(5)) = \alpha(5).$

If we differentiate,

 $(X'(s)) = T(s) - \lambda_{2}K_{1}(s)T(s) - \lambda_{3}K_{2}(s)T(s)$ = $(1 - \lambda_{2}K_{1}(s) - \lambda_{3}K_{2}(s))T(s)$

So $\alpha(s)$ is a constant vector, $\vec{\alpha}$.

We claim this is the center of the sphere.

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To prove it, $\frac{d}{ds} \langle \gamma(s) - \alpha, \gamma(s) - \alpha \rangle =$ $= 2 \langle T(s), \gamma(s) - \alpha \rangle$ $= 2 \langle T(s), \lambda_{a} F_{a}(s) + \lambda_{3} F_{3}(s) \rangle$ = 0So γ is on a sphere centered at α . \square