

Denoising Diffusion Probabilistic Models

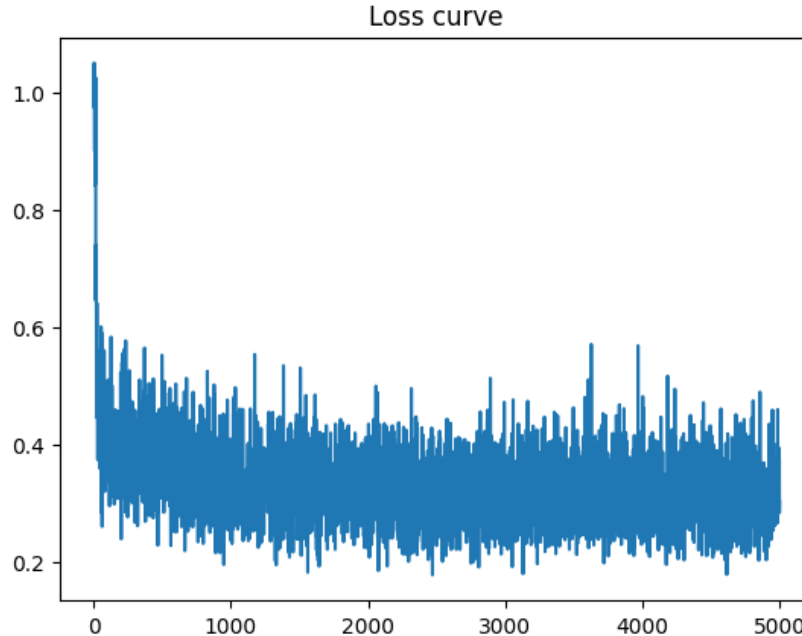
Denoising Diffusion Probabilistic Models (DDPMs) consist of a forward and a backward process. The goal is to minimize the KL distance between the distribution of the forward process ($q(\mathbf{x}_{t-1}|\mathbf{x}_t, \mathbf{x}_0)$) and the backward process ($p_{\theta}(\mathbf{x}_{t-1}|\mathbf{x}_t)$) at a given time instance t and consequently predict \mathbf{x}_{t-1} . To achieve that, we define the simplified loss that is based on the KL divergence, as follows

$$\mathcal{L} = \mathbb{E}_{t, \mathbf{x}_0, \epsilon} [\|\epsilon - \epsilon_{\theta}(\mathbf{x}_t(\mathbf{x}_0, t), t)\|^2]$$

where ϵ is white Gaussian noise and ϵ_{θ} is the neural network that predicts the noise.

Results

For some realization of the problem we got the following loss curve



While the DDPM Chamfer distance was computed to be $C(q, p_{\theta}) = 16.2925$

Last but not least, for visualization of the sampled particles and for the specific realization of the problem, we got the following figure

