

Sect 6.1 (Omitted by accident)

Thm

Let A be an $m \times n$ matrix, then the orthogonal complement of the row space of A is the null space, and orthogonal complement of the column space is the null space of A^T :

$$(\text{Row } A)^\perp = \text{Nul } A \quad (1)$$

and

$$(\text{Col } A)^\perp = \text{Nul } A^T \quad (2)$$

Pf

Let \underline{x} be in $\text{Nul } A$, then we have $A\underline{x} = \underline{0}$

If we write $A\underline{x}$

$$A\underline{x} = \begin{bmatrix} \underline{a}_1 \\ \underline{a}_2 \\ \vdots \\ \underline{a}_m \end{bmatrix} \underline{x} = \begin{bmatrix} \underline{a}_1 \underline{x} \\ \underline{a}_2 \underline{x} \\ \vdots \\ \underline{a}_m \underline{x} \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ \vdots \\ 0 \end{bmatrix}$$

\underline{a}_i is i th row of A →

$$\text{Here } \underline{a}_i \underline{x} = [a_{i1} \ a_{i2} \ \dots \ a_{in}] \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix} = \underline{a}_i \cdot \underline{x} = 0$$

So \underline{x} is orthogonal to the i th row of A for $i = 1 \dots m$. Conversely, if we assume \underline{x} is orthogonal to $\text{Row } A$, then $A\underline{x} = \underline{0}$ and

x is in $\text{Nul } A$. x orthogonal to all vectors in $\text{Row } A \Rightarrow x$ is in $(\text{Row } A)^\perp$
This shows (1).

To see (2), we note that it's also true for A^T , so we have

$$(\text{Col } A)^\perp = (\text{Row } A^T)^\perp = \text{Nul } A^T$$

This proves (2).

Sect 6.4 (Cont...)

Recall: we introduced the Gram-Schmidt process as a way to produce an orthonormal basis for a subspace W .

We now consider this for the subspace $W = \text{Col } A$ for an $m \times n$ matrix A .

Thm

If A is an $m \times n$ matrix with lin. independent columns, then A can be factored as $A = QR$ where Q is $m \times n$ and its columns form an orthonormal basis for $\text{Col } A$. R is an $n \times n$ upper triangular matrix with positive diagonal entries.

PF

The columns of $A = |a_1 \dots a_n|$ form a basis for $\text{Col } A$. Using Gram-Schmidt, construct an orthonormal basis $\{u_1 \dots u_n\}$ for $\text{Col } A$ such that $\text{span}\{u_1 \dots u_k\} = \text{span}\{a_1 \dots a_k\}$ for all $k = 1 \dots n$.

Set $Q = |u_1 \ u_2 \ \dots \ u_n|$, an $m \times n$ matrix

Since $a_k \in \text{span}\{a_1 \dots a_k\} = \text{span}\{u_1 \dots u_k\}$ there exist weights $r_{1k} \dots r_{nk}$ such that

$$a_k = r_{1k} u_1 + r_{2k} u_2 + \dots + r_{nk} u_n$$

Assume $r_{kk} > 0$ (if not, multiply u_k and r_{kk} by -1) and set the vector

$$r_k = \begin{pmatrix} r_{1k} \\ \vdots \\ r_{kk} \\ 0 \\ \vdots \\ 0 \end{pmatrix} \begin{matrix} \left. \begin{matrix} r_{1k} \\ \vdots \\ r_{kk} \end{matrix} \right\} 1 \dots k \\ \left. \begin{matrix} 0 \\ \vdots \\ 0 \end{matrix} \right\} k+1 \dots n \end{matrix}$$

$$\text{Then } Q r_k = |u_1 \ u_2 \ \dots \ u_n| \begin{pmatrix} r_{1k} \\ \vdots \\ r_{kk} \\ 0 \\ \vdots \\ 0 \end{pmatrix}$$

$$\begin{aligned} &= \underbrace{r_{1k} u_1 + r_{2k} u_2 + \dots + r_{kk} u_k}_{\text{red bracket}} + \underbrace{0 \cdot u_{k+1} + \dots + 0 \cdot u_n}_{\text{red bracket, circled 0}} \\ &= a_k \end{aligned}$$

$$\text{Let } R = \begin{bmatrix} r_{11} & r_{12} & r_{13} & \dots & r_{1n} \\ 0 & r_{22} & r_{23} & \dots & r_{2n} \\ \vdots & 0 & r_{33} & \dots & r_{3n} \\ \vdots & \vdots & 0 & \dots & \vdots \\ 0 & 0 & 0 & \dots & r_{nn} \end{bmatrix} \leftarrow \text{upper triangular}$$

$$\begin{aligned} \text{We get } QR &= \begin{bmatrix} Qr_1 & Qr_2 & \dots & Qr_n \end{bmatrix} \\ &= \begin{bmatrix} \underline{a}_1 & \underline{a}_2 & \dots & \underline{a}_n \end{bmatrix} = A \end{aligned}$$

R is upper triangular and $r_{kk} > 0$ for $k=1, \dots, n$.

\hookrightarrow This means $\det(R) > 0 \Rightarrow R$ is invertible
 Q is an $m \times n$ orthogonal matrix

Ex

$$\text{Let } A = \begin{bmatrix} 1 & 0 & 0 \\ 1 & 1 & 0 \\ 1 & 1 & 1 \\ 1 & 1 & 1 \end{bmatrix} \in \mathbb{R}^{4 \times 3}. \text{ Compute } A = QR.$$

Last class, we computed an orthonormal basis for $\{g_1, g_2, g_3\}$, given by

$$\underline{u}_1 = \begin{bmatrix} 1/2 \\ 1/2 \\ 1/2 \\ 1/2 \end{bmatrix}, \quad \underline{u}_2 = \begin{bmatrix} -3/\sqrt{12} \\ 1/\sqrt{12} \\ 1/\sqrt{12} \\ 1/\sqrt{12} \end{bmatrix}, \quad \underline{u}_3 = \begin{bmatrix} 0 \\ -2/\sqrt{6} \\ 1/\sqrt{6} \\ 1/\sqrt{6} \end{bmatrix}$$

So, we set $Q = \begin{bmatrix} \underline{u}_1 & \underline{u}_2 & \underline{u}_3 \end{bmatrix} \in \mathbb{R}^{4 \times 3}$. To find R , we note the following

$$Q^T A = Q^T (QR) = (Q^T Q) R = R$$

So we compute

$$R = \begin{vmatrix} 1/2 & 1/2 & 1/2 & 1/2 \\ -3/\sqrt{2} & 1/\sqrt{2} & 1/\sqrt{2} & 1/\sqrt{2} \\ 0 & -2/\sqrt{6} & 1/\sqrt{6} & 1/\sqrt{6} \end{vmatrix} \begin{vmatrix} 1 & 0 & 0 \\ 1 & 1 & 0 \\ 1 & 1 & 1 \end{vmatrix} = \begin{vmatrix} 2 & 3/2 & 1 \\ 0 & 3/\sqrt{2} & 3/\sqrt{2} \\ 0 & 0 & 3/\sqrt{6} \end{vmatrix}$$

- See R is upp. tri. and $\det(R) = 2 \cdot (3/\sqrt{2}) \cdot (2/\sqrt{6}) > 0$
so R is invertible
- Check that $A = QR$ for yourself.

Sect 6.5: Least-Squares Problems

Consider a system of equations where A is $m \times n$, x is $n \times 1$, b is $m \times 1$, and $m \gg n$

$$\begin{matrix} \boxed{A} \\ \boxed{x} \end{matrix} = \begin{matrix} \boxed{b} \end{matrix}$$

There are many more equations (rows) than variables (cols)
We call such system over-determined.

Oftentimes, over-determined systems have no exact \underline{x} such that $A\underline{x} = \underline{b}$. Instead, we try to find the "closest" solution, i.e., find an \underline{x} such that

$$A\underline{x} \approx \underline{b} \iff \underline{0} \approx \underline{b} - A\underline{x}$$

We define "closest" using a norm

$$\| \underline{b} - A\underline{x} \|$$

We want $\| \underline{b} - A\underline{x} \|$ to be as small as possible.

Note that

$$\| \underline{b} - A\underline{x} \| = \left(\sum_{i=1}^m (b_i - [A\underline{x}]_i)^2 \right)^{1/2}$$

We call these problems least-squares problems because the solution is the least sum of squares.

Def

If A is $m \times n$ and \underline{b} is in \mathbb{R}^m , a least-squares solution of $A\underline{x} = \underline{b}$ is $\hat{\underline{x}} \in \mathbb{R}^n$ such that

$$\| \underline{b} - A\hat{\underline{x}} \| \leq \| \underline{b} - A\underline{x} \|$$

for all $\underline{x} \in \mathbb{R}^n$.

What does a least-squares solution look like?

Geometrically,

