

Answers

MA 304 EXAM 2 — spring 2018

REMARKS There are 8 problems. Problems 1-4 are each worth 13 points while problems 5-8 are each worth 12 points. Show all *relevant* work. **NO CALCULATORS.**

1. Let S be the subspace of $C[a, b]$ spanned by e^x , xe^x , and x^2e^x . Let D be the differentiation operator of S . Find the matrix representing D with respect to $[e^x, xe^x, x^2e^x]$.

$$\begin{aligned} D e^x &= e^x \\ D x e^x &= x e^x + e^x \\ D x^2 e^x &= x^2 e^x + 2x e^x \end{aligned}$$

$$D_A = \begin{pmatrix} 1 & 1 & 0 \\ 0 & 1 & 2 \\ 0 & 0 & 1 \end{pmatrix}$$

2. Find the kernel and range of each of the following linear operators on P_3 which has a basis of $\{1, x, x^2\}$.

a. $L(p(x)) = xp'(x)$.

$$\begin{aligned} L(1) &= 0 \\ L(x) &= x \\ L(x^2) &= 2x \end{aligned}$$

$$\begin{aligned} R(L) &= \text{sp}\{x, x^2\} \\ N(L) &= \text{sp}\{1\} \end{aligned}$$

b. $L(p(x)) = p(x) - p'(x)$

$$\begin{aligned} L(1) &= 1 \\ L(x) &= x - 1 \\ L(x^2) &= x^2 - 2x \end{aligned} \quad L_A = \begin{pmatrix} 1 & -1 & 0 \\ 0 & 1 & -2 \\ 0 & 0 & 1 \end{pmatrix} \quad \det(L_A) = 1$$

$$\begin{aligned} R(L) &= \text{sp}\{1, x, x^2\} \\ N(L) &= \{0\} \end{aligned}$$

c. $L(p(x)) = p(0)x + p(1)$.

$$\begin{aligned} L(1) &= x + 1 \\ L(x) &= 0 + 1 \\ L(x^2) &= 0 + 1 \end{aligned}$$

$$\begin{aligned} R(L) &= \text{sp}\{1, x\} \\ N(L) &= \text{sp}\{x^2\} \end{aligned}$$

3. Let $L: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ be a linear operator. If

$$L((1, 2)^T) = (-2, 3)^T$$

and

$$L((1, -1)^T) = (5, 2)^T$$

find the value of $L((7, 5)^T)$.

$$\begin{aligned} a \begin{pmatrix} 1 \\ 2 \end{pmatrix} + b \begin{pmatrix} 1 \\ -1 \end{pmatrix} &= \begin{pmatrix} 7 \\ 5 \end{pmatrix} \Rightarrow \begin{pmatrix} 1 & 1 \\ 2 & -1 \end{pmatrix} \begin{pmatrix} a \\ b \end{pmatrix} = \begin{pmatrix} 7 \\ 5 \end{pmatrix} \\ \begin{pmatrix} a \\ b \end{pmatrix} &= -\frac{1}{3} \begin{pmatrix} -1 & -1 \\ -2 & 1 \end{pmatrix} \begin{pmatrix} 7 \\ 5 \end{pmatrix} \\ &= \frac{1}{3} \begin{pmatrix} 1 & 1 \\ 2 & -1 \end{pmatrix} \begin{pmatrix} 7 \\ 5 \end{pmatrix} \\ &= \frac{1}{3} \begin{pmatrix} 12 \\ 9 \end{pmatrix} = \begin{pmatrix} 4 \\ 3 \end{pmatrix} \end{aligned}$$

$$\begin{aligned} L \begin{pmatrix} 7 \\ 5 \end{pmatrix} &= 4L \begin{pmatrix} 1 \\ 2 \end{pmatrix} + 3L \begin{pmatrix} 1 \\ -1 \end{pmatrix} \\ &= 4 \begin{pmatrix} -2 \\ 3 \end{pmatrix} + 3 \begin{pmatrix} 5 \\ 2 \end{pmatrix} = \begin{pmatrix} 7 \\ 18 \end{pmatrix} \end{aligned}$$

4.

a. Find the standard matrix representation of the linear operator L which reflects each vector x about the line $x_2 = x_1$ and then projects it onto the x_1 -axis.

$$\begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

b. Let L be the linear transformation mapping P_2 into \mathbb{R}^2 defined by

$$L(p(x)) = \begin{bmatrix} \int_0^1 p(x) dx \\ p(0) \end{bmatrix}$$

Find a matrix A such that

$$L(1) \quad L(x) \\ \begin{pmatrix} 1 & 1/2 \\ 1 & 0 \end{pmatrix}$$

$$L(\alpha + \beta x) = A \begin{pmatrix} \alpha \\ \beta \end{pmatrix}$$

$$L(1) \quad L(x) \\ \begin{pmatrix} 1 & 1/2 \\ 1 & 0 \end{pmatrix}$$

$$\begin{aligned} &\begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} x \\ y \\ 1 \end{pmatrix} = \begin{pmatrix} y \\ 0 \\ 1 \end{pmatrix} \\ &\text{so } (x, y) \rightarrow (y, x) \\ &\begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} y \\ x \end{pmatrix} = \begin{pmatrix} y \\ 0 \end{pmatrix} \end{aligned}$$

$$\begin{aligned} &= \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 1 \end{pmatrix} \\ &L_M = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 1 \end{pmatrix} \end{aligned}$$

5. Let V be the subspace of $C[a, b]$ spanned by $1, e^x, e^{-x}$, and let D be the differentiation operator on V .

- a. Find the transition matrix S representing the change of coordinates from the ordered basis $[1, e^x, e^{-x}]$ to the ordered basis $[1, \cosh x, \sinh x]$ where $\cosh x = \frac{1}{2}(e^x + e^{-x})$ and $\sinh x = \frac{1}{2}(e^x - e^{-x})$.

bad - good

$$V = \begin{pmatrix} 1 & e^x & e^{-x} \\ 0 & 1/2 & 1/2 \\ 0 & 1/2 & -1/2 \end{pmatrix}$$

good to bad

$$V^{-1} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 1 \\ 0 & 1 & -1 \end{pmatrix}$$

- b. Find the matrix A representing D with respect to the ordered basis $[1, \cosh x, \sinh x]$.

$D(1) = 0$
 $D(\cosh x) = \sinh x$
 $D(\sinh x) = \cosh x$

$$A = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix}$$

6.

- a. Find the nearest point to the plane $6(x-1) + 2(y-3) + 3(z+4) = 0$ for the point $(2, 1, -2)$.

2 points in plane: $(1, 0, -2)$
 $(1, -3, 0)$

nearest point = (a, b, c) so

$[(a, b, c) - (2, 1, -2)] \cdot (1, 0, -2) = 0$
 $[(a, b, c) - (2, 1, -2)] \cdot (1, -3, 0) = 0$

- b. Find the distance from $(2, 1, -2)$ to the plane $6(x-1) + 2(y-3) + 3(z+4) = 0$.

$$d = \left| \frac{(2, 1, -2) \cdot (6, 2, 3)}{7} \right|$$

$C \rightarrow 6x + 2y + 3z = 0$
 $8/7$

7.

- a. Is it possible for a matrix to have the vector $(3, 1, 2)$ in its row space and $(2, 1, 1)^T$ in its null space? Explain.

NO! $N(A) \perp R(A^T)$

$$(2, 1, 1) \in N(A)$$

$$(3, 1, 2) \in R(A^T)$$

but $(2, 1, 1) \cdot (3, 1, 2) \neq 0$

- b. If A is an $m \times n$ matrix of rank r , what are the dimensions of $N(A)$ and $N(A^T)$? Explain.

$$A: \mathbb{R}^n \rightarrow \mathbb{R}^m$$

$$\dim N(A) + \underbrace{\dim R(A)}_r = n$$

$$\dim N(A) = n - r$$

$$\dim N(A^T) = m - r$$

$$\dim R(A^T) = \dim R(A) = r$$

$$A^T: \mathbb{R}^m \rightarrow \mathbb{R}^n$$

8. Find the best least squares fit by quadratic polynomials to the data $(-1, 0), (0, 1), (1, 3), (2, 9)$. (Write the answer in matrix form: Do not invert any matrix).

$$p(x) = a + bx + cx^2$$

$$\begin{pmatrix} 1 & -1 & 1 \\ 1 & 0 & 0 \\ 1 & 1 & 1 \\ 1 & 2 & 4 \end{pmatrix} \begin{pmatrix} a \\ b \\ c \end{pmatrix} = \begin{pmatrix} 0 \\ 1 \\ 3 \\ 9 \end{pmatrix}$$

$$A^T A \begin{pmatrix} a \\ b \\ c \end{pmatrix} = A^T \begin{pmatrix} 0 \\ 1 \\ 3 \\ 9 \end{pmatrix}$$