Sect 6.1: Inner Products, Length, and Orthogonlity

Goals: Extend R° & R° concepts for length,

distance, and perpendicularity to Rn.

Then, we look at the implications.

- · How long are vectors?
- · How "for" is one vector from mother?
- · What is the angle between two vectors?

All three of these greation are answered using the inner product.

Def For u and v in R", the inner product of u and v is given by

$$= U_{1}V_{1} + U_{2}V_{2} + \cdots + U_{n}V_{n} = \sum_{k=1}^{n} U_{k}V_{k}$$

Observations

· uTy is a scalar

-> 2 vectors give one number as output

· we often refer to the inner product on vectors as a dot product, written
$$u^{T}v = u \cdot v$$

For
$$u = \begin{vmatrix} 3 \\ 1 \\ -1 \end{vmatrix}$$
 and $y = \begin{vmatrix} 0 \\ 7 \\ 5 \end{vmatrix}$, then
$$u \cdot y = u^{T}y = \begin{vmatrix} 3 \\ 1 \\ -1 \end{vmatrix} = 3(0) + 1(2) + (-1)(5)$$

$$u \cdot y = 0 + 2 - 5 = -3$$

Properties of inner products (Thm)

Let u, v, and w be vector in Rⁿ, and let

c be a scalar in R, then

$$\frac{Pf.}{Pf.} \quad \text{for} \quad u = \begin{vmatrix} u_1 \\ u_2 \\ \vdots \\ u_n \end{vmatrix} \quad \text{and} \quad v = \begin{vmatrix} v_1 \\ v_2 \\ \vdots \\ v_n \end{vmatrix}, \quad \text{then we see}$$

$$\frac{u \cdot v}{v} = \begin{vmatrix} u_1 \\ u_2 \\ \vdots \\ u_n \end{vmatrix} \quad v = \begin{vmatrix} v_1 \\ v_2 \\ \vdots \\ v_n \end{vmatrix} = u_1 v_1 + u_2 v_2 + \dots + u_n v_n$$

$$= \begin{vmatrix} v_1 \\ v_1 \end{vmatrix} + \begin{vmatrix} v_2 \\ v_2 \end{vmatrix} + \dots + \begin{vmatrix} v_n \\ v_n \end{vmatrix} = \begin{vmatrix} v_1 \\ v_2 \end{vmatrix} + \begin{vmatrix} v_1 \\ v_2 \end{vmatrix} = \begin{vmatrix} v_1 \\ v_2 \end{vmatrix} + \begin{vmatrix} v_2 \\ v_2 \end{vmatrix} + \dots + \begin{vmatrix} v_n \\ v_n \end{vmatrix} = \begin{vmatrix} v_1 \\ v_2 \end{vmatrix} + \begin{vmatrix} v_2 \\ v_2 \end{vmatrix} + \dots + \begin{vmatrix} v_n \\ v_n \end{vmatrix} = \begin{vmatrix} v_1 \\ v_2 \end{vmatrix} + \begin{vmatrix} v_2 \\ v_2 \end{vmatrix} + \dots + \begin{vmatrix} v_n \\ v_n \end{vmatrix} = \begin{vmatrix} v_1 \\ v_2 \end{vmatrix} + \dots + \begin{vmatrix} v_n \\ v_n \end{vmatrix} + \begin{vmatrix} v_n \\ v_n$$

b)
$$(\underline{u} + \underline{v}) \cdot \underline{u} = \underline{u} \cdot \underline{w} + \underline{v} \cdot \underline{w}$$

$$\frac{Pf.}{Pf.} (\underline{u} + \underline{v}) \cdot \underline{w} = |\underline{u}_1 + \underline{v}_1 \quad \underline{u}_2 + \underline{v}_2 \quad \underline{u}_1 + \underline{v}_N | |\underline{w}_1| \\
= (\underline{u}_1 + \underline{v}_1) \underline{u}_1 + (\underline{u}_1 + \underline{v}_2) \underline{w}_2 + \dots + (\underline{u}_N + \underline{v}_N) \underline{u}_N \\
= (\underline{u}_1 + \underline{v}_1) \underline{u}_1 + (\underline{u}_1 + \underline{v}_2) \underline{w}_2 + \dots + (\underline{u}_N + \underline{v}_N) \underline{u}_N \\
= (\underline{u}_1 + \underline{v}_1) \underline{v}_1 + (\underline{v}_2 + \underline{v}_2 + \dots + \underline{u}_N) + (\underline{v}_1 \underline{u}_1 + \underline{v}_2 \underline{w}_2 + \dots + \underline{v}_N \underline{w}_N) \\
= (\underline{u}_1) \underline{v}_1 + (\underline{u}_2) \underline{v}_2 + \dots + (\underline{u}_N) \underline{v}_N \\
= (\underline{u}_1) \underline{v}_1 + (\underline{u}_2 + \dots + \underline{u}_N \underline{v}_N) = \underline{C} (\underline{u} \cdot \underline{v}) \\
= (\underline{u}_1) \underline{v}_1 + (\underline{u}_2 + \dots + \underline{u}_N \underline{v}_N) = \underline{C} (\underline{u} \cdot \underline{v}) \\
= \underline{u}_1 (\underline{v}_1) + \underline{u}_2 (\underline{v}_2) + \dots + \underline{u}_N (\underline{v}_N) = \underline{u}_1 (\underline{v}_N) \\
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= \underline{u}_1 \underline{u}_1 + \underline{u}_2 \underline{u}_2 + \dots + \underline{u}_N \underline{u}_N \\
= \underline{u}_1^2 + \underline{u}_2^2 + \dots + \underline{u}_N^2 \ge 0$$

because $U_k^2 \ge 0$ for all k = 1...n. Also we see $\underline{U} \cdot \underline{U} = 0$ if and only if $U_k^2 = 0$ for all $k = 1...n \Rightarrow U_k = 0$ for all $k = 1...n \Rightarrow U_k = 0$

Length of a Vector in \mathbb{R}^n In 2D, the length of a vector is something we see in geometry

He extend this idea analogously to IR1

The <u>norm</u> (or length) of a vector \underline{V} in \mathbb{R}^n is the non-negative scalar (≥ 0)

$$\| \underline{\vee} \| = \sqrt{\frac{2}{16}} + \sqrt{\frac{2}{16}} + \cdots + \sqrt{\frac{2}{16}}$$

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Ex Let $y = \begin{vmatrix} 3 \\ 4 \\ 0 \end{vmatrix}$, the $||y|| = \sqrt{3^2 + 4^2 + 0^2} = 5$

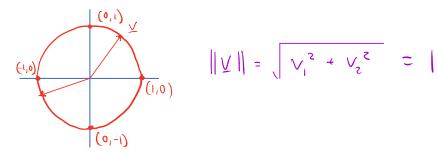
Notes

- · ue also call this the Encliden norm (there are others out there)
- We often look at the square of the norm $\|Y\| = \sqrt{Y \cdot Y} \iff \|Y\|^2 = Y \cdot Y$

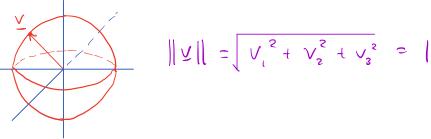
Def

We call any vector y with length (norm) $\|y\| = 1$ a unit vector. In \mathbb{R}^2 , that is

all points on circle of radius 1



In \mathbb{R}^2 , this is the surface of the unit sphere



Thought exercise: extend this idea in IR?

· He can always scale any vector so that it becomes a unit vector. This is called normalizing a vector.

So, we see that
$$\|\underline{y}\|$$

$$= \underline{y}$$

$$\|\underline{y}\|^{2} = (\underline{y} \cdot \underline{y})^{2}$$

$$= \underline{y} \cdot \underline{y} \cdot \underline{y}$$

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$$= \underline{y} \cdot \underline{y} \cdot \underline{y} \cdot \underline{y}$$

$$= \underline{y} \cdot \underline{$$

Note that normalizing a vector scales the length but does not change the direction

Find a unit vector
$$\underline{u}$$
 for $\underline{v} = \begin{bmatrix} 1 \\ -2 \\ 2 \end{bmatrix}$

$$\underline{u} = \underbrace{\underline{v}}_{\parallel \underline{v} \parallel} \text{ so we need } \|\underline{v}\|$$

$$\|\underline{v}\| = \underbrace{\begin{bmatrix} v_1^2 + v_2^2 + v_3^2 + v_4^2 \\ -1^2 + (-2)^2 + 2^2 + 0^2 \end{bmatrix}}_{= 1/2} \text{ always } \text{ take } + \frac{1}{2}$$

$$= \underbrace{\begin{bmatrix} 1^2 + (-2)^2 + 2^2 + 0^2 \\ -2 \end{bmatrix}}_{= 1/2} \text{ always } \text{ take } + \frac{1}{2}$$

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