

Coconut Rhinoceros Beetle Biological Control

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<https://github.com/aubreymoore/CRB-PPA19-Report3/raw/main/PPA19-report3.pdf>

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Notes for the Reader

- This progress report covers August 2020 through March 2021.
- Objectives and methods, as stated in the approved work plan [6] are presented in a frame at the start of each section.
- The University of Guam CRB biological control project is a long-term effort supported by multiple short-term grants. Some of the activities reported here have been partially funded by sources external to the FY19 APHIS-PPA CRB Biocontrol grant.

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1 Objective 1: CRB Control

The primary objective is to find an *Oryctes rhinoceros* nudivirus (OrNV) isolate which can be used as a highly effective biological control agent for long-term suppression of CRB-G populations. As soon as laboratory studies indicate discovery of an OrNV isolate which is a potential biological control agent for CRB, we will multiply the virus *in vivo* and initiate field releases under the conditions of an existing USDA-APHIS permit.

We have attained little progress towards completing our primary objective, which is to find an isolate of OrNV which is a promising candidate for biocontrol of CRB-G, because of COVID-19 travel restrictions and technical problems with our bioassays. Impediments towards progress are discussed in detail under the subobjectives entitled *Foreign Exploration for an Effective Biocontrol Agent for CRB-G* and *Establish Lab Colonies of CRB-G and CRB-S*.

1.1 Regional Collaboration

Work will continue with colleagues at AgResearch New Zealand, the Secretariat of the Pacific Community (SPC), Tokyo University, the University of Hawaii and others to put together a regional collaboration with the objective of finding an effective biocontrol agent for CRB-G.

1.1.1 Methods

- Moore and Grasela will participate in the CRB-G biocontrol meeting at the IAPPS meeting in Hyderabad, India, November 2019.
- Moore will continue to maintain a web site to facilitate exchange of information on CRB-G biocontrol.

1.1.2 Progress

Project staff promoted Pacific-wide collaboration among people trying to find solutions to the CRB problem by helping to organize professional meetings and by providing online tools to facilitate sharing of scientific and technical information.

CRB Action Group Meeting; December 9, 2020 This meeting was run as a Zoom webinar hosted by the University of Guam. A recording is available online.[\[5\]](#)

Agenda and Presentations:

- Regional Reports
- **Aubrey Moore:** Automated roadside video surveys for detecting and monitoring CRB damage to coconut palms. [\[9\]](#)
- **Sarah Mansfield:** Bioassays with OrNV: Progress and pitfalls.
- **Madoka Nakai and Shunsuke Tanaka:** Characterization of a Palauan isolate of *Oryctes rhinoceros* nudivirus (OrNV).
- **Kayvan Etebari:** Transcriptomic responses of different geographical populations of coconut rhinoceros beetles to *Oryctes rhinoceros* nudivirus (OrNV) infection.
- Open Discussion

CRB Action Group Meeting; March 17, 2021 This meeting was run as a Zoom webinar hosted by the University of Guam. A recording is available online [4].

Agenda and Presentations:

- Regional Reports
- **Sulav Paudel:** Review paper on biological control of CRB
- **Mark Ero:** Evaluation of CRB-G pheromone from the Solomon Islands
- **Lastus Kuniata:** Insecticide work in young oil palm in Solomon Islands
- **Katayo Sagata:** Evaluation of integrated management options in an oil palm cropping system in PNG
- Open Discussion

Rota CRB Eradication Program The PI made a presentation in a webinar organized by Department of the Interior - Office of Insular Affairs (DOI-OIA) entitled *CRB Biology: Know Your Enemy* [3]. This webinar will be converted into a podcast and published online by DOI-OIA which is supporting the Rota CRB Eradication Project with a \$250,000 grant.

LISTSERV The PI established a LISTSERV to facilitate email exchanges among members of the CRB Action Group.[2]

Online CRB Reference Library Project staff maintain an online reference library of technical and scientific information about coconut rhinoceros beetle.[8]

1.2 Foreign Exploration for an Effective Biocontrol Agent for CRB-G

Foreign exploration in search of a microbial biocontrol agent for CRB-G is already underway. During January, 2017, Moore, Iriarte and Marshall collected an isolate if OrNV from a CRB-G population in Negros Island, Philippines. Laboratory bioassays indicate that this isolate is not a good candidate for biocontrol.

We are currently performing laboratory bioassays to evaluate two novel isolates obtained from AgResearch New Zealand. In addition we are attempting to isolate OrNV from CRB adults collected in Taiwan. This population was targeted because Dr. Shizu Watanabe, University of Hawaii, reported an 82% OrNV infection rate in CRB-G collected from this island.

Our next target population is CRB-G found on the southern islands of Japan. We plan to collaborate with Dr. Madoka Nakai, Tokyo University of Agriculture and Technology, to obtain CRB-G/OrNV specimens from these islands.

1.2.1 Methods

- Subsamples of CRB collected during foreign exploration will be shipped to AgResearch New Zealand to determine CRB biotype and to isolate OrNV
- OrNV isolates collected during foreign exploration will be tested in the insect pathology lab at UOG using standard bioassay protocols.
- The PI and insect pathology post-doc will travel to Japan to collect CRB-G and OrNV,

1.2.2 Progress

check on permit
COVID

1.3 Establish Lab Colonies of CRB-G and CRB-S

We will establish sustainable laboratory colonies of CRB-G and virus susceptible beetles (CRB-S) as a source of healthy beetles for bioassays.

Note: Establishment of a CRB-S colony is contingent on receiving a USDA-APHIS import permit to import live coconut rhinoceros beetles. I requested a permit on March 19, 2019 (Application number P526-190319-001) to replace a previous permit, P526P-11-01844, which I accidentally allowed to lapse into oblivion after only one shipment.

If we are allowed to import CRB-S, this will allow us to do comparative studies to:

- Measure difference in susceptibility to OrNV isolates. (Resistance of CRB-G to OrNV has not yet actually been proven by comparative bioassays.)
- Test for behavioral differences. (It has been hypothesized that the aggregation pheromone, oryctalure, is less attractive to CRB-G than CRB-S.)

1.3.1 Methods

- Larvae and adults will be reared individually in Mason jars enclosed by metal caps. Larvae will be fed a store-bought steer manure/soil blend on which we have reared CRB larvae for many years. Adults will be bedded in peat moss and fed banana slices weekly.
- Mason jars will be placed in environmental cabinets set at 30 deg. C, 80% RH.
- Detailed records for each individual beetle will be stored in an existing online laboratory information management system (LIMS). These data will be made available to USDA-APHIS.

1.3.2 Progress

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COVID 2 attempts to visit AS

AS collection not done

PCR positives in controls

need standardized test insects

arrangement with UH

re-establish rearing colonies

2 Objective 2: Establish a Sustainable Coconut Palm Health Monitoring System

The CRB-G outbreak on Guam is currently unmonitored on an island-wide basis. An island-wide pheromone trapping system, using about 1500 traps, was operated by the University of Guam from 2008 to 2014. This monitoring system was transferred to the Guam Department of Agriculture which abandoned the effort at the end of February, 2016.

Currently, many coconut palms are being killed by CRB-G. But, in the absence of a monitoring system, we do not have an estimate of tree mortality or whether or not the damage is increasing or decreasing. Clearly, establishment of a monitoring system is necessary if we want to evaluate success of the proposed biocontrol project, or any other mitigation efforts.

Rather than re-establish a trapping survey, we intend to establish a monitoring system to track temporal and spatial changes in the extent of CRB damage to Guams coconut palms. Damage symptoms such as v-shaped cuts to fronds, bore holes, and dead standing coconut palm stems are readily observed during roadside surveys. Survey data will be collected using a digital video camera mounted on a truck. Initially, video images of coconut palm damage by CRB-G will be detected, classified and tagged by a technician. When a large number of images have been tagged, these will be used to train a fully automated CRB damage detection and monitoring system. This automated system may be useful as an early detection device for CRB. Roadside surveys on Guam will be performed bimonthly.

2.0.1 Methods

- A protocol will be developed to perform roadside surveys of CRB damage. Damage will be recorded using videos recorded by a vehicle-mounted Olympus TG-5 camera. This camera records GPS coordinates.
- Videos will be tagged using the open source Computer Vision Annotation Tool (CVAT).

- An object detector which locates and classifies CRB damage in video recordings will be trained using annotated videos from the previous step. We intend to use the TensorFlow implementation of the Faster R-CNN Deep Learning model. Training a CRB damage detector using deep learning requires use of a computer with specialized software (TensorFlow) and specialized hardware (a graphics processing unit (GPU)). Instead of purchasing a physical machine we will rent a virtual machine designed specifically for this application from Amazon Web Services.
- Results from the trained object detector will be evaluated using the human annotated videos.
- We will develop an automated processing system which takes roadside videos as input and generates CRB damage maps as output.

2.0.2 Progress

from DOI.

Damage symptoms such as v-shaped cuts to fronds, bore holes, and dead standing coconut palm stems are readily observed during roadside surveys. Survey data will be collected on a smart-phone dash-cam app which georeferences each image. Initially, images of coconut palm damage by CRB-G will be detected, classified and tagged by a technician. When a large number of images have been tagged, these will be used to train an object detector. This work will result in a fully automated CRB damage detection and monitoring system which generates detection alerts and damage maps. This automated system will be useful as an early detection device for CRB. Roadside surveys on Guam will be performed bimonthly and the system will also be tested on Tinian, an island just north of Guam on which CRB has never been detected.

The envisioned system has already been successfully prototyped. A custom object detector for CRB damage has been trained using the TensorFlow implementation of the Faster R-CNN Deep Learning model (Moore, unpublished).

Bimonthly automated roadside video surveys for CRB damage are now operational on Guam and the system has been tested on Rota. Videos recorded with a smart phone attached to a vehicle are analyzed using custom-designed artificial intelligence software which recognizes coconut palms and measures CRB damage. A nontechnical description of the survey method is given in the next section.

A presentation on this new CRB survey methodology was made at the December 9 2020 meeting of the CRB-G Action Group conducted as a Zoom webinar. Videos of all presentations at this meeting are available online [4].

Guam Roadside Video Survey 1 The following four images were extracted from a draft of the University of Guam's Western Pacific Tropical Research Center impact report for 2020. They provide a nontechnical overview of the new automated roadside video survey for CRB damage and results from the first Guam survey in October, 2020.

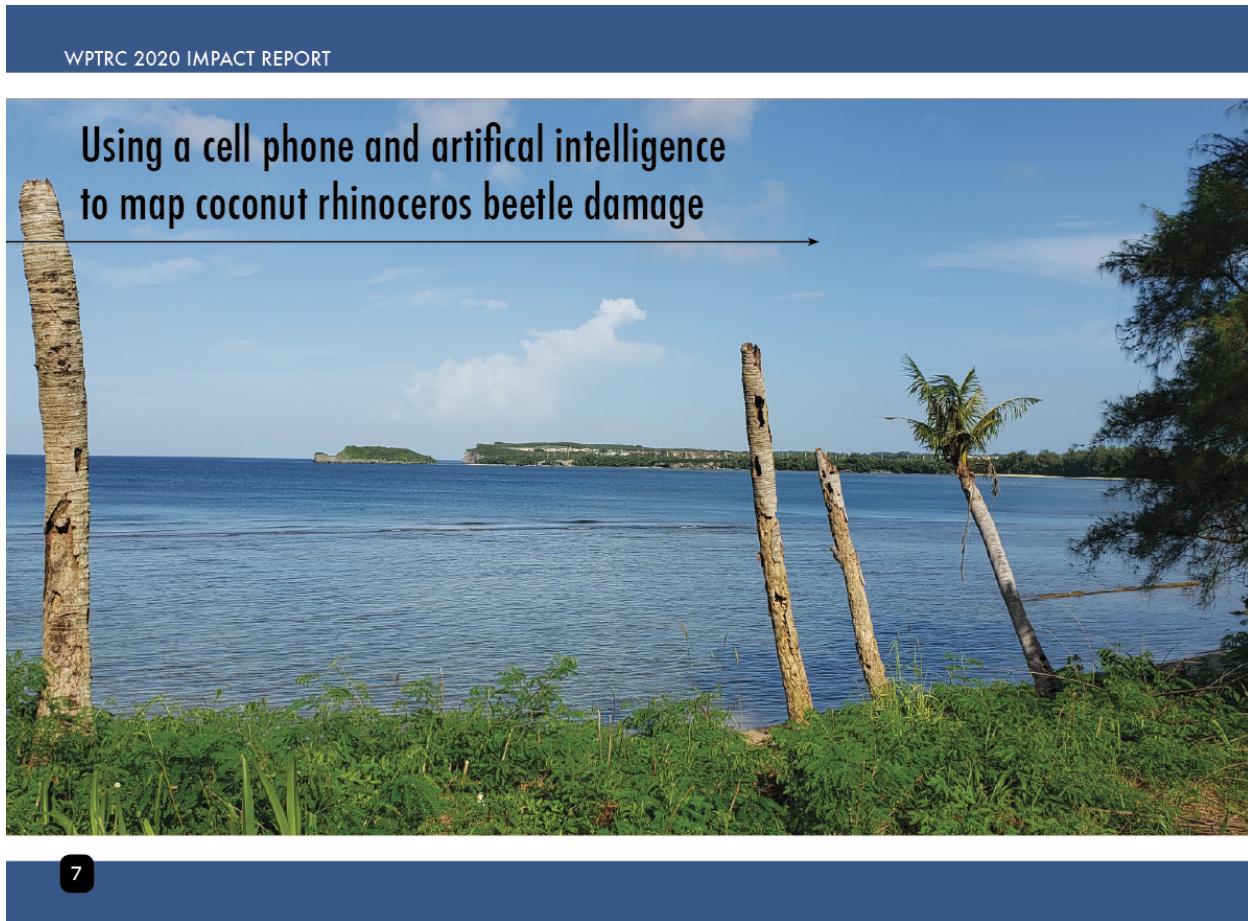


Figure 1: Feature article in the University of Guam's Western Pacific Tropical Research Center impact report for 2020.

Everyone living on Guam has seen damage to coconut palms caused by coconut rhinoceros beetles (CRB). CRB has been on Guam since 2007, however, until recently, the number of palms being damaged and killed on Guam was unknown. Standardized surveys of CRB damage are needed to monitor changes over time and space, especially in response to control activities and for early detection of CRB in new geographic areas.

UOG entomologist Aubrey Moore has developed a highly automated method for routine island-wide monitoring of CRB damage using a cell phone and artificial intelligence (AI).

Methods for monitoring CRB damage have been developed. But these rely on direct observation or image analysis by human experts and are too time-consuming and expensive for routine monitoring over large areas.

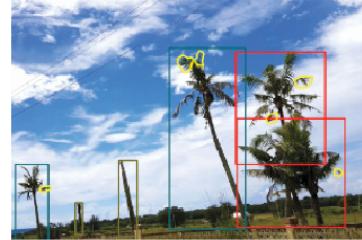
Dr. Trevor Jackson, an entomologist working for AgResearch New Zealand, has developed a survey method based on a five-level scale for classifying CRB damage to individual coconut palms. Jackson's method is being used extensively on CRB-infested islands in the South Pacific. Moore decided to develop an island-wide roadside CRB damage survey for Guam based on an automated version of Jackson's method.



A smart phone is attached to a vehicle using a magnetic mount. As the car travels, the phone records videos that are analyzed by open-source software.

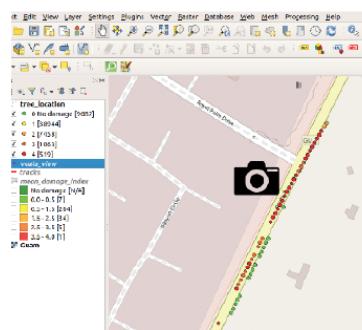
In the automated survey, a smart phone mounted on a car or truck records continuous videos while the vehicle is driven along all major roads on Guam. The smart phone uses a couple of free apps: OpenCamera records videos and GPSLogger records GPS coordinates.

Recent technical breakthroughs in AI have made it much easier to train computers to recognize objects in digital images. Moore collaborated with OnePanel Inc., an AI tech



Above: medium to severe CRB damage detected in the Royal Palms area of Dededo.

Below: each dot on the map represents a video frame in which one or more coconut palms was detected. The image at the top is a frame extract from a video with approximate at coordinates indicated by the camera icon.



Continue reading →

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Figure 2: [Continued] Feature article in the University of Guam's Western Pacific Tropical Research Center impact report for 2020.

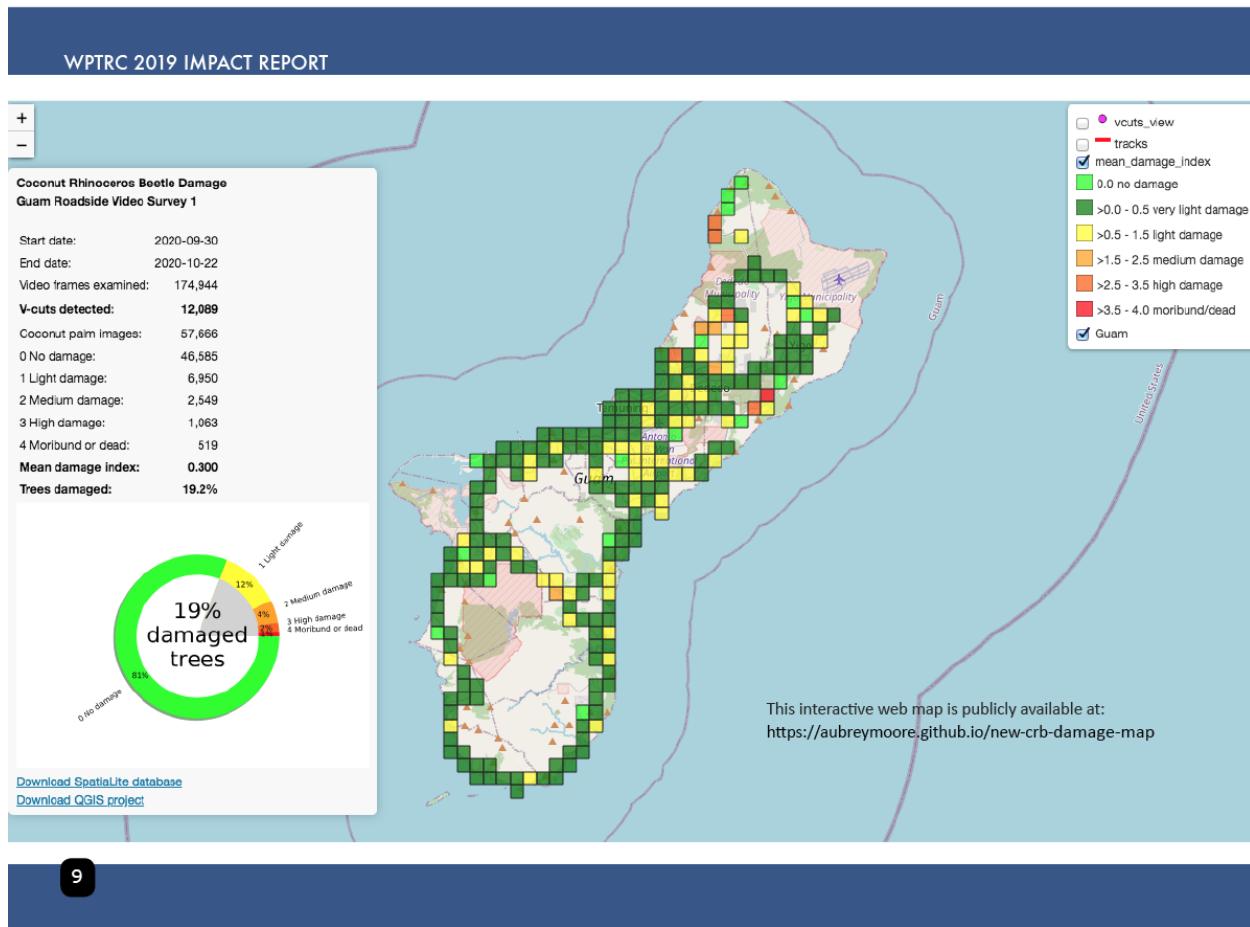


Figure 3: [Continued] Feature article in the University of Guam's Western Pacific Tropical Research Center impact report for 2020. This interactive web map is publicly available at: <https://aubreymoore.github.io/new-crb-damage-map>

company, to develop and train a couple of object detectors using a technique called “deep learning”.

The first object detector finds all images of coconut palms in the survey videos and classifies each one using Jackson’s damage scale. The second object detector locates and counts v-shaped cuts in the fronds of each coconut palm. Data extracted from the videos by the object detectors are saved in a SpatialLite database.

To visualize survey results, Moore uses Quantum GIS, to make a publicly available, interactive web map. There are links on the web map to download the survey database and QGIS map project for more detailed analysis.

The first operational island-wide survey on Guam, completed during October 2020, indicated that about 19% of Guam’s coconut palms show CRB damage symptoms. The Guam surveys will be conducted bimonthly. An island-wide roadside video survey is also being done on Rota for early detection of CRB damage.

There is interest in use of roadside video surveys for CRB damage elsewhere in the Pacific and Moore plans to evaluate drone imagery for use on islands without extensive roads. The Guam roadside video survey was designed to be adaptable by using only free



open-source software (FOSS) components. Custom-written software for the project as well videos, databases, and GIS projects from surveys will also be made available for download from public repositories hosted on GitHub.

It is interesting to note that this is not the first time that Moore has dabbled with AI. Thirty years ago he trained an artificial neural network to identify free-flying mosquitoes.

Funded by the US Department of the Interior-Office of Insular Affairs, US Forest Service, USDA-APHIS

Thanks to UOG entomology technician Christian Cayanan for doing the surveys.

Further reading:

Moore, A. 2018. The Guam Coconut Rhinoceros Beetle Problem: Past, Present and Future. Zenodo. doi.org/10.5281/zenodo.1185371}.

Moore, A. 1991. Artificial neural network trained to identify mosquitoes in flight. Journal of Insect Behavior 4, 391–396.

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Figure 4: [Continued] Feature article in the University of Guam’s Western Pacific Tropical Research Center impact report for 2020.

Guam Roadside Video Survey 2 The proportion of coconut palms damaged by CRB increased significantly from 19.2% in October 2020 to 21.5% in December 2020 ($p < 0.001$; Fisher's exact test).

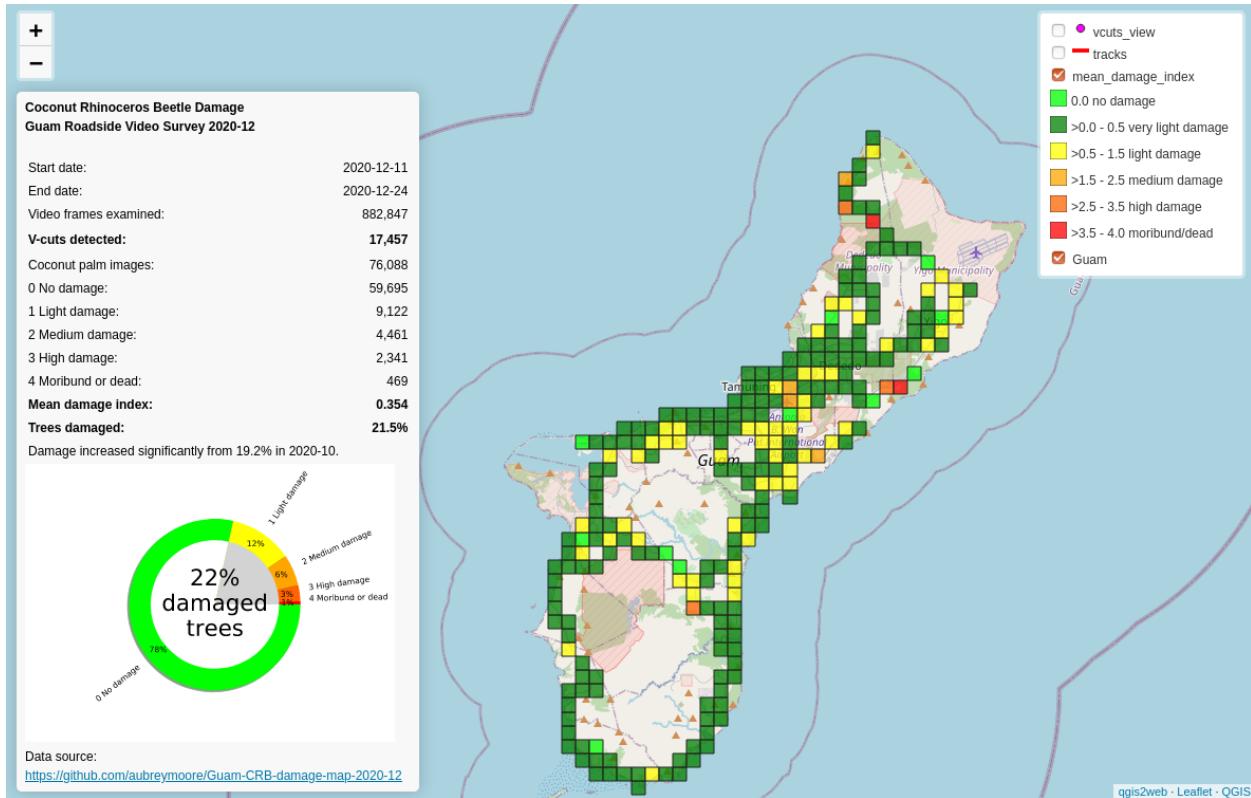


Figure 5: Screenshot of an interactive web map of results from a roadside video survey of CRB damage on Guam in December 2020 <https://aubreymoore.github.io/Guam-CRB-damage-map-2020-12/webmap/v1/>.

Rota Roadside Video Survey 1 Rota was invaded by CRB in 2017 and eradication efforts by Rota Department of Land and Natural Resources have successfully kept the population at a very low level, although the population has begun to spread to new areas of the island. In October 2020, a smart phone and associated equipment was sent to Rota-DLNR so that they could do an initial roadside video survey in support of their CRB control efforts. In addition to the equipment, a survey setup guide and [1] and a setup video [7] were prepared and sent.

The survey was performed by Mark Mangolana, Rota-DLNR and the phone containing videos from the survey was returned to the University of Guam. Videos were analyzed using the workflow developed for the Guam surveys. The resulting web map contained many false positives for CRB damage, but there is one hit which shows a classic v-shaped cut probably caused by CRB. For convenience, data for this hit (images, date, location) were documented as an iNaturalist observation (Figure 6). If this v-shaped cut was caused by CRB, there will be a bore hole. Rota-DLNR are following up to see if this is the case.

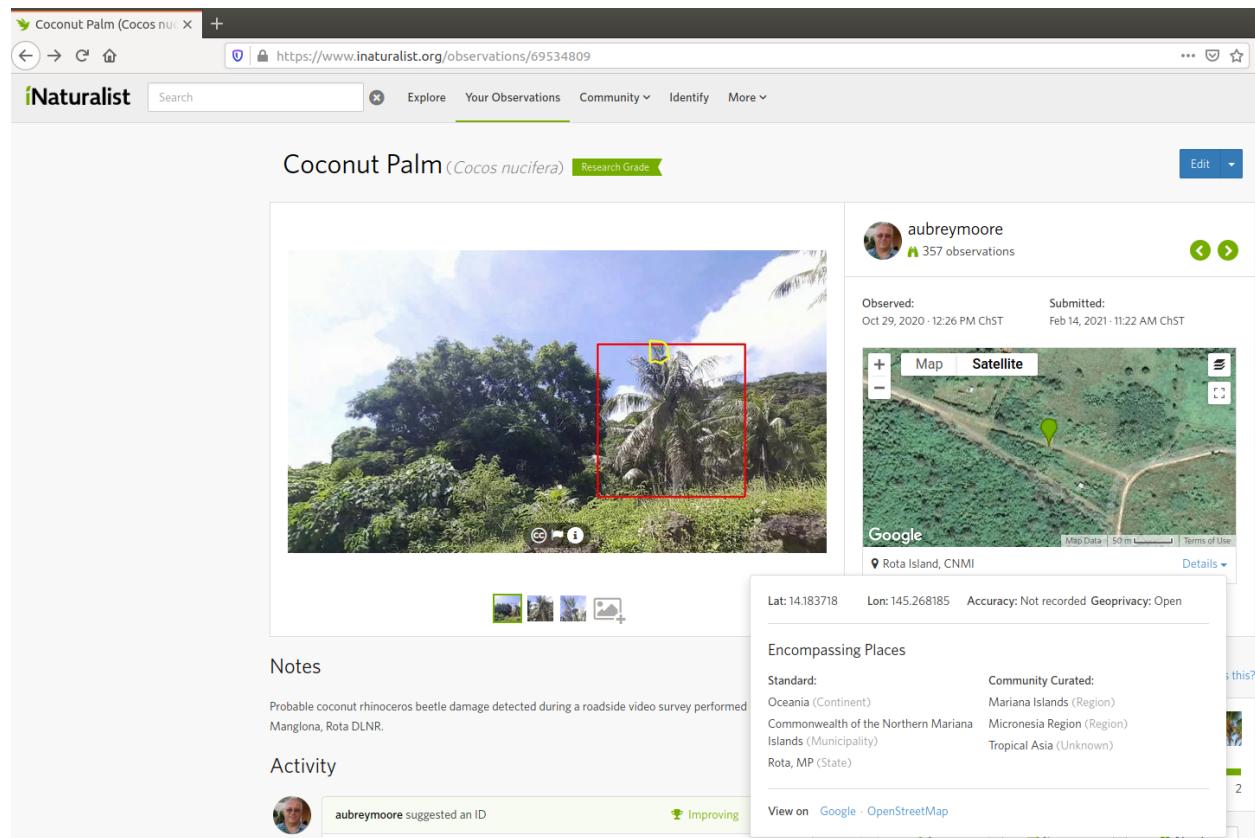


Figure 6: Screenshot of an iNaturalist observation documenting probable coconut rhinoceros beetle damage detected during a roadside video survey performed by Rota DLNR.
<https://www.inaturalist.org/observations/69534809>.

References

- [1] Aubrey Moore. *Set Up for Automated Roadside Video Surveys for Detecting and Monitoring Coconut Rhinoceros Beetle Damage on Rota*. Oct. 26, 2020. URL: <https://api.zotero.org/groups/511387/items/3X83KK58/file/view>.
- [2] Aubrey Moore. *An Online Email Discussion Site (LISTSERV) for the Coconut Rhinoceros Beetle Action Group*. 2021. URL: <http://crbg.guaminsects.net/listinfo.cgi/crbg-guaminsects.net>.
- [3] Aubrey Moore. “CRB Biology: Know Your Enemy”. Feb. 23, 2021. URL: <https://github.com/aubreymoore/CRB-CNMI/raw/main/CRB-Biology.pdf>.
- [4] Aubrey Moore. *Video Recording of the CRBG Action Group Meeting: December 9, 2020 [Conducted via Zoom]*. Dec. 9, 2020. URL: <https://aubreymoore.github.io/CRBG-action-group-webinar-20201209/>.
- [5] Aubrey Moore. *Video Recording of the CRBG Action Group Meeting: March 17, 2021 [Conducted via Zoom]*. Mar. 17, 2021. URL: <https://aubreymoore.github.io/CRB-Action-Group-Webinar-2021-03-17/>.
- [6] Aubrey Moore. *Work Plan for APHIS-PPA FY2019 Grant Entitled Biological Control of Coconut Rhinoceros Beetle Biotype G on Guam; Ammded 2020-05-18*. 2020. URL: <https://github.com/aubreymoore/FY2018-Farm-Bill-Suggestion/raw/master/extension-request/MooreFB19WorkPlan-amended.pdf>.
- [7] Aubrey Moore. *YouTube Video: Mounting a Smart Phone on a Vehicle for Roadside Video Surveys of Coconut Rhinoceros Beetle Damage*. 2020. URL: <https://www.youtube.com/watch?v=Pa-UslJV6BI>.
- [8] Aubrey Moore and James J. Grasela. *An Online Reference Library for the CRB Action Group*. 2021. URL: <https://aubreymoore.pythonanywhere.com/crblib>.
- [9] Aubrey Moore and Trevor Jackson. “Automated Roadside Video Surveys for Detecting and Monitoring Coconut Rhinoceros Beetle Damage to Coconut Palms. Presented at the Annual Meeting of the CRB-G Action Group.” Dec. 9, 2020. URL: <https://aubreymoore.github.io/crb-roadside-slides>.